

Some fixed point results in ordered complete dislocated quasi G_d metric space

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Abstract: In this paper, we discuss the fixed points of mappings satisfying contractive type condition on a closed ball in an ordered complete dislocated quasi G metric space. The notion of dominated mappings is applied to approximate the unique solution of non linear functional equations. An example is given to show the validity of our work. Our results improve/generalize several well known recent and classical results.

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1 Introduction and Preliminaries

Let $T : X \rightarrow X$ be a mapping. A point $x \in X$ is called a fixed point of T if $x = Tx$. Let x_0 be an arbitrary chosen point in X . Define a sequence $\{x_n\}$ in X by a simple iterative method given by $x_{n+1} = Tx_n$, where $n \in \{0, 1, 2, 3, \dots\}$. Such a sequence is called a picard iterative sequence and its convergence plays a very important role in proving existence of fixed point of a mapping T . A self mapping T on a metric space X is said to be a Banach contraction mapping if,

$$d(Tx, Ty) \leq kd(x, y)$$

holds for all $x, y \in X$ where $0 \leq k < 1$. Recently, many results appeared in literature related to fixed point results in complete metric spaces endowed with a partial ordering. Ran and Reurings [17] proved an analogue of Banach's fixed point theorem in metric space endowed with partial order and gave applications to matrix equations. Subsequently, Nieto et. al. [12] extended the results of [17] for non decreasing mappings and applied this results obtain a unique solution for a 1st order ordinary differential equation with periodic boundary conditions. On the other hand in 2005, Mustafa and Sims in [14] introduce the notion of a generalized metric space as generalization the usual metric space. Mustafa and others studied fixed point theorems for mappings satisfying different contractive conditions for further useful results can be seen in [3, 8, 9, 10, 15, 16, 21]. Recently, Arshad et. al. [4] proved a result concerning the existence of fixed points of a mapping satisfying a contractive condition on closed ball in a complete dislocated metric space. For further results on closed ball we refer the reader to [5, 6, 7, 13, 20] and references their in. The dominated mapping [2] which satisfies the condition $fx \preceq x$ occurs very naturally in several practical problems. For example x denotes the total quantity of food produced over a certain period of time and $f(x)$ gives the quantity of food consumed over the same period in a certain town, then we must have $fx \preceq x$.

In this paper we have obtained fixed point results for dominated self-mappings in an ordered complete dislocated quasi G_d metric space on a closed ball

under contractive condition to generalize, extend and improve some classical fixed point results. We have used weaker contractive condition and weaker restrictions to obtain unique fixed point. Our results do not exist even yet in metric spaces. An example shows how this result can be used when the corresponding results cannot.

Definition 1 Let X be a nonempty set and let $G_d : X \times X \times X \rightarrow R^+$ be a function satisfying the

following axioms:

- (i) If $G_d(x, y, z) = G_d(y, z, x) = G_d(z, x, y) = 0$, then $x = y = z$,
- (ii) $G_d(x, y, z) \leq G_d(x, a, a) + G_d(a, y, z)$ for all $x, y, z, a \in X$ (rectangle inequality).

Then the pair (X, G_d) is called the dislocated quasi G_d -metric space. It is clear that if

$G_d(x, y, z) = G_d(y, z, x) = G_d(z, x, y) = 0$ then from (i) $x = y = z$. But if $x = y = z$ then $G_d(x, y, z)$ may not be 0. It is observed that if $G_d(x, y, z) = G_d(y, z, x) = G_d(z, x, y)$ for all $x, y, z \in X$, then (X, G_d) becomes a dislocated G_d -metric space.

Example 2 If $X = R^+ \cup \{0\}$ then $G_d(x, y, z) = x + \max\{x, y, z\}$ defines a dislocated quasi metric G on X .

Definition 3 Let (X, G_d) be a G_d -metric space, and let $\{x_n\}$ be a sequence of points in X , a point x in X is said to be the limit of the sequence $\{x_n\}$ if $\lim_{m, n \rightarrow \infty} G_d(x, x_n, x_m) = 0$, and one says that sequence $\{x_n\}$ is G_d -convergent to x . Thus, if $x_n \rightarrow x$ in a G_d -metric space (X, G_d) , then for any $\epsilon > 0$, there exists $n, m \in \mathbb{N}$ such that $G_d(x, x_n, x_m) < \epsilon$, for all $n, m \geq N$.

Definition 4 Let (X, G_d) be a G_d -metric space. A sequence $\{x_n\}$ is called G_d -Cauchy sequence if, for each $\epsilon > 0$ there exists a positive integer $n^* \in \mathbb{N}$ such that $G_d(x_n, x_m, x_l) < \epsilon$ for all $n, l, m \geq n^*$; i.e. if $G_d(x_n, x_m, x_l) \rightarrow 0$ as $n, m, l \rightarrow \infty$.

Definition 5 G_d -metric space (X, G_d) is said to be G_d -complete if every G_d -Cauchy sequence in (X, G_d) is G_d -convergent in X .

Proposition 6 Let (X, G_d) be a G_d -metric space, then the following are equivalent:

- (1) $\{x_n\}$ is G_d convergent to x .
- (2) $G_d(x_n, x_n, x) \rightarrow 0$ as $n \rightarrow \infty$.
- (3) $G_d(x_n, x, x) \rightarrow 0$ as $n \rightarrow \infty$.
- (4) $G_d(x_n, x_m, x) \rightarrow 0$ as $m, n \rightarrow \infty$.

Definition 7 Let (X, G_d) be a G_d -metric space then for $x_0 \in X$, $r > 0$, the closed ball with centre x_0 and radius r is,

$$\overline{B(x_0, r)} = \{y \in X : G_d(x_0, y, y) \leq r\}.$$

Definition 8 [2] Let (X, \preceq) be a partial ordered set. Then $x, y \in X$ are called comparable if $x \preceq y$ or $y \preceq x$ holds.

Definition 9 [2] Let (X, \preceq) be a partially ordered set. A self mapping f on X is called dominated if $fx \preceq x$ for each x in X .

Example 10 [2] Let $X = [0, 1]$ be endowed with usual ordering and $f : X \rightarrow X$ be defined by $fx = x^n$ for some $n \in \mathbb{N}$. Since $fx = x^n \leq x$ for all $x \in X$, therefore f is a dominated map.

2 Fixed Points of Contractive Mapping

Theorem 11 Let (X, \preceq, G_d) be an ordered complete dislocated quasi G_d metric space, and $T : X \rightarrow X$ be a dominated mapping. Suppose there exists a, b such that $a + 3b < 1$ and for all comparable elements x, y and z in $\overline{B(x_0, r)}$, with $x_0 \in \overline{B(x_0, r)}$, $r > 0$,

$$G_d(Tx, Ty, Tz) \leq a G_d(x, y, z) + b [G_d(x, Tx, Tx) + G_d(y, Ty, Ty) + G_d(z, Tz, Tz)] \tag{2.1}$$

$$\text{where } \lambda = \frac{a + b}{1 - 2b}$$

$$\text{and } G_d(x_0, Tx_0, Tx_0) \leq (1 - \lambda)r. \tag{2.2}$$

If for a nonincreasing sequence $\{x_n\}$ in $\overline{B(x_0, r)}$, $\{x_n\} \rightarrow u$ implies that $u \preceq x_n$ and

$$\begin{aligned} &G(x_0, Tx_0, Tx_0) + G(v, Tv, Tv) + G(v, Tv, Tv) \\ &\leq G(x_0, v, v) + G(Tx_0, Tv, Tv) + G(Tx_0, Tv, Tv) \end{aligned} \tag{2.3}$$

then there exists a point x^* in $\overline{B(x_0, r)}$ such that $G_d(x^*, x^*, x^*) = 0$ and $x^* = Tx^*$.

Proof. Consider a picard sequence $x_{n+1} = Tx_n$ with initial guess x_0 . As $x_{n+1} = Tx_n \preceq x_n$ for all $n \in \{0\} \cup \mathbb{N}$. By inequality (2.2), $G_d(x_0, x_1, x_1) \leq r$. It implies that $x_1 \in \overline{B(x_0, r)}$. Similarly $x_2 \dots x_j \in \overline{B(x_0, r)}$ for some $j \in \mathbb{N}$.

$$\begin{aligned} G_d(x_j, x_{j+1}, x_{j+1}) &= G_d(Tx_{j-1}, Tx_j, Tx_j) \leq a G_d(x_{j-1}, x_j, x_j) \\ &\quad + b[G_d(x_{j-1}, Tx_{j-1}, Tx_{j-1}) + G_d(x_j, x_{j+1}, x_{j+1}) \\ &\quad + G_d(x_j, x_{j+1}, x_{j+1})] \\ (1 - 2b)G_d(x_j, x_{j+1}, x_{j+1}) &\leq (a + b)G_d(x_{j-1}, x_j, x_j) \\ G_d(x_j, x_{j+1}, x_{j+1}) &\leq \frac{(a + b)}{(1 - 2b)}G_d(x_{j-1}, x_j, x_j) \\ &\vdots \\ G_d(x_j, x_{j+1}, x_{j+1}) &\leq \lambda^j G_d(x_0, x_1, x_1). \end{aligned} \tag{2.4}$$

Now by using the inequality (2.2) and (2.4) we have

$$\begin{aligned} G_d(x_j, x_{j+1}, x_{j+1}) &\leq G_d(x_0, x_1, x_1) + G_d(x_1, x_2, x_2) + \dots + G_d(x_j, x_{j+1}, x_{j+1}) \\ G_d(x_j, x_{j+1}, x_{j+1}) &\leq (1 - \lambda)r + \lambda(1 - \lambda)r + \dots + \lambda^j(1 - \lambda)r \\ G_d(x_j, x_{j+1}, x_{j+1}) &\leq r(1 - \lambda)[1 + \lambda + \lambda^2 + \dots + \lambda^j] \\ G_d(x_j, x_{j+1}, x_{j+1}) &\leq r(1 - \lambda) \frac{(1 - \lambda^{j+1})}{(1 - \lambda)} \leq r \\ &\Rightarrow G_d(x_j, x_{j+1}, x_{j+1}) \leq r. \end{aligned}$$

Thus $x_{j+1} \in \overline{B(x_0, r)}$. Hence $x_n \in \overline{B(x_0, r)}$ for all $n \in \mathbb{N}$. Now inequality (2.4) can be written as in the form of

$$G_d(x_n, x_{n+1}, x_{n+1}) \leq \lambda^n G_d(x_0, x_1, x_1) \text{ for all } n \in \mathbb{N}. \quad (2.5)$$

By using inequality (2.5) we get

$$\begin{aligned} G_d(x_n, x_{n+i}, x_{n+i}) &\leq G_d(x_n, x_{n+1}, x_{n+1}) + \dots + G_d(x_{n+i-1}, x_{n+i}, x_{n+i}) \\ G_d(x_n, x_{n+i}, x_{n+i}) &\leq \frac{\lambda^n(1 - \lambda^i)}{(1 - \lambda)} G_d(x_0, x_1, x_1) \rightarrow 0 \text{ as } n \rightarrow \infty \end{aligned} \quad (2.6)$$

Notice that the sequence $\{x_n\}$ is Cauchy sequence in $(\overline{B(x_0, r)}, G_d)$. Therefore there exist a point $x^* \in \overline{B(x_0, r)}$.

$$\begin{aligned} \lim_{n \rightarrow \infty} G_d(x_n, x^*, x^*) &= \lim_{n \rightarrow \infty} G_d(x^*, x^*, x_n) = 0 \\ G_d(x^*, Tx^*, Tx^*) &\leq G_d(x^*, x_n, x_n) + G_d(x_n, Tx^*, Tx^*) \end{aligned}$$

By assumption $x^* \preceq x_n \preceq x_{n-1}$, therefore,

$$\begin{aligned} G_d(x^*, Tx^*, Tx^*) &\leq G_d(x^*, x_n, x_n) + G_d(Tx_{n-1}, Tx^*, Tx^*) \\ G_d(x^*, Tx^*, Tx^*) &\leq G_d(x^*, x_n, x_n) + a G_d(x_{n-1}, x^*, x^*) \\ &\quad + b[G_d(x_{n-1}, Tx_{n-1}, Tx_{n-1}) + G_d(x^*, Tx^*, Tx^*) \\ &\quad G_d(x^*, Tx^*, Tx^*)] \\ G_d(x^*, Tx^*, Tx^*) &\leq G_d(x^*, x_n, x_n) + a G_d(x_{n-1}, x^*, x^*) \\ &\quad + b[G_d(x_{n-1}, Tx_{n-1}, Tx_{n-1}) + 2G_d(x^*, Tx^*, Tx^*)] \\ (1 - 2b)G_d(x^*, Tx^*, Tx^*) &\leq G_d(x^*, x_n, x_n) + a G_d(x_{n-1}, x^*, x^*) \\ &\quad + b G_d(x_{n-1}, x_n, x_n) \end{aligned}$$

Taking $\lim_{n \rightarrow \infty}$ both sides and using (2.6) we have

$$\begin{aligned} (1 - 2b)G_d(x^*, Tx^*, Tx^*) &\leq 0 + a(0) + b(0) \\ &\Rightarrow G_d(x^*, Tx^*, Tx^*) \leq 0 \\ &\Rightarrow x^* = Tx^*. \end{aligned} \quad (2.7)$$

Similarly $G_d(Tx^*, Tx^*, x^*) = 0$ and $G_d(Tx^*, x^*, Tx^*) = 0$ and hence $x^* = Tx^*$. Now

$$\begin{aligned} G_d(x^*, x^*, x^*) &= G_d(Tx^*, Tx^*, Tx^*) \leq a G_d(x^*, x^*, x^*) \\ &\quad + 3bG_d(x^*, Tx^*, Tx^*) \\ (1 - a - 3b)G_d(x^*, x^*, x^*) &\leq 0 \\ \Rightarrow G_d(x^*, x^*, x^*) &\leq 0. \end{aligned}$$

This implies that $G_d(x^*, x^*, x^*) = 0$.

Uniqueness:

Let y^* be another point in $\overline{B(x_0, r)}$ such that

$$\begin{aligned} y^* &= Ty^*. \tag{2.8} \\ G_d(y^*, y^*, y^*) &= G_d(Ty^*, Ty^*, Ty^*) \leq a G_d(y^*, y^*, y^*) \\ &\quad + 3b[G_d(y^*, Ty^*, Ty^*)] \\ (1 - a - 3b)G_d(y^*, y^*, y^*) &\leq 0 \\ \Rightarrow G_d(y^*, y^*, y^*) &\leq 0. \\ \Rightarrow G_d(y^*, y^*, y^*) &= 0. \end{aligned}$$

If x^* and y^* are comparable then

$$\begin{aligned} G_d(x^*, y^*, y^*) &= G_d(Tx^*, Ty^*, Ty^*) \leq a G_d(x^*, y^*, y^*) \\ &\quad + b[G_d(x^*, Tx^*, Tx^*) + 2G_d(y^*, Ty^*, Ty^*)] \\ (1 - a)G_d(x^*, y^*, y^*) &\leq 0 \\ \Rightarrow G_d(x^*, y^*, y^*) &= 0. \end{aligned}$$

Similarly, $G_d(y^*, y^*, x^*) = 0$. This shows that $x^* = y^*$.

If x^* and y^* are not comparable then there exist a point $v \in \overline{B(x_0, r)}$ which is a lower bound of both x^* and y^* . Now we will to prove that $T^n v \in \overline{B(x_0, r)}$. Moreover by assumptions $v \preceq x^* \preceq x_n \preceq \dots \preceq x_0$. Now by using (2.1), we have,

$$G_d(Tx_0, Tv, Tv) \leq a G_d(x_0, v, v) + b [G_d(x_0, x_1, x_1) + 2G_d(v, Tv, Tv)].$$

By using (2.3), we have

$$\begin{aligned} G_d(Tx_0, Tv, Tv) &\leq a G_d(x_0, v, v) + b [G_d(x_0, v, v) + 2G_d(x_1, Tv, Tv)] \\ (1 - 2b)G_d(Tx_0, Tv, Tv) &\leq (a + b) G_d(x_0, v, v) \\ G_d(Tx_0, Tv, Tv) &\leq \frac{(a + b)}{(1 - 2b)} G_d(x_0, v, v) \\ G_d(Tx_0, Tv, Tv) &\leq \lambda G_d(x_0, v, v). \tag{2.9} \end{aligned}$$

Now,

$$\begin{aligned} G_d(x_0, Tv, Tv) &\leq G_d(x_0, x_1, x_1) + G_d(x_1, Tv, Tv) \\ G_d(x_0, Tv, Tv) &\leq G_d(x_0, x_1, x_1) + \lambda G_d(x_0, v, v) \text{ by (2.9)} \\ G_d(x_0, Tv, Tv) &\leq (1 - \lambda)r + \lambda r \\ G_d(x_0, Tv, Tv) &\leq r. \end{aligned}$$

It follows that $Tv \in \overline{B(x_0, r)}$. Now we will prove that $T^n v \in \overline{B(x_0, r)}$. By using mathematical induction to apply inequality (2.1). Let $T^2v, T^3v, \dots, T^jv \in \overline{B(x_0, r)}$ for some $j \in N$. As

$$T^jv \preceq T^{j-1}v \preceq \dots \preceq v \preceq x^* \preceq x_n \preceq \dots \preceq x_0.$$

Then,

$$\begin{aligned} G_d(T^jv, T^{j+1}v, T^{j+1}v) &= G_d(T(T^{j-1}v), T(T^jv), T(T^jv)) \\ G_d(T^jv, T^{j+1}v, T^{j+1}v) &\leq a G_d(T^{j-1}v, T^jv, T^jv) + b [G_d(T^{j-1}v, T^jv, T^jv) \\ &\quad + 2G_d(T^jv, T^{j+1}v, T^{j+1}v)] \\ (1 - 2b)G_d(T^jv, T^{j+1}v, T^{j+1}v) &\leq (a + b)G_d(T^{j-1}v, T^jv, T^jv) \\ G_d(T^jv, T^{j+1}v, T^{j+1}v) &\leq \lambda G_d(T^{j-1}v, T^jv, T^jv) \\ G_d(T^jv, T^{j+1}v, T^{j+1}v) &\leq \lambda^2 G_d(T^{j-2}v, T^{j-1}v, T^{j-1}v) \\ G_d(T^jv, T^{j+1}v, T^{j+1}v) &\leq \lambda^3 G_d(T^{j-3}v, T^{j-2}v, T^{j-2}v) \\ &\vdots \\ G_d(T^jv, T^{j+1}v, T^{j+1}v) &\leq \lambda^j G_d(T^{j-j}v, T^{j-(j-1)}v, T^{j-(j-1)}v) \\ G_d(T^jv, T^{j+1}v, T^{j+1}v) &\leq \lambda^j G_d(v, Tv, Tv) \end{aligned} \tag{2.10}$$

Now,

$$\begin{aligned} G_d(x_{j+1}, T^{j+1}v, T^{j+1}v) &\leq G_d(Tx_j, T(T^jv), T(T^jv)) \\ G_d(x_{j+1}, T^{j+1}v, T^{j+1}v) &\leq a G_d(x_j, T^jv, T^jv) \\ &\quad + b [G_d(x_j, Tx_j, Tx_j) + 2G_d(T^jv, T^{j+1}v, T^{j+1}v)]. \end{aligned}$$

By using (2.4) and (2.10)

$$\begin{aligned} G_d(x_{j+1}, T^{j+1}v, T^{j+1}v) &\leq a\lambda^j G_d(x_0, v, v) \\ &\quad + b[\lambda^j G_d(x_0, x_1, x_1) + 2\lambda^j G_d(v, Tv, Tv)] \\ G_d(x_{j+1}, T^{j+1}v, T^{j+1}v) &\leq a\lambda^j G_d(x_0, v, v) \\ &\quad + b\lambda^j [G_d(x_0, x_1, x_1) + 2G_d(v, Tv, Tv)] \end{aligned}$$

By using the condition (2.3)

$$\begin{aligned} G_d(x_{j+1}, T^{j+1}v, T^{j+1}v) &\leq a\lambda^j G_d(x_0, v, v) \\ &\quad + b\lambda^j [G_d(x_0, v, v) + 2\lambda G_d(x_0, v, v)] \\ G_d(x_{j+1}, T^{j+1}v, T^{j+1}v) &\leq \lambda^j (a + b + 2b\lambda) G_d(x_0, v, v) \\ G_d(x_{j+1}, T^{j+1}v, T^{j+1}v) &\leq \lambda^{j+1} G_d(x_0, v, v) \end{aligned} \tag{2.11}$$

Now ,

$$\begin{aligned}
 G_d(x_0, T^{j+1}v, T^{j+1}v) &\leq G_d(x_0, x_{j+1}, x_{j+1}) + G_d(x_{j+1}, T^{j+1}v, T^{j+1}v) \\
 G_d(x_0, T^{j+1}v, T^{j+1}v) &\leq G_d(x_0, x_1, x_1) + \dots + G_d(x_j, x_{j+1}, x_{j+1}) \\
 &\quad + G_d(x_{j+1}, T^{j+1}v, T^{j+1}v) \\
 G_d(x_0, T^{j+1}v, T^{j+1}v) &\leq G_d(x_0, x_1, x_1) + \lambda G_d(x_0, x_1, x_1) \\
 &\quad + \dots + \lambda^{j+1} G_d(x_0, v, v) \text{ by (2.5) and (2.11)} \\
 G_d(x_0, T^{j+1}v, T^{j+1}v) &\leq G_d(x_0, x_1, x_1)[1 + \lambda + \lambda^2 + \dots + \lambda^j] + \lambda^{j+1}r \text{ as } v \in \overline{B(x_0, r)} \\
 G_d(x_0, T^{j+1}v, T^{j+1}v) &\leq (1 - \lambda)r \frac{(1 - \lambda^{j+1})}{(1 - \lambda)} + \lambda^{j+1}r = r \\
 G_d(x_0, T^{j+1}v, T^{j+1}v) &\leq r.
 \end{aligned}$$

It follows that $T^{j+1}v \in \overline{B(x_0, r)}$ and hence $T^jv \in \overline{B(x_0, r)}$. Now the inequality (2.10) can be written as

$$G_d(T^n v, T^{n+1}v, T^{n+1}v) \leq \lambda^n G_d(v, Tv, Tv) \rightarrow 0 \text{ as } n \rightarrow \infty \quad (2.12)$$

Now,

$$\begin{aligned}
 G_d(x^*, y^*, y^*) &= G_d(Tx^*, Ty^*, Ty^*) \\
 G_d(x^*, y^*, y^*) &\leq G_d(Tx^*, T^{n+1}v, T^{n+1}v) + G_d(T^{n+1}v, Ty^*, Ty^*) \\
 G_d(x^*, y^*, y^*) &\leq a G_d(x^*, T^n v, T^n v) + b [G_d(x^*, Tx^*, Tx^*) \\
 &\quad + 2G_d(T^n v, T^{n+1}v, T^{n+1}v)] + a G_d(T^n v, Ty^*, Ty^*) \\
 &\quad + b [G_d(T^n v, T^{n+1}v, T^{n+1}v) + 2G_d(y^*, Ty^*, Ty^*)]
 \end{aligned}$$

By using (2.7), (2.8) and (2.12) we have

$$\begin{aligned}
 G_d(x^*, y^*, y^*) &\leq a G_d(x^*, T^n v, T^n v) + a G_d(T^n v, y^*, y^*) \\
 G_d(x^*, y^*, y^*) &\leq a [G_d(Tx^*, T^n v, T^n v) + G_d(T^n v, Ty^*, Ty^*)] \\
 G_d(x^*, y^*, y^*) &\leq a [a G_d(x^*, T^{n-1}v, T^{n-1}v) + b G_d(x^*, Tx^*, Tx^*) \\
 &\quad + 2b G_d(T^{n-1}v, T^n v, T^n v) + a G_d(T^{n-1}v, y^*, y^*) \\
 &\quad + b G_d(T^{n-1}v, T^n v, T^n v) + 2b G_d(y^*, Ty^*, Ty^*)].
 \end{aligned}$$

By using (2.7), (2.8) and (2.12) we have

$$\begin{aligned}
 G_d(x^*, y^*, y^*) &\leq a^2 [G_d(x^*, T^{n-1}v, T^{n-1}v) + G_d(T^{n-1}v, y^*, y^*)] \\
 G_d(x^*, y^*, y^*) &\leq a^3 [G_d(x^*, T^{n-2}v, T^{n-2}v) + G_d(T^{n-2}v, y^*, y^*)] \\
 &\quad \vdots \\
 G_d(x^*, y^*, y^*) &\leq a^n [G_d(x^*, Tv, Tv) + G_d(Tv, y^*, y^*)] \\
 G_d(x^*, y^*, y^*) &\rightarrow 0 \text{ as } n \rightarrow \infty \\
 G_d(x^*, y^*, y^*) &= 0 \\
 x^* &= y^*.
 \end{aligned}$$

This proves the uniqueness of the fixed point. ■

Now we give an example of an ordered complete dislocated quasi G_d -metric space in which the contraction does not hold on the whole space rather it holds on a closed ball only.

Example 12 Let $X = \mathbb{R}^+ \cup \{0\}$ be endowed with usual order and $G_d : X \times X \times X \rightarrow X$ be a complete dislocated quasi G_d metric space defined by,

$$G_d(x, y, z) = \left\{ \begin{array}{l} 0 \text{ if } x = y = z \\ \max \{2x, y, z\} \text{ otherwise.} \end{array} \right\}$$

Then (X, G_d) is a G_d complete G dislocated quasi metric space.

Let $T : X \rightarrow X$ be defined by,

$$Tx = \left\{ \begin{array}{l} \frac{x}{5} \text{ if } x \in [0, \frac{3}{2}] \\ x - \frac{1}{3} \text{ if } x \in [\frac{3}{2}, \infty) \end{array} \right\}.$$

Clearly, T is a dominated mappings. Take $x_0 = \frac{1}{3}$, $r = \frac{3}{2}$, $\overline{B(x_0, r)} = [0, \frac{3}{2}]$ and $\lambda = \frac{1}{4}$, $a + 3b < 1$, where $a = \frac{1}{10}$, and $b = \frac{1}{10}$.

$$\begin{aligned} G_d(x_0, Tx_0, Tx_0) &\leq (1 - \lambda)r \\ G_d(\frac{1}{3}, T\frac{1}{3}, T\frac{1}{3}) &= \max\{\frac{2}{3}, \frac{1}{15}, \frac{1}{15}\} = \frac{2}{3} \\ \text{Since } (1 - \lambda)r &= (1 - \frac{1}{4})\frac{3}{2} = \frac{9}{8} \\ &\Rightarrow \frac{2}{3} \leq \frac{9}{8} \\ &\Rightarrow 16 \leq 27 \end{aligned}$$

Also if x, y and $z \in [\frac{3}{2}, \infty)$. We assume that $x > y$, and $y > z$, then

$$\begin{aligned} \max\{2x - \frac{2}{3}, y - \frac{1}{3}, z - \frac{1}{3}\} &\geq \frac{1}{10} \max\{2x, y, z\} \\ &\quad \frac{1}{10} [\max\{2x, x - \frac{1}{3}, x - \frac{1}{3}\} \\ &\quad + \max\{2y, y - \frac{1}{2}, y - \frac{1}{2}\} \\ &\quad + \max\{2z, z - \frac{1}{2}, z - \frac{1}{2}\}] \\ G_d(Tx, Ty, Tz) &\geq a G_d(x, y, z) + b [G_d(x, Tx, Tx) \\ &\quad + G_d(y, Ty, Ty) + G_d(z, Tz, Tz)] \end{aligned}$$

So the contractive conditions does not holds in X . Now if x, y and $z \in \overline{B(x_0, r)}$

then,

$$\begin{aligned} G_d(Tx, Ty, Tz) &= \max\left\{\frac{2x}{5}, \frac{y}{5}, \frac{z}{5}\right\} \leq \frac{1}{10}\{2x, y, z\} \\ &\quad + \frac{1}{10}[\max\{2x, \frac{x}{5}, \frac{x}{5}\} + \max\{2y, \frac{y}{5}, \frac{y}{5}\} \\ &\quad + \max\{z, \frac{z}{5}, \frac{z}{5}\}] \\ \Rightarrow G_d(Tx, Ty, Tz) &\leq a G_d(x, y, z) + b [G_d(x, Tx, Tx) \\ &\quad + G_d(y, Ty, Ty) + G_d(z, Tz, Tz)]. \end{aligned}$$

Hence it satisfies all the requirements of Theorem 11. If we take $b = 0$ in inequality (2.1) then we obtain the following corollary.

Corollary 13 *Let (X, \preceq, G) be an ordered complete dislocated quasi G -metric space, $T : X \rightarrow X$ be a dominated mapping and x_0 be any arbitrary point in X . Suppose there exists $a \in [0, 1)$ with,*

$$G(Tx, Ty, Tz) \leq a G(x, y, z), \text{ for all } x, y \text{ and } z \in Y = \overline{B(x_0, r)},$$

and

$$G(x_0, Tx_0, Tx_0) \leq (1 - a)r.$$

If for a nonincreasing sequence $\{x_n\} \rightarrow u$ implies that $u \preceq x_n$. Then there exists a point x^ in $\overline{B(x_0, r)}$ such that $x^* = Sx^*$ and $G(x^*, x^*, x^*) = 0$. Moreover if for any three points x, y and z in $\overline{B(x_0, r)}$ such that there exists a point $v \in \overline{B(x_0, r)}$ such that $v \preceq x, v \preceq y$ and $v \preceq z$, that is, every three of elements in $\overline{B(x_0, r)}$ has a lower bound, then the point x^* is unique.*

Similarly if we take $a = 0$ in inequality (2.1) then we obtain the following corollary.

Corollary 14 *Let (X, \preceq, G) be an ordered complete dislocated quasi G -metric space $T : X \rightarrow X$ be a mapping and x_0 be an arbitrary point in X . Suppose there exists $b \in [0, \frac{1}{3})$ with*

$$G(Tx, Ty, Tz) \leq b (G(x, Tx, Tx) + G(y, Ty, Ty) + G(z, Tz, Tz))$$

for all comparable elements $x, y, z \in \overline{B(x_0, r)}$ and

$$G(x_0, Tx_0, Tx_0) \leq (1 - \lambda)r,$$

where $\lambda = \frac{b}{1-2b}$. If for non increasing sequence $\{x_n\} \rightarrow u$ implies that $u \preceq x_n$. Then there exists a point x^ in $\overline{B(x_0, r)}$ such that $x^* = Sx^*$ and $G(x^*, x^*, x^*) = 0$. Moreover, if for any three points $x, y, z \in \overline{B(x_0, r)}$, there exists a point $v \in \overline{B(x_0, r)}$ such that $v \preceq x$ and $v \preceq y, v \preceq z$.*

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