

A homotopy based computational scheme for local fractional Helmholtz and Laplace equations

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In this work, we investigate solutions for the local fractional Helmholtz and Laplace equations on Cantor set having importance in electrostatics, gravitation and fluid dynamics. To find exact solutions, the q -local fractional homotopy analysis transform method (q -LFHATM) has been used. The numerical results computed with the aid of the applied scheme shows that it is an efficient and accurate tool to solve differential equations with local fractional derivatives.

Keywords: Local fractional derivative operator; Partial differential equations; Laplace equation; Helmholtz equation; q -local fractional homotopy analysis transform method.

1 Introduction

The concept of local fractional calculus (LFC) has been used to model and analyze numerous fractal equations some of which are Fokker-Planck equation [1, 2], fractal wave equations [3], fractal-time dynamical systems [4, 5], the local fractional stress strain relations [6], the local fractional heat conduction model [7], local fractional Tricomi equation [8], local fractional Laplace equations [9], the Helmholtz equation associated with local fractional operator [10], fractal signals [11, 12], fractal Fourier analysis [13], Yang Fourier transform [14, 15, 16], Yang-Laplace transform [15, 17], fractal vehicular traffic flow [18], local fractional modelling in growths of population [19], and Boussinesq equation containing local fractional operator [20], etc. Some recent outcomes of different authors on local fractional methods involving local fractional integral transforms can be seen in a series of articles [21, 22, 23].

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This work presents a very useful scheme known as the q -local fractional homotopy analysis transform method (q -LFHATM), which is a combination of q -HAM and the local fractional Laplace transform (LFLT). The proposed q -LFHATM is implemented to analyze the local fractional Helmholtz and Laplace equations. The merger of q -HAM and LFLT resulted in lesser C.P.U time (RAM-1 GB or more and Processor 2.65 GHz or more) while solving fractional-order nonlinear problems. The ability of the proposed method to achieve the series solution of local fractional Helmholtz and Laplace equations over a vast domain by picking approximate values for parameters is one of its advantages. El-Tavil & Huseen proposed the q -HAM [24, 25] which is a smooth generalization of the HAM. The HAM was first proposed and used by Liao [26, 27] to solve several problems found in engineering, science and finance.

The rest of the article is organized as follows: Section 2 reports basic definitions and formulae of LFC and LFLT. Section 3, the working of q -LFHATM is explained. The q -LFHATM is utilized to derive the solutions of local fractional Helmholtz and Laplace equations under different fractal conditions in Section 4. Section 5 presents the glimpse of numerical simulation for fractal order $\rho = \ln 2 / \ln 3$. At the end, conclusion is reported in Section 6.

2 Preliminaries

Here, we provide certain important concepts of LFC and LFLT.

Definition 2.1. If we have a relation [12, 28]

$$|\theta(t) - \theta(t_0)| < \varepsilon^\alpha, 0 < \alpha \leq 1, \tag{1}$$

with $|\theta(t) - \theta(t_0)| < \delta$, for $\varepsilon, \alpha \in R$, then the function $\theta(t)$ is said to be local fractional continuous (LFC) at $t = t_0$ and is indicated by $\lim_{t \rightarrow t_0} \theta(t) = \theta(t_0)$.

Here, $\theta(t)$ is called LFC on (a, b) and is expressed as

$$\theta(t) \in C_\alpha(a, b). \tag{2}$$

Definition 2.2. A function $\theta(t)$ is a nondifferentiable function of exponent α ($0 < \alpha \leq 1$) if it satisfies the Hölder function of the exponent α . Then for $t, s \in T$, we have [12, 28]

$$|\theta(t) - \theta(s)| < C |t - s|^\alpha. \tag{3}$$

Definition 2.3. $\theta(t)$ is said to be continuous of α , $0 < \alpha \leq 1$, or α continuous if there exists the following condition [12] $|\theta(t) - \theta(t_0)| < \varepsilon^\alpha$,

$$\theta(t) - \theta(t_0) = o((t - t_0)^\alpha). \tag{4}$$

In view of (4), Eq. (1) presents the standard form of local fractional continuity.

Definition 2.4. If $\theta(t) \in C_\alpha(a, b)$, then local fractional derivative (LFD) of $\theta(t)$ of order α at $x = x_0$ is written as [12, 28]:

$$\theta^{(\alpha)}(t_0) = \frac{d^\alpha}{dt^\alpha} \theta(t) |_{t=t_0} = \lim_{t \rightarrow t_0} \frac{\Delta^\alpha(\theta(t) - \theta(t_0))}{(t - t_0)^\alpha}, \tag{5}$$

where $\Delta^\alpha (\theta(t) - \theta(t_0)) \cong \Gamma(\alpha + 1) (\theta(t) - \theta(t_0))$.

For any $t \in (a, b)$, we have $\theta^{(\alpha)}(t) = D_t^\alpha \theta(t)$. The LFD of $m\alpha$ order is expressed as:

$$\theta^{(m\alpha)} \equiv \overbrace{D_t^\alpha \dots D_t^\alpha}^{m \text{ times}} \theta(t),$$

whereas the local fractional partial derivative (LFPD) of $m\alpha$ order is expressed as:

$$\frac{\partial^{m\alpha} \theta(t)}{\partial t^{m\alpha}} \equiv \overbrace{\frac{\partial^\alpha}{\partial t^\alpha} \dots \frac{\partial^\alpha}{\partial t^\alpha}}^{m \text{ times}} \theta(t).$$

Definition 2.5. Let $\frac{1}{\Gamma(1+\alpha)} \int_0^\infty |\theta(t)| (dt)^\alpha < m < \infty$. Then the Yang-Laplace (YL) transform [29, 30] of $\theta(t)$ is defined as:

$$L_\alpha \{ \theta(t) \} = \theta_s^{L,\alpha}(s) = \frac{1}{\Gamma(1+\alpha)} \int_0^\infty E_\alpha(-s^\alpha t^\alpha) \theta(t) (dt)^\alpha, 0 < \alpha \leq 1. \quad (6)$$

Here, the latter integral converges and $s^\alpha \in R^\alpha$.

Definition 2.6. The inverse of YL transform of $\theta(t)$ is stated as

$$L_\alpha^{-1} (\theta_s^{L,\alpha}(s)) = \theta(t) = \frac{1}{(2\pi)^\alpha} \int_{v-i\omega}^{v+i\omega} E_\alpha(s^\alpha t^\alpha) \theta_s^{L,\alpha}(s) (ds)^\alpha, 0 < \alpha \leq 1, \quad (7)$$

where $s^\alpha = v^\alpha + i^\alpha \omega^\alpha$; fractal imaginary unit i^α and $Re(s) = \alpha > 0$. Some useful formulae of LFLT [11, 12] are mentioned here:

$$L_\alpha \{ a\theta(t) + b\phi(t) \} = a\theta_s^{L,\alpha}(s) + b\phi_s^{L,\alpha}(s), \quad (8)$$

$$L_\alpha \{ E_\alpha(c^\alpha t^\alpha) \theta(t) \} = \theta_s^{L,\alpha}(s - c), \quad (9)$$

$$L_\alpha \{ \theta^{(m\alpha)}(t) \} = s^{m\alpha} \theta_s^{L,\alpha}(s) - s^{(m-1)\alpha} \theta(0) - s^{(m-2)\alpha} \theta^{(\alpha)}(0) - \dots - \theta^{((m-1)\alpha)}(0), \quad (10)$$

$$L_\alpha \{ E_\alpha(c^\alpha t^\alpha) \} = \frac{1}{s^\alpha - c^\alpha}, \quad (11)$$

$$L_\alpha \{ \sin_\alpha(c^\alpha t^\alpha) \} = \frac{c^\alpha}{s^{2\alpha} + c^{2\alpha}}, \quad (12)$$

$$L_\alpha \{ t^{m\alpha} \} = \frac{\Gamma(1+m\alpha)}{s^{(m+1)\alpha}}. \quad (13)$$

Definition 2.7. The Mittag-Leffler function (MLF) is formulated as [12, 28]

$$E_\alpha(t^\alpha) = \sum_{m=0}^\infty \frac{t^{m\alpha}}{\Gamma(1+m\alpha)}, 0 < \alpha \leq 1. \quad (14)$$

The following results hold true;

$$\begin{aligned} \sin_{\alpha}(t^{\alpha}) &= \sum_{m=0}^{\infty} (-1)^m \frac{t^{(2m+1)\alpha}}{\Gamma(1+(2m+1)\alpha)}, \\ \cos_{\alpha}(t^{\alpha}) &= \sum_{m=0}^{\infty} (-1)^m \frac{t^{2m\alpha}}{\Gamma(1+2m\alpha)}, 0 < \alpha \leq 1. \end{aligned} \tag{15}$$

Certain fundamental formulas and results used in the work are presented below:

$$\frac{d^{\alpha}t^{m\alpha}}{dt^{\alpha}} = \frac{\Gamma(1+m\alpha)t^{(m-1)\alpha}}{\Gamma(1+(m-1)\alpha)}, \tag{16}$$

$$\frac{d^{\alpha}E_{\alpha}(t^{\alpha})}{dt^{\alpha}} = E_{\alpha}(t^{\alpha}), \tag{17}$$

$$\frac{d^{\alpha}E_{\alpha}(mt^{\alpha})}{dt^{\alpha}} = mE_{\alpha}(mt^{\alpha}). \tag{18}$$

3 Working plan of q -LFHATM

To elucidate the procedure of q -LFHATM, the following nonlinear local fractional partial differential equation (LFPDE) is investigated

$$L_{\alpha} \varepsilon(\eta, \kappa) + R_{\alpha} \varepsilon(\eta, \kappa) + N_{\alpha} \varepsilon(\eta, \kappa) = h(\eta, \kappa), \quad n - 1 < \alpha \leq n, \tag{19}$$

where L_{α} indicates the linear local fractional operator, R_{α} indicates the remaining local linear differential operator, N_{α} stands for the nonlinear differential operator and $h(\eta, \kappa)$ signifies the source term.

Operating the LFLT on Eq. (19), we obtain

$$\begin{aligned} L_{\alpha} [\varepsilon(\eta, \kappa)] - s^{-\alpha} \varepsilon(\eta, 0) - s^{-2\alpha} \varepsilon^{(\alpha)}(\eta, 0) - \dots - s^{-t\alpha} \varepsilon^{((t-1)\alpha)}(\eta, 0) \\ + s^{-t\alpha} L_{\alpha} [R_{\alpha} \varepsilon(\eta, \kappa) + N_{\alpha} \varepsilon(\eta, \kappa) - h(\eta, \kappa)] = 0. \end{aligned} \tag{20}$$

We describe the nonlinear operator as:

$$\begin{aligned} N[\psi(\eta, \kappa; l)] = L_{\alpha} [\psi(\eta, \kappa; l)] - s^{-\alpha} \psi(\eta, \kappa; l)(0^+) - s^{-2\alpha} \psi^{(\sigma)}(\eta, \kappa; l)(0^+) - \dots \\ - s^{-t\alpha} \psi^{((t-1)\alpha)}(\eta, \kappa; l)(0^+) + s^{-t\alpha} L_{\alpha} [R_{\alpha} \varepsilon(\eta, \kappa) + N_{\alpha} \varepsilon(\eta, \kappa) - h(\eta, \kappa)]. \end{aligned} \tag{21}$$

In Eq. (21), $l \in [0, 1/n]$ and $\psi(\eta, \kappa; l)$ is a real valued function of η, κ & l . Now, the homotopy is framed as:

$$(1 - nl) L_{\alpha} [[\psi(\eta, \kappa; l) - \varepsilon_0(\eta, \kappa)] = \hbar l N [\varepsilon(\eta, \kappa)]. \tag{22}$$

In Eq. (22), L_{α} stands for the LFLT operator, $n \geq 1, l \in [0, 1/n]$ is an embedding variable, $\hbar \neq 0$ stands for an auxiliary parameter, $\varepsilon_0(\eta, \kappa)$ denotes initial guess (IG) of $\varepsilon(\eta, \kappa)$ and $\psi(\eta, \kappa; l)$ is an unidentified function. Clearly, for $l = 0$ and $l = \frac{1}{n}$, the results obtained are

$$\psi(\eta, \kappa; 0) = \varepsilon_0(\eta, \kappa), \quad \psi(\eta, \kappa; \frac{1}{n}) = \varepsilon(\eta, \kappa), \tag{23}$$

respectively. Therefore, when l approaches from 0 to $\frac{1}{n}$, $\psi(\eta, \kappa; l)$ changes from the IG $\varepsilon_0(\eta, \kappa)$ to solution $\varepsilon(\eta, \kappa)$. Taylor series expansion of $\psi(\eta, \kappa; l)$ provides

$$\psi(\eta, \kappa; l) = \sum_{m=0}^{\infty} \varepsilon_m(\eta, \kappa) l^m. \tag{24}$$

where

$$\varepsilon_m(\eta, \kappa) = \frac{1}{m!} \frac{\partial^m \psi(\eta, \kappa; l)}{\partial l^m} \Big|_{l=0}. \tag{25}$$

For proper values of $u_0(x, t), n$ and \hbar , the series (10) converges for $l = \frac{1}{n}$, then we obtain

$$\varepsilon(\eta, \kappa) = \sum_{m=0}^{\infty} \varepsilon_m(\eta, \kappa) \left(\frac{1}{n}\right)^m. \tag{26}$$

Now, the set of vectors is characterized as

$$\vec{\varepsilon}_m = \{\varepsilon_0(\eta, \kappa), \varepsilon_1(\eta, \kappa), \dots, \varepsilon_m(\eta, \kappa)\}. \tag{27}$$

Next, the m th-order deformation equation is composed as

$$L_\alpha [\varepsilon_m(\eta, \kappa) - \chi_m \varepsilon_{m-1}(\eta, \kappa)] = \hbar \mathfrak{R}_m(\vec{\varepsilon}_{m-1}). \tag{28}$$

Operating the inverse LFLT on Eq. (28), we obtain

$$\varepsilon_m(\eta, \kappa) = \chi_m \varepsilon_{m-1}(\eta, \kappa) + \hbar L_\alpha^{-1}[\mathfrak{R}_m(\vec{\varepsilon}_{m-1})]. \tag{29}$$

In Eq. (29), the value of $\mathfrak{R}_k(\vec{\phi}_{k-1})$ and χ_k are presented below

$$\mathfrak{R}_m(\vec{\varepsilon}_{m-1}) = \frac{1}{(m-1)!} \frac{\partial^{m-1} N[\varepsilon(\eta, \kappa; l)]}{\partial l^{m-1}} \Big|_{l=0}, \tag{30}$$

and

$$\chi_m = \begin{cases} 0, & m \leq 1, \\ n, & m > 1. \end{cases} \tag{31}$$

4 Illustrative examples

Example 4.1 Let us take the local fractional Helmholtz equation [10] as follows

$$\frac{\partial^{2\rho} \phi(u, v)}{\partial u^{2\rho}} + \frac{\partial^{2\rho} \phi(u, v)}{\partial v^{2\rho}} = \phi(u, v), 0 < \rho \leq 1 \tag{32}$$

with initial-boundary conditions given as:

$$\phi(0, v) = 0, \frac{\partial^\rho \phi(0, v)}{\partial u^\rho} = E_\rho(v^\rho). \tag{33}$$

Applying LFLT on Eq. (32), we obtain

$$L_\rho \{\phi(u, v)\} - s^\rho \phi(0, v) - s^{-2\rho} \frac{\partial^\rho \phi(0, v)}{\partial u^\rho} + s^{-2\rho} L_\rho \left\{ \frac{\partial^{2\rho} \phi(u, v)}{\partial^{2\rho} v} - \phi(u, v) \right\} = 0,$$

or

$$L_\rho \{ \phi(u, v) \} - s^{-2\rho} E_\rho (y^\rho) + s^{-2\rho} L_\rho \left\{ \frac{\partial^{2\rho} \phi(u, v)}{\partial v^{2\rho}} - \phi(u, v) \right\} = 0. \quad (34)$$

The nonlinear operator is defined as

$$N[\psi(\eta, \kappa; l)] = L_\rho [\psi(\eta, \kappa; l)] - s^{-2\rho} E_\rho (y^\rho) + s^{-2\rho} L_\rho \left\{ \frac{\partial^{2\rho} \psi(\eta, \kappa; l)}{\partial v^{2\rho}} - \psi(\eta, \kappa; l) \right\}, \quad (35)$$

and so

$$\begin{aligned} \mathfrak{R}_m \left(\vec{\phi}_{m-1} (u, v) \right) &= L_\rho \{ \phi_{m-1} (u, v) \} \\ &- \left(1 - \frac{\chi_m}{n} \right) s^{-2\rho} E_\rho (v^\rho) + s^{-2\rho} L_\rho \left[\frac{\partial^{2\rho} \phi_{m-1} (u, v)}{\partial v^{2\rho}} - \phi_{m-1} (u, v) \right]. \end{aligned} \quad (36)$$

The m th-order deformation equation is built as

$$L_\rho \{ \phi_m (u, v) - \chi_m \phi_{m-1} (u, v) \} = \hbar \mathfrak{R}_m \left(\vec{\phi}_{m-1} (u, v) \right). \quad (37)$$

Applying inverse LFLT on Eq. (37), we obtain

$$\phi_m (u, v) = \chi_m \phi_{m-1} (u, v) + \hbar L_\rho^{-1} \left\{ \mathfrak{R}_m \left(\vec{\phi}_{m-1} (u, v) \right) \right\}. \quad (38)$$

For $m = 1$, we have

$$\phi_1 (u, v) = \chi_1 \phi_0 (u, v) + \hbar L_\rho^{-1} \left\{ \mathfrak{R}_1 \left(\vec{\phi}_0 (u, v) \right) \right\}$$

or

$$\phi_1 (u, v) = -\hbar E_\rho (v^\rho) \frac{u^\rho}{\Gamma(1 + \rho)}. \quad (39)$$

For $m = 2$, we have

$$\phi_2 (u, v) = \chi_2 \phi_1 (u, v) + \hbar L_\rho^{-1} \left\{ \mathfrak{R}_2 \left(\vec{\phi}_1 (u, v) \right) \right\},$$

or

$$\phi_2 (u, v) = -(n + \hbar) \hbar E_\rho (v^\rho) \frac{u^\rho}{\Gamma(1 + \rho)}. \quad (40)$$

For $m = 3$, we have

$$\phi_3 (u, v) = \chi_3 \phi_2 (u, v) + \hbar L_\rho^{-1} \left\{ \mathfrak{R}_3 \left(\vec{\phi}_2 (u, v) \right) \right\},$$

or

$$\phi_3 (u, v) = -(n + \hbar) \hbar^2 E_\rho (v^\rho) \frac{u^\rho}{\Gamma(1 + \rho)}, \quad (41)$$

& so on.

Hence, the nondifferentiable solution is expressed as

$$\phi(u, v) = \sum_{m=0}^{\infty} \phi_m(u, v) \left(\frac{1}{n}\right)^m.$$

$$\phi(u, v) = \phi_0(u, v) + \frac{\phi_1(u, v)}{n} + \frac{\phi_2(u, v)}{n^2} + \frac{\phi_3(u, v)}{n^3} + \dots$$

or

$$\phi(u, v) = \frac{1}{n} \left[\hbar E_{\rho}(v^{\rho}) \frac{u^{\rho}}{\Gamma(1+\rho)} \right] - \frac{1}{n^2} \left[(n + \hbar) \hbar E_{\rho}(v^{\rho}) \frac{u^{\rho}}{\Gamma(1+\rho)} \right]$$

$$- \frac{1}{n^3} \left[(n + \hbar) \hbar^2 E_{\rho}(v^{\rho}) \frac{u^{\rho}}{\Gamma(1+\rho)} \right] + \dots \tag{42}$$

On letting $\hbar = -1$ and $n = 1$, one can achieve the result

$$\phi(u, v) = \frac{u^{\rho}}{\Gamma(1+\rho)} E_{\rho}(v^{\rho}). \tag{43}$$

which is the solution of fractal problem (32).

Example 4.2 Take the following local fractional Laplace equation [9]

$$\frac{\partial^{2\rho} \phi(u, v)}{\partial u^{2\rho}} + \frac{\partial^{2\rho} \phi(u, v)}{\partial v^{2\rho}} = 0, 0 < \rho \leq 1, \tag{44}$$

with initial-boundary conditions given as:

$$\phi(0, v) = -E_{\rho}(v^{\rho}), \frac{\partial^{\rho} \phi(0, v)}{\partial u^{\rho}} = 0. \tag{45}$$

Applying LFLT on Eq. (44), we obtain

$$L_{\rho} \{ \phi(u, v) \} - s^{-\rho} \phi(0, v) - s^{-2\rho} \frac{\partial^{\rho} \phi(0, v)}{\partial u^{\rho}} + s^{-2\rho} L_{\rho} \left\{ \frac{\partial^{2\rho} \phi(u, v)}{\partial^{2\rho} v} \right\} = 0,$$

or

$$L_{\rho} \{ \phi(u, v) \} + s^{-\rho} E_{\rho}(y^{\rho}) + s^{-2\rho} L_{\rho} \left\{ \frac{\partial^{2\rho} \phi(u, v)}{\partial^{2\rho} v} \right\} = 0. \tag{46}$$

The nonlinear operator is

$$N[\psi(\eta, \kappa; l)] = L_{\rho} [\psi(\eta, \kappa; l)] + s^{-\rho} E_{\rho}(y^{\rho}) + s^{-2\rho} L_{\rho} \left\{ \frac{\partial^{2\rho} \psi(\eta, \kappa; l)}{\partial^{2\rho} v} \right\}, \tag{47}$$

and so

$$\mathfrak{R}_m \left(\vec{\phi}_{m-1}(u, v) \right) = L_{\rho} \{ \phi_{m-1}(u, v) \}$$

$$+ \left(1 - \frac{\chi_m}{n} \right) s^{-\rho} E_{\rho}(v^{\rho}) + s^{-2\rho} L_{\rho} \left[\frac{\partial^{2\rho} \phi_{m-1}(u, v)}{\partial v^{2\rho}} \right]. \tag{48}$$

The m th-order deformation equation is constituted as:

$$L_\rho \{ \phi_m(u, v) - \chi_m \phi_{m-1}(u, v) \} = \hbar \mathfrak{R}_m \left(\vec{\phi}_{m-1}(u, v) \right). \tag{49}$$

Operating the inverse LFLT, we obtain

$$\phi_m(u, v) = \chi_m \phi_{m-1}(u, v) + \hbar L_\rho^{-1} \left\{ \mathfrak{R}_m \left(\vec{\phi}_{m-1}(u, v) \right) \right\}. \tag{50}$$

Taking $m = 1, 2, 3, \dots$, we get

For $m = 1$

$$\phi_1(u, v) = -\hbar E_\rho(v^\rho) \frac{u^{2\rho}}{\Gamma(1+2\rho)}. \tag{51}$$

For $m = 2$

$$\phi_2(u, v) = -(n + \hbar) \hbar E_\rho(v^\rho) \frac{u^{2\rho}}{\Gamma(1+2\rho)} - \hbar^2 E_\rho(v^\rho) \frac{u^{4\rho}}{\Gamma(1+4\rho)}. \tag{52}$$

For $m = 3$

$$\begin{aligned} \phi_3(u, v) = & -(n + \hbar)^2 \hbar E_\rho(v^\rho) \frac{u^{2\rho}}{\Gamma(1+2\rho)} - 2(n + \hbar) \hbar^2 E_\rho(v^\rho) \frac{u^{4\rho}}{\Gamma(1+4\rho)} \\ & - \hbar^3 E_\rho(v^\rho) \frac{u^{6\rho}}{\Gamma(1+6\rho)}, \end{aligned} \tag{53}$$

& so on.

Hence, the nondifferentiable solution is presented as

$$\begin{aligned} \phi(u, v) = & -\frac{1}{n} \left[\hbar E_\rho(v^\rho) \frac{u^{2\rho}}{\Gamma(1+2\rho)} \right] - \frac{1}{n^2} \left[(n + \hbar) \hbar E_\rho(v^\rho) \frac{u^{2\rho}}{\Gamma(1+2\rho)} - \hbar^2 E_\rho(v^\rho) \frac{u^{4\rho}}{\Gamma(1+4\rho)} \right] \\ & - \frac{1}{n^3} \left[(n + \hbar)^2 \hbar E_\rho(v^\rho) \frac{u^{2\rho}}{\Gamma(1+2\rho)} + 2(n + \hbar) \hbar^2 E_\rho(v^\rho) \frac{u^{4\rho}}{\Gamma(1+4\rho)} + \hbar^3 E_\rho(v^\rho) \frac{u^{6\rho}}{\Gamma(1+6\rho)} \right] + \dots \end{aligned} \tag{54}$$

Setting $\hbar = -1$ and $n = 1$, one can have

$$\phi(u, v) = E_\rho(v^\rho) \left(-1 + \frac{u^{2\rho}}{\Gamma(1+2\rho)} - \frac{u^{4\rho}}{\Gamma(1+4\rho)} + \frac{u^{6\rho}}{\Gamma(1+6\rho)} - \dots \right).$$

It can be written as

$$\phi(u, v) = E_\rho(v^\rho) \left(\sum_{m=0}^{\infty} (-1)^m \frac{u^{2m\rho}}{\Gamma(1+2m\rho)} \right).$$

The solution of Eq. (44) is constituted as

$$\phi(u, v) = E_\rho(v^\rho) \cos_\rho(u^\rho). \tag{55}$$

Example 4.3 Finally, the following Laplace equation with LFD [9] is investigated

$$\frac{\partial^{2\rho}\phi(u, v)}{\partial u^{2\rho}} + \frac{\partial^{2\rho}\phi(u, v)}{\partial v^{2\rho}} = 0, 0 < \rho \leq 1 \tag{56}$$

with initial-boundary conditions given as:

$$\phi(0, v) = 0, \frac{\partial^\rho\phi(0, v)}{\partial u^\rho} = -E_\rho(y^\rho). \tag{57}$$

Applying LFLT on Eq. (56), we obtain

$$L_\rho\{\phi(u, v)\} - s^{-\rho}\phi(0, v) - s^{-2\rho}\frac{\partial^\rho\phi(0, v)}{\partial u^\rho} + s^{-2\rho}L_\rho\left\{\frac{\partial^{2\rho}\phi(u, v)}{\partial^{2\rho}v}\right\} = 0$$

or

$$L_\rho\{\phi(u, v)\} + s^{-2\rho}E_\rho(y^\rho) + s^{-2\rho}L_\rho\left\{\frac{\partial^{2\rho}\phi(u, v)}{\partial^{2\rho}v}\right\} = 0. \tag{58}$$

The nonlinear operator is constituted as

$$N[\psi(\eta, \kappa; l)] = L_\rho[\psi(\eta, \kappa; l)] + s^{-2\rho}E_\rho(y^\rho) + s^{-2\rho}L_\rho\left\{\frac{\partial^{2\rho}\psi(\eta, \kappa; l)}{\partial^{2\rho}v}\right\}, \tag{59}$$

and so

$$\begin{aligned} \mathfrak{R}_m\left(\vec{\phi}_{m-1}(u, v)\right) &= L_\rho\{\phi_{m-1}(u, v)\} \\ &+ \left(1 - \frac{\chi_m}{n}\right) s^{-2\rho}E_\rho(v^\rho) + s^{-2\rho}L_\rho\left[\frac{\partial^{2\rho}\phi_{m-1}(u, v)}{\partial v^{2\rho}}\right]. \end{aligned} \tag{60}$$

Next, we present the m th-order deformation equation as

$$L_\rho\{\phi_m(u, v) - \chi_m\phi_{m-1}(u, v)\} = \hbar\mathfrak{R}_m\left(\vec{\phi}_{m-1}(u, v)\right). \tag{61}$$

Applying the inverse LFLT, we obtain

$$\phi_m(u, v) = \chi_m\phi_{m-1}(u, v) + \hbar L_\rho^{-1}\left\{\mathfrak{R}_m\left(\vec{\phi}_{m-1}(u, v)\right)\right\}. \tag{62}$$

Taking $m = 1, 2, 3, \dots$, we get

For $m = 1$, we have

$$\phi_1(u, v) = \hbar E_\rho(v^\rho) \frac{u^\rho}{\Gamma(1 + \rho)}. \tag{63}$$

For $m = 2$, we obtain

$$\phi_2(u, v) = (n + \hbar) \hbar E_\rho(v^\rho) \frac{u^\rho}{\Gamma(1 + \rho)} + \hbar^2 E_\rho(v^\rho) \frac{u^{3\rho}}{\Gamma(1 + 3\rho)}. \tag{64}$$

For $m = 3$, we find

$$\phi_3(u, v) = (n + \hbar)^2 \hbar E_\rho(v^\rho) \frac{u^\rho}{\Gamma(1 + \rho)}$$

$$+2(n + \hbar) \hbar^2 E_\rho(v^\rho) \frac{u^{3\rho}}{\Gamma(1 + 3\rho)} + \hbar^3 E_\rho(v^\rho) \frac{u^{5\rho}}{\Gamma(1 + 5\rho)}, \quad (65)$$

Hence, the nondifferentiable solution is

$$\phi(u, v) = \sum_{m=0}^{\infty} \phi_m(u, v) \left(\frac{1}{n}\right)^m.$$

or

$$\begin{aligned} \phi(u, v) = & \frac{1}{n} \left[\hbar E_\rho(v^\rho) \frac{u^\rho}{\Gamma(1 + \rho)} \right] + \frac{1}{n^2} \left[(n + \hbar) \hbar E_\rho(v^\rho) \frac{u^\rho}{\Gamma(1 + \rho)} - \hbar^2 E_\rho(v^\rho) \left(\frac{u^{3\rho}}{\Gamma(1 + 3\rho)} \right) \right] \\ & + \frac{1}{n^3} \left[(n + \hbar)^2 \hbar E_\rho(v^\rho) \frac{u^\rho}{\Gamma(1 + \rho)} + 2(n + \hbar) \hbar^2 E_\rho(v^\rho) \frac{u^{3\rho}}{\Gamma(1 + 3\rho)} + \hbar^3 E_\rho(v^\rho) \frac{u^{5\rho}}{\Gamma(1 + 5\rho)} \right] + \dots \end{aligned} \quad (66)$$

On using the values $\hbar = -1$ and $n = 1$, we have

$$\phi(u, v) = E_\rho(v^\rho) \left(-\frac{u^\rho}{\Gamma(1 + \rho)} + \frac{u^{3\rho}}{\Gamma(1 + 3\rho)} - \frac{u^{5\rho}}{\Gamma(1 + 5\rho)} + \dots \right).$$

The solution of Eq. (56) in closed form is expressed as

$$\phi(u, v) = E_\rho(v^\rho) \left(\sum_{m=0}^{\infty} (-1)^m \frac{u^{(2m+1)\rho}}{\Gamma(1 + (2m + 1)\rho)} \right).$$

or

$$\phi(u, v) = E_\rho(v^\rho) \sin_\rho(u^\rho). \quad (67)$$

5 Numerical simulation

This section presents numerical outcomes for fractal problem given in Examples 4.1-4.3 under fractal initial-boundary conditions. The 3D graphs for the local fractional Helmholtz and Laplace equations are demonstrated on the Cantor set for the fractal order $\rho = \ln 2 / \ln 3$ via MATLAB. The graphics authenticates that the achieved solutions for Examples 4.1-4.3 depend on the fractal order ρ of the LFD. The 3D graphical visuals show the fractal pattern of the nondifferentiable function $\phi(u, v)$ in Examples 4.1-4.3.

6 Conclusions

In this work, the q -LFHATM is utilized to obtain the nondifferentiable solutions for the Helmholtz and Laplace equation in fractal media. The computed results establish the reliability and efficiency of the proposed technique and the applied method can be used to solve many other LFPDEs arising in fractal media. Finally, the computer simulations are also presented for fractal analysis of local fractional Helmholtz and Laplace models.

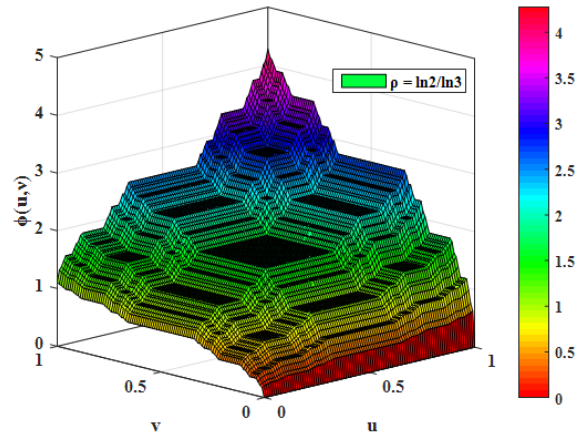


Figure 1: 3D nature of $\phi(u, v)$ w.r.t. u and v for Example 4.1

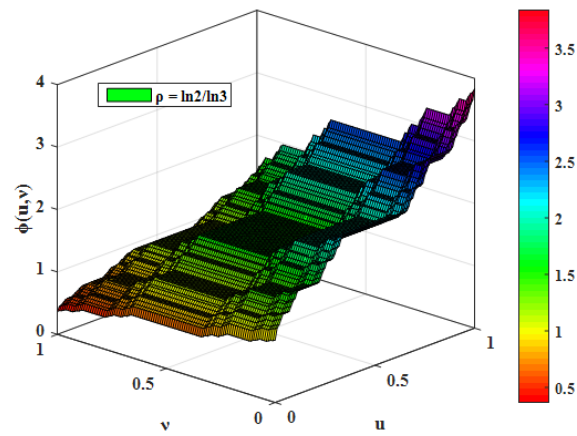


Figure 2: 3D behavior of $\phi(u, v)$ w.r.t. u and v for Example 4.2

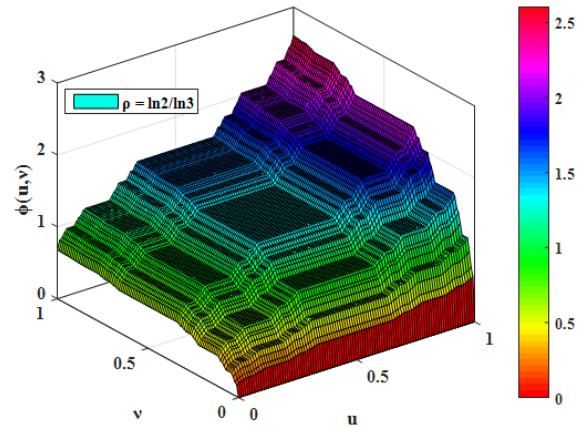


Figure 3: 3D pattern of $\phi(u, v)$ w.r.t. u and v for Example 4.3

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