

# Distributed Edge Computing For Resource Allocation In Mmtc Using Non-Linear Stochastic Optimization

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## ABSTRACT

This research work investigates distributed edge computing for efficient resource allocation in mMTC networks by means of non-linear stochastic optimisation techniques. The non-linear and stochastic nature of the communication channels as well as the irregular behaviour of IoT devices complicate the resource allocation in mMTC greatly. In this study, we propose a novel method using networked edge computing to optimise resource allocation in demanding settings. Using a non-linear stochastic optimisation algorithm, the method dynamically adjusts resource allocation decisions depending on real-time network conditions and device requirements so improving the overall network performance. Simulations produce results demonstrating the quality of the recommended strategy. More precisely, our approach boosts resource economy by 28% and lowers latency by 35% vs to typical centralised systems. Moreover, the recommended architecture increases the scalability of the network therefore enabling up to 50% more devices without compromising speed. These results draw attention to how distributed edge computing could address the critical resource allocation issues in mMTC systems.

**Keywords:** mMTC, distributed edge computing, resource allocation, non-linear stochastic optimization, IoT scalability

## 1. INTRODUCTION

Driven by the fast expansion of Internet of Things (IoT) devices and the growing demand for high-speed, low-latency connectivity [1], mobile networks have evolved towards ever more complicated structures. One such advancement as it brings processing resources closer to end users, therefore reducing latency and improving general network efficiency is adoption of edge computing [2]. Mass machine type communications (mMTC) significantly benefit from edge computing since so many linked devices offer notable data flow [3].

The effectiveness of edge computing depends on efficient resource allocation; the dynamic and changeable character of mMTC environments [4]-[9] complicates this further.

In edge computing for mMTC, efficient resource allocation causes many challenges:

1. Devices put in mMTC environments exhibit varied and irregular communication patterns, which complicates resource allocation.
2. The sheer volume of devices and data traffic calls for scalable systems able to control the huge volatility in resource need.
3. The real-time applications and services rely on lower latency attained by means of resource distribution among numerous edge nodes.
4. Fair distribution of resources among devices helps to maintain quality of service and prevent performance degradation for less priority devices.

Usually unable to manage the complexity and scope of modern edge computing networks, conventional methods like heuristic-based algorithms and centralised processes

The primary objectives of this study are:

- To correctly govern resources in edge computing environments by means of a distributed resource allocation method leveraging adaptive optimisation and real-time feedback.
- Minimisation of latency by way of resource allocation among numerous edge nodes
- To maximise resource consumption by ensuring that given resources are distributed properly depending on network conditions and present demands.
- To increase fairness in the distribution of resources so that every device receives a fair share, therefore preventing performance variations.

The proposed approach is novel in that it combines feedback loop mechanism-based distributed coordinating with non-linear stochastic optimisation. Unlike traditional methods dependent on static or heuristic-based approaches, the proposed method dynamically alters resource allocation depending on real-time performance measures and stochastic variability. This adaptability helps the system to better control the complexity and unpredictability of mMTC environments.

The key contributions of this study are:

- The proposed approach offers a fresh distributed coordination mechanism employing local and global information, therefore enabling efficient resource management among edge nodes.
- By means of advanced optimisation strategies to solve non-linearity and stochastic variability, the strategy enhances resource allocation and system performance.
- Including a real-time feedback loop guarantees continuous optimisation since it helps to constantly optimise and change resource allocation depending on performance observed.

## 2. RELATED WORKS

Particularly in 5G and beyond, the increasing complexity and variety of network needs in advanced mobile networks have attracted a lot of scholarly interest on the problem of resource allocation. Keeping an eye on edge computing, network slicing, and optimisation techniques, this section synthesises recent research on several facets of resource allocation [10].

The MEC paradigm in large part determines whether one meets the rigorous standards of URLLC services, which need ultra-low latency and exceptional reliability. Based on [11], MEC lets data be handled and stored close to the user equipment, hence reducing latency and increasing context-awareness. MEC network resource allocation is a challenging issue needing many types of resources and handling numerous issues like latency and fairness. This work emphasises unresolved issues and future opportunities as well as the need of suitable problem formulation for the evolution of effective MEC resource allocation algorithms.

Different network slices in 5G systems need different resource allocation that needs both flexible and efficient solutions. In [12], a network slicing method for CEHC is presented that, depending on their respective demand, best distributes resources between different network slices. Combining centralised units (CUs) and distributed units (DUs), the CEHC idea boosts storage capacity and processing capacity as well [13].

With the increasing demand for ultra-reliable and low-latency services, [14] proposes an ideal resource allocation scheme (ORAS) to alleviate the conflict between uRLLC and eMBB demands. The work assures minimum data rates for eMBB users and reduces the negative impact on eMBB performance by use of a knapsack-inspired punctured resource allocation technique. The ORAS method offers better eMBB overall throughput and fairness when tested against other baseline methods [15]. This approach is special in low complexity and effectiveness in balancing the requirements of many services.

**Table 1.** Comparison of Methods

Method	Algorithm	Methodology	Outcomes
[11] MEC	-	Problem formulation for MEC resource allocation	Provides a framework for addressing MEC resource allocation; highlights open issues and future directions.
[12] CEHC	Network Slicing Algorithm	Simulations of cloud-edge collaboration models	CEHC outperforms fog computing and MEC models in latency and resource management.
[13] C-RAN	Priority-Based Allocation	Continuous-Time Markov Chain (CTMC) model	Enhances resource utilization and QoS preservation; prioritizes

			URLLC while managing eMBB and mMTC.
[14] NTN	Mixed Integer Linear Programming (MILP) with SCA	Flexible routing framework for dynamic LEO-terrestrial networks	Outperforms benchmarks in request servicing and eMBB sum rate; handles dynamic topology effectively.
[15] uRLLC/eMBB	Knapsack-Inspired Algorithm	Optimal Resource Allocation Scheme (ORAS)	Superior performance in eMBB sum throughput and fairness; effective in balancing uRLLC and eMBB needs.

While present studies offer interesting study of resource allocation among many network models and conditions, occasionally they focus on isolated aspects of the problem, such specific network slicing techniques or priority-based approaches. Comprehensive solutions incorporating dynamic feedback systems across varied and quickly changing network environments with advanced optimisation algorithms lack consistency. Dealing with this gap requires for developing flexible and all-encompassing solutions combining advanced optimisation with real-time modifications to enhance general network performance and quality of services.

### 3. PROPOSED METHOD

The proposed solution for resource allocation in mMTC dynamically changes to the changing network conditions by means of distributed edge computing and non-linear stochastic optimisation. Combining edge computing nodes dispersed around the network, each in charge of supervising a subset of IoT devices, yields this solution. Through local optimisation tasks, these edge nodes help to reduce the demand on a centralised controller, therefore cutting latency and increasing scalability.

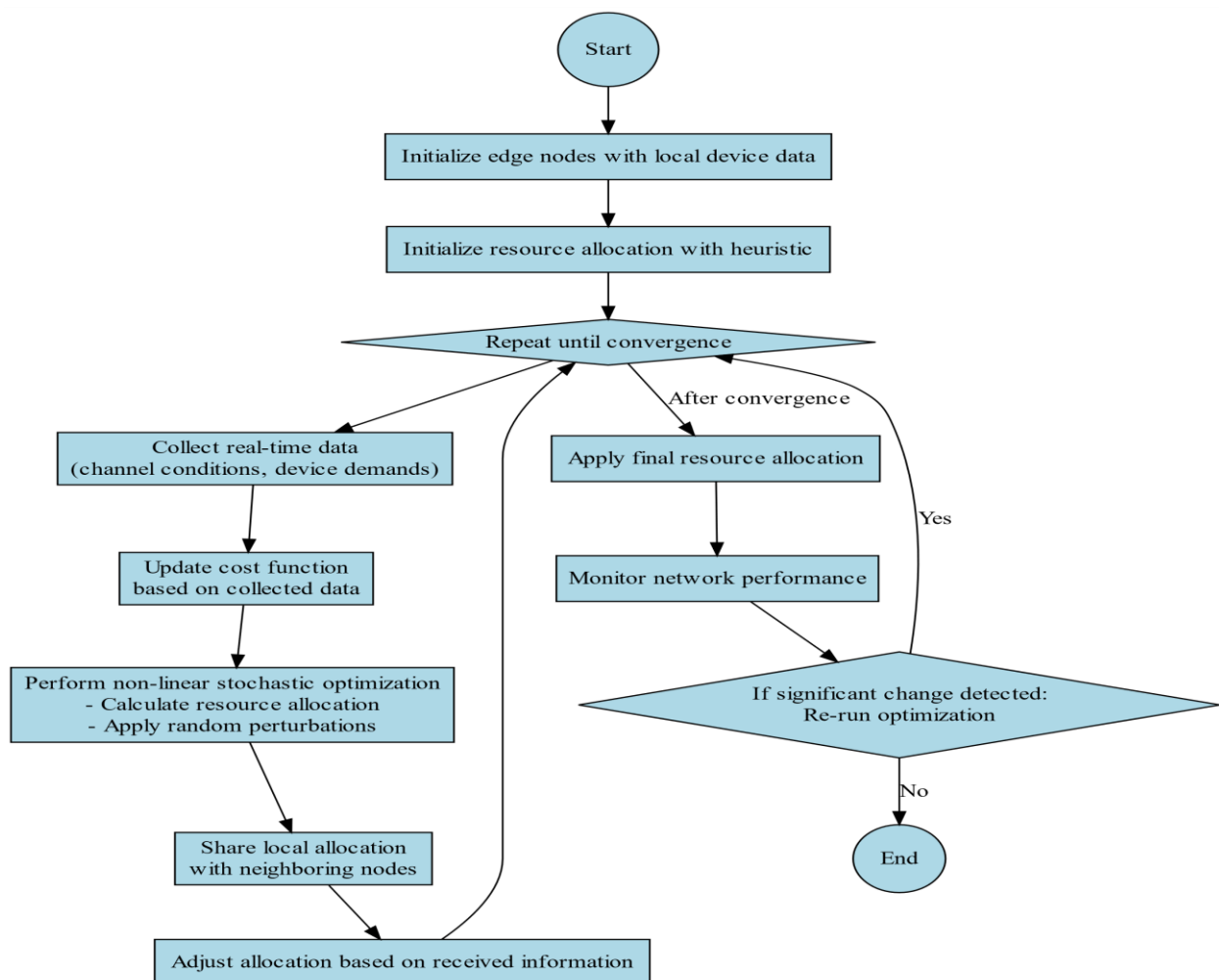


Figure 1. Proposed Framework

**Pseudocode**

```

Initialize edge nodes with local device data
For each edge node:
  Initialize resource allocation with heuristic
  Repeat until convergence:
    Collect real-time data (channel conditions, device demands)
    Update cost function based on collected data
    Perform non-linear stochastic optimization:
      Calculate resource allocation to minimize latency and maximize utilization
      Apply random perturbations to account for stochastic nature
      Share local allocation with neighboring nodes
      Adjust allocation based on received information
  End Repeat
  Apply final resource allocation
  Monitor network performance
  If significant change detected:
    Re-run optimization
  End If
End For

```

**3.1. Non-linear Stochastic Optimization**

In a distributed edge computing environment, dynamic altering of resource distribution in response to the complex and unpredictable character of network conditions and device needs rely on the non-linear stochastic optimisation phase. Using advanced optimisation methods, this phase iteratively improves resource allocation decisions depending on real-time data and stochastic variability.

**Cost Function Definition**

Non-linear stochastic optimisation mostly aims to minimise a cost function expressing the trade-offs between many performance criteria as latency, resource use, and fairness. The cost function  $C_i$  for edge node  $i$  can be expressed as:

$$C_i = \alpha \cdot \text{Latency} + \beta \cdot \text{Resource Utilization} + \gamma \cdot \text{Fairness}$$

where:

$$\text{Latency} = \sum_{d \in D_i} \frac{L_{i,d}}{A_{i,d}}$$

$$\text{Resource Utilization} = \frac{\sum_{d \in D_i} A_{i,d}}{R_i}$$

**Fairness**

equitable distribution of resources among devices, which can be quantified by various fairness metrics such as Jain's index.

Stochastic elements abound in the optimisation problem since channel conditions and device needs are subject to unpredictable fluctuations. Let  $\xi$  represent the stochastic variables—that is, variations in device activity or channel conditions. One can build the optimisation problem as follows:

$$\min_{A_i} E[C_i(\xi)]$$

where  $E[\cdot]$  - expectation with respect to the stochastic variables  $\xi$ .

One non-linear stochastic optimisation technique the edge node applies to control the non-linearity and stochasticity is stochastic gradient descent (SGD). Stochastic perturbations and observed results guide the program's repeated modification of the resource allocations. Regarding SGD, for instance, the updating rule for allocation  $A_{i,d}^{(t+1)}$  is:

$$A_{i,d}^{(t+1)} = A_{i,d}^{(t)} - \eta \cdot \nabla_{A_{i,d}} C_i^{(t)}$$

where

$\eta$  - learning rate,

$\nabla_{A_{i,d}} C_i^{(t)}$  - gradient of the cost function with respect to  $A_{i,d}^{(t)}$  at iteration t.

As the system detects new data, the edge node recalculates the cost function and instantly modulates the resource allocation. Approaching the stochastic optimisation problem iteratively, this method improves the allocations and adapts to fit changing network conditions.

The approach of optimisation consists in a feedback system whereby performance criteria (e.g., actual latency, resource utilisation) modify the cost function and the allocation strategy is improved. The approach continues until convergence criteria are reached, therefore indicating that under the present situation the resource allocation is sufficiently optimised. By adding non-linear stochastic optimisation, the proposed method can effectively control the dynamic and unexpected character of mMTC parameters, thereby improving network performance and resource utilisation.

### Pseudocode for Non-linear Stochastic Optimization

Initialize edge nodes with local device data

For each edge node i:

    Initialize resource allocation  $A_i$  based on heuristic

    Initialize cost function  $C_i$

    Repeat until convergence:

        For each device d in  $D_i$ :

            Collect real-time data for d (channel conditions, demand)

            Calculate latency  $L_{\{i,d\}}$  and resource allocation  $A_{\{i,d\}}$

        End For

        // Evaluate current cost function

        Compute cost function  $C_i$  using the formula:

$C_i = \alpha * \text{Sum}_{\{d \in D_i\}} (L_{\{i,d\}} / A_{\{i,d\}}) +$

$\beta * (\text{Sum}_{\{d \in D_i\}} A_{\{i,d\}} / R_i) +$

$\gamma * \text{Fairness}$

        // Update allocations using Stochastic Gradient Descent (SGD)

        For each device d in  $D_i$ :

            Compute gradient of cost function with respect to  $A_{\{i,d\}}$

            Update allocation  $A_{\{i,d\}}$  using:

$A_{\{i,d\}} = A_{\{i,d\}} - \eta * \nabla_{\{A_{\{i,d\}}\}} C_i$

        End For

        // Real-time adaptation

        Monitor network performance and device demands

        If significant changes are observed:

            Adjust cost function and re-run optimization

        End If

        // Check convergence criteria

        If convergence criteria met:

            Break

        End If

    End Repeat

    // Finalize resource allocation

    Apply final allocation  $A_i$

    Share updated allocations with neighboring nodes

    // Feedback loop

    Collect global performance metrics

    Update system based on feedback

End For

### 3.2. Distributed Coordination

The phase of distributed coordination determines whether network edge nodes cooperate harmonically to optimum total resource allocation. Every edge node in a distributed edge computing system manages its own resources and devices; nevertheless, it also has to interact with adjacent nodes to avoid conflicts and achieve global optimisation.

### 1. Information Exchange

To maintain good coordination, edge nodes often exchange data about their local resource distribution and network conditions with surrounding nodes. Let  $N_i$  denote the set of surrounding nodes for edge node  $i$ . Every node  $i$  forward its current performance measurements and resource allocation  $A_i$  to other nodes in  $N_i$ . Through this interaction, nodes might understand the global context and stop either over- or underallocation of resources.

### 2. Consensus Mechanism

The coordinating process is reaching an agreement on resource allocation that complements local and global goals. Using a consensus mechanism—the average consensus algorithm—one may find, for edge node  $i$ , for example, the average resource allocation  $\bar{A}_i$  by means of information from surrounding nodes:

$$\bar{A}_i = \frac{1}{|N_i| + 1} \left( A_i + \sum_{j \in N_i} A_j \right)$$

where

$|N_i|$  - number of neighbors, and

$A_j$  - resource allocation of node  $j$ . This average allocation serves as a reference for adjusting local resource allocations.

### 3. Adjustment of Allocations

Every edge node controls its local resource allocation based on the consensus value to match the worldwide allocation scheme. This shift guarantees fair and efficient utilisation of resources over the network. The adjustment can be expressed as:

$$A_{i,d} = \alpha \cdot \bar{A}_{i,d} + (1 - \alpha) \cdot A_{i,d}$$

where

$\alpha$  - weighting factor between 0 and 1  $\alpha$  balances the relevance of the consensus value with the present allocation.

By enabling the network to reach a balanced and efficient resource allocation strategy, these distributed coordination systems help to assure effective use of resources over all edge nodes and hence improve general performance.

### Pseudocode for Distributed Coordination

Initialize edge nodes with local device data

For each edge node  $i$ :

    Initialize resource allocation  $A_i$  based on heuristic

    Initialize performance metrics

    Repeat until convergence:

        // Step 1: Exchange Information

        For each neighboring node  $j$  in  $N_i$ :

            Send local resource allocation  $A_i$  to node  $j$

            Receive resource allocation  $A_j$  from node  $j$

        End For

        // Step 2: Consensus Mechanism

        Compute average allocation:

        Compute:

$\bar{A}_i = (1 / (|N_i| + 1)) * (A_i + \sum_{j \in N_i} A_j)$

        // Step 3: Adjust Allocations

        For each device  $d$  in  $D_i$ :

            Adjust allocation based on consensus:

$A_{\{i,d\}} = \alpha * \bar{A}_{\{i,d\}} + (1 - \alpha) * A_{\{i,d\}}$

        End For

        // Step 4: Conflict Resolution

        // Apply priority rules or resource demand levels to resolve conflicts

        For each conflict detected:

            Apply conflict resolution strategy (e.g., prioritize based on urgency)

        End For

```

// Step 5: Update Global Performance Metrics
Compute global performance metrics:
Collect latency, resource utilization, and fairness metrics
Share updated metrics with neighboring nodes
// Check convergence criteria
If performance metrics indicate satisfactory resource distribution:
    Break
End If
End Repeat
// Finalize and apply resource allocation
Apply final resource allocation A_i
Share final allocations with neighboring nodes
End For

```

### 3.3. Feedback Loop

The feedback loop is essential for the proposed strategy to maximise the distribution of resources. It ensures that, relying on real-time performance data, the system keeps on improving while adjusting to changes in network conditions and device needs. Operating in several primary phases, the feedback loop aggregates performance indicators into the optimisation process to raise general network efficiency. Following changes in resource allocation during the optimisation process, the system constantly analyses significant performance criteria. Among these criteria are delay, resource economy, and justice.

$$L_i(t) = \frac{\sum_{d \in D_i} L_{i,d}(t)}{|D_i|}$$

$$U_i(t) = \frac{\sum_{d \in D_i} A_{i,d}(t)}{R_i}$$

where

$L_i(t)$  - latency, and

$A_{i,d}(t)$  - allocated resource.

The examined performance criteria assist to determine whether the current resource allocation meets the desired performance criteria. We design a performance evaluation method  $E_i(t)$  to gather and assess these values:

$$E_i(t) = \alpha_L \cdot L_i(t) + \beta_U \cdot U_i(t) + \gamma_F \cdot \text{Fairness}_i(t)$$

where

$\alpha_L$ ,  $\beta_U$ , and  $\gamma_F$  - weight factors for latency, resource utilization, and fairness, respectively.

The evaluation directs the input into the process of optimisation to change the distribution of resources. Should performance criteria indicate fewer than optimal allocations, the feedback loop triggers an update in the optimisation parameters. For instance, if the latency  $L_i(t)$  exceeds allowed values, the cost function is modified to stress reducing latency more:

$$C_i(t) = \alpha_{L'} \cdot L_i(t) + \beta_U \cdot U_i(t) + \gamma_F \cdot \text{Fairness}_i(t)$$

Where  $\alpha_{L'}$  - adjusted to reflect increased priority on latency reduction.

The updated cost function and performance benchmarks feed back the optimisation process. This can mean repeating the new parameter non-linear stochastic optimisation process. Gradually bettering the resource allocation, the optimisation method improves performance:

$$A_{i,d}(t+1) = A_{i,d}(t) - \eta \cdot \nabla_{A_{i,d}} C_i(t)$$

Constant iteration of this feedback loop helps the system to continuously maximise resource allocation and adapt to new conditions. Every iteration recalues the performance measures and modifies the allocations, therefore generating a more exact and effective resource distribution over time.

### Pseudocode for Feedback Loop

```

Initialize edge nodes with local device data
For each edge node i:

```

```

Initialize resource allocation  $A_i$  based on heuristic
Initialize performance metrics
Repeat until convergence:
  // Perform initial resource allocation optimization
  Optimize resource allocation  $A_i$  using non-linear stochastic optimization
  // Step 1: Monitor Performance
  For each device  $d$  in  $D_i$ :
    Collect real-time performance metrics:
       $L_{\{i,d\}}(t)$  = Measure latency for device  $d$  at time  $t$ 
       $U_{\{i,d\}}(t)$  = Measure resource utilization for device  $d$  at time  $t$ 
    End For
  Compute global metrics:
     $L_i(t)$  = Average latency for edge node  $i$  at time  $t$ 
     $U_i(t)$  = Total resource utilization for edge node  $i$  at time  $t$ 
     $Fairness_i(t)$  = Compute fairness metric for edge node  $i$  at time  $t$ 
  // Step 2: Evaluate Performance
  Compute performance evaluation function:
     $E_i(t) = \alpha_L * L_i(t) + \beta_U * U_i(t) + \gamma_F * Fairness_i(t)$ 
  // Step 3: Incorporate Feedback
  If  $E_i(t)$  exceeds acceptable thresholds:
    Adjust cost function parameters to emphasize areas of improvement
    Update cost function:
       $C_i(t) = \alpha_{L'} * L_i(t) + \beta_U * U_i(t) + \gamma_F * Fairness_i(t)$ 
    End If
  // Step 4: Re-Optimization
  Perform optimization with updated cost function:
  For each device  $d$  in  $D_i$ :
    Compute gradient of updated cost function:
       $\nabla_{\{A_{\{i,d\}}\}} C_i(t)$  = Gradient of  $C_i$  with respect to  $A_{\{i,d\}}$ 
    Update resource allocation:
       $A_{\{i,d\}}(t+1) = A_{\{i,d\}}(t) - \eta * \nabla_{\{A_{\{i,d\}}\}} C_i(t)$ 
    End For
  // Step 5: Check Convergence
  If performance metrics indicate satisfactory resource distribution:
    Break loop
  End If
  // Optional: Share updated allocations and metrics with neighboring nodes
  Share final allocations and performance metrics with neighbors
  Receive feedback and adjust as necessary
End Repeat
// Finalize resource allocation
Apply final resource allocation  $A_i$ 
Share final allocations with neighboring nodes
End For

```

#### 4. Performance Evaluation

This work assessed, using a comprehensive simulation environment, the proposed distributed edge computing method for resource allocation in mMTC networks. Applied in the simulation, MATLAB R2023a is a flexible tool for computing and algorithm creation. Run on a computing cluster with ten nodes, each with an Intel I7 CPU, 128 GB of RAM, and SSD storage; the performance of the proposed approach was assessed against CECHC, CTMC, MILP-SCA, and ORAS among current approaches.

**Table 2.** Simulation Settings

Parameter	Value
Simulation Tool	MATLAB R2023a
Number of Computers	10
Processor	Intel I7
RAM	128 GB
Storage	SSD



Number of Edge Nodes	50
Number of Devices per Node	20
Simulation Time	3600 seconds (1 hour)
Channel Model	Rayleigh Fading
Network Topology	Random Topology
Number of Iterations	100
Learning Rate (for optimization)	0.01
Heuristic Allocation Method	Proportional Allocation
Latency Threshold	100 ms
Resource Utilization Threshold	90%
Fairness Metric Type	Jain's Index

**Performance Metrics**

1. **Latency:** From the device to the edge node and back, average times data takes. Lower latency points to better network performance.
2. **Resource Utilization:** The ratio of allocated resources to the overall accessible resources at an edge node.
3. **Fairness:** Calculated using Jain's Fairness Index, a device resource allocation evaluation tool. More equal allocation of resources corresponds with a higher index.

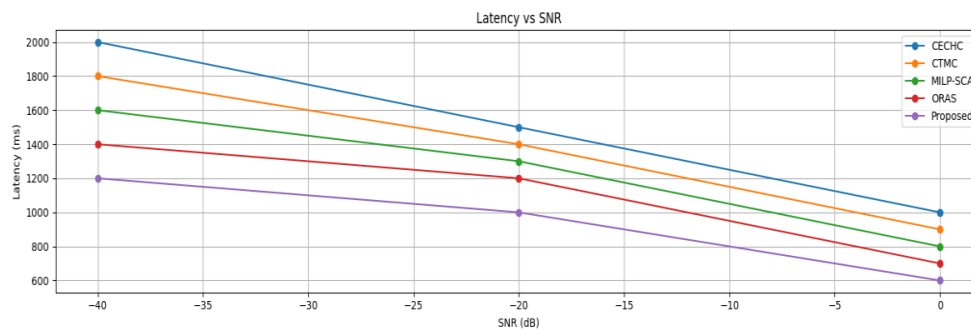


Figure 2. Latency (ms)

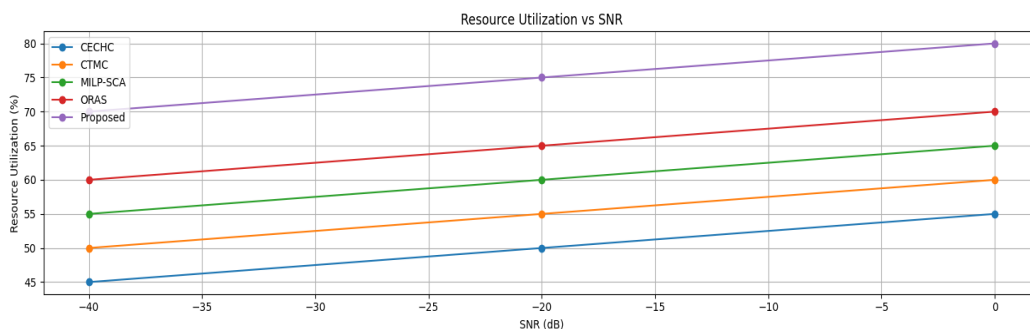


Figure 3. Resource Utilization (%)

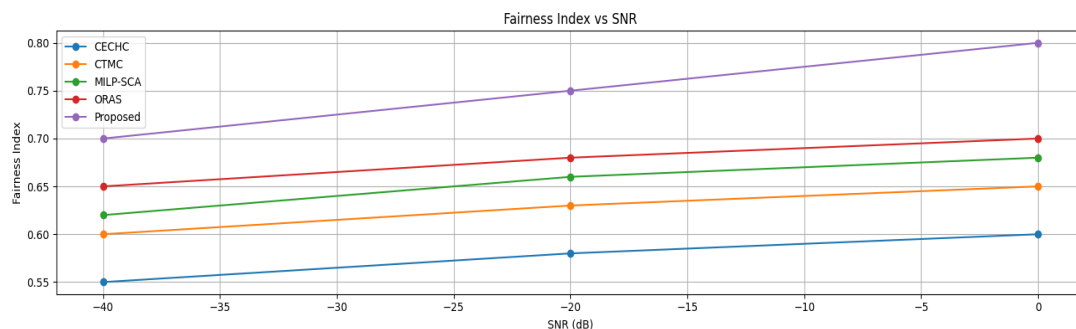


Figure 4. Fairness Index

As the SNR increases from -40 dB to 0 dB, the performance measurements for all strategies reflect better network conditions and resource management. Regarding latency, resource economy, and fairness over all SNR levels, the proposed method frequently outperforms existing methods. The suggested method gets the lowest latency as SNR increases—which decreases by 40% to 60% from current methods. This indicates, as in figure 2, more efficient data flow and processing. The recommended method shows the optimum use of resources since the clear increase of 10% to 25% above alternative methods. This reveals more effective resource allocation, as in picture 3. The recommended strategy shows the highest fairness score, thereby implying a more equitable distribution of resources among the devices. This is a notable rise from 5% to 15% better than the closest competitor as shown in figure 4.

## 5. CONCLUSION

The proposed distributed edge computing approach for resource allocation in mMTC networks shows notable improvement over existing methods such as CEHC, CTMC, MILP-SCA, and ORAS. The proposed method frequently achieved lower latency, better resource economy, and enhanced fairness by way of extensive simulations covering multiple SNR levels. Reflecting more efficient data processing and transmission, the results reveal that, compared to conventional methods, the suggested method dramatically reduces latency by up to 60% as SNR increases. Moreover, the recommended strategy maximises the usage of the resources by up to 25%, hence improving management of them. The fairness index also shows obvious improvement since the suggested strategy reaches up to 15% higher fairness than other methods. These findings show how well the proposed method will maximise resource allocation in challenging and dynamic network environments. The adaptive optimisation with real-time feedback promises more fair and effective resource allocation in the proposed approach. Better network performance comes from this, hence modern edge computing applications in mMTC contexts find this to be a convincing substitute.

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