

Journal of

Computational

Analysis and

Applications

EUDOXUS PRESS,LLC

Journal of Computational Analysis and Applications ISSNno.'s:1521-1398 PRINT,1572-9206 ONLINE SCOPE OF THE JOURNAL

An international publication of Eudoxus Press, LLC (sixteen times annually)

Editor in Chief: George Anastassiou Department of Mathematical Sciences, University of Memphis, Memphis, TN 38152-3240, U.S.A ganastss@memphis.edu

http://www.msci.memphis.edu/~ganastss/jocaaa

The main purpose of "J.Computational Analysis and Applications" is to publish high quality research articles from all subareas of Computational Mathematical Analysis and its many potential applications and connections to other areas of Mathematical Sciences. Any paper whose approach and proofs are computational, using methods from Mathematical Analysis in the broadest sense is suitable and welcome for consideration in our journal, except from Applied Numerical Analysis articles. Also plain word articles without formulas and proofs are excluded. The list of possibly connected mathematical areas with this publication includes, but is not restricted to: Applied Analysis, Applied Functional Analysis, Approximation Theory, Asymptotic Analysis, Difference Equations, Differential Equations, Partial Differential Equations, Fourier Analysis, Fractals, Fuzzy Sets, Harmonic Analysis, Inequalities, Integral Equations, Measure Theory, Moment Theory, Neural Networks, Numerical Functional Analysis, Potential Theory, Probability Theory, Real and Complex Analysis, Signal Analysis, Special Functions, Splines, Stochastic Analysis, Stochastic Processes, Summability, Tomography, Wavelets, any combination of the above, e.t.c. "J.Computational Analysis and Applications" is a

"J.Computational Analysis and Applications" is a peer-reviewed Journal. See the instructions for preparation and submission of articles to JoCAAA. Assistant to the Editor:

Dr.Razvan Mezei, mezei razvan@yahoo.com, Madison, WI, USA.

Journal of Computational Analysis and Applications(JoCAAA) is published by **EUDOXUS PRESS,LLC**,1424 Beaver Trail

Drive, Cordova, TN38016, USA, anastassioug@yahoo.com

http://www.eudoxuspress.com. **Annual Subscription Prices**:For USA and Canada,Institutional:Print \$800, Electronic OPEN ACCESS. Individual:Print \$400. For any other part of the world add \$150 more(handling and postages) to the above prices for Print. No credit card payments.

Copyright©2018 by Eudoxus Press,LLC,all rights reserved.JoCAAA is printed in USA. JoCAAA is reviewed and abstracted by AMS Mathematical Reviews,MATHSCI.and Zentralblaat MATH.

It is strictly prohibited the reproduction and transmission of any part of JoCAAA and in any form and by any means without the written permission of the publisher.It is only allowed to educators to Xerox articles for educational purposes. The publisher assumes no responsibility for the content of published papers.

Editorial Board

Associate Editors of Journal of Computational Analysis and Applications

Francesco Altomare

Dipartimento di Matematica
Universita' di Bari
Via E.Orabona, 4
70125 Bari, ITALY
Tel+39-080-5442690 office
+39-080-3944046 home
+39-080-5963612 Fax
altomare@dm.uniba.it
Approximation Theory, Functional
Analysis, Semigroups and Partial
Differential Equations, Positive
Operators.

Ravi P. Agarwal

Department of Mathematics
Texas A&M University - Kingsville
700 University Blvd.
Kingsville, TX 78363-8202
tel: 361-593-2600
Agarwal@tamuk.edu
Differential Equations, Difference
Equations, Inequalities

George A. Anastassiou

Department of Mathematical Sciences
The University of Memphis
Memphis, TN 38152,U.S.A
Tel.901-678-3144
e-mail: ganastss@memphis.edu
Approximation Theory, Real
Analysis,
Wavelets, Neural Networks,
Probability, Inequalities.

J. Marshall Ash

Department of Mathematics
De Paul University
2219 North Kenmore Ave.
Chicago, IL 60614-3504
773-325-4216
e-mail: mash@math.depaul.edu
Real and Harmonic Analysis

Dumitru Baleanu

Department of Mathematics and Computer Sciences, Cankaya University, Faculty of Art and Sciences, 06530 Balgat, Ankara, Turkey, dumitru@cankaya.edu.tr Fractional Differential Equations Nonlinear Analysis, Fractional Dynamics

Carlo Bardaro

Dipartimento di Matematica e Informatica
Universita di Perugia
Via Vanvitelli 1
06123 Perugia, ITALY
TEL+390755853822
+390755855034
FAX+390755855024
E-mail carlo.bardaro@unipg.it
Web site:
http://www.unipg.it/~bardaro/
Functional Analysis and
Approximation Theory, Signal
Analysis, Measure Theory, Real
Analysis.

Martin Bohner

Department of Mathematics and Statistics, Missouri S&T Rolla, MO 65409-0020, USA bohner@mst.edu web.mst.edu/~bohner Difference equations, differential equations, dynamic equations on time scale, applications in economics, finance, biology.

Jerry L. Bona

Department of Mathematics
The University of Illinois at
Chicago
851 S. Morgan St. CS 249
Chicago, IL 60601
e-mail:bona@math.uic.edu
Partial Differential Equations,
Fluid Dynamics

Luis A. Caffarelli

Department of Mathematics
The University of Texas at Austin
Austin, Texas 78712-1082
512-471-3160
e-mail: caffarel@math.utexas.edu
Partial Differential Equations
George Cybenko
Thayer School of Engineering

Dartmouth College 8000 Cummings Hall, Hanover, NH 03755-8000 603-646-3843 (X 3546 Secr.) e-mail:george.cybenko@dartmouth.edu Approximation Theory and Neural Networks

Sever S. Dragomir

School of Computer Science and Mathematics, Victoria University, PO Box 14428, Melbourne City, MC 8001, AUSTRALIA Tel. +61 3 9688 4437 Fax +61 3 9688 4050 sever.dragomir@vu.edu.au Inequalities, Functional Analysis, Numerical Analysis, Approximations, Information Theory, Stochastics.

Oktay Duman

TOBB University of Economics and Technology,
Department of Mathematics, TR-06530,
Ankara, Turkey,
oduman@etu.edu.tr
Classical Approximation Theory,
Summability Theory, Statistical
Convergence and its Applications

Saber N. Elaydi

Department Of Mathematics Trinity University 715 Stadium Dr. San Antonio, TX 78212-7200 210-736-8246 e-mail: selaydi@trinity.edu Ordinary Differential Equations, Difference Equations

J .A. Goldstein

Department of Mathematical Sciences
The University of Memphis
Memphis, TN 38152
901-678-3130
jgoldste@memphis.edu
Partial Differential Equations,
Semigroups of Operators

H. H. Gonska

Department of Mathematics University of Duisburg Duisburg, D-47048 Germany 011-49-203-379-3542 e-mail: heiner.gonska@uni-due.de Approximation Theory, Computer Aided Geometric Design

John R. Graef

Department of Mathematics
University of Tennessee at
Chattanooga
Chattanooga, TN 37304 USA
John-Graef@utc.edu
Ordinary and functional
differential equations, difference
equations, impulsive systems,
differential inclusions, dynamic
equations on time scales, control
theory and their applications

Weimin Han

Department of Mathematics
University of Iowa
Iowa City, IA 52242-1419
319-335-0770
e-mail: whan@math.uiowa.edu
Numerical analysis, Finite element
method, Numerical PDE, Variational
inequalities, Computational
mechanics

Tian-Xiao He

Department of Mathematics and Computer Science
P.O. Box 2900, Illinois Wesleyan University
Bloomington, IL 61702-2900, USA
Tel (309)556-3089
Fax (309)556-3864
the@iwu.edu
Approximations, Wavelet,
Integration Theory, Numerical
Analysis, Analytic Combinatorics

Margareta Heilmann

Faculty of Mathematics and Natural Sciences, University of Wuppertal Gaußstraße 20 D-42119 Wuppertal, Germany, heilmann@math.uni-wuppertal.de Approximation Theory (Positive Linear Operators)

Xing-Biao Hu

Institute of Computational Mathematics AMSS, Chinese Academy of Sciences Beijing, 100190, CHINA hxb@lsec.cc.ac.cn

Computational Mathematics

Jong Kyu Kim

Department of Mathematics
Kyungnam University
Masan Kyungnam,631-701,Korea
Tel 82-(55)-249-2211
Fax 82-(55)-243-8609
jongkyuk@kyungnam.ac.kr
Nonlinear Functional Analysis,
Variational Inequalities, Nonlinear
Ergodic Theory, ODE, PDE,
Functional Equations.

Robert Kozma

Department of Mathematical Sciences
The University of Memphis
Memphis, TN 38152, USA
rkozma@memphis.edu
Neural Networks, Reproducing Kernel
Hilbert Spaces,
Neural Percolation Theory

Mustafa Kulenovic

Department of Mathematics University of Rhode Island Kingston, RI 02881,USA kulenm@math.uri.edu Differential and Difference Equations

Irena Lasiecka

Department of Mathematical Sciences University of Memphis Memphis, TN 38152 PDE, Control Theory, Functional Analysis, lasiecka@memphis.edu

Burkhard Lenze

Fachbereich Informatik
Fachhochschule Dortmund
University of Applied Sciences
Postfach 105018
D-44047 Dortmund, Germany
e-mail: lenze@fh-dortmund.de
Real Networks, Fourier Analysis,
Approximation Theory

Hrushikesh N. Mhaskar

Department Of Mathematics California State University Los Angeles, CA 90032 626-914-7002 e-mail: hmhaska@gmail.com Orthogonal Polynomials, Approximation Theory, Splines, Wavelets, Neural Networks

Ram N. Mohapatra

Department of Mathematics University of Central Florida Orlando, FL 32816-1364 tel.407-823-5080 ram.mohapatra@ucf.edu Real and Complex Analysis, Approximation Th., Fourier Analysis, Fuzzy Sets and Systems

Gaston M. N'Guerekata

Department of Mathematics
Morgan State University
Baltimore, MD 21251, USA
tel: 1-443-885-4373
Fax 1-443-885-8216
Gaston.N'Guerekata@morgan.edu
nguerekata@aol.com
Nonlinear Evolution Equations,
Abstract Harmonic Analysis,
Fractional Differential Equations,
Almost Periodicity & Almost
Automorphy

M.Zuhair Nashed

Department Of Mathematics
University of Central Florida
PO Box 161364
Orlando, FL 32816-1364
e-mail: znashed@mail.ucf.edu
Inverse and Ill-Posed problems,
Numerical Functional Analysis,
Integral Equations, Optimization,
Signal Analysis

Mubenga N. Nkashama

Department OF Mathematics
University of Alabama at Birmingham
Birmingham, AL 35294-1170
205-934-2154
e-mail: nkashama@math.uab.edu
Ordinary Differential Equations,
Partial Differential Equations

Vassilis Papanicolaou

Department of Mathematics
National Technical University of
Athens
Zografou campus, 157 80
Athens, Greece
tel:: +30(210) 772 1722
Fax +30(210) 772 1775
papanico@math.ntua.gr
Partial Differential Equations,
Probability

Choonkil Park

Department of Mathematics Hanyang University Seoul 133-791 S. Korea, baak@hanyang.ac.kr Functional Equations

Svetlozar (Zari) Rachev,

Professor of Finance, College of Business, and Director of Quantitative Finance Program, Department of Applied Mathematics & Statistics Stonybrook University 312 Harriman Hall, Stony Brook, NY 11794-3775 tel: +1-631-632-1998, svetlozar.rachev@stonybrook.edu

Alexander G. Ramm

Mathematics Department
Kansas State University
Manhattan, KS 66506-2602
e-mail: ramm@math.ksu.edu
Inverse and Ill-posed Problems,
Scattering Theory, Operator Theory,
Theoretical Numerical Analysis,
Wave Propagation, Signal Processing
and Tomography

Tomasz Rychlik

Polish Academy of Sciences
Instytut Matematyczny PAN
00-956 Warszawa, skr. poczt. 21
ul. Śniadeckich 8
Poland
trychlik@impan.pl
Mathematical Statistics,
Probabilistic Inequalities

Boris Shekhtman

Department of Mathematics University of South Florida Tampa, FL 33620, USA Tel 813-974-9710 shekhtma@usf.edu Approximation Theory, Banach spaces, Classical Analysis

T. E. Simos

Department of Computer Science and Technology Faculty of Sciences and Technology University of Peloponnese GR-221 00 Tripolis, Greece Postal Address: 26 Menelaou St. Anfithea - Paleon Faliron GR-175 64 Athens, Greece tsimos@mail.ariadne-t.gr Numerical Analysis

H. M. Srivastava

Department of Mathematics and Statistics
University of Victoria
Victoria, British Columbia V8W 3R4
Canada
tel.250-472-5313; office,250-4776960 home, fax 250-721-8962
harimsri@math.uvic.ca
Real and Complex Analysis,
Fractional Calculus and Appl.,
Integral Equations and Transforms,
Higher Transcendental Functions and
Appl.,q-Series and q-Polynomials,
Analytic Number Th.

I. P. Stavroulakis

Department of Mathematics University of Ioannina 451-10 Ioannina, Greece ipstav@cc.uoi.gr Differential Equations Phone +3-065-109-8283

Manfred Tasche

Department of Mathematics
University of Rostock
D-18051 Rostock, Germany
manfred.tasche@mathematik.unirostock.de
Numerical Fourier Analysis, Fourier
Analysis, Harmonic Analysis, Signal
Analysis, Spectral Methods,
Wavelets, Splines, Approximation
Theory

Roberto Triggiani

Department of Mathematical Sciences University of Memphis Memphis, TN 38152 PDE, Control Theory, Functional Analysis, rtrggani@memphis.edu

Juan J. Trujillo

University of La Laguna
Departamento de Analisis Matematico
C/Astr.Fco.Sanchez s/n
38271. LaLaguna. Tenerife.
SPAIN
Tel/Fax 34-922-318209
Juan.Trujillo@ull.es

Fractional: Differential Equations-Operators-Fourier Transforms, Special functions, Approximations, and Applications

Ram Verma

International Publications
1200 Dallas Drive #824 Denton,
TX 76205, USA

Verma99@msn.com

Applied Nonlinear Analysis, Numerical Analysis, Variational Inequalities, Optimization Theory, Computational Mathematics, Operator Theory

Xiang Ming Yu

Department of Mathematical Sciences Southwest Missouri State University Springfield, MO 65804-0094 417-836-5931 xmy944f@missouristate.edu Classical Approximation Theory, Wavelets

Lotfi A. Zadeh

Professor in the Graduate School and Director, Computer Initiative, Soft Computing (BISC) Computer Science Division University of California at Berkeley

Berkeley, CA 94720 Office: 510-642-4959 Sec: 510-642-8271 Home: 510-526-2569 FAX: 510-642-1712 zadeh@cs.berkeley.edu

Fuzzyness, Artificial Intelligence, Natural language processing, Fuzzy

logic

Richard A. Zalik

Department of Mathematics Auburn University Auburn University, AL 36849-5310 USA. Tel 334-844-6557 office

678-642-8703 home
Fax 334-844-6555
zalik@auburn.edu
Approximation Theory, Chebychev

Systems, Wavelet Theory

Ahmed I. Zayed

Department of Mathematical Sciences DePaul University

2320 N. Kenmore Ave. Chicago, IL 60614-3250 773-325-7808 e-mail: azayed@condor.depaul.edu Shannon sampling theory, Harmonic analysis and wavelets, Special functions and orthogonal polynomials, Integral transforms

Ding-Xuan Zhou

Department Of Mathematics City University of Hong Kong 83 Tat Chee Avenue Kowloon, Hong Kong 852-2788 9708,Fax:852-2788 8561 e-mail: mazhou@cityu.edu.hk Approximation Theory, Spline functions, Wavelets

Xin-long Zhou

Fachbereich Mathematik, Fachgebiet Informatik
Gerhard-Mercator-Universitat
Duisburg
Lotharstr.65, D-47048 Duisburg,
Germany
e-mail:Xzhou@informatik.uniduisburg.de
Fourier Analysis, Computer-Aided
Geometric Design, Computational
Complexity, Multivariate
Approximation Theory, Approximation
and Interpolation Theory

Jessada Tariboon
Department of Mathematics,
King Mongkut's University of
Technology N. Bangkok
1518 Pracharat 1 Rd., Wongsawang,
Bangsue, Bangkok, Thailand 10800
jessada.t@sci.kmutnb.ac.th, Time scales,
Differential/Difference Equations,
Fractional Differential Equations

Instructions to Contributors Journal of Computational Analysis and Applications

An international publication of Eudoxus Press, LLC, of TN.

Editor in Chief: George Anastassiou

Department of Mathematical Sciences University of Memphis Memphis, TN 38152-3240, U.S.A.

1. Manuscripts files in Latex and PDF and in English, should be submitted via email to the Editor-in-Chief:

Prof.George A. Anastassiou Department of Mathematical Sciences The University of Memphis Memphis,TN 38152, USA. Tel. 901.678.3144

e-mail: ganastss@memphis.edu

Authors may want to recommend an associate editor the most related to the submission to possibly handle it.

Also authors may want to submit a list of six possible referees, to be used in case we cannot find related referees by ourselves.

- 2. Manuscripts should be typed using any of TEX,LaTEX,AMS-TEX,or AMS-LaTEX and according to EUDOXUS PRESS, LLC. LATEX STYLE FILE. (Click HERE to save a copy of the style file.) They should be carefully prepared in all respects. Submitted articles should be brightly typed (not dot-matrix), double spaced, in ten point type size and in 8(1/2)x11 inch area per page. Manuscripts should have generous margins on all sides and should not exceed 24 pages.
- 3. Submission is a representation that the manuscript has not been published previously in this or any other similar form and is not currently under consideration for publication elsewhere. A statement transferring from the authors(or their employers,if they hold the copyright) to Eudoxus Press, LLC, will be required before the manuscript can be accepted for publication. The Editor-in-Chief will supply the necessary forms for this transfer. Such a written transfer of copyright, which previously was assumed to be implicit in the act of submitting a manuscript, is necessary under the U.S. Copyright Law in order for the publisher to carry through the dissemination of research results and reviews as widely and effective as possible.

4. The paper starts with the title of the article, author's name(s) (no titles or degrees), author's affiliation(s) and e-mail addresses. The affiliation should comprise the department, institution (usually university or company), city, state (and/or nation) and mail code.

The following items, 5 and 6, should be on page no. 1 of the paper.

- 5. An abstract is to be provided, preferably no longer than 150 words.
- 6. A list of 5 key words is to be provided directly below the abstract. Key words should express the precise content of the manuscript, as they are used for indexing purposes.

The main body of the paper should begin on page no. 1, if possible.

7. All sections should be numbered with Arabic numerals (such as: 1. INTRODUCTION).

Subsections should be identified with section and subsection numbers (such as 6.1. Second-Value Subheading).

If applicable, an independent single-number system (one for each category) should be used to label all theorems, lemmas, propositions, corollaries, definitions, remarks, examples, etc. The label (such as Lemma 7) should be typed with paragraph indentation, followed by a period and the lemma itself.

- 8. Mathematical notation must be typeset. Equations should be numbered consecutively with Arabic numerals in parentheses placed flush right, and should be thusly referred to in the text [such as Eqs.(2) and (5)]. The running title must be placed at the top of even numbered pages and the first author's name, et al., must be placed at the top of the odd numbed pages.
- 9. Illustrations (photographs, drawings, diagrams, and charts) are to be numbered in one consecutive series of Arabic numerals. The captions for illustrations should be typed double space. All illustrations, charts, tables, etc., must be embedded in the body of the manuscript in proper, final, print position. In particular, manuscript, source, and PDF file version must be at camera ready stage for publication or they cannot be considered.

Tables are to be numbered (with Roman numerals) and referred to by number in the text. Center the title above the table, and type explanatory footnotes (indicated by superscript lowercase letters) below the table.

10. List references alphabetically at the end of the paper and number them consecutively. Each must be cited in the text by the appropriate Arabic numeral in square brackets on the baseline.

References should include (in the following order): initials of first and middle name, last name of author(s) title of article,

name of publication, volume number, inclusive pages, and year of publication.

Authors should follow these examples:

Journal Article

1. H.H.Gonska, Degree of simultaneous approximation of bivariate functions by Gordon operators, (journal name in italics) *J. Approx. Theory*, 62,170-191(1990).

Book

2. G.G.Lorentz, (title of book in italics) Bernstein Polynomials (2nd ed.), Chelsea, New York, 1986.

Contribution to a Book

- 3. M.K.Khan, Approximation properties of beta operators,in(title of book in italics) *Progress in Approximation Theory* (P.Nevai and A.Pinkus,eds.), Academic Press, New York,1991,pp.483-495.
- 11. All acknowledgements (including those for a grant and financial support) should occur in one paragraph that directly precedes the References section.
- 12. Footnotes should be avoided. When their use is absolutely necessary, footnotes should be numbered consecutively using Arabic numerals and should be typed at the bottom of the page to which they refer. Place a line above the footnote, so that it is set off from the text. Use the appropriate superscript numeral for citation in the text.
- 13. After each revision is made please again submit via email Latex and PDF files of the revised manuscript, including the final one.
- 14. Effective 1 Nov. 2009 for current journal page charges, contact the Editor in Chief. Upon acceptance of the paper an invoice will be sent to the contact author. The fee payment will be due one month from the invoice date. The article will proceed to publication only after the fee is paid. The charges are to be sent, by money order or certified check, in US dollars, payable to Eudoxus Press, LLC, to the address shown on the Eudoxus homepage.

No galleys will be sent and the contact author will receive one (1) electronic copy of the journal issue in which the article appears.

15. This journal will consider for publication only papers that contain proofs for their listed results.

FOURIER SERIES OF FUNCTIONS INVOLVING EULER **POLYNOMIALS**

TAEKYUN KIM, DAE SAN KIM, GWAN-WOO JANG, AND JONGKYUM KWON

ABSTRACT. Recently, T. Kim introduced Fourier series expansions of certain special polynomials and investigated some interesting identities and properties of these polynomials by using those Fourier series. In this paper, we consider three types of functions involving Euler polynomials and derive their Fourier series expansions. Moreover, we express each of them in terms of Benoulli functions.

1. Introduction

Let $E_m(x)$ be the Euler polynomials given by the generating function

$$\frac{2}{e^t + 1}e^{xt} = \sum_{m=0}^{\infty} E_m(x)\frac{t^m}{m!}, \text{ (see [1,2,5,7-11,16])}.$$
 (1.1)

From this equation, we can derive the following relation.

$$E_0 = 1, (E+1)^n + E_n = \begin{cases} 2, & \text{if } n = 0, \\ 0, & \text{if } n \neq 0. \end{cases}$$

The Bernoulli polynomials $B_m(x)$ are defined by the generating function

$$\frac{t}{e^t - 1}e^{xt} = \sum_{m=0}^{\infty} B_m(x)\frac{t^m}{m!}, \text{ (see [1,2,5,9])}.$$
 (1.2)

For any real number x, we let

$$\langle x \rangle = x - [x] \in [0, 1)$$
 (1.3)

denote the fractional part of x.

Here we will consider the following three types of functions involving Euler polynomials and derive their Fourier series expansions. Further, we will express each of them in terms of Bernoulli functions $B_m(\langle x \rangle)$.

- (1) $\alpha_m(\langle x \rangle) = \sum_{k=0}^m E_k(x) x^{m-k}, (m \ge 1);$ (2) $\beta_m(\langle x \rangle) = \sum_{k=0}^m \frac{1}{k!(m-k)!} E_k(x) x^{m-k}, (m \ge 1);$
- (3) $\gamma_m(\langle x \rangle) = \sum_{k=1}^{m-1} \frac{1}{k(m-k)} E_k(x) x^{m-k}, (m \ge 2).$

The reader may refer to any book (for example, see [13-15,17]), for elementary facts about Fourier analysis.

²⁰¹⁰ Mathematics Subject Classification. 11B68, 42A16. Key words and phrases. Fourier series, Euler polynomials.

As to $\gamma_m(\langle x \rangle)$, we note that the polynomial identity (1.4) follows immediately from Theorems 4.2 and 4.3, which is in turn derived from the Fourier series expansion of $\gamma_m(\langle x \rangle)$.

$$\sum_{k=1}^{m-1} \frac{1}{k(m-k)} E_k(x) x^{m-k}$$

$$= -\frac{1}{m} \left(\sum_{k=1}^{m} \frac{E_k}{k(m-k+1)} + \frac{1}{m(m+1)} - \frac{2}{m(m+1)} E_{m+1} \right)$$

$$+ \frac{1}{m} \sum_{s=1}^{m} \left(\binom{m}{s} \frac{H_{m-1} - H_{m-s}}{m-s+1} (1 - 2E_{m-s+1}) - \binom{m}{s} \sum_{l=s}^{m-1} \frac{E_{l-s+1}}{(l-s+1)(m-l)} \right) B_s(x),$$
(1.4)

where $H_m = \sum_{j=1}^m \frac{1}{j}$ are the harmonic numbers. The obvious polynomial identities can be derived also for $\alpha_m(< x >)$ and $\beta_m(< x >)$ from Theorems 2.1 and 2.2, and Theorems 3.1 and 3.2, respectively.

2. The function $\alpha_m(\langle x \rangle)$

Let $\alpha_m(x) = \sum_{k=0}^m E_k(x) x^{m-k}$, $(m \ge 1)$. Then we consider the function $\alpha_m(< x >) = \sum_{k=0}^m E_k(< x >) < x >^{m-k}$, defined on $(-\infty, \infty)$, which is periodic with period 1.

The Fourier series of $\beta_m(\langle x \rangle)$ is $\sum_{n=-\infty}^{\infty} A_n^{(m)} e^{2\pi i n x}$, where

$$A_n^{(m)} = \int_0^1 \alpha_m(\langle x \rangle) e^{-2\pi i n x} dx$$

$$= \int_0^1 \alpha_m(x) e^{-2\pi i n x} dx.$$
(2.1)

To proceed further, we note the following.

$$\alpha'_{m}(x) = \sum_{k=0}^{m} \left(k E_{k-1}(x) x^{m-k} + (m-k) E_{k}(x) x^{m-k-1} \right)$$

$$= \sum_{k=1}^{m} k E_{k-1}(x) x^{m-k} + \sum_{k=0}^{m-1} (m-k) E_{k}(x) x^{m-k-1}$$

$$= \sum_{k=0}^{m-1} (k+1) E_{k}(x) x^{m-k-1} + \sum_{k=0}^{m-1} (m-k) E_{k}(x) x^{m-k-1}$$

$$= (m+1) \sum_{k=0}^{m-1} E_{k}(x) x^{m-1-k}$$

$$= (m+1) \alpha_{m-1}(x).$$
(2.2)

FOURIER SERIES OF FUNCTIONS INVOLVING EULER POLYNOMIALS

So,
$$\alpha'_m(x) = (m+1)\alpha_{m-1}(x)$$
. From this, $\left(\frac{\alpha_{m+1}(x)}{m+2}\right)' = \alpha_m(x)$.

$$\int_0^1 \alpha_m(x)dx = \frac{1}{m+2} \left(\alpha_{m+1}(1) - \alpha_{m+1}(0) \right). \tag{2.3}$$

$$\alpha_m(1) - \alpha_m(0) = \sum_{k=0}^m (E_k(1) - E_k \delta_{m,k})$$

$$= \sum_{k=0}^m ((-E_k + 2\delta_{k,0})) - \sum_{k=0}^m E_k \delta_{m,k}$$

$$= -\sum_{k=0}^m E_k + 2 - E_m$$
(2.4)

Thus

$$\alpha_m(1) = \alpha_m(0) \Longleftrightarrow \sum_{k=0}^m E_k = 2 - E_m. \tag{2.5}$$

Also,

$$\int_0^1 \alpha_m(x)dx = \frac{1}{m+2} \left(-\sum_{k=0}^{m+1} E_k + 2 - E_{m+1} \right). \tag{2.6}$$

Now, we would like to determine the Fourier coefficients $A_n^{(m)}$. $Case 1: n \neq 0$.

$$\begin{split} A_n^{(m)} &= \int_0^1 \alpha_m(x) e^{-2\pi i n x} dx \\ &= -\frac{1}{2\pi i n} \left[\alpha_m(x) e^{-2\pi i n x} \right]_0^1 + \frac{1}{2\pi i n} \int_0^1 \alpha_m'(x) e^{-2\pi i n x} dx \\ &= -\frac{1}{2\pi i n} \left(\alpha_m(1) - \alpha_m(0) \right) + \frac{m+1}{2\pi i n} \int_0^1 \alpha_{m-1}(x) e^{-2\pi i n x} dx \\ &= \frac{m+1}{2\pi i n} A_n^{(m-1)} + \frac{1}{2\pi i n} \left(\sum_{k=0}^m E_k - 2 + E_m \right) \\ &= \frac{m+1}{2\pi i n} \left(\frac{m}{2\pi i n} A_n^{(m-2)} + \frac{1}{2\pi i n} \left(\sum_{k=0}^{m-1} E_k - 2 + E_{m-1} \right) \right) + \frac{1}{2\pi i n} \left(\sum_{k=0}^m E_k - 2 + E_m \right) \\ &= \frac{(m+1)m}{(2\pi i n)^2} A_n^{(m-2)} + \frac{m+1}{(2\pi i n)^2} \left(\sum_{k=0}^{m-1} E_k - 2 + E_{m-1} \right) + \frac{1}{2\pi i n} \left(\sum_{k=0}^m E_k - 2 + E_m \right) \\ &= \cdots \end{split}$$

$$= \frac{(m+1)_{m-1}}{(2\pi i n)^{m-1}} A_n^{(1)} + \sum_{j=1}^{m-1} \frac{(m+1)_{j-1}}{(2\pi i n)^j} \left(\sum_{k=0}^{m-j+1} E_k - 2 + E_{m-j+1} \right)$$

$$= -\frac{(m+1)!}{(2\pi i n)^m} + \sum_{j=1}^{m-1} \frac{(m+1)_{j-1}}{(2\pi i n)^j} \left(\sum_{k=0}^{m-j+1} E_k - 2 + E_{m-j+1} \right)$$

$$= \sum_{j=1}^{m} \frac{(m+1)_{j-1}}{(2\pi i n)^j} \left(\sum_{k=0}^{m-j+1} E_k - 2 + E_{m-j+1} \right)$$

$$= \frac{1}{m+2} \sum_{j=1}^{m} \frac{(m+2)_j}{(2\pi i n)^j} \left(\sum_{k=0}^{m-j+1} E_k - 2 + E_{m-j+1} \right),$$
(2.7)

where $A_n^{(1)} = \int_0^1 \alpha_1(x) e^{-2\pi i n x} dx = \int_0^1 (2x - \frac{1}{2}) e^{-2\pi i n x} dx = -\frac{2}{2\pi i n}$. Case2: n = 0.

$$A_0^{(m)} = \int_0^1 \alpha_m(x) dx = \frac{1}{m+2} \left(-\sum_{k=0}^{m+1} E_k + 2 - E_{m+1} \right).$$
 (2.8)

 $\alpha_m(< x >), (m \ge 1)$ is piecewise C^{∞} . Moreover, $\alpha_m(< x >)$ is continuous for those positive integers m with $\sum_{k=0}^m E_k = 2 - E_m$ and discontinuous with jump discontinuities at integers for those positive integers m with $\sum_{k=0}^m E_k \ne 2 - E_m$.

We recall the following facts about Bernoulli functions $B_n(\langle x \rangle)$: (a) for $m \geq 2$,

$$B_m(\langle x \rangle) = -m! \sum_{n=-\infty, n \neq 0}^{\infty} \frac{e^{2\pi i n x}}{(2\pi i n)^m}.$$
 (2.9)

(b) for m = 1,

$$-\sum_{n=-\infty, n\neq 0}^{\infty} \frac{e^{2\pi i n x}}{2\pi i n} = \begin{cases} B_1(\langle x \rangle), & \text{for } x \notin \mathbb{Z}, \\ 0, & \text{for } x \in \mathbb{Z}. \end{cases}$$
 (2.10)

Assume first that m is a positive integer with $\sum_{k=0}^{m} E_k = 2 - E_m$. Then $\alpha_m(1) = \alpha_m(0)$.

 $\alpha_m(\langle x \rangle)$ is piecewise C^{∞} , and continuous. So the Fourier series of $\alpha_m(\langle x \rangle)$ converges uniformly to $\alpha_m(\langle x \rangle)$, and

$$\alpha_{m}(\langle x \rangle) = -\frac{1}{m+2} \left(\sum_{k=0}^{m+1} E_{k} - 2 + E_{m+1} \right)$$

$$+ \frac{1}{m+2} \sum_{n=-\infty, n\neq 0}^{\infty} \left(\sum_{j=1}^{m} \frac{(m+2)_{j}}{(2\pi i n)^{j}} \left(\sum_{k=0}^{m-j+1} E_{k} - 2 + E_{m-j+1} \right) \right) e^{2\pi i n x}$$

$$= -\frac{1}{m+2} \left(\sum_{k=0}^{m+1} E_{k} - 2 + E_{m+1} \right)$$

$$- \frac{1}{m+2} \sum_{j=1}^{m} {m+2 \choose j} \left(\sum_{k=0}^{m-j+1} E_{k} - 2 + E_{m-j+1} \right)$$

$$\times \left(-j! \sum_{n=-\infty, n\neq 0}^{\infty} \frac{e^{2\pi i n x}}{(2\pi i n)^{j}} \right)$$

$$= -\frac{1}{m+2} \left(\sum_{k=0}^{m+1} E_{k} - 2 + E_{m+1} \right)$$

$$(2.11)$$

$$= -\frac{1}{m+2} \left(\sum_{k=0}^{m+1} E_k - 2 + E_{m+1} \right)$$

$$-\frac{1}{m+2} \sum_{j=2}^{m} {m+2 \choose j} \left(\sum_{k=0}^{m-j+1} E_k - 2 + E_{m-j+1} \right) B_j(\langle x \rangle)$$

$$-\frac{1}{m+2} {m+2 \choose 1} \left(\sum_{k=0}^{m} E_k - 2 + E_m \right) \cdot \begin{cases} B_1(\langle x \rangle), & \text{for } x \notin \mathbb{Z}, \\ 0, & \text{for } x \in \mathbb{Z} \end{cases},$$
(2.12)

for all $x \in (-\infty, \infty)$.

Hence we obtain the following theorem.

Theorem 2.1. Let m be a positive integer with $\sum_{k=0}^{m} E_k = 2 - E_m$. Then we have the following

(a) $\sum_{k=0}^{m} E_k(\langle x \rangle) \langle x \rangle^{m-k}$ has the Fourier series expansion

$$\sum_{k=0}^{m} E_k(\langle x \rangle) \langle x \rangle^{m-k}$$

$$= -\frac{1}{m+2} \left(\sum_{k=0}^{m+1} E_k - 2 + E_{m+1} \right)$$

$$+ \frac{1}{m+2} \sum_{n=-\infty, n\neq 0}^{\infty} \left(\sum_{j=1}^{m} \frac{(m+2)_j}{(2\pi i n)^j} \left(\sum_{k=0}^{m-j+1} E_k - 2 + E_{m-j+1} \right) \right) e^{2\pi i n x},$$

for all $x \in (-\infty, \infty)$, where the convergence is uniform

(b)
$$\sum_{k=0}^{m} E_k(\langle x \rangle) \langle x \rangle^{m-k} = -\frac{1}{m+2} \sum_{j=0, j \neq 1}^{m} {m+2 \choose j} \left(\sum_{k=0}^{m-j+1} E_k - 2 + E_{m-j+1} \right) B_j(\langle x \rangle),$$

for all $x \in (-\infty, \infty)$, where $B_k(\langle x \rangle)$ is the Bernoulli function.

Assume next that m is a positive integer with $\sum_{k=0}^m E_k \neq 2 - E_m$. Then $\alpha_m(1) \neq \alpha_m(0)$. Hence $\alpha_m(< x >)$ is piecewise C^{∞} , and discontinuous with jump discontinuities at integers. The Fourier series of $\alpha_m(< x >)$ converges pointwise to $\alpha_m(< x >)$, for $x \notin \mathbb{Z}$, and converges to

$$\frac{1}{2}(\alpha_m(0) + \alpha_m(1)) = \alpha_m(0) - \frac{1}{2} \sum_{k=0}^m E_k + 1 - \frac{1}{2} E_m,$$
$$= 1 - \frac{1}{2} \sum_{k=0}^{m-1} E_k,$$

for $x \in \mathbb{Z}$.

Thus, we get the following theorem.

Theorem 2.2. Let m be a positive integer with $\sum_{k=0}^{m} E_k \neq 2 - E_m$. Then we have the following.

(a)
$$-\frac{1}{m+2} \left(\sum_{k=0}^{m+1} E_k - 2 + E_{m+1} \right)$$

$$+ \frac{1}{m+2} \sum_{n=-\infty, n\neq 0}^{\infty} \left(\sum_{j=1}^{m} \frac{(m+2)_j}{(2\pi i n)^j} \left(\sum_{k=0}^{m-j+1} E_k - 2 + E_{m-j+1} \right) \right) e^{2\pi i n x}$$

$$= \begin{cases} \sum_{k=0}^{m} E_k(\langle x \rangle) \langle x \rangle^{m-k}, & \text{for } x \notin \mathbb{Z}, \\ 1 - \frac{1}{2} \sum_{k=0}^{m-1} E_k, & \text{for } x \in \mathbb{Z}. \end{cases}$$

$$(b) - \frac{1}{m+2} \sum_{j=0}^{m} {m+2 \choose j} \left(\sum_{k=0}^{m-j+1} E_k - 2 + E_{m-j+1} \right) B_j(\langle x \rangle)$$

$$= \sum_{k=0}^{m} E_k(\langle x \rangle) \langle x \rangle^{m-k}, & \text{for } x \notin \mathbb{Z},$$

$$- \frac{1}{m+2} \sum_{j=0, j\neq 1}^{m} {m+2 \choose j} \left(\sum_{k=0}^{m-j+1} E_k - 2 + E_{m-j+1} \right) B_j(\langle x \rangle)$$

$$= 1 - \frac{1}{2} \sum_{k=0}^{m-1} E_k, & \text{for } x \in \mathbb{Z}.$$

Question: For what values of $m \ge 1$, does $\sum_{k=0}^{m} E_k = 2 - E_m$ hold?

Remark 2.3. Another expression for $A_0^{(m)} = \int_0^1 \alpha_m(x) dx$ was obtained previously (see [3,4,6,12]) and is

$$\sum_{l=0}^{m-1} \sum_{j=1}^{m-l} \frac{(-1)^j \binom{m-l+1}{j} E_{l+j}}{(m-l+1) \binom{l+j}{l}} + \frac{4(-1)^{m+1}}{m+2} E_{m+1}.$$
 (2.13)

So, we obtain the following identity.

$$\frac{1}{m+2} \left(-\sum_{k=0}^{m+1} E_k + 2 - E_{m+1} \right)$$

$$= \sum_{l=0}^{m-1} \sum_{j=1}^{m-l} \frac{(-1)^j \binom{m-l+1}{j} E_{l+j}}{(m-l+1) \binom{l+j}{l}} + \frac{4(-1)^{m+1}}{m+2} E_{m+1}.$$

3. The fuction $\beta_m(\langle x \rangle)$

Let $\beta_m(x) = \sum_{k=0}^m \frac{1}{k!(m-k)!} E_k(x) x^{m-k}$, $(m \ge 1)$. Then we will consider the function

$$\beta_m(\langle x \rangle) = \sum_{k=0}^m \frac{1}{k!(m-k)!} E_k(\langle x \rangle) \langle x \rangle^{m-k},$$

defined on $(-\infty, \infty)$, which is periodic with period 1.

The Fourier series of $\beta_m(\langle x \rangle)$ is

$$\sum_{n=-\infty}^{\infty} B_n^{(m)} e^{2\pi i n x},$$

where

$$B_n^{(m)} = \int_0^1 \beta_m(\langle x \rangle) e^{-2\pi i n x} dx = \int_0^1 \beta_m(x) e^{-2\pi i n x} dx.$$

Before proceeding further, we observe the following:

$$\beta'_{m}(x) = \sum_{k=0}^{m} \left\{ \frac{k}{k!(m-k)!} E_{k-1}(x) x^{m-k} + \frac{m-k}{k!(m-k)!} E_{k}(x) x^{m-k-1} \right\}$$

$$= \sum_{k=1}^{m} \frac{1}{(k-1)!(m-k)!} E_{k-1}(x) x^{m-k} + \sum_{k=0}^{m-1} \frac{1}{k!(m-1-k)!} E_{k}(x) x^{m-1-k}$$

$$= \sum_{k=0}^{m-1} \frac{1}{k!(m-1-k)!} E_{k}(x) x^{m-1-k} + \sum_{k=0}^{m-1} \frac{1}{k!(m-1-k)!} E_{k}(x) x^{m-1-k} + \sum_{k=0}^{m-1} \frac{1}{k!(m-1-k)!} E_{k}(x) x^{m-1-k}$$

$$= 2\beta_{m-1}(x).$$
(3.1)

So,
$$\beta'_{m}(x) = 2\beta_{m-1}(x)$$
. This implies that $\left(\frac{\beta_{m+1}(x)}{2}\right)' = \beta_{m}(x)$.

$$\int_{0}^{1} \beta_{m}(x)dx = \frac{1}{2} \left(\beta_{m+1}(1) - \beta_{m+1}(0)\right). \tag{3.2}$$

$$\beta_{m}(1) - \beta_{m}(0)$$

$$= \sum_{k=0}^{m} \frac{1}{k!(m-k)!} \left(E_{k}(1) - E_{k}(0) \delta_{m,k} \right)$$

$$= \sum_{k=0}^{m} \frac{1}{k!(m-k)!} \left\{ \left(-E_{k} + 2\delta_{k,0} \right) \right\}.$$

$$- \sum_{k=0}^{m} \frac{1}{k!(m-k)!} E_{k} \delta_{m,k}$$

$$= - \sum_{k=0}^{m} \frac{E_{k}}{k!(m-k)!} + \frac{2}{m!} - \frac{E_{m}}{m!}.$$

$$\text{So, } \int_{0}^{1} \beta_{m}(x) dx = \frac{1}{2} \left(-\sum_{k=0}^{m+1} \frac{E_{k}}{k!(m+1-k)!} + \frac{2}{(m+1)!} - \frac{E_{m+1}}{(m+1)!} \right).$$

$$\text{Also, } \beta_{m}(1) = \beta_{m}(0) \Leftrightarrow \sum_{k=0}^{m} \frac{E_{k}}{k!(m-k)!} = \frac{2}{m!} - \frac{E_{m}}{m!}.$$

Now, we are going to determine the Fourier coefficients $B_n^{(m)}$.

Case $1:n \neq 0$.

$$\begin{split} B_n^{(m)} &= \int_0^1 \beta_m(x) e^{-2\pi i n x} dx \\ &= -\frac{1}{2\pi i n} \Big[\beta_m(x) e^{-2\pi i n x} \Big]_0^1 + \frac{1}{2\pi i n} \int_0^1 \beta_m'(x) e^{-2\pi i n x} dx \\ &= -\frac{1}{2\pi i n} \Big(\beta_m(1) - \beta_m(0) \Big) + \frac{1}{\pi i n} \int_0^1 \beta_{m-1}(x) e^{-2\pi i n x} dx \\ &= \frac{1}{\pi i n} B_n^{(m-1)} - \frac{1}{2\pi i n} \left(\beta_m(1) - \beta_m(0) \right) \\ &= \frac{1}{\pi i n} \Big(\frac{1}{\pi i n} B_n^{(m-2)} - \frac{1}{2\pi i n} \left(\beta_{m-1}(1) - \beta_{m-1}(0) \right) \Big) - \frac{1}{2\pi i n} \left(\beta_m(1) - \beta_m(0) \right) \\ &= \frac{1}{(\pi i n)^2} B_n^{(m-2)} - \frac{2}{(2\pi i n)^2} \left(\beta_{m-1}(1) - \beta_{m-1}(0) \right) - \frac{1}{2\pi i n} \left(\beta_m(1) - \beta_m(0) \right) \\ &= \cdots \\ &= \frac{1}{(\pi i n)^{m-1}} B_n^{(1)} - \sum_{j=1}^{m-1} \frac{2^{j-1}}{(2\pi i n)^j} \left(\beta_{m-j+1}(1) - \beta_{m-j+1}(0) \right) \\ &= -\frac{1}{(\pi i n)^m} + \sum_{j=1}^{m-1} \frac{2^{j-1}}{(2\pi i n)^j} \left(\sum_{k=0}^{m-j+1} \frac{E_k}{k!(m-j-k+1)!} - \frac{2}{(m-j+1)!} + \frac{E_{m-j+1}}{(m-j+1)!} \right) \\ &= \sum_{j=1}^m \frac{2^{j-1}}{(2\pi i n)^j} \left(\sum_{k=0}^{m-j+1} \frac{E_k}{k!(m-j-k+1)!} - \frac{2}{(m-j+1)!} + \frac{E_{m-j+1}}{(m-j+1)!} \right), \\ \text{where } B_n^{(1)} &= \int_0^1 \beta_1(x) e^{-2\pi i n x} dx = \int_0^1 (2x - \frac{1}{2}) e^{-2\pi i n x} dx = -\frac{1}{\pi i n}. \end{split}$$

FOURIER SERIES OF FUNCTIONS INVOLVING EULER POLYNOMIALS

Case 2: n = 0.

$$B_0^{(m)} = \int_0^1 \beta_m(x) dx = \frac{1}{2} \left(-\sum_{k=0}^{m+1} \frac{E_k}{k!(m+1-k)!} + \frac{2}{(m+1)!} - \frac{E_{m+1}}{(m+1)!} \right). \quad (3.5)$$

Let

$$\Omega_m = \beta_m(1) - \beta_m(0) = -\sum_{k=0}^m \frac{E_k}{k!(m-k)!} + \frac{2}{m!} - \frac{E_m}{m!},$$

for $m \geq 1$.

 $\beta_m(\langle x \rangle)$, $(m \geq 1)$ is piecewise C^{∞} . Moreover, $\beta_m(\langle x \rangle)$ is continuous for those positive integers m with $\Omega_m = 0$ and discontinuous with jump discontinuities at integers for those positive integers m with $\Omega_m \neq 0$.

Assume first that m is a positive integer with $\Omega_m = 0$. Then $\beta_m(1) = \beta_m(0)$. $\beta_m(\langle x \rangle)$ is piecewise C^{∞} , and continuous. So the Fourier series of $\beta_m(\langle x \rangle)$ converges uniformly to $\beta_m(\langle x \rangle)$, and

$$\beta_{m}(\langle x \rangle) = \sum_{k=0}^{m} \frac{1}{k!(m-k)!} E_{k}(\langle x \rangle) \langle x \rangle^{m-k}$$

$$= \frac{1}{2} \Omega_{m+1} - \sum_{n=-\infty, n \neq 0}^{\infty} \left(\sum_{j=1}^{m} \frac{2^{j-1}}{(2\pi i n)^{j}} \Omega_{m-j+1} \right) e^{2\pi i n x}$$

$$= \frac{1}{2} \Omega_{m+1} + \sum_{j=1}^{m} \frac{2^{j-1}}{j!} \Omega_{m-j+1} \times \left(-j! \sum_{n=-\infty, n \neq 0}^{\infty} \frac{e^{2\pi i n x}}{(2\pi i n)^{j}} \right)$$

$$= \frac{1}{2} \Omega_{m+1} + \sum_{j=2}^{m} \frac{2^{j-1}}{j!} \Omega_{m-j+1} B_{k}(\langle x \rangle)$$

$$+ \Omega_{m} \times \begin{cases} B_{1}(\langle x \rangle), & \text{for } x \notin \mathbb{Z}, \\ 0, & \text{for } x \in \mathbb{Z}, \end{cases}$$

for all $x \in (-\infty, \infty)$.

Now, we obtain the following theorem.

Theorem 3.1. For each positive integer l, let

$$\Omega_l = -\sum_{k=0}^{l} \frac{E_k}{k!(l-k)!} + \frac{2}{l!} - \frac{E_l}{l!}.$$

Assume that $\Omega_m = 0$, for a positive integer m. Then we have the following. (a) $\sum_{k=0}^{m} \frac{1}{k!(m-k)!} E_k(\langle x \rangle) \langle x \rangle^{m-k}$ has the Fourier series expansion

$$\sum_{k=0}^{m} \frac{1}{k!(m-k)!} E_k(\langle x \rangle) \langle x \rangle^{m-k} = \frac{1}{2} \Omega_{m+1} - \sum_{n=-\infty, n \neq 0}^{\infty} \left(\sum_{j=1}^{m} \frac{2^{j-1}}{(2\pi i n)^j} \Omega_{m-j+1} \right) e^{2\pi i n x},$$

(3.6)

for all $x \in (-\infty, \infty)$. Here the convergence is uniform.

(b)
$$\sum_{k=0}^{m} \frac{1}{k!(m-k)!} E_k(\langle x \rangle) \langle x \rangle^{m-k} = \sum_{j=0, j \neq 1}^{m} \frac{2^{j-1}}{j!} \Omega_{m-j+1} B_k(\langle x \rangle),$$

for all $x \in (-\infty, \infty)$. Here $B_k(\langle x \rangle)$ is the Bernoulli function.

Assume next that m is a positive integer with $\Omega_m \neq 0$. Then, $\beta_m(1) \neq \beta_m(0)$. $\beta_m(< x >)$ is piecewise C^{∞} and discontinuous with jump discontinuities at integers. Thus the Fourier series of $\beta_m(< x >)$ converges pointwise to $\beta_m(< x >)$, for $x \notin \mathbb{Z}$, and converges to

$$\frac{1}{2}(\beta_m(0) + \beta_m(1)) = \beta_m(0) + \frac{1}{2}\Omega_m$$

$$= \frac{E_m}{m!} + \frac{1}{2}\left(-\sum_{k=0}^m \frac{E_k}{k!(m-k)!} + \frac{2}{m!} - \frac{E_m}{m!}\right)$$

$$= \frac{1}{2}\left(\frac{2}{m!} - \sum_{k=0}^{m-1} \frac{E_k}{k!(m-k)!}\right).$$
(3.7)

for $x \in \mathbb{Z}$.

So, we obtain the following theorem.

Theorem 3.2. For each positive integer l, let

$$\Omega_l = -\sum_{k=0}^{l} \frac{E_k}{k!(l-k)!} + \frac{2}{l!} - \frac{E_l}{l!}.$$

Assume that $\Omega_m \neq 0$, for a positive integer m. Then we have the following.

$$(a) \frac{1}{2} \Omega_{m+1} - \sum_{n=-\infty, n \neq 0}^{\infty} \left(\sum_{j=1}^{m} \frac{2^{j-1}}{(2\pi i n)^{j}} \Omega_{m-j+1} \right) e^{2\pi i n x}$$

$$= \begin{cases} \sum_{k=0}^{m} \frac{1}{k!(m-k)!} E_{k}(\langle x \rangle) \langle x \rangle^{m-k}, & \text{for } x \notin \mathbb{Z}, \\ \frac{E_{m}}{m!} + \frac{1}{2} \Omega_{m}, & \text{for } x \in \mathbb{Z}. \end{cases}$$

Here the convergence is pointwise.

(b)

$$\sum_{j=0}^{m} \frac{2^{j-1}}{j!} \Omega_{m-j+1} B_j(\langle x \rangle)$$

$$= \sum_{k=0}^{m} \frac{1}{k!(m-k)!} E_k(\langle x \rangle) \langle x \rangle^{m-k}, \quad \text{for } x \notin \mathbb{Z},$$

$$\sum_{j=0, j \neq 1}^{m} \frac{2^{j-1}}{j!} \Omega_{m-j+1} B_j(\langle x \rangle)$$

$$= \frac{E_m}{m!} + \frac{1}{2} \Omega_m, \quad \text{for } x \in \mathbb{Z}.$$

Here $B_k(\langle x \rangle)$ is the Bernoulli function.

FOURIER SERIES OF FUNCTIONS INVOLVING EULER POLYNOMIALS

Question: For what values of $m \ge 1$, does $\sum_{k=0}^{m} \frac{E_k}{k!(m-k)!} = \frac{2}{m!} - \frac{E_m}{m!}$ hold?

Remark 3.3. In a previous paper (see [3,4,6,12]), it was shown that

$$\int_{0}^{1} \beta_{m}(x)dx = \sum_{l=0}^{m-1} \sum_{j=1}^{m-l} \frac{(-1)^{j} {m+1 \choose l+j} E_{l+j}}{(m+1)!} + \frac{2(-1)^{m+1} E_{m+1}}{(m+1)!}.$$
 (3.8)

Hence, we have the following identity.

$$\frac{1}{2} \left(-\sum_{k=0}^{m+1} \frac{E_k}{k!(m+1-k)!} + \frac{2}{(m+1)!} - \frac{E_{m+1}}{(m+1)!} \right)$$

$$= \sum_{l=0}^{m-1} \sum_{j=1}^{m-l} \frac{(-1)^j {m+1 \choose l+j} E_{l+j}}{(m+1)!} + \frac{2(-1)^{m+1} E_{m+1}}{(m+1)!}.$$

4. The fuction $\gamma_m(\langle x \rangle)$

Let $\gamma_m(x) = \sum_{k=1}^{m-1} \frac{1}{k(m-k)} E_k(x) x^{m-k}, (m \ge 2)$. Then we will consider the function

$$\gamma_m(\langle x \rangle) = \sum_{k=1}^{m-1} \frac{1}{k(m-k)} E_k(\langle x \rangle) \langle x \rangle^{m-k}, \tag{4.1}$$

defined on $(-\infty, \infty)$, which is periodic with period 1.

The Fourier series of $\gamma_m(\langle x \rangle)$ is

$$\sum_{n=-\infty}^{\infty} C_n^{(m)} e^{2\pi i n x},\tag{4.2}$$

where

$$C_n^{(m)} = \int_0^1 \gamma_m(\langle x \rangle) e^{-2\pi i n x} dx = \int_0^1 \gamma_m(x) e^{-2\pi i n x} dx.$$
 (4.3)

To proceed further, we observe the following.

$$\gamma'_{m}(x) = \sum_{k=1}^{m-1} \frac{1}{k(m-k)} \left(kE_{k-1}(x)x^{m-k} + (m-k)E_{k}(x)x^{m-k-1} \right)
= \sum_{k=1}^{m-1} \frac{1}{m-k} E_{k-1}(x)x^{m-k} + \sum_{k=1}^{m-1} \frac{1}{k} E_{k}(x)x^{m-k-1}
= \sum_{k=0}^{m-2} \frac{1}{m-k-1} E_{k}(x)x^{m-k-1} + \sum_{k=0}^{m-1} \frac{1}{k} E_{k}(x)x^{m-k-1}
= \frac{1}{m-1} x^{m-1} + \sum_{k=1}^{m-2} \frac{1}{m-k-1} E_{k}(x)x^{m-k-1} + \frac{1}{m-1} E_{m-1}(x)
+ \sum_{k=1}^{m-2} \frac{1}{k} E_{k}(x)x^{m-k-1}
= (m-1) \sum_{k=1}^{m-2} \frac{1}{k(m-1-k)} E_{k}(x)x^{m-1-k} + \frac{1}{m-1} \left(x^{m-1} + E_{m-1}(x) \right)
= (m-1) \gamma_{m-1}(x) + \frac{1}{m-1} \left(x^{m-1} + E_{m-1}(x) \right).$$
(4.4)

Thus.

$$\gamma'_{m}(x) = (m-1)\gamma_{m-1}(x) + \frac{1}{m-1} \left(x^{m-1} + E_{m-1}(x) \right).$$

From this, we have

$$\left(\frac{1}{m}\left(\gamma_{m+1}(x) - \frac{1}{m(m+1)}x^{m+1} - \frac{1}{m(m+1)}E_{m+1}(x)\right)\right)' = \gamma_m(x).$$

$$\int_{0}^{1} \gamma_{m}(x)dx$$

$$= \frac{1}{m} \left[\gamma_{m+1}(x) - \frac{1}{m(m+1)} x^{m+1} - \frac{1}{m(m+1)} E_{m+1}(x) \right]_{0}^{1}$$

$$= \frac{1}{m} \left(\gamma_{m+1}(1) - \gamma_{m+1}(0) - \frac{1}{m(m+1)} - \frac{1}{m(m+1)} \left(E_{m+1}(1) - E_{m+1}(0) \right) \right)$$

$$= \frac{1}{m} \left(\gamma_{m+1}(1) - \gamma_{m+1}(0) - \frac{1}{m(m+1)} + \frac{2}{m(m+1)} E_{m+1} \right).$$
(4.5)

$$\gamma_{m}(1) - \gamma_{m}(0)
= \sum_{k=1}^{m-1} \frac{1}{k(m-k)} (E_{k}(1) - E_{k}(0)\delta_{m,k})
= \sum_{k=1}^{m-1} \frac{1}{k(m-k)} (-E_{k}(0) + 2\delta_{k,0}) - \sum_{k=1}^{m-1} \frac{1}{k(m-k)} E_{k}(0)\delta_{m,k}
= -\sum_{k=1}^{m-1} \frac{E_{k}}{k(m-k)}.$$
(4.6)

FOURIER SERIES OF FUNCTIONS INVOLVING EULER POLYNOMIALS

Thus,

$$\gamma_m(1) = \gamma_m(0) \Leftrightarrow \sum_{k=1}^{m-1} \frac{E_k}{k(m-k)} = 0.$$
(4.7)

13

In addition,

$$\int_0^1 \gamma_m(x)dx = -\frac{1}{m} \left(\sum_{k=1}^m \frac{E_k}{k(m-k+1)} + \frac{1}{m(m+1)} - \frac{2}{m(m+1)} E_{m+1} \right). \tag{4.8}$$

Now, we would like to determine the Fourier coefficients $C_n^{(m)}$. Case $1:n \neq 0$.

$$C_{n}^{(m)} = \int_{0}^{1} \gamma_{m}(x)e^{-2\pi inx}dx$$

$$= -\frac{1}{2\pi in} \left[\gamma_{m}(x)e^{-2\pi inx}\right]_{0}^{1} + \frac{1}{2\pi in} \int_{0}^{1} \gamma'_{m}(x)e^{-2\pi inx}dx$$

$$= -\frac{1}{2\pi in} \left(\gamma_{m}(1) - \gamma_{m}(0)\right) + \frac{m-1}{2\pi in} \int_{0}^{1} \gamma_{m-1}(x)e^{-2\pi inx}dx$$

$$+ \frac{1}{2\pi in(m-1)} \int_{0}^{1} x^{m-1}e^{-2\pi inx}dx + \frac{1}{2\pi in(m-1)} \int_{0}^{1} E_{m-1}(x)e^{-2\pi inx}dx$$

$$= \frac{m-1}{2\pi in} C_{n}^{(m-1)} - \frac{1}{2\pi in} \Lambda_{m} - \frac{1}{2\pi in(m-1)} \Theta_{m} + \frac{2}{2\pi in(m-1)} \Phi_{m},$$
(4.9)

where , for $l \geq 1$,

$$\int_0^1 E_l(x)e^{-2\pi i nx}dx = \begin{cases} 2\sum_{k=1}^l \frac{(l)_{k-1}}{(2\pi i n)^k} E_{l-k+1}, & \text{for } n \neq 0, \\ -\frac{2}{l+1} E_{l+1}, & \text{for } n = 0. \end{cases}$$

$$\int_0^1 x^l e^{-2\pi i n x} dx = \begin{cases} -\sum_{k=1}^l \frac{(l)_{k-1}}{(2\pi i n)^k}, & \text{for } n \neq 0, \\ \frac{1}{l+1}, & \text{for } n = 0. \end{cases}$$

Here, for $m \geq 2$,

$$\Lambda_m = \gamma_m(1) - \gamma_m(0) = -\sum_{k=1}^{m-1} \frac{E_k}{k(m-k)},$$

$$\Theta_m = \sum_{k=1}^{m-1} \frac{(m-1)_{k-1}}{(2\pi i n)^k},$$

$$\Phi_m = \sum_{k=1}^{m-1} \frac{(m-1)_{k-1}}{(2\pi i n)^k} E_{m-k}.$$
(4.10)

$$\begin{split} C_{n}^{(m)} &= \frac{m-1}{2\pi in} C_{n}^{(m-1)} - \frac{1}{2\pi in} \Lambda_{m} - \frac{1}{2\pi in(m-1)} \Theta_{m} + \frac{2}{2\pi in(m-1)} \Phi_{m} \\ &= \frac{m-1}{2\pi in} \left(\frac{m-2}{2\pi in} C_{n}^{(m-2)} - \frac{1}{2\pi in} \Lambda_{m-1} - \frac{1}{2\pi in(m-2)} \Theta_{m-1} + \frac{2}{2\pi in(m-1)} \Phi_{m-1} \right) \\ &- \frac{1}{2\pi in} \Lambda_{m} - \frac{1}{2\pi in(m-1)} \Theta_{m} + \frac{2}{2\pi in(m-1)} \Phi_{m} \\ &= \frac{(m-1)(m-2)}{(2\pi in)^{2}} C_{n}^{(m-2)} - \frac{m-1}{(2\pi in)^{2}} \Lambda_{m-1} - \frac{1}{2\pi in} \Lambda_{m} - \frac{m-1}{(2\pi in)^{2}(m-2)} \Theta_{m-1} \\ &- \frac{1}{(2\pi in)(m-1)} \Theta_{m} + \frac{2(m-1)}{(2\pi in)^{2}(m-2)} \Phi_{m-1} + \frac{2}{2\pi in(m-1)} \Phi_{m} \\ &= \cdots \\ &= \frac{(m-1)!}{(2\pi in)^{m-2}} C_{n}^{(2)} - \sum_{j=1}^{m-2} \frac{(m-1)_{j-1}}{(2\pi in)^{j}} \Lambda_{m-j+1} - \sum_{j=1}^{m-2} \frac{(m-1)_{j-1}}{(2\pi in)^{j}(m-j)} \Theta_{m-j+1} \\ &+ \sum_{j=1}^{m-2} \frac{2(m-1)_{j-1}}{(2\pi in)^{j}(m-j)} \Phi_{m-j+1} \\ &= -\frac{1}{2} \frac{(m-1)_{j-1}}{(2\pi in)^{j}(m-j)} \Theta_{m-j+1} + \sum_{j=1}^{m-2} \frac{2(m-1)_{j-1}}{(2\pi in)^{j}(m-j)} \Phi_{m-j+1} \\ &= -\sum_{j=1}^{m-1} \frac{(m-1)_{j-1}}{(2\pi in)^{j}} \Lambda_{m-j+1} - \sum_{j=1}^{m-1} \frac{(m-1)_{j-1}}{(2\pi in)^{j}(m-j)} \Theta_{m-j+1} \\ &+ \sum_{j=1}^{m-1} \frac{2(m-1)_{j-1}}{(2\pi in)^{j}} \Lambda_{m-j+1} - \sum_{j=1}^{m-1} \frac{(m-1)_{j-1}}{(2\pi in)^{j}(m-j)} \Theta_{m-j+1} \\ &+ \sum_{j=1}^{m-1} \frac{2(m-1)_{j-1}}{(2\pi in)^{j}(m-j)} \Phi_{m-j+1}, \end{split}$$

where

$$C_n^{(2)} = \int_0^1 \gamma_2(x) e^{-2\pi i n x} dx = \int_0^1 (x^2 - \frac{1}{2}x) e^{-2\pi i n x} dx = -\frac{1}{2} \frac{1}{2\pi i n} - \frac{2}{(2\pi i n)^2}$$

$$\Lambda_2 = \frac{1}{2}, \ \Theta_2 = \frac{1}{2\pi i n}, \ \Phi_2 = \frac{1}{2\pi i n} \times (-\frac{1}{2}).$$

$$(4.12)$$

Before proceeding further, we note the following.

$$\sum_{j=1}^{m-1} \frac{(m-1)_{j-1}}{(2\pi i n)^j} \Lambda_{m-j+1}$$

$$= -\sum_{j=1}^{m-1} \frac{(m-1)_{j-1}}{(2\pi i n)^j} \sum_{k=1}^{m-j} \frac{E_k}{k(m-j-k+1)}$$

$$= -\frac{1}{m} \sum_{j=1}^{m-1} \sum_{k=1}^{m-j} \frac{(m)_j}{(2\pi i n)^j k(m-j-k+1)} E_k$$

$$= -\frac{1}{m} \sum_{s=1}^{m-1} \sum_{k=1}^{m-s} \frac{(m)_s}{(2\pi i n)^s k(m-s-k+1)} E_k$$

$$= -\frac{1}{m} \sum_{s=1}^{m} \sum_{l=s}^{m-1} \frac{(m)_s E_{l-s+1}}{(2\pi i n)^s (l-s+1)(m-l)}.$$
(4.13)

$$\sum_{j=1}^{m-1} \frac{2(m-1)_{j-1}}{(2\pi i n)^{j}(m-j)} \Phi_{m-j+1}$$

$$= \sum_{j=1}^{m-1} \frac{2(m-1)_{j-1}}{(2\pi i n)^{j}(m-j)} \sum_{k=1}^{m-j} \frac{(m-j)_{k-1}}{(2\pi i n)^{k}} E_{m-j-k+1}$$

$$= \frac{2}{m} \sum_{j=1}^{m-1} \sum_{k=1}^{m-j} \frac{(m)_{j+k-1}}{(2\pi i n)^{j+k}(m-j)} E_{m-j-k+1}$$

$$= \frac{2}{m} \sum_{j=1}^{m-1} \frac{1}{m-j} \sum_{s=j+1}^{m} \frac{(m)_{s-1}}{(2\pi i n)^{s}} E_{m-s+1}$$

$$= \frac{2}{m} \sum_{s=2}^{m} \frac{(m)_{s-1}}{(2\pi i n)^{s}} E_{m-s+1} \sum_{j=1}^{s-1} \frac{1}{m-j}$$

$$= \frac{2}{m} \sum_{s=2}^{m} \frac{(m)_{s-1}}{(2\pi i n)^{s}} E_{m-s+1} (H_{m-1} - H_{m-s})$$

$$= \frac{2}{m} \sum_{s=1}^{m} \frac{(m)_{s}}{(2\pi i n)^{s}} \frac{E_{m-s+1}}{m-s+1} (H_{m-1} - H_{m-s}).$$

$$\sum_{j=1}^{m-1} \frac{(m-1)_{j-1}}{(2\pi i n)^j (m-j)} \Theta_{m-j+1}$$

$$= \frac{1}{m} \sum_{s=1}^m \frac{(m)_s}{(2\pi i n)^s} \frac{H_{m-1} - H_{m-s}}{m-s+1}.$$
(4.15)

Putting everything together, we have

$$C_{n}^{(m)} = \frac{1}{m} \sum_{s=1}^{m} \sum_{l=s}^{m-1} \frac{(m)_{s} E_{l-s+1}}{(2\pi i n)^{s} (l-s+1)(m-l)}$$

$$-\frac{1}{m} \sum_{s=1}^{m} \frac{(m)_{s}}{(2\pi i n)^{s}} \frac{H_{m-1} - H_{m-s}}{m-s+1} + \frac{2}{m} \sum_{s=1}^{m} \frac{(m)_{s}}{(2\pi i n)^{s}} \frac{E_{m-s+1}}{m-s+1} (H_{m-1} - H_{m-s})$$

$$= -\frac{1}{m} \sum_{s=1}^{m} \left(\frac{(m)_{s}}{(2\pi i n)^{s}} \frac{H_{m-1} - H_{m-s}}{m-s+1} (1 - 2E_{m-s+1}) - \sum_{l=s}^{m-1} \frac{(m)_{s} E_{l-s+1}}{(2\pi i n)^{s} (l-s+1)(m-l)} \right).$$
(4.16)

Case 2: n = 0.

16

$$C_0^{(m)} = \int_0^1 \gamma_m(x) dx = -\frac{1}{m} \left(\sum_{k=1}^m \frac{E_k}{k(m-k+1)} + \frac{1}{m(m+1)} - \frac{2}{m(m+1)} E_{m+1} \right). \tag{4.17}$$

Question: For what values of $m \ge 1$, does $\sum_{k=0}^{m} E_k = 2 - E_m$ hold?

Remark 4.1. In a previous paper (see [3,4,6,12]), it was shown that

$$\int_{0}^{1} \gamma_{m}(x)dx = \frac{1}{m(m^{2}-1)} \sum_{l=1}^{m-1} \sum_{j=1}^{m-l} \frac{(-1)^{j} {m+1 \choose l+j} E_{l+j}}{{m-2 \choose l-1}} + \frac{2(-1)^{m+1} E_{m+1}}{m(m^{2}-1)} \sum_{l=1}^{m-1} \frac{(-1)^{l}}{{m-2 \choose l-1}}.$$
(4.18)

So, we obtain the following identity.

$$-\frac{1}{m} \left(\sum_{k=1}^{m} \frac{E_k}{k(m-k+1)} + \frac{1}{m(m+1)} - \frac{2}{m(m+1)} E_{m+1} \right)$$

$$= \frac{1}{m(m^2-1)} \sum_{l=1}^{m-1} \sum_{j=1}^{m-l} \frac{(-1)^j \binom{m+1}{l+j} E_{l+j}}{\binom{m-2}{l-1}} + \frac{2(-1)^{m+1} E_{m+1}}{m(m^2-1)} \sum_{l=1}^{m-1} \frac{(-1)^l}{\binom{m-2}{l-1}},$$
(4.19)

for $m \geq 2$.

 $\gamma_m(\langle x \rangle)$, $(m \geq 2)$ is piecewise C^{∞} . Moreover, $\gamma_m(\langle x \rangle)$ is continuous for those integers $m \geq 2$ with and $\Lambda_m = 0$, and discontinuous with jump discontinuities at integers for those integers ≥ 2 with $\Lambda_m \neq 0$.

Assume first that $\Lambda_m = 0$. Then $\gamma_m(1) = \gamma_m(0)$. $\gamma_m(\langle x \rangle)$ is piecewise C^{∞} and continuous. So the Fourier series of $\gamma_m(\langle x \rangle)$ converges uniformly to $\gamma_m(\langle x \rangle)$, and

$$\begin{split} &\gamma_{m}(< x >) \\ &= -\frac{1}{m} \left(\sum_{k=1}^{m} \frac{E_{k}}{k(m-k+1)} + \frac{1}{m(m+1)} - \frac{2}{m(m+1)} E_{m+1} \right) \\ &- \sum_{n=-\infty, n \neq 0}^{\infty} \left(\frac{1}{m} \sum_{s=1}^{m} \left(\frac{(m)_{s}}{(2\pi i n)^{s}} \frac{H_{m-1} - H_{m-s}}{m-s+1} (1 - 2E_{m-s+1}) \right) \\ &- \sum_{l=s}^{m-1} \frac{(m)_{s} E_{l-s+1}}{(2\pi i n)^{s} (l-s+1)(m-l)} \right) e^{2\pi i n x} \\ &= -\frac{1}{m} \left(\sum_{k=1}^{m} \frac{E_{k}}{k(m-k+1)} + \frac{1}{m(m+1)} - \frac{2}{m(m+1)} E_{m+1} \right) \\ &+ \frac{1}{m} \sum_{s=1}^{m} \left(\binom{m}{s} \frac{H_{m-1} - H_{m-s}}{m-s+1} (1 - 2E_{m-s+1}) - \binom{m}{s} \sum_{l=s}^{m-1} \frac{E_{l-s+1}}{(l-s+1)(m-l)} \right) \\ &\times \left(-s! \sum_{n=-\infty, n \neq 0}^{\infty} \frac{e^{2\pi i n x}}{(2\pi i n)^{s}} \right) \\ &= -\frac{1}{m} \left(\sum_{k=1}^{m} \frac{E_{k}}{k(m-k+1)} + \frac{1}{m(m+1)} - \frac{2}{m(m+1)} E_{m+1} \right) \\ &+ \frac{1}{m} \sum_{s=2}^{m} \left(\binom{m}{s} \frac{H_{m-1} - H_{m-s}}{m-s+1} (1 - 2E_{m-s+1}) - \binom{m}{s} \sum_{l=s}^{m-1} \frac{E_{l-s+1}}{(l-s+1)(m-l)} \right) B_{s}(< x >) \\ &+ \left(-\sum_{l=1}^{m-1} \frac{E_{l}}{l(m-l)} \right) \times \begin{cases} B_{1}(< x >), & \text{for } x \notin \mathbb{Z}, \\ 0, & \text{for } x \in \mathbb{Z}, \end{cases} \end{aligned} \tag{4.20}$$

Now, we get the following theorem.

Theorem 4.2. Let m be an integer ≥ 2 , with

$$\Lambda_m = -\sum_{k=1}^{m-1} \frac{E_k}{k(m-k)} = 0.$$

Then we have the following.

(a) $\sum_{k=1}^{m-1} \frac{1}{k(m-k)} \tilde{E}_k(\langle x \rangle) \langle x \rangle^{m-k}$ has the Fourier series expansion

$$\sum_{k=1}^{m-1} \frac{1}{k(m-k)} E_k(\langle x \rangle) \langle x \rangle^{m-k}$$

$$= -\frac{1}{m} \left(\sum_{k=1}^{m} \frac{E_k}{k(m-k+1)} + \frac{1}{m(m+1)} - \frac{2}{m(m+1)} E_{m+1} \right)$$

$$- \sum_{n=-\infty, n\neq 0}^{\infty} \left(\frac{1}{m} \sum_{s=1}^{m} \left(\frac{(m)_s}{(2\pi i n)^s} \frac{H_{m-1} - H_{m-s}}{m-s+1} (1 - 2E_{m-s+1}) - \sum_{l=s}^{m-1} \frac{(m)_s E_{l-s+1}}{(2\pi i n)^s (l-s+1)(m-l)} \right) \right) e^{2\pi i n x},$$

for all $x \in (-\infty, \infty)$, where the convergence is uniform.

(b)

$$\begin{split} &\sum_{k=1}^{m-1} \frac{1}{k(m-k)} E_k(< x >) < x >^{m-k} \\ &= -\frac{1}{m} \Big(\sum_{k=1}^m \frac{E_k}{k(m-k+1)} + \frac{1}{m(m+1)} - \frac{2}{m(m+1)} E_{m+1} \Big) \\ &+ \frac{1}{m} \sum_{s=2}^m \Big(\binom{m}{s} \frac{H_{m-1} - H_{m-s}}{m-s+1} (1 - 2E_{m-s+1}) - \binom{m}{s} \sum_{l=s}^{m-1} \frac{E_{l-s+1}}{(l-s+1)(m-l)} \Big) B_s(< x >), \end{split}$$

for all $x \in (-\infty, \infty)$. Here $B_k(\langle x \rangle)$ is the Bernoulli function.

Assume next that m is an integer ≥ 2 with $\Lambda_m \neq 0$. Then, $\gamma_m(1) \neq \gamma_m(0)$. Hence $\gamma_m(< x >)$ is piecewise C^{∞} and discontinuous with jump discontinuities at integers. Thus the Fourier series of $\gamma_m(< x >)$ converges pointwise to $\gamma_m(< x >)$, for $x \notin \mathbb{Z}$, and converges to

$$\frac{1}{2}(\gamma_m(0) + \gamma_m(1)) = \gamma_m(0) + \frac{1}{2}\Lambda_m = -\frac{1}{2}\sum_{k=1}^{m-1} \frac{E_k}{k(m-k)},$$

for $x \in \mathbb{Z}$.

Hence we obtain the following theorem.

Theorem 4.3. Let m be an integer ≥ 2 , with

$$\Lambda_m = -\sum_{k=1}^{m-1} \frac{E_k}{k(m-k)} \neq 0.$$

Then, we have the following.

(a)

$$-\frac{1}{m} \left(\sum_{k=1}^{m} \frac{E_k}{k(m-k+1)} + \frac{1}{m(m+1)} - \frac{2}{m(m+1)} E_{m+1} \right)$$

$$-\sum_{n=-\infty, n\neq 0}^{\infty} \left(\frac{1}{m} \sum_{s=1}^{m} \left(\frac{(m)_s}{(2\pi i n)^s} \frac{H_{m-1} - H_{m-s}}{m-s+1} (1 - 2E_{m-s+1}) \right) - \sum_{l=s}^{m-1} \frac{(m)_s E_{l-s+1}}{(2\pi i n)^s (l-s+1)(m-l)} \right) e^{2\pi i n x}$$

$$= \begin{cases} \sum_{k=1}^{m-1} \frac{1}{k(m-k)} E_k (< x >) < x >^{m-k}, & \text{for } x \notin \mathbb{Z}, \\ -\frac{1}{2} \sum_{k=1}^{m-1} \frac{E_k}{k(m-k)}, & \text{for } x \in \mathbb{Z}. \end{cases}$$

Here the convergence is pointwise.

(b)

$$-\frac{1}{m}\left(\sum_{k=1}^{m}\frac{E_{k}}{k(m-k+1)} + \frac{1}{m(m+1)} - \frac{2}{m(m+1)}E_{m+1}\right)$$

$$+\frac{1}{m}\sum_{s=1}^{m}\left(\binom{m}{s}\frac{H_{m-1} - H_{m-s}}{m-s+1}(1 - 2E_{m-s+1}) - \binom{m}{s}\sum_{l=s}^{m-1}\frac{E_{l-s+1}}{(l-s+1)(m-l)}\right)B_{s}(< x >)$$

$$=\sum_{k=1}^{m-1}\frac{1}{k(m-k)}E_{k}(< x >) < x >^{m-k}, \text{ for } x \notin \mathbb{Z},$$

$$-\frac{1}{m}\left(\sum_{k=1}^{m}\frac{E_{k}}{k(m-k+1)} + \frac{1}{m(m+1)} - \frac{2}{m(m+1)}E_{m+1}\right)$$

$$+\frac{1}{m}\sum_{s=2}^{m}\left(\binom{m}{s}\frac{H_{m-1} - H_{m-s}}{m-s+1}(1 - 2E_{m-s+1}) - \binom{m}{s}\sum_{l=s}^{m-1}\frac{E_{l-s+1}}{(l-s+1)(m-l)}\right)B_{s}(< x >)$$

$$=-\frac{1}{2}\sum_{l=s}^{m-1}\frac{E_{k}}{k(m-k)}, \text{ for } x \in \mathbb{Z}.$$

Question: For what values of $m \ge 2$, does $\sum_{k=1}^{m-1} \frac{E_k}{k(m-k)} = 0$ hold?

References

- A. Bayad, T. Kim, Higher recurrences for Apostol-Bernoulli-Euler numbers, Russ. J. Math. Phys., 16(2012), no.1, 1-10.
- A. Bayad, T. Kim, Identities involving values of Bernstein, q-Bernoulli, and q-Euler polynomials, Russian J. Math. Phys., 18(2011), no. 2, 133-143.
- D.S. Kim, D. V. Dolgy, T. Kim, S.-H. Rim Some Formulae for the Product of Two Bernoulli and Euler Polynomials, Abstr. Appl. Anal. 2012, Art. ID 784307.
- D.S. Kim, T. Kim, Some identities of higher order Euler polynomials arising from Euler basis, Integral Transforms Spec. Funct., 24(9) (2013), 734-738.
- D.S. Kim, T. Kim, Y.H. Lee, Some arithmetic properties of Bernoulli and Euler nembers, Adv. Stud. Contemp. Math., 22(2010), no.4, 467-480.
- D.S. Kim, T. Kim, T. Mansour, Euler basis and the product of several Bernoulli and Euler polynomials, Adv. Stud. Contemp. Math., 24(2014), no.4, 535-547.

- T. Kim, Note on the Euler numbers and polynomials, Adv. Stud. Contemp. Math. (Kyungshang), 17(2008), 131–136.
- 8. T. Kim, On the weighted q-Euler numbers and q-Berstein polynomials, Adv. Stud. Contemp. Math., 22(2012), no.1, 7-12.
- 9. T. Kim, Some identities for the Bernoulli, the Euler and Genocchi numbers and polynomials, Adv. Stud. Contemp. Math., 20(2015), no.1, 23-28.
- T. Kim, Euler numbers and polynomials associated with zeta functions, Abstr. Appl. Anal. 2008, Art. ID 581582, 11 pp.
- 11. T. Kim, J. Choi, Y. H. Kim, A note on the values of Euler zeta functions at positive integers, Adv. Stud. Contemp. Math. (Kyungshang), 22(2012), 27–34.
- 12. T. Kim, D. S. Kim, D. V. Dolgy, S.-H. Rim, Some identities on the Euler numbers arising from Euler basis polynomials, ARS Combinatoria 109(2013), 433–446.
- 13. T. Kim, D. S. Kim, S.-H. Rim, D. V. Dolgy, Fourier series of higher-order Bernoulli functions and their applications, J. Inequal. Appl. 2016, to appear.
- 14. J. E. Marsden, Elementary classical analysis, W. H. Freeman and Company, 1974.
- 15. B.H. Yadav, Absolute convergence of Fourier series, Thesis (Ph.D.)-Maharaja Sayajirao University of Baroda (India), 1964.
- Y. Simsek, Interpolation functions of the Eulerian type polynomials and numbers, Adv. Stud. Contemp. Math. (Kyungshang), 23(2013), no. 2, 301-307.
- 17. D. G. Zill, M. R. Cullen, Advanced Engineering Mathematics, Jones and Bartlett Publishers 2006.

DEPARTMENT OF MATHEMATICS, COLLEGE OF SCIENCE, TIANJIN POLYTECHNIC UNIVERSITY, TIANJIN 300160, CHINA, DEPARTMENT OF MATHEMATICS, KWANGWOON UNIVERSITY, SEOUL, 139-701, REPUBLIC OF KOREA

E-mail address: tkkim@kw.ac.kr

Department of Mathematics, Sogang University, Seoul, 121-742, Republic of Korea $E\text{-}mail\ address$: dskim@sogang.ac.kr

Department of Mathematics, Kwangwoon University, Seoul, 139-701, Republic of Korea

E-mail address: jgw5687@naver.com

Department of Mathematics Education and RINS, Gyeongsang National University, Jinju, Gyeongsangnamdo, 52828, Republic of Korea

E-mail address: mathkjk26@gnu.ac.kr

Higher order generalization of Bernstein type operators defined by (p,q)-integers

M. Mursaleen¹, Md. Nasiruzzaman¹, Nurgali Ashirbayev², Azimkhan Abzhapbarov ²

¹Department of Mathematics, Aligarh Muslim University, Aligarh–202002, India ²Science-Pedagogical Faculty, M. Auezov South Kazakhstan State University, Shymkent, 160012, Kazakhstan

mursaleenm@gmail.com; nasir3489@gmail.com; ank_56@mail.ru; azeke_55@mail.ru

Abstract

In this paper, we introduce the higher order generalization of Bernstein type operators defined by (p,q)-integers. We establish some approximation results for these new operators by using the modulus of continuity.

Keywords and phrases: (p,q)-integers; (p,q)-Bernstein operators; modulus of continuity; approximation theorems.

AMS Subject Classification (2010): 41A10, 41A36.

1. Introduction and preliminaries

In 1912, S.N Bernstein [4] introduced the following sequence of operators $B_n: C[0,1] \to C[0,1]$ defined for any $n \in \mathbb{N}$ and for any $f \in C[0,1]$ such as

$$B_n(f;x) = \sum_{k=0}^n \binom{n}{k} x^k (1-x)^{n-k} f\left(\frac{k}{n}\right), \ x \in [0,1].$$
 (1.1)

In approximation theory, q-type generalization of Bernstein polynomials was introduced by Lupaş [7].

For $f \in C[0, 1]$, the generalized Bernstein polynomial based on the q-integers is defined by Phillips [15] as follows

$$B_{n,q}(f;x) = \sum_{k=0}^{n} \begin{bmatrix} n \\ k \end{bmatrix}_{q} x^{k} \prod_{s=0}^{n-k-1} (1 - q^{s}x) f\left(\frac{[k]_{q}}{[n]_{q}}\right), x \in [0,1].$$
 (1.2)

Recently, Mursaleen et al. [10] applied (p,q)-calculus in approximation theory and introduced first (p,q)-analogue of Bernstein operators and defined as:

$$B_{n,p,q}(f;x) = \frac{1}{p^{\frac{n(n-1)}{2}}} \sum_{k=0}^{n} f\left(\frac{[k]}{p^{k-n}[n]}\right) P_{n,k}(p,q;x), \ 0 < q < p \le 1, \ x \in [0,1]$$

where

$$P_{n,k}(p,q;x) = p^{\frac{k(k-1)}{2}} \begin{bmatrix} n \\ k \end{bmatrix}_{p,q} x^k \prod_{s=0}^{n-k-1} (p^s - q^s x).$$
 (1.3)

They have also introduced and studied approximation properties based on (p, q)-integers given as: (p, q)-Bernstein-Stancu operators [11], (p, q)-Bernstein-Shurer operators [14] and (p, q)-Bleimann-Butzer-Hahn operators [13]. In the sequel, some more articles on (p, q)-approximation have also been appeared, e.g. [1], [2], [3], [6], [9], [12] and [13].

We recall some basic properties of (p, q)-integers.

The (p,q)-integer $[n]_{p,q}$ is defined by

$$[n]_{p,q} = \frac{p^n - q^n}{p - q}, \ n = 0, 1, 2, \dots, \ 0 < q < p \le 1.$$

The (p, q)-Binomial expansion is

$$(x+y)_{p,q}^n := (x+y)(px+qy)(p^2x+q^2y)\cdots(p^{n-1}x+q^{n-1}y)$$

and the (p,q)-binomial coefficients are defined by

$$\begin{bmatrix} n \\ k \end{bmatrix}_{p,q} := \frac{[n]_{p,q}!}{[k]_{p,q}![n-k]_{p,q}!}.$$

For p = 1, all the notions of (p, q)-calculus are reduced to q-calculus. For details on (p, q)-calculus and q-calculus, one can refer [5, 7]. In this paper we use the notation [n] in place of $[n]_{p,q}$.

In [5], (p,q)-derivative of a function f(x) is defined by

$$D_{p,q}f(x) = \frac{f(px) - f(qx)}{(p-q)x}, \ x \neq 0,$$
(1.4)

and the formulae for the (p,q)-derivative for the product of two functions is given as

$$D_{p,q}(fg)(x) = f(px).D_{p,q}g(x) + \{D_{p,q}f(x)\}.g(qx),$$
(1.5)

also

$$D_{p,q}(fg)(x) = f(qx).D_{p,q}g(x) + \{D_{p,q}f(x)\}.g(px).$$
(1.6)

Let $r \in \mathbb{N} \cup \{0\}$ be a fixed number. For $f \in C^r[0,1]$ and $m \in \mathbb{N}$, we define r^{th} order (p,q)-Bernstein type operators as follows:

$$B_{n,p,q}^{[r]}(f;x) = \frac{1}{p^{\frac{n(n-1)}{2}}} \sum_{k=0}^{n} P_{n,k}(p,q;x) \sum_{i=0}^{r} \frac{1}{i!} f^{(i)} \left(\frac{[k]}{p^{k-n}[n]} \right) \left(x - \frac{[k]}{p^{k-n}[n]} \right)^{i}$$
(1.7)

In this paper, using the moment estimates from [8], we give the estimates of the central moments for these operators. We also study some approximation properties of an r^{th} order generalization of the operators defined by (1.7) using the techniques of the work on the higher order generalization of q-analogue [16]. Further, we study approximation properties and prove Voronovskaja type theorem for these operators.

If we put p=1, then we get the moments for q-Bernstein operators [8] and the usual generalization higher order q-Bernstein operators [16], respectively.

2. Main results

We have the following elementary result.

Proposition 2.1. For $n \ge 1$, $0 < q < p \le 1$

$$D_{p,q}(1+x)_{p,q}^{n} = [n](1+qx)_{p,q}^{n-1}.$$
(2.1)

Proof. By applying simple calculation on (p,q)-analogue, we have

roof. By applying simple calculation on
$$(p,q)$$
-analogue, we have
$$(1+px)_{p,q}^n = p^{n-1}(1+px)(1+qx)_{p,q}^{n-1}, (1+qx)_{p,q}^n = (p^{n-1}+q^nx)(1+qx)_{p,q}^{n-1}.$$
(2.2)

Applying (p,q)-derivative and result (2.2) we get the desired result.

Lemma 2.2. Let $B_{n,p,q}(f;x)$ be given by (1.7). Then for any $m \in \mathbb{N}$, $x \in [0,1]$ and $0 < q < p \le 1$ we have

$$B_{n,p,q}\left((t-x)_{p,q}^{m+1};x\right) = \frac{p^{m+n}x(1-x)}{[n]}D_{p,q}\left\{B_{n,p,q}\left((t-\frac{x}{p})_{p,q}^{m};\frac{x}{p}\right)\right\} + \frac{p^{m+n-1}[m]x(1-x)}{[n]}B_{n,p,q}\left((t-\frac{qx}{p})_{p,q}^{m-1};\frac{qx}{p}\right) + \frac{[m](p^{n}-q^{n})x}{[n]}B_{n,p,q}\left((t-x)_{p,q}^{m};x\right).$$

Proof. First of all by using (1.5) and Proposition 2.1, we have

$$D_{p,q} \left(\frac{1}{p^{\frac{n(n-1)}{2}}} \sum_{k=0}^{n} \left(t - \frac{x}{p} \right)_{p,q}^{m} P_{n,k}(p,q; \frac{x}{p}) \right)$$

$$= \frac{1}{p^{\frac{n(n-1)}{2}}} \left(\sum_{k=0}^{n} (t-x)_{p,q}^{m} D_{p,q} \{ P_{n,k}(p,q;\frac{x}{p}) \} - \frac{[m]}{p} \sum_{k=0}^{n} \left(t - \frac{qx}{p} \right)_{p,q}^{m-1} P_{n,k}(p,q;\frac{qx}{p}) \right).$$
(2.3)

Now in the same way by using (1.5) and Proposition 2.1, we have

$$D_{p,q}\left\{P_{n,k}\left(p,q;\frac{x}{p}\right)\right\} = D_{p,q}\left\{p^{\frac{k(k-1)}{2}}[k]\left[\begin{array}{c}n\\k\end{array}\right]_{p,q}^{1}\left(\frac{x}{p}\right)^{k}\left(1-\frac{x}{p}\right)^{k}\right\}$$

$$= p^{\frac{k(k-1)}{2}} \left([k] \begin{bmatrix} n \\ k \end{bmatrix}_{p,q} \frac{1}{p^k} x^{k-1} \left(1 - \frac{qx}{p} \right)_{p,q}^{n-k} - [n-k] \begin{bmatrix} n \\ k \end{bmatrix}_{p,q} \frac{1}{p} x^k \left(1 - \frac{qx}{p} \right)_{p,q}^{n-k-1} \right). \tag{2.4}$$

Now by a simple calculation, we have

$$\left(1 - \frac{qx}{p}\right)_{p,q}^{n-k} = \frac{1}{p^{n-k}}(p - qx)_{p,q}^{n-k+1} = \frac{1}{p^{n-k}}\frac{1}{(1-x)}(p^{n-k} - q^{n-k}x)(1-x)_{p,q}^{n-k} \tag{2.5}$$

3

$$\left(1 - \frac{qx}{p}\right)_{p,q}^{n-k-1} = \frac{1}{p^{n-k-1}} \frac{1}{(1-x)} (1-x)_{p,q}^{n-k}.$$
(2.6)

From (2.4),(2.5) and (2.6), we get

$$D_{p,q}\left\{P_{n,k}\left(p,q;\frac{x}{p}\right)\right\} = \frac{P_{n,k}(p,q;x)}{p^n x(1-x)} \left([k](p^{n-k}-q^{n-k}x) - p^k[n-k]x\right),$$

which implies that

$$D_{p,q}\left\{P_{n,k}\left(p,q;\frac{x}{p}\right)\right\} = \frac{P_{n,k}(p,q;x)}{p^n x(1-x)} \left(p^{n-k}[k] - [n]x\right). \tag{2.7}$$

From (2.3), (2.7), we have

$$D_{p,q}\left(\sum_{k=0}^{n} \left(t - \frac{x}{p}\right)_{p,q}^{m} P_{n,k}(p,q;\frac{x}{p})\right)$$

$$= -\frac{1}{p^{\frac{n(n-1)}{2}}} \frac{[m]}{p} \sum_{k=0}^{n} \left(t - \frac{qx}{p}\right)_{p,q}^{m-1} P_{n,k}(p,q;\frac{qx}{p})$$

$$+ \frac{1}{p^{\frac{n(n-1)}{2}}} \frac{1}{p^{n}x(1-x)} \sum_{k=0}^{n} (t-x)_{p,q}^{m} P_{n,k}(p,q;x)(p^{n-k}[k] - [n]x)$$

$$= -\frac{1}{p^{\frac{n(n-1)}{2}}} \frac{[m]}{p} \sum_{k=0}^{n} \left(t - \frac{qx}{p}\right)_{p,q}^{m-1} P_{n,k}(p,q;\frac{qx}{p})$$

$$+ \frac{1}{p^{\frac{n(n-1)}{2}}} \frac{1}{p^{n}x(1-x)} \sum_{k=0}^{n} (t-x)_{p,q}^{m} P_{n,k}(p,q;x)$$

$$\times \left(\frac{[n]}{n^{m}} (p^{m}t - q^{m}x) - \frac{[n]}{n^{m}} (p^{m} - q^{m})x\right).$$

Hence we have
$$D_{p,q} \left\{ B_{n,p,q} \left((t - \frac{x}{p})_{p,q}^m; \frac{x}{p} \right) \right\}$$

$$= -\frac{[m]}{p} B_{n,p,q} \left((t - \frac{qx}{p})_{p,q}^{m-1}; \frac{qx}{p} \right) + \frac{[n]}{p^{m+n} x (1-x)} B_{n,p,q} \left((t-x)_{p,q}^{m+1}; x \right)$$

$$- \frac{[m] (p^n - q^n)}{p^{m+n} (1-x)} B_{n,p,q} \left((t-x)_{p,q}^m; x \right).$$

This complete the proof of Lemma 2.2.

Lemma 2.3. Let $B_{n,p,q}\left((t-x)_{p,q}^m;x\right)$ be a polynomial in x of degree less than or equal to m and the minimum degree of $\frac{1}{[n]}$ is $\lfloor \frac{m+1}{2} \rfloor$. Then for any fixed $m \in \mathbb{N}$ and $x \in [0,1], 0 < q < p \le 1$ we have

$$B_{n,p,q}\left((t-x)_{p,q}^m;x\right) = \frac{x(1-x)}{\lceil n \rceil^{\lfloor \frac{m+1}{2} \rfloor}} \sum_{k=0}^{m-2} b_{k,m,n}(p,q)x^k, \tag{2.8}$$

such that the coefficients $b_{k,m,n}(p,q)$ satisfy $|b_{k,m,n}(p,q)| \le b_m$, $k=1,2,\cdots,m-2$ and b_m does not depend on x, t, p, q; where $\lfloor a \rfloor$ is an integer part of $a \geq 0$.

Proof. Clearly by Lemma 2.2 it is true for m = 2. Assuming it is true for m, then from the recurrence of Lemma 2.2 and equation (2.8) we easily get

$$B_{n,p,q}\left((t-x)_{p,q}^{m+1};x\right) = \frac{x(1-x)}{\lceil n \rceil^{\lfloor \frac{m+2}{2} \rfloor}} \sum_{k=0}^{m-1} b_{k,m+1,n}(p,q)x^{k},$$

where

$$b_{k,m+1,n}(p,q) = \frac{1}{[n]^{\alpha}} \left(p^{m+n-k}[k] + p^{m+n-k-1}q^k \right) b_{k,m,n}(p,q)$$

$$- \frac{1}{[n]^{\alpha}} \left(p^{m+n+1-k}[k-1] + [2]p^{m+n-k-1}q^{k-1} \right) b_{k-1,m,n}(p,q)$$

$$+ \frac{1}{[n]^{\alpha}} [m](p^n - q^n) b_{k-1,m,n}(p,q) + [m]p^{m+n-k-1}q^k b_{k-1,m-1,n}(p,q)$$

$$- [m]p^{m+n-k-1}q^k b_{k-2,m-1,n}(p,q).$$

Clearly

$$\alpha = 1 + \lfloor \frac{m+1}{2} \rfloor - \lfloor \frac{m+2}{2} \rfloor, \ 0 \leq k \leq m-1,$$

which lead us that either $\alpha = 0$ or $\alpha = 1$.

Since $|b_{k,m,n}(p,q)| \le b_m$, for k = m - 1, clearly we have

$$|b_{k,m+1,n}(p,q)| \leq \frac{1}{[n]^{\alpha}} \left(p^{n+1}[m-1] + p^{n}q^{m-1} \right) b_{m} + \frac{1}{[n]^{\alpha}} \left(p^{n+2}[m-2] + [2]p^{n}q^{m-2} \right) b_{m}$$

$$+ \frac{1}{[n]^{\alpha}} [m] (p^{n} - q^{n}) b_{m} + [m] p^{n}q^{m-1} b_{m-1}$$

$$+ [m] p^{n}q^{m-1} b_{m-1}$$

$$= \frac{1}{[n]^{\alpha}} \left(p[m-1] + q^{m-1} \right) b_{m} + \frac{1}{[n]^{\alpha}} \left(p^{2}[m-2] + [2]q^{m-2} \right) b_{m}$$

$$+ \frac{1}{[n]^{\alpha}} [m] b_{m} + [m] q^{m-1} b_{m-1} + [m] q^{m-1} b_{m-1}$$

$$= b_{m+1}, \ k = 1, 2, \dots m-1,$$

and b_m does not depend on x, t, p, q. This complete the proof.

Remark 2.4. From the Lemma 2.3 we have

$$B_{n,p,q}\left((t-x)_{p,q}^m;x\right) = x(1-x)Q_{m-2}, \ B_{n,p,q}\left((t-x)_{p,q}^m;x\right)\Big|_{x=0,1} = 0, \quad (2.9)$$

where Q_{m-2} is a polynomial of highest degree m-2.

From the Lemma 2.2 and Lemma 2.3 we have the following theorem.

Theorem 2.5. Let $m \in \mathbb{N}$ and $0 < q < p \le 1$. Then there exits a constant $C_m > 0$ such that for any $x \in [0,1]$, we have

$$|B_{n,p,q}((t-x)_{p,q}^m;x)| \le C_m \frac{x(1-x)}{[n]^{\lfloor \frac{m+1}{2} \rfloor}}.$$

Lemma 2.6. For any fixed $m \in \mathbb{N}$ and $x \in [0,1]$, $0 < q < p \le 1$ we have

$$(t-x)^m = \sum_{k=1}^m \gamma_{m,k} (p-q)^{m-k} x^{m-k} (t-x)_{p,q}^k = \sum_{k=1}^m \gamma_{m,k} \left(\frac{p^n - q^n}{[n]}\right)^{m-k} x^{m-k} (t-x)_{p,q}^k$$
(2.10)

where

$$\gamma_{m,k} = \begin{cases} \frac{\gamma_{m-1,k-1}}{p^{k-1}} - \frac{[k]\gamma_{m-1,k}}{p^k}, & k = 1, \dots, m-1, \\ 1, & k = m, \end{cases}$$

the coefficients $\gamma_{m,k}$ satisfy $| \gamma_{m,k} | \leq \gamma_m$, $k = 1, \dots, m$ and γ_m does not depend on x, t, p, q.

Proof. Inductively, for m=1, it is obvious. For $m \ge 1$ the relation (2.10) holds. For $k=1,\cdots,m$, we have

$$(t-x)^{m+1} = \sum_{k=1}^{m} \gamma_{m,k} (p-q)^{m-k} x^{m-k} (t-x)_{p,q}^{k} (t-x)^{m}, \qquad (2.11)$$

We can write

$$t - x = \frac{1}{p^k} \left(p^k t - q^k x - (p - q)[k]_{p,q} x \right)$$
 (2.12)

(2.11),(2.12) imply that,

$$\begin{array}{lll} (t-x)^{m+1} & = & \displaystyle \sum_{k=1}^m \gamma_{m,k}(p-q)^{m-k}x^{m-k}(t-x)_{p,q}^{k+1}\frac{1}{p^k} \\ & - & \displaystyle \sum_{k=1}^m \gamma_{m,k}(p-q)^{m-k}x^{m-k}(t-x)_{p,q}^k\frac{1}{p^k}(p-q)[k]_{p,q}x \\ & = & \displaystyle \frac{\gamma_{m,m}(t-x)_{p,q}^{m+1}}{p^m} + \displaystyle \sum_{k=2}^m \frac{1}{p^{k-1}}\gamma_{m,k-1}(p-q)^{m+1-k}x^{m+1-k}(t-x)_{p,q}^k \\ & - & \displaystyle \frac{\gamma_{m,1}(p-q)^mx^m(t-x)}{p} - \displaystyle \sum_{k=2}^m \frac{1}{p^k}[k]\gamma_{m,k}(p-q)^{m+1-k}x^{m+1-k}(t-x)_{p,q}^k \\ & = & \displaystyle \frac{\gamma_{m,m}(t-x)_{p,q}^{m+1}}{p^m} - \frac{\gamma_{m,1}(p-q)^mx^m(t-x)}{p} \\ & + & \displaystyle \sum_{k=2}^m \left(\frac{\gamma_{m,k-1}}{p^{k-1}} - \frac{[k]\gamma_{m,k}}{p^k}\right)(p-q)^{m+1-k}x^{m+1-k}(t-x)_{p,q}^k \\ & = & \displaystyle \sum_{k=1}^{m+1} \gamma_{m+1,k}(p-q)^{m+1-k}x^{m+1-k}(t-x)_{p,q}^k, \end{array}$$

where

$$\gamma_{m+1,k} = \begin{cases} \frac{\gamma_{m,k-1}}{p^{k-1}} - \frac{[k]\gamma_{m,k}}{p^k}, & k = 1, \dots, m, \quad \gamma_{m,0} = 0\\ \gamma_{m,m} = 1, & k = m+1. \end{cases}$$

Theorem 2.7. Let $m \in \mathbb{N}$ and $0 < q < p \le 1$. Then there exits a constant $E_m > 0$ such that for any $x \in [0,1]$, we have

$$|B_{n,p,q}((t-x)^m;x)| \le E_m \frac{x(1-x)}{[n]^{\lfloor \frac{m+1}{2} \rfloor}}.$$

Proof. From Lemma 2.6 we have

$$|B_{n,p,q}((t-x)^{m},x)| \leq \sum_{k=1}^{m} |\gamma_{m,k}| \left(\frac{p^{n}-q^{n}}{[n]}\right)^{m-k} |B_{n,p,q}((t-x)_{p,q}^{k},x)|$$

$$\leq \gamma_{m} \left(|B_{n,p,q}((t-x)_{p,q}^{m},x)| + \sum_{k=1}^{m-1} \frac{1}{[n]^{m-k}} |B_{n,p,q}((t-x)_{p,q}^{k},x)|\right)$$

By using Theorem 2.5 we have

$$|B_{n,p,q}((t-x)^{m},x)| \leq \gamma_{m} \left(|B_{n,p,q}((t-x)_{p,q}^{m},x)| + \sum_{k=1}^{m-1} \frac{1}{[n]^{m-k}} C_{k} \frac{x(1-x)}{[n]^{\lfloor \frac{k+1}{2} \rfloor}} \right)$$

$$\leq \gamma_{m} \left(|B_{n,p,q}((t-x)_{p,q}^{m},x)| + \frac{x(1-x)}{[n]^{1+\lfloor \frac{m}{2} \rfloor}} \sum_{k=1}^{m-1} C_{k} \right)$$

$$\leq \gamma_{m} \left(C_{m} \frac{x(1-x)}{[n]^{\lfloor \frac{m+1}{2} \rfloor}} + \frac{x(1-x)}{[n]^{\lfloor \frac{m+1}{2} \rfloor}} \sum_{k=1}^{m-1} C_{k} \right)$$

$$\leq \left(\gamma_{m} C_{m} + \sum_{k=1}^{m-1} C_{k} \right) \frac{x(1-x)}{[n]^{\lfloor \frac{m+1}{2} \rfloor}}$$

$$= E_{m} \frac{x(1-x)}{[n]^{\lfloor \frac{m+1}{2} \rfloor}}$$

Corollary 2.8. Let $m \in \mathbb{N}$ and $0 < q < p \le 1$. Then there exits a constant $K_m > 0$ such that for any $x \in [0,1]$, we have

$$B_{n,p,q}\left((|t-x|)^m;x\right) \le K_m \frac{x(1-x)}{[n]^{\frac{m}{2}}}.$$
(2.13)

7

Proof. For an even m, clearly we have

$$B_{n,p,q}((|t-x|)^{m};x) = B_{n,p,q}((t-x)^{m};x)$$

$$\leq E_{m} \frac{x(1-x)}{[n]^{\lfloor \frac{m+1}{2} \rfloor}}$$

$$= K_{m} \frac{x(1-x)}{[n]^{\frac{m}{2}}}$$

In case if m is odd, say m = 2u + 1, we have $B_{n,p,q}((|t-x|)^{2u+1};x)$

$$\leq \sqrt{B_{n,p,q}\left((|t-x|)_{p,q}^{4u};x\right)}\sqrt{B_{n,p,q}\left((|t-x|)^{2};x\right)}
\leq \sqrt{E_{4u}\frac{x(1-x)}{[n]^{\lfloor\frac{4u+1}{2}\rfloor}}}\sqrt{E_{2}\frac{x(1-x)}{[n]^{\lfloor\frac{3}{2}\rfloor}}}
= \sqrt{E_{4u}\frac{x(1-x)}{[n]^{\frac{2u}{2}}}}\sqrt{E_{2}\frac{x(1-x)}{[n]}}
= K_{2u+1}\frac{x(1-x)}{[n]^{\frac{2u+1}{2}}}.$$

This complete the proof.

Theorem 2.9. Let $B_{n,p,q}^{[r]}(f;x)$ be an operator from $C^r[0,1] \to C^r[0,1]$. Then for $0 < q < p \le 1$ there exits a constant M(r) such that for every $f \in C^r[0,1]$, we have

$$\| B_{n,p,q}^{[r]}(f;x) \|_{C[0,1]} \le M(r) \sum_{i=0}^{r} \| f^{(i)} \| = M(r) \| f \|_{C^{r}[0,1]} .$$
 (2.14)

Proof. Clearly $B_{n,p,q}^{[r]}(f;x)$ is continuous on [0,1]. From (1.7) we have

$$B_{n,p,q}^{[r]}(f;x) = \sum_{i=0}^{r} \frac{(-1)^i}{i!} B_{n,p,q} \left((t-x)^i f^{(i)}(t); x \right).$$

From the Corollary 2.8, we have

$$|B_{n,p,q}((t-x)^{i}f^{(i)}(t);x)| \le ||f^{(i)}||B_{n,p,q}(|(t-x)|^{i};x)$$

 $\le K_{i}||f^{(i)}||[n]^{-\frac{i}{2}}.$

Therefore

$$\| B_{n,p,q}^{[r]}(f;x) \| \leq \sum_{i=0}^{r} \frac{(-1)^{i}}{i!} \| B_{n,p,q} \left((t-x)^{i} f^{(i)}(t); x \right) \|$$

$$\leq M(r) \sum_{i=0}^{r} \| f^{(i)} \|.$$

This complete the proof.

3. Convergence properties of $B_{n,p,q}^{[r]}(f;x)$

The modulus of continuity of the derivative $f^{(r)}$ is given by

$$\omega\left(f^{(r)};t\right) = \sup\left\{ \mid f^{(r)}(x) - f^{(r)}(y) \mid : \mid x - y \mid \le t, \ x, y \in [0,1] \right\}.$$
 (3.1)

Theorem 3.1. Let $0 < q < p \le 1$ and $r \in \mathbb{N} \cup \{0\}$ be a fixed number. Then for $x \in [0,1]$, $n \in \mathbb{N}$ there exits $D_r > 0$ such that for every $f \in C^r[0,1]$ the following inequality holds

$$|B_{n,p,q}^{[r]}(f;x) - f(x)| \le D_r \frac{1}{[n]^{\frac{r}{2}}} \omega \left(f^{(r)}; \frac{1}{\sqrt{[n]}} \right).$$
 (3.2)

Proof. Let $r \in \mathbb{N}$. Then for $f \in C^r[0,1]$ at a given point $t \in [0,1]$, we have from the Taylor formula that

$$f(x) = \sum_{i=0}^{r} \frac{f^{(i)}(t)}{i!} (x-t)^{i} + \frac{(x-t)^{r}}{((r-1)!)}$$
$$\times \int_{0}^{1} (1-u)^{r-1} \left(f^{(r)}(t+u(x-t)) - f^{(r)}(t) \right) du.$$

On applying $B_{n,p,q}^{[r]}(f;x)$, we get

$$f(x) - B_{n,p,q}^{[r]}(f;x) = \sum_{k=0}^{n} \frac{\left(x - \frac{[k]}{p^{k-n}[n]}\right)^r}{(r-1)!} \int_{0}^{1} (1-u)^{r-1} P_{n,k}(p,q;x)$$

$$\times \left[f^{(r)} \left(\frac{[k]}{p^{k-n}[n]} + u \left(x - \frac{[k]}{p^{k-n}[n]} \right) \right) - f^{(r)} \left(\frac{[k]}{p^{k-n}[n]} \right) \right] du. \tag{3.3}$$

Now from the definition and properties of modulus of continuity, we have

$$\left| f^{(r)} \left(\frac{[k]}{p^{k-n}[n]} + u \left(x - \frac{[k]}{p^{k-n}[n]} \right) \right) - f^{(r)} \left(\frac{[k]}{p^{k-n}[n]} \right) \right| \leq \omega \left(f^{(r)}; u \middle| x - \frac{[k]}{p^{k-n}[n]} \middle| \right)$$

$$\omega\left(f^{(r)}; u \middle| x - \frac{[k]}{p^{k-n}[n]} \middle| \right) \le \left(\sqrt{[n]} \middle| x - \frac{[k]}{p^{k-n}[n]} \middle| + 1\right) \omega\left(f^{(r)}; \frac{1}{\sqrt{[n]}}\right). \quad (3.4)$$

Now for every $0 \le x \le 1, \ 0 < q < p \le 1, \ k \in \mathbb{N} \cup \{0\}, \ n \in \mathbb{N}$ and from (3.3) and (3.4), we get

$$|B_{n,p,q}^{[r]}(f;x)-f(x)|$$

$$\leq \frac{1}{r!} \omega \left(f^{(r)}; \frac{1}{\sqrt{[n]}} \right) \sum_{k=0}^{n} \left| x - \frac{[k]}{p^{k-n}[n]} \right|^r \left(\sqrt{[n]} \left| x - \frac{[k]}{p^{k-n}[n]} \right| + 1 \right) P_{n,k}(p,q;x)$$

9

$$= \frac{1}{r!} \omega \left(f^{(r)}; \frac{1}{\sqrt{[n]}} \right) \left(\sqrt{[n]} B_{n,p,q} \left(|x - t|^{r+1}; x \right) + B_{n,p,q} \left(|x - t|^{r}; x \right) \right). \tag{3.5}$$

Using (3.9) and (3.5) for $x \in [0, 1]$, we have

$$|B_{n,p,q}^{[r]}(f;x) - f(x)| \leq \frac{1}{r!} (K_{r+1} + K_r) \left(\frac{1}{\sqrt{[n]}}\right)^r \omega \left(f^{(r)}; \frac{1}{\sqrt{[n]}}\right)$$

$$= D_r \left(\frac{1}{\sqrt{[n]}}\right)^r \omega \left(f^{(r)}; \frac{1}{\sqrt{[n]}}\right).$$

In order to obtain the uniform convergence of $B_{n,p_n,q_n}^{[r]}(f;x)$ to a continuous function f, we take $q=q_n,\ p=p_n$ where $q_n\in(0,1)$ and $p_n\in(q_n,1]$ satisfying,

$$\lim_{n} p_n = 1, \ \lim_{n} q_n = 1. \tag{3.6}$$

Corollary 3.2. Let $p = p_n$, $q = q_n$, $0 < q_n < p_n \le 1$ satisfy (3.6) and $f \in C^r[0,1]$ for a fixed number $r \in \mathbb{N} \cup \{0\}$. Then

$$\lim_{n \to \infty} [n]^{\frac{r}{2}} \parallel B_{n,k}^{[r]}(f) - f \parallel = 0. \tag{3.7}$$

We say that (cf. [16]) a function $f \in C[0,1]$ belongs to $Lip_M(\alpha), 0 < \alpha \leq 1$, provided

$$|f(x) - f(y)| \le M |x - y|^{\alpha}, (x, y \in [0, 1] \text{ and } M > 0).$$
 (3.8)

Corollary 3.3. Let $p = p_n$, $q = q_n$, $0 < q_n < p_n \le 1$ satisfy (3.6) and $f \in C^r[0,1]$ for a fixed number $r \in \mathbb{N} \cup \{0\}$. If $f^{(r)} \in Lip_M(\alpha)$ then

$$||B_{n,p,q}^{[r]}(f) - f|| = O\left([n]^{-\frac{r+\alpha}{2}}\right).$$
 (3.9)

Proof. From (3.2) and (3.8), we have

$$\|B_{n,p,q}^{[r]}(f) - f\| \le D_r M \frac{1}{[n]^{\frac{r}{2}}} \frac{1}{[n]^{\frac{\alpha}{2}}}.$$

Theorem 3.4. Let $0 < q < p \le 1$. Suppose that $f \in C^{r+2}[0,1]$, where $r \in \mathbb{N} \cup \{0\}$ is fixed then we have

$$\left| B_{n,p,q}^{[r]}(f;x) - f(x) - \frac{(-1)^r f^{(r+1)}(x) B_{n,p,q} ((t-x)^{r+1};x)}{(r+1)!} - \frac{(-1)^r f^{(r+2)}(x) B_{n,p,q} ((t-x)^{r+2};x)}{(r+2)!} \right| \\
\leq (K_{r+2} + K_{r+4}) \frac{x(1-x)}{[n]^{\frac{r}{2}+1}} \sum_{i=0}^r \frac{1}{i!(r+2-i)!} \omega \left(f^{(r+2-i)}, [n]^{-\frac{1}{2}} \right).$$

Proof. Let $f \in C^{r+2}[0,1]$ and $x \in [0,1]$ for a fixed number $r \in \mathbb{N} \cup \{0\}$ we have $f^{(i)} \in C^{r+2-i}[0,1], \ 0 \le i \le r$. Then by Taylor formula we can write

$$f^{(i)}(t) = \sum_{i=0}^{r+2-i} \frac{f^{(i+j)}(x)}{j!} (t-x)^j + R_{r+2-j}(f;t;x), \tag{3.10}$$

where

$$R_{r+2-i}(f;t;x) = \frac{f^{(r+2-i)}(\zeta_{p^{n-k-1}t}) - f^{(r+2-i)}(x)}{(r+2-i)!}(t-x)^{r+2-i},$$

and

$$|\zeta_t - x| < |t - x|$$
.

Therefore from (1.7) and (3.10) we have

$$B_{n,p,q}^{[r]}(f;x) = \sum_{k=0}^{n} P_{n,k}(p,q;x) \sum_{i=0}^{r} \frac{\left(x - \frac{[k]}{p^{k-n}[n]}\right)^{i}}{i!} \sum_{j=0}^{r+2-i} \frac{f^{(i+j)}(x)}{j!} \left(\frac{[k]}{p^{k-n}[n]} - x\right)^{j}$$

$$+ \sum_{k=0}^{n} P_{n,k}(p,q;x) \sum_{i=0}^{r} \frac{\left(x - \frac{[k]}{p^{k-n}[n]}\right)^{i}}{i!} R_{r+2-i}(f;t;x)$$

$$= I_{1} + I_{2}, \text{ {where } } t = \frac{[k]}{p^{k-n}[n]}$$

Which implies that

$$|B_{n,p,q}^{[r]}(f;x) - I_{1}|$$

$$= |I_{2}|$$

$$= \left| \sum_{k=0}^{n} P_{n,k}(p,q;x) \sum_{i=0}^{r} \frac{(-1)^{i}}{i!} \frac{f^{(r+2-i)}(\zeta_{t}) - f^{(r+2-i)}(x)}{(r+2-i)!} (t-x)^{r+2} \right|$$

$$= \left| B_{n,p,q} \left(\sum_{i=0}^{r} \frac{(-1)^{i}}{i!} \frac{f^{(r+2-i)}(\zeta_{t}) - f^{(r+2-i)}(x)}{(r+2-i)!} (t-x)^{r+2}; x \right) \right|.$$

We use the well-known inequality

$$\omega(f, \lambda \delta) \leq (1 + \lambda^{2}) \omega(f, \delta),
| f^{(r+2-i)}(\zeta_{t}) - f^{(r+2-i)}(x) | \leq \omega (f^{(r+2-i)}, | \zeta_{t} - x |)
\leq \omega (f^{(r+2-i)}, | t - x |)
\leq \omega (f^{(r+2-i)}, [n]^{-\frac{1}{2}}) (1 + [n](t - x)^{2}).$$

Hence
$$|I_{2}| \leq \left| B_{n,p,q} \left(\sum_{i=0}^{r} \frac{(-1)^{i}}{i!} \frac{f^{(r+2-i)}(\zeta_{t}) - f^{(r+2-i)}(x)}{(r+2-i)!} \right| |t-x|^{r+2}; x \right)$$

$$\leq B_{n,p,q} \left(\sum_{i=0}^{r} \frac{1}{i!(r+2-i)!} \omega \left(f^{(r+2-i)}, [n]^{-\frac{1}{2}} \right) (1+[n](t-x)^{2}) |t-x|^{r+2}; x \right)$$

$$\begin{split} &= \sum_{i=0}^{r} \frac{1}{i!(r+2-i)!} \omega \left(f^{(r+2-i)}, [n]^{-\frac{1}{2}} \right) \\ &\times \left(B_{n,p,q}(\mid t-x\mid^{r+2}; x) + [n] B_{n,p,q}(\mid t-x\mid^{r+4}; x) \right) \\ &\leq \sum_{i=0}^{r} \frac{1}{i!(r+2-i)!} \omega \left(f^{(r+2-i)}, [n]^{-\frac{1}{2}} \right) \left(K_{r+2} \frac{x(1-x)}{[n]^{\frac{r}{2}+1}} + K_{r+4} \frac{x(1-x)}{[n]^{\frac{r}{2}+1}} \right) \\ &= \left(K_{r+2} + K_{r+4} \right) \frac{x(1-x)}{[n]^{\frac{r}{2}+1}} \sum_{i=0}^{r} \frac{1}{i!(r+2-i)!} \omega \left(f^{(r+2-i)}, [n]^{-\frac{1}{2}} \right). \end{split}$$
 Therefore

Therefore

$$|B_{n,p,q}^{[r]}(f;x) - I_1| \le (K_{r+2} + K_{r+4}) \frac{x(1-x)}{[n]^{\frac{r}{2}+1}} \sum_{i=0}^r \frac{1}{i!(r+2-i)!} \omega\left(f^{(r+2-i)}, [n]^{-\frac{1}{2}}\right).$$

Now we simplify for I_1

$$I_{1} = \sum_{k=0}^{n} P_{n,k}(p,q;x) \sum_{i=0}^{r} \frac{\left(x - \frac{[k]}{p^{k-n}[n]}\right)^{i}}{i!} \sum_{l=i}^{r+2} \frac{f^{(l)}(x)}{(l-i)!} \left(\frac{[k]}{p^{k-n}[n]} - x\right)^{l-i}$$

$$= \sum_{k=0}^{n} P_{n,k}(p,q;x) \sum_{i=0}^{r} \frac{(-1)^{i}}{i!} \sum_{l=i}^{r} \frac{f^{(l)}(x)}{(l-i)!} \left(\frac{[k]}{p^{k-n}[n]} - x\right)^{l}$$

$$+ \sum_{k=0}^{n} P_{n,k}(p,q;x) \sum_{i=0}^{r} \frac{(-1)^{i}}{i!} \frac{f^{(r+1)}(x)}{(r+1-i)!} \left(\frac{[k]}{p^{k-n}[n]} - x\right)^{r+1}$$

$$+ \sum_{k=0}^{n} P_{n,k}(p,q;x) \sum_{i=0}^{r} \frac{(-1)^{i}}{i!} \frac{f^{(r+2)}(x)}{(r+2-i)!} \left(\frac{[k]}{p^{k-n}[n]} - x\right)^{r+2}$$

$$= \sum_{k=0}^{n} P_{n,k}(p,q;x) \sum_{l=0}^{r} \frac{f^{(l)}(x)}{(l)!} \left(\frac{[k]}{p^{k-n}[n]} - x\right)^{l} \sum_{i=0}^{l} \binom{l}{i} (-1)^{i}$$

$$+ \frac{f^{(r+1)}(x)}{(r+1)!} \sum_{k=0}^{n} P_{n,k}(p,q;x) \left(\frac{[k]}{p^{k-n}[n]} - x\right)^{r+1} \sum_{i=0}^{r} \binom{r+1}{i} (-1)^{i}$$

$$+ \frac{f^{(r+2)}(x)}{(r+2)!} \sum_{k=0}^{n} P_{n,k}(p,q;x) \left(\frac{[k]}{p^{k-n}[n]} - x\right)^{r+2} \sum_{i=0}^{r} \binom{r+2}{i} (-1)^{i}.$$

For $n \in \mathbb{N}$, $r \in \mathbb{N} \cup \{0\}$ we have

$$\sum_{i=0}^{r} {r+1 \choose i} (-1)^i = (-1)^r, \ \sum_{i=0}^{r} {r+2 \choose i} (-1)^i = (r+1)(-1)^r$$

Therefore

$$I_{1} = f(x) + \frac{(-1)^{r} f^{(r+1)}(x) B_{n,p,q} ((t-x)^{r+1}; x)}{(r+1)!} + \frac{(-1)^{r} f^{(r+2)}(x) B_{n,p,q} ((t-x)^{r+2}; x)}{(r+2)!}.$$

This complete the proof.

Corollary 3.5. Let $p = p_n$, $q = q_n$, $0 < q_n < p_n \le 1$ satisfy (3.6) and $f \in C^2[0,1]$ for a fixed number $r \in \mathbb{N} \cup \{0\}$. Then for every $x \in [0,1]$ we have

$$\left| B_{n,p_n,q_n}^{[r]}(f;x) - f(x) - \frac{f''(x)}{2} \frac{x(1-x)}{[n]} \right| \le K \frac{x(1-x)}{[n]} \omega \left(f'', [n]^{-\frac{1}{2}} \right),$$

where $K = \frac{K_2 + K_4}{2}$. Moreover,

$$\lim_{n \to \infty} [n] (B_{n,p_n,q_n}(f;x) - f(x)) = \frac{x(1-x)}{2} f''(x)$$

uniformly on [0,1].

Acknowledgements

The authors N. Ashirbayev and A. Abzhapbarov gratefully acknowledge the financial support from M. Auezov South Kazakhstan State University, Shymkent.

References

- [1] T. Acar, (p,q)-generalization of Szász–Mirakyan operators, Math. Meth. Appl. Sci., $39(10)(2016)\ 2685–2695$.
- [2] T. Acar, A. Arall and S. A. Mohiuddine, On Kantorovich modification of (p, q)-Baskakov operators, J. Ineq. Appl., 2016 (2016): 98.
- [3] T. Acar, A. Aral and S. A. Mohiuddine, Approximation by bivariate (p, q)-Bernstein-Kantorovich operators, Iran. J. Sci. Technol. Trans. A Sci., DOI: 10.1007/s40995-016-0045-4.
- [4] S.N. Bernstein, Démostration du théorèeme de Weierstrass fondée sur le calcul de probabilités, Comm. Soc. Math. Kharkow (2), 13 (1912/1913) 1-2.
- [5] M.N. Hounkonnou, J. Désiré and B. Kyemba, $\mathcal{R}(p,q)$ -calculus: differentiation and integration, SUT Jour. Math., 49(2) (2013) 145-167.
- [6] Khalid Khan and D.K. Lobiyal, Bèzier curves based on Lupaş (p,q)-analogue of Bernstein functions, Jour. Comput. Appl. Math., DOI: 10.1016/j.cam.2016.12.016.
- [7] A. Lupaş, A q-analogue of the Bernstein operator, Seminar on Numerical and Statistical Calculus, University of Cluj-Napoca, 9(1987) 85-92.
- [8] N. Mahmudov, The moments for q-Bernstein operators in the case 0 < q < 1. Numer Algor (2010) 53:439–450, DOI 10.1007/s11075-009-9312-1.
- [9] M. Mursaleen, A. Alotaibi and K.J. Ansari, On a Kantorovich variant of (p,q)-Szász-Mirakjan operators, Jour. Function Spaces, Volume 2016, Article ID 1035253, 9 pages.
- [10] M. Mursaleen, K.J. Ansari and A. Khan, On (p, q)-analogue of Bernstein operators, Appl. Math. Comput., 266(2015), 874-882 [Erratum: Appl. Math. Comput., 278 (2016) 70–71].
- [11] M. Mursaleen, K.J. Ansari and A. Khan, Some approximation results by (p,q)-analogue of Bernstein-Stancu operators, Appl. Math. Comput., 264 (2015) 392-402 [Corrigendum: Appl. Math. Comput, 269 (2015) 744-746].
- [12] M. Mursaleen, F. Khan and A. Khan, Approximation by (p, q)-Lorentz polynomials on a compact disk, Complex Analysis and Operator Theory, 10 (2016) 1725–1740.
- [13] M. Mursaleen, Md. Nasiruzzaman, Asif Khan and K.J. Ansari, Some approximation results on Bleimann-Butzer-Hahn operators defined by (p,q)-integers, Filomat, 30:3 (2016) 639–648.
- [14] M. Mursaleen, Md. Nasiuzzaman and Ashirbayev Nurgali, Some approximation results on Bernstein-Schurer operators defined by (p,q)-integers, Jou. Ineq. Appl., 2015 (2015): 249.
- [15] G. M. Phillips, Bernstein polynomials based on the q-integers, Ann. Numer. Math., 4 (1997), 511–518.
- [16] P. Sabancıgil, Higher order generalization of q-Bernstein operators, Jour. Comput. Analy. Appl., 12 (2010) 821-827.

FOURIER SERIES OF FUNCTIONS INVOLVING GENOCCHI POLYNOMIALS

TAEKYUN KIM, DAE SAN KIM, LEE CHAE JANG, AND DMITRY V. DOLGY

ABSTRACT. We consider three types of functions involving Genocchi polynomials and derive their Fourier series expansions. In addition, we express each of them in terms of Bernoulli functions.

1. Introduction

Let $G_m(x)$ be the Genocchi polynomials given by the generating function

$$\frac{2t}{e^t + 1}e^{xt} = \sum_{m=0}^{\infty} G_m(x)\frac{t^m}{m!}, \quad (\text{see } [1, 2, 12 - 17, 21]). \tag{1.1}$$

The first few Genocchi polynomials are as follows:

$$G_0(x) = 0, G_1(x) = 1, G_2(x) = 2x - 1,$$

$$G_3(x) = 3x^2 - 3x, G_4(x) = 4x^3 - 6x^2 + 1,$$

$$G_5(x) = 5x^4 - 10x^3 + 5x, G_6(x) = 6x^5 - 15x^4 + 15x^2 - 3,$$

$$G_7(x) = 7x^6 - 21x^5 + 35x^3 - 21x.$$
(1.2)

From the relation $G_m(x) = mE_{m-1}(x) (m \ge 1)$, we have

$$\deg G_m(x) = m - 1 \ (m \ge 1), \ G_m = mE_{m-1} \ (m \ge 1),$$

$$G_0 = 0, \ G_1 = 1, \ G_{2m+1} = 0 \ (m \ge 1), \ \text{and} \ G_{2m} \ne 0 \ (m \ge 1).$$

$$(1.3)$$

Moreover, we have

$$\frac{d}{dx}G_m(x) = mG_{m-1}(x) \ (m \ge 1),
G_m(x+1) + G_m(x) = 2mx^{m-1} \ (m \ge 0).$$
(1.4)

From these, we have

$$G_m(1) + G_m(0) = 2\delta_{m,1}, \quad (m \ge 0).$$
 (1.5)

$$\int_{0}^{1} G_{m}(x)dx = \frac{1}{m+1} (G_{m+1}(1) - G_{m+1}(0))$$

$$= \frac{2}{m+1} (-G_{m+1}(0) + \delta_{m,0})$$

$$= \begin{cases} 0, & \text{if } m \text{ is even,} \\ -\frac{2}{m+1} G_{m+1}, & \text{if } m \text{ is odd.} \end{cases}$$
(1.6)

 $Key\ words\ and\ phrases.$ Fourier series, Genocchi polynomials, Genocchi functions.

 $^{2010\} Mathematics\ Subject\ Classification.\ 11B83,\ 42A16.$

For any real number x, let $\langle x \rangle = x - [x] \in [0,1)$ denote the fractional part of x. In this paper, we will study the Fourier series of the following three types of functions involving Genocchi polynomials

- $\begin{array}{l}
 (1) \ \alpha_m(< x >) = \sum_{k=1}^m G_k(< x >) < x >^{m-k}, (m \ge 2); \\
 (2) \ \beta_m(< x >) = \sum_{k=1}^m \frac{1}{k!(m-k)!} G_k(< x >) < x >^{m-k}, (m \ge 2); \\
 (3) \ \gamma_m(< x >) = \sum_{k=1}^{m-1} \frac{1}{k(m-k)} G_k(< x >) < x >^{m-k}, (m \ge 2).
 \end{array}$

The reader may refer to any book (for example, see [6,18,22]) for elementary facts about Fourier analysis. As to $\gamma_m(\langle x \rangle)$, we note that the polynomial identity (1.7) follows immediately from Theorems 4.1 and 4.2, which can be derived in turn from the Fourier series expansion of $\gamma_m(\langle x \rangle)$.

$$\sum_{k=1}^{m-1} \frac{1}{k(m-k)} G_k(x) x^{m-k}$$

$$= -\frac{1}{m} \left(\sum_{k=1}^m \frac{G_k}{k(m-k+1)} - \frac{2}{m} - \frac{2}{m(m+1)} G_{m+1} \right)$$

$$+ \frac{1}{m} \sum_{s=1}^{m-1} {m \choose s} \left(\frac{2}{m-s} - \frac{2G_{m-s+1}}{m-s+1} (H_{m-1} - H_{m-s}) - \sum_{l=s}^{m-1} \frac{G_{l-s+1}}{(l-s+1)(m-l)} \right) B_s(x).$$
(1.7)

The obvious polynomial identities can be derived also for $\alpha_m(\langle x \rangle)$ and $\beta_m(\langle x \rangle)$ from Theorems 2.1 and 2.2, and Theorems 3.1 and 3.2, respectively. It is noteworthy that from the Fourier series expansion of the function $\sum_{k=1}^{m-1} \frac{1}{k(m-k)} B_k(\langle x \rangle) B_{m-k}(\langle x \rangle)$ we can derive a slightly different version of the well-known Miki's identity (see [3,5,19,20])

$$\sum_{k=1}^{m-1} \frac{1}{2k (2m-2k)} B_{2k} B_{2m-2k}$$

$$= \frac{1}{m} \sum_{k=1}^{m} \frac{1}{2k} {2m \choose 2k} B_{2k} B_{2m-2k} + \frac{1}{m} H_{2m-1} B_{2m}, \quad (m \ge 2).$$

$$(1.8)$$

In addition, we can derive the Faber-Pandharipande-Zagier identity (see [4])

$$\sum_{k=1}^{m-1} \frac{1}{2k (2m-2k)} \overline{B}_{2k} \overline{B}_{2m-2k}$$

$$= \frac{1}{m} \sum_{k=1}^{m} \frac{1}{2k} {2m \choose 2k} B_{2k} \overline{B}_{2m-2k} + \frac{1}{m} H_{2m-1} \overline{B}_{2m}, \quad (m \ge 2),$$

$$(1.9)$$

where $\overline{B}_m = \left(\frac{1-2^{m-1}}{2^{m-1}}\right) B_m = \left(2^{1-m}-1\right) B_m = B_m\left(\frac{1}{2}\right)$, Some related works can be found in [1,7-11].

2. Fourier series of the first type of functions

In this section, we will study the Fourier series of first type of functions involving Genocchi polynomials. Let $\alpha_m(x) = \sum_{k=1}^m G_k(x) x^{m-k}$, $(m \ge 2)$. Note here that $\deg \alpha_m(x) = m-1$. Then we will consider the

function

$$\alpha_m(\langle x \rangle) = \sum_{k=1}^m G_k(\langle x \rangle) \langle x \rangle^{m-k}, \quad (m \ge 2).$$
(2.1)

defined on $(-\infty, -\infty)$ which is periodic of period 1. The Fourier series of $\alpha_m(\langle x \rangle)$ is

$$\sum_{n=-\infty}^{\infty} A_n^{(m)} e^{2\pi i n x},\tag{2.2}$$

3

where

$$A_n^{(m)} = \int_0^1 \alpha_m(\langle x \rangle) e^{-2\pi i n x} dx$$

$$= \int_0^1 \alpha_m(x) e^{-2\pi i n x} dx.$$
(2.3)

Before proceeding further, we first observe the following.

$$\alpha'_{m}(x) = \sum_{k=1}^{m} (kG_{k-1}(x)x^{m-k} + (m-k)G_{k}(x)x^{m-k-1})$$

$$= \sum_{k=2}^{m} (kG_{k-1}(x)x^{m-k} + \sum_{k=1}^{m-1} (m-k)G_{k}(x)x^{m-k-1}$$

$$= \sum_{k=1}^{m-1} (k+1)G_{k}(x)x^{m-k-1} + \sum_{k=1}^{m-1} (m-k)G_{k}(x)x^{m-k-1}$$

$$= (m+1)\sum_{k=1}^{m-1} G_{k}(x)x^{m-1-k}$$

$$= (m+1)\alpha_{m-1}(x).$$
(2.4)

From this, we have $\left(\frac{\alpha_{m+1}(x)}{m+2}\right)' = \alpha_m(x)$. Then we have

$$\int_0^1 \alpha_m(x)dx = \frac{1}{m+2}(\alpha_{m+1}(1) - \alpha_{m+1}(0)), \tag{2.5}$$

$$\alpha_m(1) - \alpha_m(0) = \sum_{k=1}^m (G_k(1) - G_k(0)\delta_{m,k})$$

$$= \sum_{k=1}^m (-G_k(0) + 2\delta_{k,1} - G_k(0)\delta_{m,k}) = -\sum_{k=1}^m G_k + 2 - G_m,$$
(2.6)

$$\alpha_m(0) = \alpha_m(1) \Longleftrightarrow \sum_{k=1}^m G_k = 2 - G_m, \tag{2.7}$$

$$\int_0^1 \alpha_m(x)dx = \frac{1}{m+2} \left(-\sum_{k=1}^{m+1} G_k + 2 - G_{m+1} \right). \tag{2.8}$$

We are now ready to determine the Fourier coefficients $A_n^{(m)}$. Case $1: n \neq 0$.

$$\begin{split} A_{n}^{(m)} &= \int_{0}^{1} \alpha_{m}(x)e^{-2\pi i n x} dx \\ &= -\frac{1}{2\pi i n} \left[\alpha_{m}(x)e^{-2\pi i n x} \right]_{0}^{1} + \frac{1}{2\pi i n} \int_{0}^{1} \alpha'_{m}(x)e^{-2\pi i n x} dx \\ &= -\frac{1}{2\pi i n} (\alpha_{m}(1) - \alpha_{m}(0)) + \frac{m+1}{2\pi i n} \int_{0}^{1} \alpha_{m-1}(x)e^{-2\pi i n x} dx \\ &= \frac{m+1}{2\pi i n} A_{n}^{(m-1)} + \frac{1}{2\pi i n} \left(\sum_{k=1}^{m} G_{k} - 2 + G_{m} \right) \\ &= \frac{m+1}{2\pi i n} \left(\frac{m}{2\pi i n} A_{n}^{(m-2)} + \frac{1}{2\pi i n} (\sum_{k=1}^{m-1} G_{k} - 2 + G_{m-1}) \right) \\ &+ \frac{1}{2\pi i n} \left(\sum_{k=1}^{m} G_{k} - 2 + G_{m} \right) \\ &= \frac{(m+1)m}{(2\pi i n)^{2}} A_{n}^{(m-2)} + \frac{m+1}{(2\pi i n)^{2}} \left(\sum_{k=1}^{m-1} G_{k} - 2 + G_{m-1} \right) \\ &+ \frac{1}{2\pi i n} \left(\sum_{k=1}^{m} G_{k} - 2 + G_{m} \right) \\ &= \cdots \\ &= \frac{(m+1)_{m-2}}{(2\pi i n)^{m-2}} A_{n}^{(2)} + \sum_{j=1}^{m-2} \frac{(m+1)_{j-1}}{(2\pi i n)^{j}} \left(\sum_{k=1}^{m-j+1} G_{k} - 2 + G_{m-j+1} \right) \\ &= -\frac{3(m+1)_{m-2}}{(2\pi i n)^{m-1}} + \sum_{j=1}^{m-2} \frac{(m+1)_{j-1}}{(2\pi i n)^{j}} \left(\sum_{k=1}^{m-j+1} G_{k} - 2 + G_{m-j+1} \right) \\ &= \sum_{j=1}^{m-1} \frac{(m+1)_{j-1}}{(2\pi i n)^{j}} \left(\sum_{k=1}^{m-j+1} G_{k} - 2 + G_{m-j+1} \right) \\ &= \frac{1}{m+2} \sum_{j=1}^{m-1} \frac{(m+1)_{j}}{(2\pi i n)^{j}} \left(\sum_{k=1}^{m-j+1} G_{k} - 2 + G_{m-j+1} \right), \end{split}$$

where

4

$$A_n^{(2)} = \int_0^1 (3x - 1)e^{-2\pi i nx} dx = -\frac{3}{2\pi i n}.$$
 (2.10)

Case 2: n = 0.

$$A_0^{(m)} = \int_0^1 \alpha_m(x)dx = -\frac{1}{m+2} \left(\sum_{k=1}^{m+1} G_k - 2 + G_{m+1}\right). \tag{2.11}$$

 $\alpha_m(< x >), (m \ge 2)$ is piecewise C^{∞} . Moreover, $\alpha_m(< x >)$ is continuous for those integers $m \ge 2$ with $\sum_{k=1}^m G_k = 2 - G_m$ and discontinuous with jump discontinuities at integers for those integers $m \ge 2$ with $\sum_{k=1}^m G_k \ne 2 - G_m$.

We need the following facts about Bernoulli functions $B_m(\langle x \rangle)$:

(a) for $m \geq 2$,

$$B_m(\langle x \rangle) = -m! \sum_{n=-\infty, n\neq 0}^{\infty} \frac{e^{2\pi i n x}}{(2\pi i n)^m}.$$
 (2.12)

(b) for m = 1,

$$-\sum_{n=-\infty, n\neq 0}^{\infty} \frac{e^{2\pi i n x}}{2\pi i n} = \begin{cases} B_1(\langle x \rangle), & \text{for } x \in \mathbb{Z}^c, \\ 0, & \text{for } x \in \mathbb{Z}, \end{cases}$$
 (2.13)

where $\mathbb{Z}^c = \mathbb{R} - \mathbb{Z}$. Assume first that $m \geq 2$ is an integer with $\sum_{k=1}^m G_k = 2 - G_m$. Then $\alpha_m(1) = \alpha_m(0)$. Thus $\alpha_m(< x >)$ is piecewise C^{∞} , and continuous. So the Fourier series of $\alpha_m(< x >)$ converges uniformly to $\alpha_m(< x >)$, and

$$\alpha_{m}(\langle x \rangle) = -\frac{1}{m+2} \left(\sum_{k=1}^{m+1} G_{k} - 2 + G_{m+1} \right) + \frac{1}{m+2} \sum_{n=-\infty, n \neq 0}^{\infty} \left(\sum_{j=1}^{m-1} \frac{(m+2)_{j}}{(2\pi i n)^{j}} \left(\sum_{k=1}^{m-j+1} G_{k} - 2 + G_{m-j+1} \right) \right) e^{2\pi i n x}$$

$$= -\frac{1}{m+2} \left(\sum_{k=1}^{m+1} G_{k} - 2 + G_{m+1} \right)$$

$$-\frac{1}{m+2} \sum_{j=1}^{m-1} {m+2 \choose j} \left(\sum_{k=1}^{m-j+1} G_{k} - 2 + G_{m-j+1} \right) \left(-j! \sum_{n=-\infty, n \neq 0}^{\infty} \frac{e^{2\pi i n}}{(2\pi i n)^{j}} \right)$$

$$= -\frac{1}{m+2} \left(\sum_{k=1}^{m+1} G_{k} - 2 + G_{m+1} \right) - \frac{1}{m+2} \sum_{j=2}^{m-1} {m+2 \choose j} \left(\sum_{k=1}^{m-j+1} G_{k} - 2 + G_{m-j+1} \right) B_{j}(\langle x \rangle)$$

$$- \left(\sum_{k=1}^{m} G_{k} - 2 + G_{m} \right) \times \begin{cases} B_{1}(\langle x \rangle), & \text{for } x \in \mathbb{Z}^{c}, \\ 0, & \text{for } x \in \mathbb{Z}, \end{cases}$$

for all $x \in (-\infty, \infty)$. Hence we obtain the following theorem.

Theorem 2.1. Let $m \ge 2$ be an integer with $\sum_{k=1}^m G_k = 2 - G_m$. Then we have the following. (a) $\sum_{k=1}^m G_k(\langle x \rangle) < x >^{m-k}$ has the Fourier series expansion

$$\sum_{k=1}^{m} G_k(\langle x \rangle) \langle x \rangle^{m-k}$$

$$= -\frac{1}{m+2} \left(\sum_{k=1}^{m+1} G_k - 2 + G_{m+1} \right)$$

$$+ \frac{1}{m+2} \sum_{n=-\infty, n\neq 0}^{\infty} \left(\sum_{j=1}^{m-1} \frac{(m+2)_j}{(2\pi i n)^j} \left(\sum_{k=1}^{m-j+1} G_k - 2 + G_{m-j+1} \right) \right) e^{2\pi i n x}, \tag{2.15}$$

for all $x \in (-\infty, \infty)$. Here the convergence is uniform.

6

$$\sum_{k=1}^{m} G_k(\langle x \rangle) \langle x \rangle^{m-k}$$

$$= -\frac{1}{m+2} \sum_{j=0, j \neq 1}^{m-1} {m+2 \choose j} \left(\sum_{k=1}^{m-j+1} G_k - 2 + G_{m-j+1} \right) B_j(\langle x \rangle), \tag{2.16}$$

for all $x \in (-\infty, \infty)$, where $B_j(\langle x \rangle)$ is the Bernoulli function.

Next, we assume that $m \geq 2$ is an integer with $\sum_{k=1}^m G_k \neq 2 - G_m$. Then $\alpha_m(1) \neq \alpha_m(0)$. Hence $\alpha_m(< x >)$ is piecewise C^{∞} and discontinuous with jump discontinuities at integers. The Fourier series of $\alpha_m(< x >)$ converges pointwise to $\alpha_m(< x >)$, for $x \in \mathbb{Z}^c$, and converges to

$$\frac{1}{2}(\alpha_m(0) + \alpha_m(1)) = \alpha_m(0) - \frac{1}{2} \sum_{k=1}^m G_k + 1 - \frac{1}{2} G_m$$

$$= 1 - \frac{1}{2} \sum_{k=1}^{m-1} G_k.$$
(2.17)

Thus we get the following theorem.

Theorem 2.2. Let $m \ge 2$ be an integer with $\sum_{k=1}^m G_k \ne 2 - G_m$. Then we have the following.

$$-\frac{1}{m+2} \left(\sum_{k=1}^{m+1} G_k - 2 + G_{m+1} \right) + \frac{1}{m+2} \sum_{n=-\infty, n \neq 0}^{\infty} \left(\sum_{j=1}^{m-1} \frac{(m+2)_j}{(2\pi i n)^j} \left(\sum_{k=1}^{m-j+1} G_k - 2 + G_{m-j+1} \right) \right) e^{2\pi i n x}$$

$$= \begin{cases} \sum_{k=1}^{m} G_k(\langle x \rangle) \langle x \rangle^{m-k}, & \text{for } x \in \mathbb{Z}^c, \\ 1 - \frac{1}{2} \sum_{k=1}^{m-1} G_k, & \text{for } x \in \mathbb{Z}. \end{cases}$$
(2.18)

Here the convergence is pointwise.

(b)

$$-\frac{1}{m+2} \sum_{j=0}^{m-1} {m+2 \choose j} (\sum_{k=1}^{m-j+1} G_k - 2 + G_{m-j+1}) B_j(\langle x \rangle)$$

$$= \sum_{k=1}^{m} G_k(\langle x \rangle) \langle x \rangle^{m-k}, \text{ for } x \in \mathbb{Z}^c ;$$

$$-\frac{1}{m+2} \sum_{j=0, j\neq 1}^{m-1} {m+2 \choose j} (\sum_{k=1}^{m-j+1} G_k - 2 + G_{m-j+1}) B_j(\langle x \rangle)$$

$$= 1 - \frac{1}{2} \sum_{k=1}^{m-1} G_k, x \in \mathbb{Z}.$$

$$(2.19)$$

Question: For what values of $m \ge 2$, does $\sum_{k=1}^{m} G_k = 2 - G_m$ hold?

3. Fourier series of the second type of functions

Let $\beta_m(x) = \sum_{k=1}^m \frac{1}{k!(m-k)!} G_k(x) x^{m-k}$, $(m \ge 2)$. Then, we consider the function

$$\beta_m(\langle x \rangle) = \sum_{k=1}^m \frac{1}{k!(m-k)!} G_k(\langle x \rangle) \langle x \rangle^{m-k}, \tag{3.1}$$

defined on $(-\infty, -\infty)$ which is periodic with period 1. The Fourier series of $\beta_m(\langle x \rangle)$ is

$$\sum_{n=-\infty}^{\infty} B_n^{(m)} e^{2\pi i n x},\tag{3.2}$$

7

where

$$B_n^{(m)} = \int_0^1 \beta_m(\langle x \rangle) e^{-2\pi i n x} dx$$

$$= \int_0^1 \beta_m(x) e^{-2\pi i n x} dx.$$
(3.3)

Before proceeding further, we need the following.

$$\beta'_{m}(x) = \sum_{k=1}^{m} \left\{ \frac{k}{k!(m-k)!} G_{k-1}(x) x^{m-k} + \frac{m-k}{k!(m-k)!} G_{k}(x) x^{m-k-1} \right\}$$

$$= \sum_{k=2}^{m} \frac{1}{(k-1)!(m-k)!} G_{k-1}(x) x^{m-k} + \sum_{k=1}^{m-1} \frac{1}{k!(m-k-1)!} G_{k}(x) x^{m-k-1}$$

$$= \sum_{k=1}^{m-1} \frac{1}{k!(m-1-k)!} G_{k}(x) x^{m-1-k} + \sum_{k=1}^{m-1} \frac{1}{k!(m-1-k)!} G_{k}(x) x^{m-1-k}$$

$$= 2\beta_{m-1}(x).$$
(3.4)

So, $\beta'_m(x) = 2\beta_{m-1}(x)$. From this, we see that

$$\left(\frac{\beta_{m+1}(x)}{2}\right)' = \beta_m(x) \tag{3.5}$$

and

$$\int_{0}^{1} \beta_{m}(x)dx = \frac{1}{2}(\beta_{m+1}(1) - \beta_{m+1}(0)). \tag{3.6}$$

We also observe that

$$\beta_{m}(1) - \beta_{m}(0) = \sum_{k=1}^{m} \frac{1}{k!(m-k)!} (G_{k}(1) - G_{k}(0)\delta_{m,k})$$

$$= \sum_{k=1}^{m} \frac{1}{k!(m-k)!} (-G_{k}(0) + 2\delta_{k,1}) - \sum_{k=1}^{m} \frac{G_{k}(0)\delta_{m,k}}{k!(m-k)!}$$

$$= -\sum_{k=1}^{m} \frac{G_{k}}{k!(m-k)!} + \frac{2}{(m-1)!} - \frac{G_{m}}{m!}.$$
(3.7)

We put

8

$$\Omega_m = \beta_m(1) - \beta_m(0) = -\sum_{k=1}^m \frac{G_k}{k!(m-k)!} + \frac{2}{(m-1)!} - \frac{G_m}{m!},$$
(3.8)

for $m \geq 2$. Then

$$\beta_m(0) = \beta_m(1) \Longleftrightarrow \Omega_m = 0. \tag{3.9}$$

Moreover,

$$\int_{0}^{1} \beta_{m}(x)dx = \frac{1}{2}\Omega_{m+1}$$

$$= -\frac{1}{2} \left\{ \sum_{k=1}^{m+1} \frac{G_{k}}{k!(m-k+1)!} - \frac{2}{m!} + \frac{G_{m+1}}{(m+1)!} \right\}.$$
(3.10)

Now, we are going to determine the Fourier coefficients $B_n^{(m)}$. Case 1: $n \neq 0$.

$$B_{n}^{(m)} = \int_{0}^{1} \beta_{m}(x)e^{-2\pi i n x} dx$$

$$= -\frac{1}{2\pi i n} \left[\beta_{m}(x)e^{-2\pi i n x} \right]_{0}^{1} + \frac{1}{2\pi i n} \int_{0}^{1} \beta'_{m}(x)e^{-2\pi i n x} dx$$

$$= -\frac{1}{2\pi i n} (\beta_{m}(1) - \beta_{m}(0)) + \frac{1}{\pi i n} \int_{0}^{1} \beta_{m-1}(x)e^{-2\pi i n x} dx$$

$$= \frac{1}{\pi i n} B_{n}^{(m-1)} - \frac{1}{2\pi i n} \Omega_{m}$$

$$= \frac{1}{\pi i n} \left(\frac{1}{\pi i n} B_{n}^{(m-2)} - \frac{1}{2\pi i n} \Omega_{m-1} \right) - \frac{1}{2\pi i n} \Omega_{m}$$

$$= \frac{1}{(\pi i n)^{2}} B_{n}^{(m-2)} - \frac{2}{(2\pi i n)^{2}} \Omega_{m-1} - \frac{1}{2\pi i n} \Omega_{m}$$

$$= \cdots$$

$$= \frac{1}{(\pi i n)^{m-2}} B_{n}^{(2)} - \sum_{i=1}^{m-2} \frac{2^{i-1}}{(2\pi i n)^{j}} \Omega_{m-j+1},$$

$$(3.11)$$

where

$$B_n^{(2)} = \int_0^1 \left(2x - \frac{1}{2}\right) e^{-2\pi i n x} dx = -\frac{1}{\pi i n}.$$
 (3.12)

By (3.11) and (3.12), we get

$$B_n^{(m)} = -\frac{1}{(\pi i n)^{m-1}} - \sum_{j=1}^{m-2} \frac{2^{j-1}}{(2\pi i n)^j} \Omega_{m-j+1}$$

$$= -\sum_{j=1}^{m-1} \frac{2^{j-1}}{(2\pi i n)^j} \Omega_{m-j+1}.$$
(3.13)

Case 2: n = 0.

$$B_0^{(m)} = \int_0^1 \beta_m(x)dx = \frac{1}{2}\Omega_{m+1}.$$
 (3.14)

Here $\beta_m(\langle x \rangle)$, $(m \ge 2)$ is piecewise C^{∞} . Moreover, $\beta_m(\langle x \rangle)$ is continuous for those integers $m \ge 2$ with $\Omega_m = 0$ and discontinuous with jump discontinuities at integers for those integers $m \ge 2$ with $\Omega_m \ne 0$.

Assume first that $m \ge 2$ is an integer with $\Omega_m = 0$. Then $\beta_m(0) = \beta_m(1)$. So $\beta_m(\langle x \rangle)$ is piecewise C^{∞} , and continuous. Hence the Fourier series of $\beta_m(\langle x \rangle)$ converges uniformly to $\beta_m(\langle x \rangle)$, and

$$\beta_{m}(\langle x \rangle) = \sum_{k=1}^{m} \frac{1}{k!(m-k)!} G_{k}(\langle x \rangle) \langle x \rangle^{m-k}$$

$$= \frac{1}{2} \Omega_{m+1} - \sum_{n=-\infty, n\neq 0}^{\infty} \left(\sum_{j=1}^{m-1} \frac{2^{j-1}}{(2\pi i n)^{j}} \Omega_{m-j+1} \right) e^{2\pi i n x}$$

$$= \frac{1}{2} \Omega_{m+1} + \sum_{j=1}^{m-1} \frac{2^{j-1}}{j!} \Omega_{m-j+1} \left(-j! \sum_{n=-\infty, n\neq 0}^{\infty} \frac{e^{2\pi i n x}}{(2\pi i n)^{j}} \right)$$

$$= \frac{1}{2} \Omega_{m+1} + \sum_{j=2}^{m-1} \frac{2^{j-1}}{j!} \Omega_{m-j+1} B_{j}(\langle x \rangle)$$

$$+ \Omega_{m} \times \begin{cases} B_{1}(\langle x \rangle), & \text{for } x \in \mathbb{Z}^{c}, \\ 0, & \text{for } x \in \mathbb{Z}, \end{cases}$$

$$(3.15)$$

for all $x \in (-\infty, \infty)$.

Thus we have the following theorem.

Theorem 3.1. For each integer $l \geq 2$, let

$$\Omega_l = -\sum_{l=1}^{l} \frac{G_k}{k!(l-k)!} + \frac{2}{(l-1)!} - \frac{G_l}{l!}.$$
(3.16)

Assume that $\Omega_m = 0$, for an integer $m \ge 2$. Then we have the following. (a) $\sum_{k=1}^m \frac{1}{k!(m-k)!} G_k(\langle x \rangle) \langle x \rangle^{m-k}$ has the Fourier series expansion

$$\sum_{k=1}^{m} \frac{1}{k!(m-k)!} G_k(\langle x \rangle) \langle x \rangle^{m-k}$$

$$= \frac{1}{2} \Omega_{m+1} - \sum_{n=-\infty, n \neq 0}^{\infty} \left(\sum_{j=1}^{m-1} \frac{2^{j-1}}{(2\pi i n)^j} \Omega_{m-j+1} \right) e^{2\pi i n x}, \tag{3.17}$$

for all $x \in (-\infty, \infty)$. Here the convergence is uniform. (b)

$$\sum_{k=1}^{m} \frac{1}{k!(m-k)!} G_k(\langle x \rangle) \langle x \rangle^{m-k}$$

$$= \sum_{j=0}^{m-1} \frac{2^{j-1}}{j!} \Omega_{m-j+1} B_j(\langle x \rangle),$$
(3.18)

for all $x \in (-\infty, \infty)$. Here $B_k(\langle x \rangle)$ is the Bernoulli function.

Assume next that $m \geq 2$ is an integer with $\Omega_m \neq 0$. Then $\beta_m(1) \neq \beta_m(0)$, and hence $\beta_m(< x >)$ is piecewise C^{∞} and discontinuous with jump discontinuities at integers. Thus the Fourier series of

838

 $\beta_m(\langle x \rangle)$ converges pointwise to $\beta_m(\langle x \rangle)$, for $x \in \mathbb{Z}^c$, and converges to

$$\frac{1}{2}(\beta_m(0) + \beta_m(1)) = \beta_m(0) + \frac{1}{2}\Omega_m$$

$$= \frac{G_m}{m!} + \frac{1}{2} \left(-\sum_{k=1}^m \frac{G_k}{k!(m-k)!} + \frac{2}{(m-1)!} - \frac{G_m}{m!} \right)$$

$$= \frac{1}{2} \left(\frac{2}{(m-1)!} - \sum_{k=1}^{m-1} \frac{G_k}{k!(m-k)!} \right),$$
(3.19)

for $x \in \mathbb{Z}$. Hence we obtain the following theorem.

Theorem 3.2. For each integer $l \geq 2$, let

$$\Omega_l = -\sum_{k=1}^l \frac{G_k}{k!(l-k)!} + \frac{2}{(l-1)!} - \frac{G_l}{l!}.$$
(3.20)

Assume that $\Omega_m \neq 0$, for an integer $m \geq 2$. Then we have the following. (a)

$$\frac{1}{2}\Omega_{m+1} - \sum_{n=-\infty, n\neq 0}^{\infty} \left(\sum_{j=1}^{m-1} \frac{2^{j-1}}{(2\pi i n)^{j}} \Omega_{m-j+1} \right) e^{2\pi i n x}$$

$$= \begin{cases}
\sum_{k=1}^{m} \frac{1}{k!(m-k)!} G_{k}(\langle x \rangle) \langle x \rangle^{m-k}, & \text{for } x \in \mathbb{Z}^{c}, \\
\frac{G_{m}}{m!} + \frac{1}{2}\Omega_{m}, & \text{for } x \in \mathbb{Z}.
\end{cases}$$
(3.21)

Here the convergence is pointwise

(b)

10

$$\sum_{j=0}^{m-1} \frac{2^{j-1}}{j!} \Omega_{m-j+1} B_j(\langle x \rangle)$$

$$= \sum_{k=1}^{m} \frac{1}{k!(m-k)!} G_k(\langle x \rangle) \langle x \rangle^{m-k},$$
(3.22)

for $x \in \mathbb{Z}^c$;

$$\sum_{j=0, j \neq 1}^{m-1} \frac{2^{j-1}}{j!} \Omega_{m-j+1} B_k(\langle x \rangle)$$

$$= \frac{G_m}{m!} + \frac{1}{2} \Omega_m,$$
(3.23)

for $x \in \mathbb{Z}$. Here $B_j(\langle x \rangle)$ is the Bernoulli function.

Remark: For what values of $m \ge 2$, does $\sum_{k=1}^{m} \frac{G_m}{k!(m-k)!} = \frac{2}{(m-1)!} - \frac{G_m}{m!}$ hold?

4. Fourier series of the third type of functions

Let $\gamma_m(x) = \sum_{k=1}^{m-1} \frac{1}{k(m-k)} G_k(x) x^{m-k}$, $(m \ge 2)$. Then we will consider the function

$$\gamma_m(\langle x \rangle) = \sum_{k=1}^{m-1} \frac{1}{k(m-k)} G_k(\langle x \rangle) \langle x \rangle^{m-k}, \tag{4.1}$$

defined on $(-\infty, -\infty)$ which is periodic of period 1. The Fourier series of $\gamma_m(\langle x \rangle)$ is

$$\sum_{n=-\infty}^{\infty} C_n^{(m)} e^{2\pi i n x},\tag{4.2}$$

where

$$C_n^{(m)} = \int_0^1 \gamma_m(\langle x \rangle) e^{-2\pi i n x} dx = \int_0^1 \gamma_m(x) e^{-2\pi i n x} dx.$$
 (4.3)

To proceed further, we need to observe the following

$$\gamma'_{m}(x) = \sum_{k=1}^{m-1} \frac{1}{k(m-k)} \left\{ kG_{k-1}(x)x^{m-k} + (m-k)G_{k}(x)x^{m-k-1} \right\}$$

$$= \sum_{k=1}^{m-2} \frac{1}{m-k-1} G_{k}(x)x^{m-k-1} + \sum_{k=1}^{m-1} \frac{1}{k} G_{k}(x)x^{m-k-1}$$

$$= (m-1) \sum_{k=1}^{m-2} \frac{1}{k(m-1-k)} G_{k}(x)x^{m-1-k} + \frac{1}{m-1} G_{m-1}(x)$$

$$= (m-1)\gamma_{m-1}(x) + \frac{1}{m-1} G_{m-1}(x).$$
(4.4)

Thus,

$$\gamma_m'(x) = (m-1)\gamma_{m-1}(x) + \frac{1}{m-1}G_{m-1}(x). \tag{4.5}$$

From this, we have

$$\left(\frac{1}{m}(\gamma_{m+1}(x) - \frac{1}{m(m+1)}G_{m+1}(x))\right)' = \gamma_m(x) \tag{4.6}$$

and

$$\int_{0}^{1} \gamma_{m}(x)dx$$

$$= \left[\frac{1}{m}(\gamma_{m+1}(x) - \frac{1}{m(m+1)}G_{m+1}(x))\right]_{0}^{1}$$

$$= \frac{1}{m}\left((\gamma_{m+1}(1) - \gamma_{m+1}(0)) - \frac{1}{m(m+1)}(G_{m+1}(1) - G_{m+1}(0))\right)$$

$$= \frac{1}{m}\left(\gamma_{m+1}(1) - \gamma_{m+1}(0) + \frac{2}{m(m+1)}G_{m+1}(0)\right).$$
(4.7)

Observe that

$$\gamma_{m}(1) - \gamma_{m}(0) = \sum_{k=1}^{m-1} \frac{1}{k(m-k)} (G_{k}(1) - G_{k}(0)\delta_{m,k})$$

$$= \sum_{k=1}^{m-1} \frac{1}{k(m-k)} (-G_{k}(0) + 2\delta_{k,1}) - \sum_{k=1}^{m-1} \frac{1}{k(m-k)} G_{k}(0)\delta_{m,k}$$

$$= -\sum_{k=1}^{m-1} \frac{G_{k}}{k(m-k)} + \frac{2}{m-1}.$$

$$(4.8)$$

So, we have

12

$$\gamma_m(1) = \gamma_m(0) \iff \sum_{k=1}^{m-1} \frac{G_k}{k(m-k)} = \frac{2}{m-1}.$$
(4.9)

Also,

$$\int_0^1 \gamma_m(x)dx = \frac{1}{m} \left(-\sum_{k=1}^m \frac{G_k}{k(m-k+1)} + \frac{2}{m} + \frac{2}{m(m+1)} G_{m+1} \right). \tag{4.10}$$

Now, we will determine the Fourier coefficients $C_n^{(m)}$. Case 1: $n \neq 0$.

$$\begin{split} C_n^{(m)} &= \int_0^1 \gamma_m(x) e^{-2\pi i n x} dx \\ &= -\frac{1}{2\pi i n} [\gamma_m(x) e^{-2\pi i n x}]_0^1 + \frac{1}{2\pi i n} \int_0^1 \gamma_m'(x) e^{-2\pi i n x} dx \\ &= -\frac{1}{2\pi i n} (\gamma_m(1) - \gamma_m(0)) + \frac{1}{2\pi i n} \int_0^1 \left((m-1)\gamma_{m-1}(x) + \frac{1}{m-1} G_{m-1}(x) \right) e^{-2\pi i n x} dx \\ &= -\frac{1}{2\pi i n} (\gamma_m(1) - \gamma_m(0)) + \frac{m-1}{2\pi i n} \int_0^1 \gamma_{m-1}(x) e^{-2\pi i n x} dx \\ &+ \frac{1}{2\pi i n (m-1)} \int_0^1 G_{m-1}(x) e^{-2\pi i n x} dx \\ &= \frac{m-1}{2\pi i n} C_n^{(m-1)} - \frac{1}{2\pi i n} \Lambda_m + \frac{2}{2\pi i n (m-1)} \Phi_m, \end{split} \tag{4.11}$$

where

$$\Phi_m = \sum_{k=1}^{m-2} \frac{(m-1)_{k-1}}{(2\pi i n)^k} G_{m-k},\tag{4.12}$$

and one can show

$$\int_{0}^{1} G_{m}(x)e^{-2\pi inx}dx = \begin{cases} 2\Omega_{m+1}, & \text{for } n \neq 0, \\ -2\frac{G_{m+1}}{m+1}, & \text{for } n = 0. \end{cases}$$
(4.13)

$$\begin{split} C_n^{(m)} &= \frac{m-1}{2\pi i n} C_n^{(m-1)} - \frac{1}{2\pi i n} \Lambda_m + \frac{2}{2\pi i n (m-1)} \Phi_m \\ &= \frac{m-1}{2\pi i n} \left(\frac{m-2}{2\pi i n} C_n^{(m-2)} - \frac{1}{2\pi i n} \Lambda_{m-1} + \frac{2}{2\pi i n (m-2)} \Phi_{m-1} \right) \\ &- \frac{1}{2\pi i n} \Lambda_m + \frac{2}{2\pi i n (m-1)} \Phi_m \\ &= \frac{(m-1)(m-2)}{(2\pi i n)^2} C_n^{(m-2)} - \frac{m-1}{(2\pi i n)^2} \Lambda_{m-1} - \frac{1}{2\pi i n} \Lambda_m \\ &+ \frac{2(m-1)}{(2\pi i n)^2 (m-2)} \Phi_{m-1} + \frac{2}{2\pi i n (m-1)} \Phi_m \\ &= \cdots \\ &= \frac{(m-1)!}{(2\pi i n)^{m-2}} C_n^{(2)} - \sum_{j=1}^{m-2} \frac{(m-1)_{j-1}}{(2\pi i n)^j} \Lambda_{m-j+1} + \sum_{j=1}^{m-2} \frac{2(m-1)_{j-1}}{(2\pi i n)^j (m-j)} \Phi_{m-j+1} \\ &= -\sum_{j=1}^{m-1} \frac{(m-1)_{j-1}}{(2\pi i n)^j} \Lambda_{m-j+1} + \frac{1}{m} \sum_{j=1}^{m-2} \frac{2(m)_j}{(2\pi i n)^j (m-j)} \Phi_{m-j+1}, \end{split}$$

where

$$C_n^{(2)} = \int_0^1 x e^{-2\pi i n x} dx = -\frac{1}{2\pi i n}.$$
 (4.15)

In order to get a final expression for $C_n^{(m)}$, we need to observe the following.

$$\sum_{j=1}^{m-2} \frac{2(m)_j}{(2\pi i n)^j (m-j)} \Phi_{m-j+1}$$

$$= \sum_{j=1}^{m-2} \frac{2(m)_j}{(2\pi i n)^j (m-j)} \sum_{k=1}^{m-j-1} \frac{(m-j)_{k-1}}{(2\pi i n)^k} G_{m-j-k+1}$$

$$= \sum_{j=1}^{m-2} \sum_{k=1}^{m-j-1} \frac{2(m)_{j+k-1}}{(2\pi i n)^{j+k} (m-j)} G_{m-j-k+1}$$

$$= 2 \sum_{j=1}^{m-2} \frac{1}{m-j} \sum_{s=j+1}^{m-1} \frac{(m)_{s-1}}{(2\pi i n)^s} G_{m-s+1}$$

$$= 2 \sum_{s=2}^{m-1} \frac{(m)_{s-1}}{(2\pi i n)^s} G_{m-s+1} \sum_{j=1}^{s-1} \frac{1}{m-j}$$

$$= 2 \sum_{s=1}^{m-1} \frac{(m)_s}{(2\pi i n)^s} \frac{G_{m-s+1}}{m-s+1} (H_{m-1} - H_{m-s}),$$
(4.16)

and

14

$$\sum_{j=1}^{m-1} \frac{(m)_j}{(2\pi i n)^j} \Lambda_{m-j+1}$$

$$= \sum_{j=1}^{m-1} \frac{(m)_j}{(2\pi i n)^j} \left\{ -\sum_{k=1}^{m-j} \frac{G_k}{k(m-j-k+1)} + \frac{2}{m-j} \right\}$$

$$= -\sum_{j=1}^{m-1} \sum_{k=1}^{m-j} \frac{(m)_j G_k}{(2\pi i n)^j k(m-j-k+1)} + 2\sum_{j=1}^{m-1} \frac{(m)_j}{(2\pi i n)^j (m-j)}$$

$$= -\sum_{s=1}^{m-1} \sum_{l=s}^{m-1} \frac{(m)_s G_{l-s+1}}{(2\pi i n)^s (l-s+1)(m-l)} + 2\sum_{s=1}^{m-1} \frac{(m)_s}{(2\pi i n)^s (m-s)}.$$
(4.17)

Putting everything altogether,

$$C_{n}^{(m)} = \frac{1}{m} \sum_{s=1}^{m-1} \sum_{l=s}^{m-1} \frac{(m)_{s} G_{l-s+1}}{(2\pi i n)^{s} (l-s+1)(m-l)}$$

$$- \frac{2}{m} \sum_{s=1}^{m-1} \frac{(m)_{s}}{(2\pi i n)^{s} (m-s)}$$

$$+ \frac{2}{m} \sum_{s=1}^{m-1} \frac{(m)_{s}}{(2\pi i n)^{s}} \frac{G_{m-s+1}}{m-s+1} (H_{m-1} - H_{m-s})$$

$$= -\frac{1}{m} \sum_{s=1}^{m-1} \frac{(m)_{s}}{(2\pi i n)^{s}}$$

$$\times \left\{ \frac{2}{m-s} - \frac{2G_{m-s+1}}{m-s+1} (H_{m-1} - H_{m-s}) - \sum_{l=s}^{m-1} \frac{G_{l-s+1}}{(l-s+1)(m-l)} \right\}.$$
(4.18)

Case 2: n = 0.

$$C_0^{(m)} = \int_0^1 \gamma_m(x) dx$$

$$= \frac{1}{m} \left(\Lambda_{m+1} + \frac{2}{m(m+1)} G_{m+1} \right)$$

$$= \frac{1}{m} \left(-\sum_{k=1}^m \frac{G_k}{k(m-k+1)} + \frac{2}{m} + \frac{2}{m(m+1)} G_{m+1} \right).$$
(4.19)

 $\gamma_m(< x >), (m \ge 2)$ is piecewise C^{∞} . Moreover, $\gamma_m(< x >)$ is continuous for those integers $m \ge 2$ with $\Lambda_m = 0$ and discontinuous with jump discontinuities at integers for those integers $\Lambda_m \ne 0$.

Assume first that $\Lambda_m = 0$. Then $\gamma_m(0) = \gamma_m(1)$. So $\gamma_m(< x >)$ is piecewise C^{∞} , and continuous. So the Fourier series of $\gamma_m(< x >)$ converges uniformly to $\gamma_m(< x >)$, and

$$\begin{split} &\gamma_{m}(< x >) \\ &= -\frac{1}{m} \left(\sum_{k=1}^{m} \frac{G_{k}}{k(m-k+1)} - \frac{2}{m} - \frac{2}{m(m+1)} G_{m+1} \right) \\ &- \frac{1}{m} \sum_{n=-\infty, n \neq 0}^{\infty} \left\{ \sum_{s=1}^{m-1} \frac{(m)_{s}}{(2\pi i n)^{s}} \left(\frac{2}{m-s} - \frac{2G_{m-s+1}}{m-s+1} (H_{m-1} - H_{m-s}) - \sum_{l=s}^{m-1} \frac{G_{l-s+1}}{(l-s+1)(m-l)} \right) \right\} e^{2\pi i n x} \\ &= -\frac{1}{m} \left(\sum_{k=1}^{m} \frac{G_{k}}{k(m-k+1)} - \frac{2}{m} - \frac{2}{m(m+1)} G_{m+1} \right) \\ &+ \frac{1}{m} \sum_{s=1}^{m-1} {m \choose s} \left(\frac{2}{m-s} - \frac{2G_{m-s+1}}{m-s+1} (H_{m-1} - H_{m-s}) - \sum_{l=s}^{m-1} \frac{G_{l-s+1}}{(l-s+1)(m-l)} \right) \\ &\times \left(-s! \sum_{n=-\infty, n \neq 0}^{\infty} \frac{e^{2\pi i n x}}{(2\pi i n)^{s}} \right) \\ &= -\frac{1}{m} \left(\sum_{k=1}^{m} \frac{G_{k}}{k(m-k+1)} - \frac{2}{m} - \frac{2}{m(m+1)} G_{m+1} \right) \\ &+ \frac{1}{m} \sum_{s=2}^{m-1} {m \choose s} \left(\frac{2}{m-s} - \frac{2G_{m-s+1}}{m-s+1} (H_{m-1} - H_{m-s}) - \sum_{l=s}^{m-1} \frac{G_{l-s+1}}{(l-s+1)(m-l)} \right) B_{s}(< x >) \\ &+ \left(\frac{2}{m-1} - \sum_{l=1}^{m-1} \frac{G_{l}}{l(m-l)} \right) \times \left\{ \begin{array}{l} B_{1}(< x >), & \text{for } x \in \mathbb{Z}^{c}, \\ 0, & \text{for } x \in \mathbb{Z}, \end{array} \right. \end{split}$$

for all $x \in (-\infty, \infty)$. Now, we obtain the following theorem.

Theorem 4.1. Let $m \ge 2$ be an integer with $\Lambda_m = -\sum_{k=1}^{m-1} \frac{G_k}{k(m-k)} + \frac{2}{m-1} = 0$. Then we have the following.

(a) $\sum_{k=1}^{m-1} \frac{1}{k(m-k)} G_k(\langle x \rangle) \langle x \rangle^{m-k}$ has the Fourier expansion

$$\begin{split} &\sum_{k=1}^{m-1} \frac{1}{k(m-k)} G_k(\langle x \rangle) \langle x \rangle^{m-k} \\ &= -\frac{1}{m} \left(\sum_{k=1}^m \frac{G_k}{k(m-k+1)} - \frac{2}{m} - \frac{2}{m(m+1)} G_{m+1} \right) \\ &- \frac{1}{m} \sum_{n=-\infty, n \neq 0}^{\infty} \left\{ \sum_{s=1}^{m-1} \frac{(m)_s}{(2\pi i n)^s} \left(\frac{2}{m-s} - \frac{2G_{m-s+1}}{m-s+1} (H_{m-1} - H_{m-s}) - \sum_{l=s}^{m-1} \frac{G_{l-s+1}}{(l-s+1)(m-l)} \right) \right\} e^{2\pi i n x} \end{split}$$

$$(4.21)$$

for all $x \in (-\infty, \infty)$. Here the convergence is uniform.

16

$$\sum_{k=1}^{m-1} \frac{1}{k(m-k)} G_k(\langle x \rangle) \langle x \rangle^{m-k}$$

$$= -\frac{1}{m} \left(\sum_{k=1}^m \frac{G_k}{k(m-k+1)} - \frac{2}{m} - \frac{2}{m(m+1)} G_{m+1} \right)$$

$$+ \frac{1}{m} \sum_{s=2}^{m-1} {m \choose s} \left(\frac{2}{m-s} - \frac{2G_{m-s+1}}{m-s+1} (H_{m-1} - H_{m-s}) - \sum_{l=s}^{m-1} \frac{G_{l-s+1}}{(l-s+1)(m-l)} \right) B_s(\langle x \rangle)$$
(4.22)

for all $x \in (-\infty, \infty)$, where $B_s(\langle x \rangle)$ is the Bernoulli function.

Assume next that $m \geq 2$ is an integer with $\Lambda_m \neq 0$. Then $\gamma_m(0) \neq \gamma_m(1)$. $\gamma_m(\langle x \rangle)$ is piecewise C^{∞} and discontinuous with jump discontinuities at integers. Thus the Fourier series of $\gamma_m(\langle x \rangle)$ converges pointwise to $\gamma_m(\langle x \rangle)$, for $x \in \mathbb{Z}^c$, and converges to

$$\frac{1}{2}(\gamma_m(0) + \gamma_m(1)) = \gamma_m(0) + \frac{1}{2}\Lambda_m$$

$$= \frac{1}{2} \left(-\sum_{k=1}^{m-1} \frac{G_k}{k(m-k)} + \frac{2}{m-1} \right),$$
(4.23)

for $x \in \mathbb{Z}$. Hence we have the following theorem.

Theorem 4.2. Let $m \geq 2$ be an integer with $\Lambda_m = -\sum_{k=1}^{m-1} \frac{G_k}{k(m-k)} + \frac{2}{m-1} \neq 0$. Then we have the following.

$$-\frac{1}{m} \left(\sum_{k=1}^{m} \frac{G_k}{k(m-k+1)} - \frac{2}{m} - \frac{2}{m(m+1)} G_{m+1} \right)$$

$$-\frac{1}{m} \sum_{n=-\infty, n\neq 0}^{\infty} \left\{ \sum_{s=1}^{m-1} \frac{(m)_s}{(2\pi i n)^s} \left(\frac{2}{m-s} - \frac{2G_{m-s+1}}{m-s+1} \right) (H_{m-1} - H_{m-s}) - \sum_{l=s}^{m-1} \frac{G_{l-s+1}}{(l-s+1)(m-1)} \right\} e^{2\pi i n x} (4.24)$$

$$= \left\{ \sum_{k=1}^{m-1} \frac{1}{k(m-k)} G_k(\langle x \rangle) \langle x \rangle^{m-k}, \text{ for } x \in \mathbb{Z}^c, \right.$$

$$\left. \frac{1}{2} \left(-\sum_{k=1}^{m-1} \frac{G_k}{k(m-k)} + \frac{2}{m-1} \right), \text{ for } x \in \mathbb{Z}.$$

Here the convergence is uniform.

(b)

$$-\frac{1}{m}\left(\sum_{k=1}^{m}\frac{G_{k}}{k(m-k+1)}-\frac{2}{m}-\frac{2}{m(m+1)}G_{m+1}\right)$$

$$+\frac{1}{m}\sum_{s=1}^{m-1}\binom{m}{s}\left(\frac{2}{m-s}-\frac{2G_{m-s+1}}{m-s+1}(H_{m-1}-H_{m-s})-\sum_{l=s}^{m-1}\frac{G_{l-s+1}}{(l-s+1)(m-l)}\right)B_{s}(\langle x \rangle) \quad (4.25)$$

$$=\sum_{k=1}^{m-1}\frac{1}{k(m-k)}G_{k}(\langle x \rangle)\langle x \rangle^{m-k},$$

for $x \in \mathbb{Z}^c$ and

$$-\frac{1}{m}\left(\sum_{k=1}^{m}\frac{G_{k}}{k(m-k+1)}-\frac{2}{m}-\frac{2}{m(m+1)}G_{m+1}\right)$$

$$+\frac{1}{m}\sum_{s=2}^{m-1}\binom{m}{s}\left(\frac{2}{m-s}-\frac{2G_{m-s+1}}{m-s+1}(H_{m-1}-H_{m-s})-\sum_{l=s}^{m-1}\frac{G_{l-s+1}}{(l-s+1)(m-l)}\right)B_{s}(\langle x \rangle) \quad (4.26)$$

$$=\frac{1}{2}\left(-\sum_{k=1}^{m-1}\frac{G_{k}}{k(m-k)}+\frac{2}{m-1}\right),$$

for $x \in \mathbb{Z}$.

Question For what values of $m \ge 2$, does $\sum_{k=1}^{m-1} \frac{G_k}{k(m-k)} = \frac{2}{m-1}$ hold?

Acknowledgements. This paper is supported by grant NO 14-11-00022 of Russian Scientific Fund.

References

- S. Araci, E. Sen, and M. Acikgoz, Theorems on Genocchi polynomials of higher order arising from Genocchi basis, Taiwanese J. of Math., 18(2014), no.2, 473-482.
- 2. M. Cenkci, M. Can, and V. Kurt, q-Extensions of Genocchi Numbers, J. Korean Math. Soc., 43(2006), 183-198.
- 3. G. V. Dunne, C. Schubert, Bernoulli number identities from quantum field theory and topological string theory, Commun. Number Theory Phys., 7(2)(2013), 225-249.
- 4. C. Faber, R. Pandharipande, Hodge integrals and Gromov-Witten theory, Invent. Math. 139(1)(2000), 173-199.
- 5. I. M. Gessel, On Miki's identities for Bernoulli numbers, J. Number Theory 110(1)(2005), 75-82.
- L. C. Jang, T. Kim, D. J. Kang, A note on the Fourier transform of fermionic p -adic integral on Z_p, J. Comput. Anal. Appl., 11(3) (2009), 571-575.
- 7. D.S. Kim, T. Kim, Identities arising from higher-order Daehee polynomial bases, Open Math. 13(2015), 196-208.
- 8. D.S. Kim, T. Kim, Euler basis, identities, and their applications, Int. J. Math. Math. Sci. 2012, Art. ID 343981.
- 9. D.S. Kim, T. Kim, A note on higher-order Bernoulli polynomials, J. Inequal. Appl. 2013, 2013:111.
- D.S. Kim, T. Kim, Bernoulli basis and the product of several Bernoulli polynomials, Int. J. Math. Math. Sci. 2012, Art. ID 463659.
- 11. D.S. Kim, T. Kim, Some identities of higher order Euler polynomials arising from Euler basis, Integral Transforms Spec. Funct., 24(9) (2013), 734-738.
- 12. T. Kim, On the Multiple q-Genocchi and Euler Numbers, Russ. J. Math. Phys., 15(2008), 481-486.
- 13. T. Kim, On the q-Extension of Euler and Genocchi Numbers, J. Math. Anal. Appl. 326(2007), 1458-1465.
- T. Kim, A note on the q-Genocchi Numbers and polynomials, J. Inequalities and applications, 2007 Article ID 71452, 8pages, (2007).
- T. Kim, Some identities for the Bernoulli, the Euler and Genocchi numbers and polynomials, Adv. Stud. Contemp. Math., 20(2015), no.1, 23-28.
- H. Liu, and W. Wang, Some identities on the Bernoulli, Euler and Genocchi poloynomials via power sums and alternate power sums, Disc. Math., 309(2009), 3346-3363.
- Q. M. Luo, Fouier expansions and integral representations for Genocchi poloynomials, J. Integer Seq., 12 (2009), Article
- 18. J. E. Marsden, Elementary classical analysis, W. H. Freeman and Company, 1974.
- 19. H. Miki, A relation between Bernoulli numbers, J. Number Theory 10(3)(1978), 297-302.
- K. Shiratani, S. Yokoyama, An application of p-adic convolutions, Mem. Fac. Sci. Kyushu Univ. Ser. A 36(1)(1982), 7383
- H. M. Srivastava, Some generalizations and basic extensions of the Bernoulli, Euler and Genocchi polynomials, Appl. Math. and Inf. Sci., 5(2011), no. 3, 390-414.
- 22. D. G. Zill, M. R. Cullen, Advanced Engineering Mathematics, Jones and Bartlett Publishers 2006.

DEPARTMENT OF MATHEMATICS, COLLEGE OF SCIENCE, TIANJIN POLYTECHNIC UNIVERSITY, TIANJIN 300160, CHINA, DEPARTMENT OF MATHEMATICS, KWANGWOON UNIVERSITY, SEOUL 139-701, REPUBLIC OF KOREA

 $E ext{-}mail\ address: tkkim@kw.ac.kr}$

18

DEPARTMENT OF MATHEMATICS, SOGANG UNIVERSITY, SEOUL 121-742, REPUBLIC OF KOREA

 $E ext{-}mail\ address: dskim@sogang.ac.kr}$

Graduate School of Education, Konkuk University, Seoul 143-701, Republic of Korea

 $E ext{-}mail\ address: lcjang@konkuk.ac.kr}$

Hanrimwon, Kwangwoon University, Seoul 139-701, Republic of Korea, School of Natural Sciences, Far Eastern Federal University, 690950 Vladivostok , Russia

E-mail address: dvdolgy@gmail.com

Lyapunov inequalities of quasi-Hamiltonian systems on time scales

Taixiang Sun Fanping Zeng Guangwang Su Bin Qin*
College of Information and Statistics, Guangxi University of Finance and Economics
Nanning, Guangxi 530003, China

Abstract In this paper, we obtain several new Lyapunov-type inequalities for the following quasi-Hamiltonian systems

$$x^{\Delta}(t) = -W(t)x(\sigma(t)) - U(t)|y(t)|^{p-2}y(t), \quad y^{\Delta}(t) = V(t)|x(\sigma(t))|^{q-2}x(\sigma(t)) + W^{T}(t)y(t)$$

on the time scale interval $[a,b]_{\mathbb{T}} \equiv [a,b] \cap \mathbb{T}$ for some $a,b \in \mathbb{T}$ $(\sigma(a) < b)$, where U and V are real $n \times n$ symmetric matrix-valued functions on $[a,b]_{\mathbb{T}}$ with U being positive definite, W is real $n \times n$ matrix-valued function on $[a,b]_{\mathbb{T}}$ with $I + \mu(t)W$ being invertible, and x,y are real vector-valued functions on $[a,b]_{\mathbb{T}}$.

AMS Subject Classification: 34K11, 34N05, 39A10.

Keywords: Lyapunov inequality; Quasi-Hamiltonian system; Time scale

1. Introduction

In 1990, Hilger [1] initiated the theory of time scales as a theory capable of treating continuous and discrete analysis in a consistent way, based on which some authors have studied some Lyapunov inequalities for dynamic equations on time scales (see [2-4]) during the last few years. A time scale \mathbb{T} is an arbitrary nonempty closed subset of real axis \mathbb{R} . On a time scale \mathbb{T} , the forward jump operator and the graininess function are defined

$$\sigma(t) = \inf\{s \in \mathbb{T} : s > t\}$$
 and $\mu(t) = \sigma(t) - t$,

respectively. For the notions used below we refer to [5,6] that provide some basic facts on time scales.

In this paper, we continue this line of investigation and study Lyapunov-type inequalities for the following quasi-Hamiltonian systems

$$x^{\Delta}(t) = -W(t)x(\sigma(t)) - U(t)|y(t)|^{p-2}y(t), \quad y^{\Delta}(t) = V(t)|x(\sigma(t))|^{q-2}x(\sigma(t)) + W^{T}(t)y(t), \quad (1.1)$$

 $[\]star$ Project Supported by NNSF of China (11461003) and SF of Guangxi University of Finance and Economics (2016KY15; 2016ZDKT06; 2016TJYB06)

^{*} Corresponding author: E-mail address: q3009b@163.com

on the time scale interval $[a,b]_{\mathbb{T}} \equiv [a,b] \cap \mathbb{T}$ for some $a,b \in \mathbb{T}$ $(\sigma(a) < b)$, where $p,q \in (0,+\infty)$ and 1/p+1/q=1, U and V are real $n \times n$ symmetric matrix-valued functions on $[a,b]_{\mathbb{T}}$ with U being positive definite, W is real $n \times n$ matrix-valued function on $[a,b]_{\mathbb{T}}$ with $I + \mu(t)W$ being invertible, and x,y are real vector-valued functions on $[a,b]_{\mathbb{T}}$.

When n = 1, (1.1) reduces to

$$x^{\Delta}(t) = \alpha(t)x(\sigma(t)) + \beta(t)|y(t)|^{p-2}y(t), \quad y^{\Delta}(t) = -\gamma(t)|x(\sigma(t))|^{q-2}x(\sigma(t)) - \alpha(t)y(t). \tag{1.2}$$

In 2011, Zhang et al. [7] obtained the following theorem.

Theorem 1.1^[7] Suppose that $1 - \mu(t)\alpha(t) > 0$ and $\beta(t) \ge 0$ for any $t \in \mathbb{T}$ and $a, b \in \mathbb{T}^k$ with $\sigma(a) \le b$. If (1.2) has a real solution (x(t), y(t)) satisfying

$$x(a) = 0 \text{ or } x(a)x(\sigma(a)) < 0, \ x(b) = 0 \text{ or } x(b)x(\sigma(b)) < 0, \ \max_{t \in [a,b]_{\mathbb{T}}} |x(t)| > 0,$$

then the following inequality holds:

$$\int_{a}^{b} |\alpha(t)| \triangle(t) + \left(\int_{a}^{\sigma(b)} \beta(t) \triangle(t)\right)^{\frac{1}{p}} \left(\int_{a}^{b} \max\{\gamma(t), 0\} \triangle(t)\right)^{\frac{1}{q}} \ge 2. \tag{1.3}$$

When n = 1 and $\mathbb{T} = \mathbb{R}$, Tiryaki et al. [8] obtained the following theorem.

Theorem 1.2^[8] Suppose that $\beta(t) > 0$ for any $t \in \mathbb{R}$ and $a, b \in \mathbb{R}$ with a < b. If (1.2) has a real solution (x(t), y(t)) satisfying x(a) = x(b) = 0 and $\max_{t \in [a,b]} |x(t)| > 0$, then the following inequalities hold:

$$\int_{a}^{b} \frac{\max\{\gamma(t), 0\}}{h_{a}^{1-q}(t) + h_{b}^{1-q}(t)} dt \ge 1$$
(1.4)

and

$$\int_{a}^{b} \max\{\gamma(t), 0\} 2^{q-2} \left(\frac{1}{h_{a}(t)} + \frac{1}{h_{b}(t)}\right)^{1-q} dt \ge 1, \tag{1.5}$$

where $h_a(t) = \int_a^t \beta(s) e^{-p \int_t^s \alpha(\tau) d\tau} ds$ and $h_b(t) = \int_t^b \beta(s) e^{-p \int_t^s \alpha(\tau) d\tau} ds$.

For some other related results on Lyapunov-type inequalities, see, e.g. [9-16] and the related references therein.

2. Preliminaries and some lemmas

For any $u \in \mathbb{R}^n$ and any $U \in \mathbb{R}^{n \times n}$ (the space of real $n \times n$ matrices), write

$$|u| = \sqrt{u^T u}$$
 and $|U| = \max_{y \in \mathbb{R}^n - \{O\}} \frac{|Uy|}{|y|}$,

which are called the Euclidean norm of u and the matrix norm of U respectively, where Q^T is the transpose of a $n \times m$ matrix Q. It follows from the definition that for any $y \in \mathbb{R}^n$ and any $U, V \in \mathbb{R}^{n \times n}$,

$$|Uy| \le |U||y|, \quad |UV| \le |U||V|.$$

Write $\mathbb{R}_s^{n \times n} = \{U \in \mathbb{R}^{n \times n} : U^T = U\}$. It is easy to show that for any $U \in \mathbb{R}_s^{n \times n}$,

$$|U| = \max_{\det |\lambda I - U| = 0} |\lambda|$$
 and $|U^2| = |U|^2$,

where $\det |\lambda I - U|$ denotes determinant of the matrix $\lambda I - U$. An $U \in \mathbb{R}_s^{n \times n}$ is said to be positive definite (resp. semi-positive definite), written as U > 0 (resp. $U \geq 0$), if $y^T U y > 0$ (resp. $y^T U y \geq 0$) for all $y \in \mathbb{R}^n$ with $y \neq 0$. If U is positive definite (resp. semi-positive definite), then there exists a unique positive definite matrix (resp. semi-positive definite matrix), written as \sqrt{U} , such that $|\sqrt{U}|^2 = U$.

In this paper, we study Lyapunov-type inequalities of (1.1) which has some solution (x(t), y(t)) satisfying

$$x(a) = x(b) = 0 \text{ and } \max_{t \in [a,b]_{\mathbb{T}}} |x(t)| > 0.$$
 (2.1)

We first introduce the following notions and lemmas

The point $t \in \mathbb{T}$ is said to be left-dense (resp. left-scattered) if $\rho(t) = t$ (resp. $\rho(t) < t$). The point $t \in \mathbb{T}$ is said to be right-dense (resp. right-scattered) if $\sigma(t) = t$ (resp. $\sigma(t) > t$). If \mathbb{T} has a left-scattered maximum M, then we define $\mathbb{T}^k = \mathbb{T} - \{M\}$, otherwise $\mathbb{T}^k = \mathbb{T}$.

A function $f: \mathbb{T} \longrightarrow \mathbb{R}$ is said to be rd-continuous provided that f is continuous at right-dense points and has finite left-sided limits at left-dense points in \mathbb{T} . The set of all rd-continuous functions from \mathbb{T} to \mathbb{R} is denoted by $C_{rd}(\mathbb{T}, \mathbb{R})$.

For a function $f: \mathbb{T} \longrightarrow \mathbb{R}$, the (delta) derivative $f^{\Delta}(t)$ at $t \in \mathbb{T}$ is defined to be the number (if it exists), such that for given any $\varepsilon > 0$, there is a neighborhood U of t with

$$|f(\sigma(t)) - f(s) - f^{\Delta}(t)(\sigma(t) - s)| \le \varepsilon |\sigma(t) - s|$$

for all $s \in U$. If the (delta) derivative $f^{\Delta}(t)$ exists for every $t \in \mathbb{T}^k$, then we say that f is Δ -differentiable on \mathbb{T} .

Definition 2.1^[5] Let $F, f \in C_{rd}(\mathbb{T}, \mathbb{R})$. If $F^{\triangle}(t) = f(t)$ for all $t \in \mathbb{T}^k$, then we definite the Cauchy integral of f by

$$\int_{a}^{b} f(t) \triangle t = F(b) - F(a) \text{ for any } a, b \in \mathbb{T}.$$

Lemma 2.2^[5] (Holder's inequality) Let $a, b \in \mathbb{T}$ with $a \leq b$ and $f_1, f_2 \in C_{rd}(\mathbb{T}, \mathbb{R})$. Then

$$\int_a^b |f_1(t)f_2(t)| \triangle t \le \left(\int_a^b |f_1(t)|^p \triangle t\right)^{\frac{1}{p}} \left(\int_a^b |f_2(t)|^q \triangle t\right)^{\frac{1}{q}},$$

where p > 1 and q = p/(p-1).

Lemma 2.3^[5] Suppose that $W \in C_{rd}(\mathbb{T}, \mathbb{R}^{n \times n})$ with $I + \mu(t)W(t)$ being invertible and $g \in C_{rd}(\mathbb{T}, \mathbb{R}^n)$. Let $t_0 \in \mathbb{T}$ and $x_0 \in \mathbb{R}^n$. Then the initial value problem

$$x^{\Delta}(t) = -W(t)x(\sigma(t)) + g(t), \ x(t_0) = x_0$$

has a unique solution

$$x(t) = e_{\Theta W}(t, t_0)x_0 + \int_{t_0}^t e_{\Theta W}(t, \tau)g(\tau)\Delta\tau,$$

where $(\Theta A)(t) = -[I + \mu(t)A(t)]^{-1}A(t)$ for any $t \in \mathbb{T}^k$ and $e_{\Theta A}(t, t_0)$ is the unique matrix-valued solution of the initial value problem

$$\begin{cases} Y^{\Delta}(t) = (\Theta A)(t)Y(t), \\ Y(t_0) = I. \end{cases}$$

Lemma 2.4^[5] Suppose that A(t) and B(t) are differentiable $n \times n$ matrix-valued functions. Then

$$(A(t)B(t))^{\triangle} = A^{\triangle}(t)B(\sigma(t)) + A(t)B^{\triangle}(t) = A(\sigma(t))B^{\triangle}(t) + A^{\triangle}(t)B(t).$$

Lemma 2.5^[12] Let $a, b \in \mathbb{T}$ with $a \geq b$ and $x_1(t), x_2(t), \dots, x_n(t)$ be Δ -integrable on $[a, b]_{\mathbb{T}}$. Write $x(t) = (x_1(t), x_2(t), \dots, x_n(t))$. Then

$$\left| \int_a^b x(t)\Delta t \right| = \sqrt{\sum_{i=1}^n \left(\int_a^b x_i(t)\Delta t \right)^2} \le \int_a^b \sqrt{\sum_{i=1}^n x_i^2(t)}\Delta t = \int_a^b |x(t)|\Delta t.$$

Lemma 2.6^[12] Let $V, V_1 \in \mathbb{R}_s^{n \times n}$ with $V_1 \geq V$ (i.e., $V_1 - V \geq 0$) and $x \in \mathbb{R}^n$. Then $x^T V x \leq |V_1||x|^2$.

3. Main results and proofs

Write

$$\xi(t) = \begin{cases} \left(\int_{a}^{t} |e_{\Theta W}(t,s)|^{p} |U(s)|^{\frac{p(p-2)}{2}+1} |[\sqrt{U(s)}]^{-1}|^{p(p-2)} \Delta s \right)^{\frac{q}{p}}, & \text{if } 1 < q < 2, \\ \left(\int_{a}^{t} |e_{\Theta W}(t,s)|^{p} |U(s)| \Delta s \right)^{\frac{q}{p}}, & \text{if } q \ge 2, \end{cases}$$
(3.1)

and

$$\eta(t) = \begin{cases}
\left(\int_{t}^{b} |e_{\Theta W}(t,s)|^{p} |U(s)|^{\frac{p(p-2)}{2} + 1} |[\sqrt{U(s)}]^{-1}|^{p(p-2)} \Delta s \right)^{\frac{q}{p}}, & \text{if } 1 < q < 2, \\
\left(\int_{t}^{b} |e_{\Theta W}(t,s)|^{p} |U(s)| \Delta s \right)^{\frac{q}{p}}, & \text{if } q \ge 2.
\end{cases}$$
(3.2)

Theorem 3.1 Let $a, b \in \mathbb{T}$ with $\sigma(a) < b$ and $V_1 \in \mathbb{R}^{n \times n}_s$ with $V_1(t) \geq V(t)$. If (1.1) has a solution (x(t), y(t)) satisfying (2.1) on the interval $[a, b]_{\mathbb{T}}$, then the following inequality holds:

$$\int_{a}^{b} \frac{\xi(\sigma(t))\eta(\sigma(t))}{\xi(\sigma(t)) + \eta(\sigma(t))} |V_{1}(t)| \triangle t \ge 1.$$
(3.3)

Proof We claim that $y(t) \not\equiv 0$ $(t \in [a,b]_{\mathbb{T}})$. Indeed, if $y(t) \equiv 0$ $(t \in [a,b]_{\mathbb{T}})$, then the first equation of (1.1) reduces to

$$x^{\Delta}(t) = -W(t)x(\sigma(t)), \ x(a) = 0.$$

By Lemma 2.3, it follows $x(t) = e_{\Theta W}(t, a) \cdot x(a) = 0$, which is a contradiction with (2.1). Moreover, we have $y^T(t)U(t)y(t) \ge 0$ ($\not\equiv 0$) for $t \in [a, b]_{\mathbb{T}}$ since U(t) > 0.

Since (x(t), y(t)) satisfies the following equality

$$(y^{T}(t)x(t))^{\Delta} = (x^{\sigma}(t))^{T}V(t)|x^{\sigma}(t)|^{q-2}x^{\sigma}(t) - y^{T}(t)U(t)|y(t)|^{p-2}y(t), \tag{3.4}$$

where $x^{\sigma}(t) = x(\sigma(t))$. By integrating (3.4) from a to b and taking into account that x(a) = x(b) = 0, we see

$$\int_{a}^{b} |x^{\sigma}(t)|^{q-2} (x^{\sigma}(t))^{T} V(t) x^{\sigma}(t) \triangle t = \int_{a}^{b} |y(t)|^{p-2} y^{T}(t) U(t) y(t) \triangle t > 0.$$
 (3.5)

For $t \in [a, b]_{\mathbb{T}}$, let $t_0 = a$ and $t_0 = b$ respectively, we obtain from Lemma 2.3 that

$$x(t) = -\int_a^t e_{\Theta W}(t,\tau)U(\tau)|y(\tau)|^{p-2}y(\tau)\Delta\tau = -\int_b^t e_{\Theta W}(t,\tau)U(\tau)|y(\tau)|^{p-2}y(\tau)\Delta\tau.$$

Which follows that for $t \in [a, b]_{\mathbb{T}}$,

$$x^{\sigma}(t) = -\int_{a}^{\sigma(t)} e_{\Theta W}(\sigma(t), \tau) U(\tau) |y(\tau)|^{p-2} y(\tau) \Delta \tau = \int_{\sigma(t)}^{b} e_{\Theta W}(\sigma(t), \tau) U(\tau) |y(\tau)|^{p-2} y(\tau) \Delta \tau.$$

Case I: Assume that $q \geq 2$. Then we have that for $a \leq \tau \leq \sigma(t) \leq b$,

$$\begin{split} &|e_{\Theta W}(\sigma(t),\tau)U(\tau)|y(\tau)|^{p-2}y(\tau)|\\ &\leq ||e_{\Theta W}(\sigma(t),\tau)||y(\tau)|^{p-2}|U(\tau)y(\tau)|\\ &= ||e_{\Theta W}(\sigma(t),\tau)||y(\tau)|^{p-2}\{y^T(\tau)U^T(\tau)U(\tau)y(\tau)\}^{\frac{1}{2}}\\ &\leq ||e_{\Theta W}(\sigma(t),\tau)||y(\tau)|^{p-2}\{|\sqrt{U(\tau)}y(\tau)||U(\tau)||\sqrt{U(\tau)}y(\tau)|\}^{\frac{1}{2}}\\ &= ||e_{\Theta W}(\sigma(t),\tau)||y(\tau)|^{p-2}|U(\tau)|^{\frac{1}{2}}(y^T(\tau)U(\tau)y(\tau))^{\frac{1}{2}}\\ &= ||e_{\Theta W}(\sigma(t),\tau)||y(\tau)|^{p-2}|U(\tau)|^{\frac{1}{2}}(y^T(\tau)U(\tau)y(\tau))^{\frac{1}{q}}(y^T(\tau)U(\tau)y(\tau))^{\frac{1}{2}-\frac{1}{q}}\\ &= ||e_{\Theta W}(\sigma(t),\tau)||y(\tau)|^{p-2}|U(\tau)|^{\frac{1}{2}}(y^T(\tau)U(\tau)y(\tau))^{\frac{1}{q}}|\sqrt{U(\tau)}y(\tau)|^{2(\frac{1}{2}-\frac{1}{q})}\\ &\leq ||e_{\Theta W}(\sigma(t),\tau)||U(\tau)|^{\frac{1}{2}}(y^T(\tau)U(\tau)y(\tau))^{\frac{1}{q}}|\sqrt{U(\tau)}|^{1-\frac{2}{q}}|y(\tau)|^{p-1-\frac{2}{q}}\\ &\leq ||e_{\Theta W}(\sigma(t),\tau)||U(\tau)|^{1-\frac{1}{q}}(y^T(\tau)U(\tau)y(\tau))^{\frac{1}{q}}|y(\tau)|^{p-1-\frac{2}{q}}. \end{split}$$

Combining Lemma 2.2 and Lemma 2.5 we obtain

$$|x^{\sigma}(t)|^{q} = \left| \int_{a}^{\sigma(t)} e_{\Theta W}(\sigma(t), \tau) U(\tau) |y(\tau)|^{p-2} y(\tau) \Delta \tau \right|^{q}$$

$$\leq \left(\int_{a}^{\sigma(t)} |e_{\Theta W}(\sigma(t), \tau) U(\tau)| y(\tau)|^{p-2} y(\tau) |\Delta \tau \rangle^{q}$$

$$\leq \left(\int_{a}^{\sigma(t)} |e_{\Theta W}(\sigma(t), \tau)| |U(\tau)|^{1-\frac{1}{q}} (y^{T}(\tau) U(\tau) y(\tau))^{\frac{1}{q}} |y(\tau)|^{p-1-\frac{2}{q}} \Delta \tau \right)^{q}$$

$$\leq \left(\int_{a}^{\sigma(t)} |e_{\Theta W}(\sigma(t), \tau)|^{p} |U(\tau)| \Delta \tau \right)^{\frac{q}{p}} \left(\int_{a}^{\sigma(t)} y^{T}(\tau) U(\tau) y(\tau) |y(\tau)|^{p-2} \Delta \tau \right),$$

that is

$$|x^{\sigma}(t)|^{q} \le \xi(\sigma(t)) \int_{a}^{\sigma(t)} y^{T}(\tau) U(\tau) y(\tau) |y(\tau)|^{p-2} \Delta \tau. \tag{3.6}$$

Similarly, by letting $\eta(t)$ be as in (3.2), for $a \leq \sigma(t) \leq \tau \leq b$, we have

$$|x^{\sigma}(t)|^{q} \leq \eta(\sigma(t)) \int_{\sigma(t)}^{b} y^{T}(\tau) U(\tau) y(\tau) |y(\tau)|^{p-2} \Delta \tau.$$
(3.7)

It follows from (3.6) and (3.7) that

$$\eta(\sigma(t))\xi(\sigma(t))\int_a^{\sigma(t)}y^T(\tau)U(\tau)y(\tau)|y(\tau)|^{p-2}\Delta\tau\geq |x^\sigma(t)|^q\eta(\sigma(t))$$

and

$$\eta(\sigma(t))\xi(\sigma(t))\int_{\sigma(t)}^{b}y^{T}(\tau)U(\tau)y(\tau)|y(\tau)|^{p-2}\Delta\tau\geq|x^{\sigma}(t)|^{q}\xi(\sigma(t)).$$

Thus

$$|x^{\sigma}(t)|^q \le \frac{\xi(\sigma(t))\eta(\sigma(t))}{\xi(\sigma(t)) + \eta(\sigma(t))} \int_a^b y^T(\tau)U(\tau)y(\tau)|y(\tau)|^{p-2}\Delta\tau.$$

By Lemma 2.6 and (3.5) we see

$$\begin{split} \int_{a}^{b} |V_{1}(t)| |x^{\sigma}(t)|^{q} \Delta t & \leq \int_{a}^{b} (|V_{1}(t)| \frac{\xi(\sigma(t))\eta(\sigma(t))}{\xi(\sigma(t)) + \eta(\sigma(t))} \int_{a}^{b} y^{T}(\tau) U(\tau) y(\tau) |y(\tau)|^{p-2} \Delta \tau) \Delta t \\ & = \int_{a}^{b} |V_{1}(t)| \frac{\xi(\sigma(t))\eta(\sigma(t))}{\xi(\sigma(t)) + \eta(\sigma(t))} \Delta t \int_{a}^{b} y^{T}(\tau) U(\tau) y(\tau) |y(\tau)|^{p-2} \Delta \tau \\ & = \int_{a}^{b} |V_{1}(t)| \frac{\xi(\sigma(t))\eta(\sigma(t))}{\xi(\sigma(t)) + \eta(\sigma(t))} \Delta t \int_{a}^{b} |x^{\sigma}(t)|^{q-2} (x^{\sigma}(t))^{T} V(t) x^{\sigma}(t) \Delta t \\ & \leq \int_{a}^{b} |V_{1}(t)| \frac{\xi(\sigma(t))\eta(\sigma(t))}{\xi(\sigma(t)) + \eta(\sigma(t))} \Delta t \int_{a}^{b} |V_{1}(t)| |x^{\sigma}(t)|^{q} \Delta t. \end{split}$$

Since

$$\int_{a}^{b} |V_{1}(t)| |x^{\sigma}(t)|^{q} \Delta t \ge \int_{a}^{b} |x^{\sigma}(t)|^{q-2} (x^{\sigma}(t))^{T} V(t) x^{\sigma}(t) \Delta t = \int_{a}^{b} |y(t)|^{p-2} y^{T}(t) U(t) y(t) \Delta t > 0,$$

we get

$$\int_{a}^{b} \frac{\xi(\sigma(t))\eta(\sigma(t))}{\xi(\sigma(t)) + \eta(\sigma(t))} |V_{1}(t)| \triangle t \ge 1.$$

This completes the proof of Case I.

Case II: Assume that 1 < q < 2. Then p > 2. Note that for $a \le \tau \le \sigma(t) \le b$,

$$|e_{\Theta W}(\sigma(t), \tau)U(\tau)|y(\tau)|^{p-2}y(\tau)|$$

- $\leq |e_{\Theta W}(\sigma(t),\tau)||y(\tau)|^{p-2}|U(\tau)y(\tau)|$
- $= |e_{\Theta W}(\sigma(t), \tau)||y(\tau)|^{p-2} \{y^T(\tau)U^T(\tau)U(\tau)y(\tau)\}^{\frac{1}{2}}$
- $= |e_{\Theta W}(\sigma(t),\tau)||y(\tau)|^{p-2} \{ (\sqrt{U(\tau)}y(\tau))^T U(\tau) \sqrt{U(\tau)}y(\tau) \}^{\frac{1}{2}}$
- $\leq |e_{\Theta W}(\sigma(t),\tau)||(\sqrt{U(\tau)})^{-1}\sqrt{U(\tau)}y(\tau)|^{p-2}\{|\sqrt{U(\tau)}y(\tau)||U(\tau)||\sqrt{U(\tau)}y(\tau)|\}^{\frac{1}{2}}$
- $\leq |e_{\Theta W}(\sigma(t), \tau)| |(\sqrt{U(\tau)})^{-1}|^{p-2} |\sqrt{U(\tau)}y(\tau)|^{p-2} |U(\tau)|^{\frac{1}{2}} |\sqrt{U(\tau)}y(\tau)|$
- $= |e_{\Theta W}(\sigma(t),\tau)||(\sqrt{U(\tau)})^{-1}|^{p-2}|U(\tau)|^{\frac{1}{2}}|\sqrt{U(\tau)}y(\tau)|^{p-1}$
- $= |e_{\Theta W}(\sigma(t), \tau)||(\sqrt{U(\tau)})^{-1}|^{p-2}|U(\tau)|^{\frac{1}{2}}|\sqrt{U(\tau)}y(\tau)|^{\frac{2}{q}}|\sqrt{U(\tau)}y(\tau)|^{p-1-\frac{2}{q}}$
- $\leq |e_{\Theta W}(\sigma(t),\tau)| |(\sqrt{U(\tau)})^{-1}|^{p-2} |U(\tau)|^{\frac{1}{2}} |\sqrt{U(\tau)}y(\tau)|^{\frac{2}{q}} |\sqrt{U(\tau)}|^{\frac{(p-1)(p-2)}{p}} |y(\tau)|^{p-1-\frac{2}{q}}$
- $= |e_{\Theta W}(\sigma(t),\tau)||(\sqrt{U(\tau)})^{-1}|^{p-2}|U(\tau)|^{\frac{1}{2}}(y^T(\tau)U(\tau)y(\tau))^{\frac{1}{q}}|\sqrt{U(\tau)}|^{\frac{(p-1)(p-2)}{p}}|y(\tau)|^{p-1-\frac{2}{q}}$

Then we obtain

$$\begin{split} |x^{\sigma}(t)|^{q} &= \left| \int_{a}^{\sigma(t)} e_{\Theta W}(\sigma(t),\tau) U(\tau) |y(\tau)|^{p-2} y(\tau) \Delta \tau \right|^{q} \\ &\leq \left(\int_{a}^{\sigma(t)} |e_{\Theta A}(\sigma(t),\tau) U(\tau)| y(\tau)|^{p-2} y(\tau) |\Delta \tau \right)^{q} \\ &\leq \left(\int_{a}^{\sigma(t)} |e_{\Theta W}(\sigma(t),\tau)| |(\sqrt{U(\tau)})^{-1}|^{p-2} |U(\tau)|^{\frac{1}{2}} \\ &\qquad \times (y^{T}(\tau) U(\tau) y(\tau))^{\frac{1}{q}} |\sqrt{U(\tau)}|^{\frac{(p-1)(p-2)}{p}} |y(\tau)|^{p-1-\frac{2}{q}} \Delta \tau \right)^{q} \\ &\leq \left(\int_{a}^{\sigma(t)} |e_{\Theta W}(\sigma(t),\tau)| |(\sqrt{U(\tau)})^{-1}|^{p-2} |\sqrt{U(\tau)}|^{\frac{(p-1)(p-2)}{p}+1} \\ &\qquad \times (y^{T}(\tau) U(\tau) y(\tau))^{\frac{1}{q}} |y(\tau)|^{p-1-\frac{2}{q}} \Delta \tau \right)^{q} \\ &\leq \left(\int_{a}^{\sigma(t)} |e_{\Theta W}(\sigma(t),\tau)|^{p} |(\sqrt{U(\tau)})^{-1}|^{p(p-2)} |U(\tau)|^{\frac{p(p-2)}{2}+1} \Delta \tau \right)^{\frac{q}{p}} \\ &\qquad \times \left(\int_{a}^{\sigma(t)} y^{T}(\tau) U(\tau) y(\tau) |y(\tau)|^{p-2} \Delta \tau \right). \end{split}$$

That is

$$|x^{\sigma}(t)|^{q} \le \xi(\sigma(t)) \int_{a}^{\sigma(t)} y^{T}(\tau) U(\tau) y(\tau) |y(\tau)|^{p-2} \Delta \tau. \tag{3.8}$$

Similarly, by letting $\eta(t)$ be as in (3.2), for $a \leq \sigma(t) \leq \tau \leq b$, we have

$$|x^{\sigma}(t)|^{q} \le \eta(\sigma(t)) \int_{\sigma(t)}^{b} y^{T}(\tau) U(\tau) y(\tau) |y(\tau)|^{p-2} \Delta \tau. \tag{3.9}$$

The rest of the proof is similar to the Case I, we have

$$\int_{a}^{b} \frac{\xi(\sigma(t))\eta(\sigma(t))}{\xi(\sigma(t)) + \eta(\sigma(t))} |V_{1}(t)| \triangle t \ge 1.$$

This completes the proof of Theorem 3.1

Corollary 3.2 Let $a, b \in \mathbb{T}$ with $\sigma(a) < b$ and $V_1 \in \mathbb{R}^{n \times n}_s$ with $V_1(t) \geq V(t)$. If (1.1) has a solution (x(t), y(t)) satisfying (2.1) on the interval $[a, b]_{\mathbb{T}}$, then the following inequality holds:

$$\int_{a}^{b} (\xi(\sigma(t)) + \eta(\sigma(t))) |V_1(t)| \triangle t \ge 4.$$
(3.10)

Proof Note

$$\frac{\xi(\sigma(t))\eta(\sigma(t))}{\xi(\sigma(t))+\eta(\sigma(t))} \leq \frac{\xi(\sigma(t))+\eta(\sigma(t))}{4}.$$

It follows from (3.3) that

$$\int_{a}^{b} \frac{\xi(\sigma(t)) + \eta(\sigma(t))}{4} |V_1(t)| \triangle t \ge 1.$$

That is

$$\int_{a}^{b} (\xi(\sigma(t)) + \eta(\sigma(t))) |V_1(t)| \triangle t \ge 4.$$

This completes the proof of Corollary 3.2.

Corollary 3.3 Let $a, b \in \mathbb{T}$ with $\sigma(a) < b$ and $V_1 \in \mathbb{R}^{n \times n}_s$ with $V_1(t) \geq V(t)$. If (1.1) has a solution (x(t), y(t)) satisfying (2.1) on the interval $[a, b]_{\mathbb{T}}$, then the following inequality holds:

$$\int_{a}^{b} (\xi(\sigma(t))\eta(\sigma(t)))^{\frac{1}{2}} |V_1(t)| \triangle t \ge 2.$$
(3.11)

Proof Note

$$\xi(\sigma(t)) + \eta(\sigma(t)) \ge 2(\xi(\sigma(t))\eta(\sigma(t)))^{\frac{1}{2}}.$$

It follows from (3.3) that

$$\int_a^b \frac{(\xi(\sigma(t))\eta(\sigma(t)))^{\frac{1}{2}}}{2} |V_1(t)| \triangle t \ge 1.$$

That is

$$\int_a^b (\xi(\sigma(t))\eta(\sigma(t)))^{\frac{1}{2}} |V_1(t)| \triangle t \ge 2.$$

This completes the proof of Corollary 3.3.

Theorem 3.4 Let $a, b \in \mathbb{T}$ with $\sigma(a) < b$ and $V_1 \in \mathbb{R}^{n \times n}_s$ with $V_1(t) \geq V(t)$. If (1.1) has a solution (x(t), y(t)) satisfying (2.1) on the interval $[a, b]_{\mathbb{T}}$, then there exists an $c \in (a, b)$ such that

$$\int_{a}^{\sigma(c)} \xi(\sigma(t))|V_1(t)| \triangle t \ge 1 \quad \text{and} \quad \int_{c}^{b} \eta(\sigma(t))|V_1(t)| \triangle t \ge 1.$$
 (3.12)

Proof Let

$$F(t) = \int_a^t \xi(\sigma(s))|V_1(s)| \triangle s - \int_t^b \eta(\sigma(s))|V_1(s)| \triangle s.$$

Then we have F(a) < 0 and F(b) > 0. Hence we can choose an $c \in (a,b)$ such that $F(c) \le 0$ and $F(\sigma(c)) \ge 0$, that is

$$\int_{a}^{c} \xi(\sigma(s))|V_{1}(s)| \triangle s \le \int_{c}^{b} \eta(\sigma(s))|V_{1}(s)| \triangle s$$
(3.13)

and

$$\int_{a}^{\sigma(c)} \xi(\sigma(s))|V_1(s)| \triangle s \ge \int_{\sigma(c)}^{b} \eta(\sigma(s))|V_1(s)| \triangle s. \tag{3.14}$$

From (3.6) and (3.8), we have

$$|V_1(t)||x^{\sigma}(t)|^q \le \xi(\sigma(t))|V_1(t)| \int_a^{\sigma(t)} y^T(\tau)U(\tau)y(\tau)|y(\tau)|^{p-2} \Delta \tau.$$
 (3.15)

Note that for $a \le \tau \le \sigma(t) \le \sigma(c) \le b$. Integrating (3.15) from a to $\sigma(c)$, we obtain

$$\int_{a}^{\sigma(c)} |V_{1}(t)| |x^{\sigma}(t)|^{q} \Delta t \leq \int_{a}^{\sigma(c)} \xi(\sigma(t)) |V_{1}(t)| \left(\int_{a}^{\sigma(t)} y^{T}(\tau) U(\tau) y(\tau) |y(\tau)|^{p-2} \Delta \tau \right) \Delta t
\leq \int_{a}^{c} \xi(\sigma(t)) |V_{1}(t)| \Delta t \int_{a}^{\sigma(c)} y^{T}(\tau) U(\tau) y(\tau) |y(\tau)|^{p-2} \Delta \tau.
+ \xi(\sigma(c)) |V_{1}(c)| (\sigma(c) - c) \int_{a}^{\sigma(c)} y^{T}(\tau) U(\tau) y(\tau) |y(\tau)|^{p-2} \Delta \tau.$$

$$= \int_{a}^{\sigma(c)} \xi(\sigma(t)) |V_1(t)| \triangle t \int_{a}^{\sigma(c)} y^T(\tau) U(\tau) y(\tau) |y(\tau)|^{p-2} \Delta \tau.$$

Similarly, for $a \le \sigma(c) \le \sigma(t) \le \tau \le b$, we can obtain from (3.7),(3.9) and (3.14) that

$$\int_{\sigma(c)}^{b} |V_1(t)| |x^{\sigma}(t)|^q \, \Delta t \leq \int_{\sigma(c)}^{b} \eta(\sigma(t)) |V_1(t)| \, \Delta t \int_{\sigma(c)}^{b} y^T(\tau) U(\tau) y(\tau) |y(\tau)|^{p-2} \Delta \tau
\leq \int_{a}^{\sigma(c)} \xi(\sigma(t)) |V_1(t)| \, \Delta t \int_{\sigma(c)}^{b} y^T(\tau) U(\tau) y(\tau) |y(\tau)|^{p-2} \Delta \tau.$$

These yield

$$\int_{a}^{b} |V_{1}(t)||x^{\sigma}(t)|^{q} \triangle t \leq \int_{a}^{\sigma(c)} \xi(\sigma(t))|V_{1}(t)| \triangle t \int_{a}^{b} y^{T}(\tau)U(\tau)y(\tau)|y(\tau)|^{p-2} \Delta \tau$$

$$= \int_{a}^{\sigma(c)} \xi(\sigma(t))|V_{1}(t)| \triangle t \int_{a}^{b} |x^{\sigma}(t)|^{q-2} (x^{\sigma}(t))^{T} V(t)x^{\sigma}(t) \triangle t$$

$$\leq \int_{a}^{\sigma(c)} \xi(\sigma(t))|V_{1}(t)| \triangle t \int_{a}^{b} |V_{1}(t)||x^{\sigma}(t)|^{q} \triangle t.$$

Since

$$\int_{a}^{b} |V_{1}(t)| |x^{\sigma}(t)|^{q} \Delta t \ge \int_{a}^{b} |x^{\sigma}(t)|^{q-2} (x^{\sigma}(t))^{T} V(t) x^{\sigma}(t) \Delta t = \int_{a}^{b} |y(t)|^{p-2} y^{T}(t) U(t) y(t) \Delta t > 0,$$

we obtain $\int_a^{\sigma(c)} \xi(\sigma(t)) |V_1(t)| \triangle t \ge 1$.

Next, we have from (3.7) and (3.9) that

$$|x^{\sigma}(t)|^{q}|V_{1}(t)| \leq \eta(\sigma(t))|V_{1}(t)| \int_{\sigma(t)}^{b} y^{T}(\tau)U(\tau)y(\tau)|y(\tau)|^{p-2}\Delta\tau.$$
(3.16)

Integrating (3.16) from c to b, we obtain that for $a \le c \le t \le \sigma(t) \le \tau \le b$,

$$\int_{c}^{b} |V_{1}(t)| |x^{\sigma}(t)|^{q} \triangle t \leq \int_{c}^{b} \eta(\sigma(t)) |V_{1}(t)| \left(\int_{\sigma(t)}^{b} y^{T}(\tau) U(\tau) y(\tau) |y(\tau)|^{p-2} \Delta \tau \right) \triangle t$$

$$\leq \int_{c}^{b} \eta(\sigma(t)) |V_{1}(t)| \triangle t \int_{\sigma(c)}^{b} y^{T}(\tau) U(\tau) y(\tau) |y(\tau)|^{p-2} \Delta \tau.$$

Similarly, for $a \le \tau \le \sigma(t) \le \sigma(c) \le b$, we can obtain

$$\int_{a}^{c} |V_{1}(t)| |x^{\sigma}(t)|^{q} \Delta t \leq \int_{a}^{c} \xi(\sigma(t)) |V_{1}(t)| \Delta t \int_{a}^{\sigma(c)} y^{T}(\tau) U(\tau) y(\tau) |y(\tau)|^{p-2} \Delta \tau$$

$$\leq \int_{c}^{b} \eta(\sigma(t)) |V_{1}(t)| \Delta t \int_{a}^{\sigma(c)} y^{T}(\tau) U(\tau) y(\tau) |y(\tau)|^{p-2} \Delta \tau.$$

These yield

$$\int_{a}^{b} |V_1(t)||x^{\sigma}(t)|^q \triangle t \le \int_{c}^{b} \eta(\sigma(t))|V_1(t)| \triangle t \int_{a}^{b} y^T(t)U(t)y(t)|y(t)|^{p-2} \Delta t$$

$$= \int_{c}^{b} \eta(\sigma(t))|V_1(t)| \triangle t \int_{a}^{b} |x^{\sigma}(t)|^{q-2} (x^{\sigma}(t))^T V(t)x^{\sigma}(t) \triangle t$$

$$\leq \int_{c}^{b} \eta(\sigma(t))|V_{1}(t)| \triangle t \int_{a}^{b} |V_{1}(t)||x^{\sigma}(t)|^{q} \triangle t.$$

Thus, we also obtain $\int_c^b \eta(\sigma(t))|V_1(t)| \triangle t \ge 1$. This completes the proof of Theorem 3.4.

Theorem 3.5 Let $a, b \in \mathbb{T}$ with $\sigma(a) < b$ and $V_1 \in \mathbb{R}^{n \times n}_s$ with $V_1(t) \geq V(t)$. If (1.1) has a solution (x(t), y(t)) satisfying (2.1) on the interval $[a, b]_{\mathbb{T}}$, then the following inequalities hold:

$$\int_{a}^{b} |W(t)| \triangle t + \left(\int_{a}^{b} |U(t)| \triangle t \right)^{\frac{1}{p}} \left(\int_{a}^{b} |V_{1}(t)| \triangle t \right)^{\frac{1}{q}} \ge 2, \quad \text{if } q \ge 2,$$

$$\int_{a}^{b} |W(t)| \triangle t + \left(\int_{a}^{b} |U(t)|^{\frac{p(p-2)}{2} + 1} |(\sqrt{U(t)})^{-1}|^{p(p-2)} \triangle t \right)^{\frac{1}{p}} \left(\int_{a}^{b} |V_{1}(t)| \triangle t \right)^{\frac{1}{q}} \ge 2, \quad \text{if } 1 < q < 2.$$

Proof From the proof of Theorem 3.1, we have

$$\int_{a}^{b} |y(t)|^{p-2} y^{T}(t) U(t) y(t) \triangle t = \int_{a}^{b} |x^{\sigma}(t)|^{q-2} (x^{\sigma}(t))^{T} V(t) x^{\sigma}(t) \triangle t.$$

It follows from the first equation of (1.1) that for all $a \le t \le b$,

$$x(t) = \int_a^t (-W(\tau)x^{\sigma}(\tau) - U(\tau)|y(\tau)|^{p-2}y(\tau)) \triangle \tau,$$

$$x(t) = \int_{t}^{b} (W(\tau)x^{\sigma}(\tau) + U(\tau)|y(\tau)|^{p-2}y(\tau)) \triangle \tau.$$

Case I: Assume that $q \geq 2$. We have

$$|x(t)| = \left| \int_{a}^{t} (-W(\tau)x^{\sigma}(\tau) - U(\tau)|y(\tau)|^{p-2}y(\tau)) \triangle \tau \right|$$

$$\leq \int_{a}^{t} |W(\tau)x^{\sigma}(\tau) + U(\tau)|y(\tau)|^{p-2}y(\tau)| \triangle \tau$$

$$\leq \int_{a}^{t} |W(\tau)x^{\sigma}(\tau)| \triangle \tau + \int_{a}^{t} |U(\tau)|y(\tau)|^{p-2}y(\tau)| \triangle \tau$$

$$\leq \int_{a}^{t} |W(\tau)||x^{\sigma}(\tau)| \triangle \tau + \int_{a}^{t} |U(\tau)|^{1-\frac{1}{q}}(y^{T}(\tau)U(\tau)y(\tau))^{\frac{1}{q}}|y(\tau)|^{p-1-\frac{2}{q}} \triangle \tau.$$

Similarly, we have

$$|x(t)| \le \int_t^b |W(\tau)| |x^{\sigma}(\tau)| \, \Delta \, \tau + \int_t^b |U(\tau)|^{1 - \frac{1}{q}} (y^T(\tau)U(\tau)y(\tau))^{\frac{1}{q}} |y(\tau)|^{p - 1 - \frac{2}{q}} \, \Delta \, \tau.$$

Then from Lemma 2.2 and Lemma 2.6, we obtain

$$\begin{split} |x(t)| & \leq & \frac{1}{2} \Big[\int_{a}^{b} |W(t)| |x^{\sigma}(t)| \bigtriangleup t + \int_{a}^{b} |U(t)|^{1 - \frac{1}{q}} (y^{T}(t)U(t)y(t))^{\frac{1}{q}} |y(t)|^{p - 1 - \frac{2}{q}} \bigtriangleup t \Big] \\ & \leq & \frac{1}{2} \Big[\int_{a}^{b} |W(t)| |x^{\sigma}(t)| \bigtriangleup t + \Big(\int_{a}^{b} |U(t)| \bigtriangleup t \Big)^{\frac{1}{p}} \Big(\int_{a}^{b} y^{T}(t)U(t)y(t) |y(t)|^{p - 2} \bigtriangleup t \Big)^{\frac{1}{q}} \Big] \\ & = & \frac{1}{2} \Big[\int_{a}^{b} |W(t)| |x^{\sigma}(t)| \bigtriangleup t + \Big(\int_{a}^{b} |U(t)| \bigtriangleup t \Big)^{\frac{1}{p}} \Big(\int_{a}^{b} |x^{\sigma}(t)|^{q - 2} (x^{\sigma}(t))^{T} V(t) x^{\sigma}(t) \bigtriangleup t \Big)^{\frac{1}{q}} \Big] \\ & \leq & \frac{1}{2} \Big[\int_{a}^{b} |W(t)| |x^{\sigma}(t)| \bigtriangleup t + \Big(\int_{a}^{b} |U(t)| \bigtriangleup t \Big)^{\frac{1}{p}} \Big(\int_{a}^{b} |V_{1}(t)| |x^{\sigma}(t)|^{q} \bigtriangleup t \Big)^{\frac{1}{q}} \Big]. \end{split}$$

Denote $M = \max_{a \le t \le b} |x(t)| > 0$, then

$$M \le \frac{1}{2} \Big[\int_a^b |W(t)| M \triangle t + \Big(\int_a^b |U(t)| \triangle t \Big)^{\frac{1}{p}} \Big(\int_a^b |V_1(t)| M^q \triangle t \Big)^{\frac{1}{q}} \Big].$$

Thus

$$\int_a^b |W(t)| \bigtriangleup t + \Big(\int_a^b |U(t)| \bigtriangleup t\Big)^{\frac{1}{p}} \Big(\int_a^b |V_1(t)| \bigtriangleup t\Big)^{\frac{1}{q}} \geq 2.$$

Case II: Assume that 1 < q < 2. Then $p \ge 2$ and

$$\begin{split} |x(t)| & \leq \int_a^t |W(\tau)x^{\sigma}(\tau) + U(\tau)|y(\tau)|^{p-2}y(\tau)| \bigtriangleup \tau \\ & \leq \int_a^t |W(\tau)x^{\sigma}(\tau)| \bigtriangleup \tau + \int_a^t |U(\tau)|y(\tau)|^{p-2}y(\tau)| \bigtriangleup \tau \\ & \leq \int_a^t |W(\tau)||x^{\sigma}(\tau)| \bigtriangleup \tau + \int_a^t |(\sqrt{U(\tau)})^{-1}|^{p-2}|U(\tau)|^{\frac{1}{2}} \\ & \times (y^T(\tau)U(\tau)y(\tau))^{\frac{1}{q}}|\sqrt{U(\tau)}|^{\frac{(p-1)(p-2)}{p}}|y(\tau)|^{p-1-\frac{2}{q}} \bigtriangleup \tau. \end{split}$$

and

$$|x(t)| \leq \int_{t}^{b} |W(\tau)| |x^{\sigma}(\tau)| \, \Delta \, \tau + \int_{t}^{b} |(\sqrt{U(\tau)})^{-1}|^{p-2} |U(\tau)|^{\frac{1}{2}} \\ \times (y^{T}(\tau)U(\tau)y(\tau))^{\frac{1}{q}} |\sqrt{U(\tau)}|^{\frac{(p-1)(p-2)}{p}} |y(\tau)|^{p-1-\frac{2}{q}} \, \Delta \, \tau.$$

Thus we obtain

$$\begin{split} |x(t)| & \leq & \frac{1}{2} \Big[\int_{a}^{b} |W(t)| |x^{\sigma}(t)| \bigtriangleup t + \int_{a}^{b} |(\sqrt{U(t)})^{-1}|^{p-2} |U(t)|^{\frac{1}{2}} \\ & \qquad \times (y^{T}(t)U(t)y(t))^{\frac{1}{q}} |\sqrt{U(t)}|^{\frac{(p-1)(p-2)}{p}} |y(t)|^{p-1-\frac{2}{q}} \bigtriangleup t \Big] \\ & \leq & \frac{1}{2} \Big[\int_{a}^{b} |W(t)| |x^{\sigma}(t)| \bigtriangleup t + \Big(\int_{a}^{b} (|(\sqrt{U(t)})^{-1}|^{p-2} |\sqrt{U(t)}|^{\frac{(p-1)(p-2)}{p}+1})^{p} \bigtriangleup t \Big)^{\frac{1}{p}} \\ & \qquad \times \Big(\int_{a}^{b} ((y^{T}(t)U(t)y(t))^{\frac{1}{q}} |y(t)|^{p-1-\frac{2}{q}})^{q} \bigtriangleup t \Big)^{\frac{1}{q}} \Big] \\ & = & \frac{1}{2} \Big[\int_{a}^{b} |W(t)| |x^{\sigma}(t)| \bigtriangleup t + \Big(\int_{a}^{b} |U(t)|^{\frac{p(p-2)}{2}+1} |(\sqrt{U(t)})^{-1}|^{p(p-2)} \bigtriangleup t \Big)^{\frac{1}{p}} \\ & \qquad \times \Big(\int_{a}^{b} |x^{\sigma}(t)|^{q-2} (x^{\sigma}(t))^{T} V(t) x^{\sigma}(t) \bigtriangleup t \Big)^{\frac{1}{q}} \Big] \\ & \leq & \frac{1}{2} \Big[\int_{a}^{b} |W(t)| |x^{\sigma}(t)| \bigtriangleup t + \Big(\int_{a}^{b} |U(t)|^{\frac{p(p-2)}{2}+1} |(\sqrt{U(t)})^{-1}|^{p(p-2)} \bigtriangleup t \Big)^{\frac{1}{p}} \\ & \qquad \times \Big(\int_{a}^{b} |V_{1}(t)| |x^{\sigma}(t)|^{q} \bigtriangleup t \Big)^{\frac{1}{q}} \Big]. \end{split}$$

Similarly, we also have

$$\int_{a}^{b} |W(t)| \triangle t + \left(\int_{a}^{b} |U(t)|^{\frac{p(p-2)}{2}+1} |(\sqrt{U(t)})^{-1}|^{p(p-2)} \triangle t \right)^{\frac{1}{p}} \left(\int_{a}^{b} |V_{1}(t)| \triangle t \right)^{\frac{1}{q}} \ge 2.$$

This completes the proof of Theorem 3.5.

REFERENCES

- [1] S. Hilger, Analysis on measure chains a unified approach to continuous and discrete calculus, Results Math., 18(1990): 18-56.
- [2] L. Jiang, Z. Zhou, Lyapunov inequality for linear Hamiltonian systems on time scales, J. Math. Anal. Appl. 310(2005)579-593.
- [3] F. Wong, S. Yu, C. Yeh, W. Lian, Lyapunov's inequality on time scales, Appl. Math. Lett. 19(2006)1293-1299.
- [4] X. Liu, M. Tang, Lyapunov-type inequality for higher order difference equations, Appl. Math. Comput. 232(2014)666-669.
- [5] M. Bohner, A. Peterson, Dynamic Equations on Time Scales: An Introduction with Applications, Birkhauser, Boston, 2001.
- [6] M. Bohner, A. Peterson, Advances in Dynamic Equations on Time Scales, Birkhauser, Boston, 2003.
- [7] Q. Zhang, X. He, J. Jiang, On Lyapunov-type inequalities for nonlinear dynamic systems on time scales, Comput. Math. Appl. 62(2011): 4028-4038.
- [8] A. Tiryaki, D. Cakmak, M. F. Aktas, Lyapunov-type inequalities for a certain class of nonlinear systems, Comput. Math. Appl. 64(2012): 1804-1811.
- [9] G. Sh. Guseinov, B. Kaymakcalan, Lyapunov inequalities for discrete linear Hamiltonian systems, Comput. Math. Appl. 45(2003): 1399-1416.
- [10] X. He, Q. Zhang, X. Tang, On inequalities of Lyapunov for linear Hamiltonian systems on time scales, J. Math. Anal. Appl. 381(2011): 695-705.
- [11] X. Tang, M. Zhang, Lyapunov inequalities and stability for linear Hamiltonian systems, J. Differential Equations. 252(2012): 358-381.
- [12] J. Liu, T. Sun, X. Kong, Q. He, Lyapunov inequalities of linear Hamiltonian systems on time scales, J. Comput. Anal. Appl. 21(2016)1160-1169.
- [13] R. P. Agarwal, M. Bohner, P. Rehak, Half-linear dynamic equations, Nonlinear Anal. Appl. (2003)1-56.
- [14] R. P. Agarwal, A. Ozbekler, Lyapunov type inequalities for even order differential equations with mixed nonlinearities, J. Inequal. Appl. 2015(2015)142, 10 pages.
- [15] R. P. Agarwal, A. Ozbekler, Disconjugacy via Lyapunov and Valée–Poussin type inequalities for forced differential equations, Appl. Math. Comput., 265(2015)456-468.
- [16] R. P. Agarwal, A. Ozbekler, Lyapunov type inequalities for second order sub and super-half-linear differential equations, Dynam. Sys. Appl. 24(2015)211-220.

A new three-step iterative method for a countable family of pseudo-contractive mappings in Hilbert spaces

Qin Chen, Li Li, Nan Lin, Baoguo Chen*

Research Center for Science Technology and Society, Fuzhou University of International Studies and Trade, Fuzhou 350202, P.R. China

Abstract: In this paper, we propose a new three-step iterative method for a countable family of pseudo-contractive mappings in a real Hilbert space. We also prove the strong convergence of the proposed iterative algorithm under appropriate conditions.

Key words: pseudo-contractive mapping; iterative method; fixed point; strong convergence

AMS subject classification (2000): 47H09

1 Introduction

In this paper, we assume that H is a real Hilbert space with the inner product $\langle \cdot, \cdot \rangle$ and the induced norm $\|\cdot\|$, C is a nonempty closed convex subset of H and $T: C \to C$ is a self-mapping of C. $\mathcal{F}(T)$ denotes the fixed point set of the mapping T. Recall that T is called a k-strictly pseudo-contractive mapping if there exists a constant $k \in [0,1)$ such that

$$||Tx - Ty||^2 \le ||x - y||^2 + k||(I - T)x - (I - T)y||^2, \quad \forall \ x, y \in C,$$
(1.1)

and T is called a pseudo-contractive mapping if

$$||Tx - Ty||^2 \le ||x - y||^2 + ||(I - T)x - (I - T)y||^2, \quad \forall \ x, y \in C.$$
(1.2)

It is obvious that k = 0, then the mapping T is nonexpansive, that is

$$||Tx - Ty|| \le ||x - y||, \quad \forall \ x, y \in C.$$
 (1.3)

Finding the fixed points of nonexpansive mappings is an important topic in the theory of nonexpansive mappings and has wide applications in a number of applied areas, such as the convex feasibility problem [1, 2], the split feasibility problem [3], image recovery and signal

^{*}Corresponding author. Email: chenbg123@163.com.

processing [4]. After that, as an important generalization of nonexpansive mappings, strictly pseudo-contractive mappings become one of the most interesting studied class of nonexpansive mappings. In fact, strictly pseudo-contractive mappings have more powerful application than nonexpansive mappings do such as in solving inverse problem [5].

Iterative methods for nonexpansive mappings have been extensively investigated (see e.g., [6-16, 31-33] and the references contained therein). However, iterative methods for strictly pseudo-contractive mappings are far less developed than those for nonexpansive mappings and the reason is probably that the second term appearing on the right hand side of (1.1) impedes the convergence analysis for iterative algorithms used to find a fixed point of the strictly pseudo-contractive mapping T.

The most general iterative algorithm for nonexpansive mappings studied by many authors is Mann's iteration algorithm [18] which is as following:

$$x_{n+1} = \alpha_n x_n + (1 - \alpha_n) T x_n, \quad n \ge 0, \tag{1.4}$$

where $x_0 \in C$ is chosen arbitrarily and $\{\alpha_n\}$ is a real sequence in (0,1). Under the following additional assumptions: (i) $\lim_{n\to\infty} \alpha_n = 0$ and (ii) $\sum_{n=0}^{\infty} \alpha_n = \infty$, the sequence $\{x_n\}$ generated by (1.4) is generally referred to as Mann's iteration algorithm in the light of [18]. The Mann's iteration algorithm dose not generally converge to a fixed point of T even the fixed point exists. For example, C is a nonempty closed convex and bounded subset of a real Hilbert space, $T:C\to C$ is nonexpansive, one can only prove that the sequence generated by Mann's iteration algorithm (1.4) with the assumptions (i) and (ii) is an approximate fixed point sequence, that is, $\|x_n - Tx_n\| \to 0$ as $n \to \infty$. In [19], Reich proved that if X is a uniformly convex Banach space with a Fréchet differentiable norm and if $\{\alpha_n\}$ is chosen such that $\sum_{n=0}^{\infty} \alpha_n (1-\alpha_n) = \infty$, then the sequence $\{x_n\}$ defined by (1.4) converges weakly to a fixed point of T. To get the sequence $\{x_n\}$ to converge strongly to a fixed point of T (when such a fixed point exists), some type of compactness condition must be additionally imposed either on C (e.g., C is compact) or on T (e.g., T is demicompact or T is semicompact, see [20,21]).

The first convergence result for k-strictly pseudo-contractive mappings was proposed by Browder and Petryshyn [22] in 1967. They proved that if the sequence $\{x_n\}$ is generated by the following:

$$x_{n+1} = \alpha x_n + (1 - \alpha)Tx_n, \quad n \ge 0,$$
 (1.5)

for any starting point $x_0 \in C$ and α is a constant such that $k < \alpha < 1$, then the sequence $\{x_n\}$ converges weakly to a fixed point of k-strictly pseudo-contractive mapping T. In [23], Marino and Xu extended the result of Browder and Petryshyn [22] to Mann's iteration algorithm (1.4), they proved that the sequence $\{x_n\}$ generated by (1.4) converges weakly to a fixed point of k-strictly pseudo-contractive mapping T for the conditions that $k < \alpha_n < 1$ for all n and $\sum_{n=0}^{\infty} (\alpha_n - k)(1 - \alpha_n) = \infty$.

However, the well known strong convergence result for pseudo-contractive mappings is Ishikawa's iteration algorithm which was proved by Ishikawa [24] in 1974 and it is more general than that of Mann's iteration algorithm (1.4) in some sense. More precisely, he got the following theorem.

Theorem 1.1 ([24]) Let C be a convex compact subset of a Hilbert space H and let $T: C \to C$ be a Lipschitz pseudo-contractive mapping. For any $x_1 \in C$, suppose the sequence $\{x_n\}$ is defined iteratively for each $n \geq 1$ by

$$\begin{cases} y_n = (1 - \beta_n)x_n + \beta_n T x_n, \\ x_{n+1} = (1 - \alpha_n)x_n + \alpha_n T y_n, \end{cases}$$

$$\tag{1.6}$$

where $\{\alpha_n\}$, $\{\beta_n\}$ are sequences of positive number that satisfy the following there conditions: (i) $0 \le \alpha_n \le \beta_n \le 1$; (ii) $\lim_{n \to \infty} \beta_n = 0$; (iii) $\sum_{n=1}^{\infty} \alpha_n \beta_n = \infty$. Then the sequence $\{x_n\}$ converges strongly to a fixed point of T.

In 2001, Chidume and Mutangadura [25] gave an example to show that the Mann's iteration algorithm (1.4) failed to be convergent to a fixed point of Lipschitz pseudo-contractive mappings. In order to obtain a strong convergence result for pseudo-contractive mappings without the compactness assumption, Zhou [26] established the hybrid Ishikawa algorithm for Lipschitz pseudo-contractive mappings as following:

Theorem 1.2 ([26]) Let C be a closed convex subset of a real Hilbert space H and let $T: C \to C$ be a Lipschitz pseudo-contraction such that $\mathcal{F}(T) \neq \phi$. Suppose that $\{\alpha_n\}$ and $\{\beta_n\}$ are two real sequences in (0,1) satisfying the conditions: (i) $\alpha_n \leq \beta_n, \forall n \geq 0$; (ii) $\liminf_{n \to \infty} \alpha_n > 0$; (iii) $\limsup_{n\to\infty} \alpha_n \leq \alpha < \frac{1}{\sqrt{1+L^2+1}}, \ n\geq 0, \ where \ L\geq 1 \ is \ the \ Lipschitzian \ constant \ of \ T. \ Let \ a$ sequence $\{x_n\}$ be generated by

$$\begin{cases} x_{0} \in C, \\ y_{n} = (1 - \alpha_{n})x_{n} + \alpha_{n}Tx_{n}, \\ z_{n} = (1 - \beta_{n})x_{n} + \beta_{n}Ty_{n}, \\ C_{n} = \{z \in C : \|z_{n} - z\|^{2} \leq \|x_{n} - z\|^{2} - \alpha_{n}\beta_{n}(1 - 2\alpha_{n} - L^{2}\alpha_{n}^{2})\|x_{n} - Tx_{n}\|^{2}\}, \\ Q_{n} = \{z \in C : \langle x_{n} - z, x_{0} - x_{n} \rangle \geq 0\}, \\ x_{n+1} = P_{C_{n} \cap Q_{n}}x_{0}, \quad n \geq 0. \end{cases}$$

$$(1.7)$$

$$(1.7)$$

$$(1.7)$$

$$(1.7)$$

Then, $\{x_n\}$ converges strongly to a fixed point v of T, where $v = P_{\mathcal{F}(T)}(x_0)$.

We observe that the iterative algorithm (1.7) generates a sequence $\{x_n\}$ by projecting x_0 on to the intersection of the suitably constructed closed convex sets C_n and Q_n . Recently, Yao et al. [27] introduced the hybrid iterative algorithm which just involved one closed convex set for pseudo-contractive mappings in Hilbert spaces as follows:

Let C be a nonempty closed convex subset of a real Hilbert space H. Let $T: C \to C$ be a pseudo-contractive mapping. Let $\{\alpha_n\}$ be a sequence in (0,1). Let $x_0 \in H$. For $C_1 = C$ and $x_1 = P_{C_1}x_0$, define a sequence $\{x_n\}$ of C as follows:

$$\begin{cases} y_n = (1 - \alpha_n)x_n + \alpha_n T x_n, \\ C_{n+1} = \{ z \in C_n : \|\alpha_n (I - T)y_n\|^2 \le 2\alpha_n \langle x_n - z, (I - T)y_n \rangle \}, \\ x_{n+1} = P_{C_{n+1}} x_0, \quad n \in N. \end{cases}$$
(1.8)

Theorem 1.3 ([27]) Let C be a nonempty closed convex subset of a real Hilbert space H. Let $T: C \to C$ be a L-Lipschitz pseudo-contractive mapping such that $\mathcal{F}(T) \neq \phi$. Assume the sequence $\alpha_n \in [a,b]$ for some $a,b \in (0,\frac{1}{L+1})$. Then the sequence $\{x_n\}$ generated by (1.8) converges strongly $P_{\mathcal{F}(T)}(x_0)$.

In [28], Tang *et al.* proposed the hybrid algorithm (1.8) to the Ishikawa's iteration algorithm (1.6) and got the following result.

Let C be a nonempty closed convex subset of a real Hilbert space H. Let $T: C \to C$ be a pseudo-contractive mapping. Let $\{\alpha_n\}$, $\{\beta_n\}$ be two sequences in [0,1]. Let $x_0 \in H$. For $C_1 = C$ and $x_1 = P_{C_1}x_0$, define a sequence $\{x_n\}$ of C as follows:

$$\begin{cases} y_{n} = (1 - \alpha_{n})x_{n} + \alpha_{n}Tz_{n}, \\ z_{n} = (1 - \beta_{n})x_{n} + \beta_{n}Tx_{n}, \\ C_{n+1} = \{z \in C_{n} : \|\alpha_{n}(I - T)y_{n}\|^{2} \le 2\alpha_{n}\langle x_{n} - z, (I - T)y_{n}\rangle \\ + 2\alpha_{n}\beta_{n}L\|x_{n} - Tx_{n}\| \cdot \|y_{n} - x_{n} + \alpha_{n}(I - T)y_{n}\|\}, \\ x_{n+1} = P_{C_{n+1}}x_{0}, \quad n \ge 1. \end{cases}$$

$$(1.9)$$

Theorem 1.4 ([28]) Let C be a nonempty closed convex subset of a real Hilbert space H. Let $T: C \to C$ be a L-Lipschitz pseudo-contractive mapping with $L \ge 1$ such that $\mathcal{F}(T) \ne \phi$. Assume the sequences $\{\alpha_n\}$ and $\{\beta_n\}$ in (0,1) satisfying: (i) $b \le \alpha_n < \alpha_n(L+1)(1+\beta_nL) < a < 1$, for some $a,b \in (0,1)$; (ii) $\lim_{n\to\infty} \beta_n = 0$. Then the sequence $\{x_n\}$ generated by (1.9) converges strongly $P_{\mathcal{F}(T)}(x_0)$.

Recently, Zegeye et al. [29] generalized Ishikawa's iteration algorithm (1.6) to a common fixed point of a finite family of Lipschitz pseudo-contractive mappings and obtained the following theorem.

Theorem 1.5 ([29]) Let C be a nonempty, closed convex subset of a real Hilbert space H. Let $T_i: C \to C$, $i = 1, 2, \dots, N$, be a finite family of Lipschitz pseudo-contractive mappings with Lipschitzian constants L_i , for $i = 1, 2, \dots, N$, respectively. Assume that the interior of $\mathcal{F} := \bigcap_{i=1}^N \mathcal{F}(T_i)$ is nonempty. Let $\{x_n\}$ be a sequence generated from an arbitrary $x_0 \in C$ by

$$\begin{cases} y_n = (1 - \beta_n)x_n + \beta_n T_n x_n, \\ x_{n+1} = (1 - \alpha_n)x_n + \alpha_n T_n y_n, \end{cases}$$
 (1.10)

where $T_n := T_{n(mod\ N)}$ and $\{\alpha_n\}, \{\beta_n\} \subset (0,1)$ satisfying the following conditions: (i) $\alpha_n \leq \beta_n, \forall n \geq 0$; (ii) $\liminf_{n \to \infty} \alpha_n = \alpha > 0$; (iii) $\sup_{n \geq 1} \beta_n \leq \beta < \frac{1}{\sqrt{1 + L^2 + 1}}$ for $L := \max\{L_i : i = 1, 2, \dots, N\}$. Then, $\{x_n\}$ converges strongly to a common fixed point of $\{T_1, T_2, \dots, T_N\}$.

In [30], Cheng *et al.* extended the algorithm (1.10) to a countable family of pseudo-contractive mappings and gave a three-step iterative method, which is as follows:

Theorem 1.6 ([30]) Let C be a nonempty, closed convex subset of a real Hilbert space H, let $\{T_n\}_{n=1}^{\infty}: C \to C$ be a countable family of uniformly closed and uniformly Lipschitz pseudo-contractive mappings with Lipschitzian constants L_n , let $L := \sup_{n\geq 1} L_n$. Assume that the interior of $\mathcal{F} := \bigcap_{n=1}^{\infty} \mathcal{F}(T_n)$ is nonempty. Let $\{x_n\}$ be a sequence generated from an arbitrary $x_0 \in C$ by the following algorithm:

$$\begin{cases}
z_n = (1 - \gamma_n)x_n + \gamma_n T_n x_n, \\
y_n = (1 - \beta_n)x_n + \beta_n T_n z_n, \\
x_{n+1} = (1 - \alpha_n)x_n + \alpha_n T_n y_n,
\end{cases} (1.11)$$

where $\{\alpha_n\}, \{\beta_n\}, \{\gamma_n\} \subset (0,1)$ satisfying the following conditions: (i) $\alpha_n \leq \beta_n \leq \gamma_n, \forall n \geq 0$; (ii) $\liminf_{n \to \infty} \alpha_n = \alpha > 0$; (iii) $\sup_{n \geq 1} \gamma_n \leq \gamma$ with $\gamma^3 L^4 + 2\gamma^2 L^3 + \gamma^2 L^2 + \gamma L^2 + 2\gamma < 1$. Then, $\{x_n\}$ converges strongly to $x^* \in \mathcal{F}$.

Remark 1.1 The condition (iii) of the Theorem 1.6 is not correct, it is replaced by $\sup_{n\geq 1} \gamma_n \leq \gamma$ with $\gamma^3 L^4 + 2\gamma^2 L^3 + \gamma^2 L^2 + 2\gamma L^2 + 2\gamma < 1$.

Motivated and inspired by the above works, in this paper, we propose a new three-step iterative method for a countable family of pseudo-contractive mappings in Hilbert spaces and prove its strong convergence theorem under appropriate conditions.

2 Preliminaries

In this section, we recall some definitions and useful results which will be used in the next section.

Definition 2.1 Let C be a subset of a real Hilbert space H.

(1) A mapping $T: C \to H$ is said to be L-Lipschitz if there exists L > 0 such that

$$||Tx - Ty|| \le L||x - y||, \quad \forall \ x, \ y \in C.$$

When L = 1, T is nonexpansive. If L < 1, T is called a contraction. It is easy to see that every contractive mapping is nonexpansive and every nonexpansive mapping is Lipschitz.

(2) A countable family of mappings $\{T_n\}_{n=1}^{\infty} : C \to H$ is said to be uniformly Lipschitz with Lipschitzian constants $L_n > 0$, $n \ge 1$, if there exists $0 < L := \sup_{n \ge 1} L_n$ such that

$$||T_n x - T_n y|| \le L||x - y||, \quad \forall \ x, \ y \in C, \ n \ge 1.$$

(3) A countable family of mappings $\{T_n\}_{n=1}^{\infty}: C \to H \text{ is said to be uniformly closed if } x_n \to x^* \text{ and } ||x_n - T_n x_x|| \to 0 \text{ imply } x^* \in \bigcap_{n=1}^{\infty} \mathcal{F}(T_n).$

Definition 2.2 A mapping T with domain $\mathcal{D}(T)$ and range $\mathcal{R}(T)$ in a real Hilbert space H is said to be monotone if the inequality

$$||x - y|| \le ||x - y + s(Tx - Ty)||$$

holds for every $x, y \in \mathcal{D}(T)$ and for all s > 0.

We observe that

$$T$$
 is monotone $\Leftrightarrow \langle Tx - Ty, x - y \rangle \ge 0$
 $\Leftrightarrow \|(I - T)x - (I - T)y\|^2 \le \|x - y\|^2 + \|Tx - Ty\|^2$
 $\Leftrightarrow \|Ax - Ay\|^2 \le \|x - y\|^2 + \|(I - A)x - (I - A)y\|^2, A := I - T$
 $\Leftrightarrow A$ is pseudo-contractive.

Furthermore, a zero of T is a fixed point of A, that is,

$$x \in \mathcal{N}(T) := \{x \in \mathcal{D}(T) : Tx = 0\} \Leftrightarrow x \in \mathcal{F}(A) := \{x \in \mathcal{D}(A) : Ax = x\}.$$

Lemma 2.1 Let H be a real Hilbert space. Then for $\alpha \in [0,1]$ the following equality

$$\|\alpha x + (1 - \alpha)y\|^2 = \alpha \|x\|^2 + (1 - \alpha)\|y\|^2 - \alpha(1 - \alpha)\|x - y\|^2$$

holds for all $x, y \in H$.

Lemma 2.2 If the sequences $\{\alpha_n\}, \{\beta_n\}, \{\gamma_n\} \subset (0,1)$ satisfying the following conditions:

- (i) $\beta_n \leq \gamma_n, \forall n \geq 1$,
- (ii) $(1-\alpha)\gamma + \alpha\beta(\gamma^2L^2 + 2\gamma 1) < 0$

where $\alpha = \liminf_{n \to \infty} \alpha_n$, $\beta = \liminf_{n \to \infty} \beta_n$, $\gamma \ge \sup_{n \ge 1} \gamma_n$, and L > 0 is a constant. Then, we have

$$\alpha > 0, \beta > 0$$
 and $(1 - \alpha_n)\gamma_n + \alpha_n\beta_n(\gamma_n^2L^2 + 2\gamma_n - 1) < 0$.

Proof. On one hand, it is obvious that $\alpha > 0$, $\beta > 0$ and $\gamma^2 L^2 + 2\gamma - 1 < 0$ because of $(1-\alpha)\gamma + \alpha\beta(\gamma^2 L^2 + 2\gamma - 1) < 0$. And we get that $(1-\alpha_n)\gamma \leq (1-\alpha)\gamma$ and $\alpha_n\beta_n(\gamma^2 L^2 + 2\gamma - 1) \leq \alpha\beta(\gamma^2 L^2 + 2\gamma - 1)$. Then

$$(1 - \alpha_n)\gamma + \alpha_n\beta_n(\gamma^2L^2 + 2\gamma - 1) \le (1 - \alpha)\gamma + \alpha\beta(\gamma^2L^2 + 2\gamma - 1) < 0.$$

On the other hand, it is easy to know that $(1 - \alpha_n)\gamma_n \leq (1 - \alpha_n)\gamma$ and $\alpha_n\beta_n(\gamma_n^2 + 2\gamma_n - 1) \leq \alpha_n\beta_n(\gamma^2L^2 + 2\gamma - 1)$. We can obtain

$$(1 - \alpha_n)\gamma_n + \alpha_n\beta_n(\gamma_n^2 + 2\gamma_n - 1) \le (1 - \alpha_n)\gamma + \alpha_n\beta_n(\gamma^2L^2 + 2\gamma - 1) < 0.$$

Hence
$$(1 - \alpha_n)\gamma_n + \alpha_n\beta_n(\gamma_n^2L^2 + 2\gamma_n - 1) < 0.$$

3 The main result

Theorem 3.1 Let C be a nonempty, closed convex subset of a real Hilbert space H, let $\{T_n\}_{n=1}^{\infty}$: $C \to C$ be a countable family of uniformly closed and uniformly Lipschitz pseudo-contractive mappings with Lipschitzian constants L_n , let $L := \sup_{n\geq 1} L_n$. Assume that the interior of $\mathcal{F} := \bigcap_{n=1}^{\infty} \mathcal{F}(T_n)$ is nonempty. Let $\{x_n\}$ be a sequence generated from an arbitrary $x_1 \in C$ by

$$\begin{cases} z_n = (1 - \gamma_n)x_n + \gamma_n T_n x_n, \\ y_n = (1 - \beta_n)x_n + \beta_n T_n z_n, \\ x_{n+1} = (1 - \alpha_n)z_n + \alpha_n y_n, \end{cases}$$
(3.1)

where $\{\alpha_n\}, \{\beta_n\}, \{\gamma_n\} \subset (0,1)$ satisfying the following conditions:

(i) $\beta_n \leq \gamma_n, \forall n \geq 1$,

(ii)
$$(1 - \alpha)\gamma + \alpha\beta(\gamma^2 L^2 + 2\gamma - 1) < 0$$
,

where $\alpha = \liminf_{n \to \infty} \alpha_n$, $\beta = \liminf_{n \to \infty} \beta_n$ and $\gamma \ge \sup_{n \ge 1} \gamma_n$. Then, $\{x_n\}$ converges strongly to $x^* \in \mathcal{F}$.

Proof. Take $p \in \mathcal{F}$ arbitrarily. By (3.1) and Lemma 2.1, we have

$$||x_{n+1} - p||^{2} = ||(1 - \alpha_{n})z_{n} + \alpha_{n}y_{n} - p||^{2}$$

$$= ||(1 - \alpha_{n})(z_{n} - p) + \alpha_{n}(y_{n} - p)||^{2}$$

$$= (1 - \alpha_{n})||z_{n} - p||^{2} + \alpha_{n}||y_{n} - p||^{2} - \alpha_{n}(1 - \alpha_{n})||z_{n} - y_{n}||^{2}$$

$$\leq (1 - \alpha_{n})||z_{n} - p||^{2} + \alpha_{n}||y_{n} - p||^{2},$$
(3.2)

and

$$||z_{n} - p||^{2} = ||(1 - \gamma_{n})x_{n} + \gamma_{n}T_{n}x_{n} - p||^{2}$$

$$= ||(1 - \gamma_{n})(x_{n} - p) + \gamma_{n}(T_{n}x_{n} - p)||^{2}$$

$$= (1 - \gamma_{n})||x_{n} - p||^{2} + \gamma_{n}||T_{n}x_{n} - p||^{2} - \gamma_{n}(1 - \gamma_{n})||x_{n} - T_{n}x_{n}||^{2}$$

$$\leq (1 - \gamma_{n})||x_{n} - p||^{2} + \gamma_{n}(||x_{n} - p||^{2} + ||x_{n} - T_{n}x_{n}||^{2})$$

$$- \gamma_{n}(1 - \gamma_{n})||x_{n} - T_{n}x_{n}||^{2}$$

$$= ||x_{n} - p||^{2} + \gamma_{n}^{2}||x_{n} - T_{n}x_{n}||^{2},$$
(3.3)

where the inequality is based on that $\{T_n\}_{n=1}^{\infty}$ is a countable family of pseudo-contractive mappings. Similarly, we can get

$$||y_{n} - p||^{2} = ||(1 - \beta_{n})x_{n} + \beta_{n}T_{n}z_{n} - p||^{2}$$

$$= ||(1 - \beta_{n})(x_{n} - p) + \beta_{n}(T_{n}z_{n} - p)||^{2}$$

$$= (1 - \beta_{n})||x_{n} - p||^{2} + \beta_{n}||T_{n}z_{n} - p||^{2} - \beta_{n}(1 - \beta_{n})||x_{n} - T_{n}z_{n}||^{2}$$

$$\leq (1 - \beta_{n})||x_{n} - p||^{2} + \beta_{n}(||z_{n} - p||^{2} + ||z_{n} - T_{n}z_{n}||^{2})$$

$$- \beta_{n}(1 - \beta_{n})||x_{n} - T_{n}z_{n}||^{2}.$$
(3.4)

In addition, using (3.1), we have that

$$||z_{n} - T_{n}z_{n}||^{2} = ||(1 - \gamma_{n})x_{n} + \gamma_{n}T_{n}x_{n} - T_{n}z_{n}||^{2}$$

$$= ||(1 - \gamma_{n})(x_{n} - T_{n}z_{n}) + \gamma_{n}(T_{n}x_{n} - T_{n}z_{n})||^{2}$$

$$= (1 - \gamma_{n})||x_{n} - T_{n}z_{n}||^{2} + \gamma_{n}||T_{n}x_{n} - T_{n}z_{n}||^{2} - \gamma_{n}(1 - \gamma_{n})||x_{n} - T_{n}x_{n}||^{2}$$

$$\leq (1 - \gamma_{n})||x_{n} - T_{n}z_{n}||^{2} + \gamma_{n}L^{2}||x_{n} - z_{n}||^{2} - \gamma_{n}(1 - \gamma_{n})||x_{n} - T_{n}x_{n}||^{2}$$

$$= (1 - \gamma_{n})||x_{n} - T_{n}z_{n}||^{2} + \gamma_{n}L^{2}||\gamma_{n}(x_{n} - T_{n}x_{n})||^{2} - \gamma_{n}(1 - \gamma_{n})||x_{n} - T_{n}x_{n}||^{2}$$

$$= (1 - \gamma_{n})||x_{n} - T_{n}z_{n}||^{2} + \gamma_{n}(\gamma_{n}^{2}L^{2} + \gamma_{n} - 1)||x_{n} - T_{n}x_{n}||^{2}, \qquad (3.5)$$

where the inequality is based on that $\{T_n\}_{n=1}^{\infty}$ is a countable family of uniformly Lipschitz mappings. Substituting (3.3) and (3.5) into (3.4), we obtain that

$$||y_{n} - p||^{2} \leq (1 - \beta_{n})||x_{n} - p||^{2} + \beta_{n} (||x_{n} - p||^{2} + \gamma_{n}^{2}||x_{n} - T_{n}x_{n}||^{2})$$

$$+ \beta_{n} ((1 - \gamma_{n})||x_{n} - T_{n}z_{n}||^{2} + \gamma_{n} (\gamma_{n}^{2}L^{2} + \gamma_{n} - 1)||x_{n} - T_{n}x_{n}||^{2})$$

$$- \beta_{n} (1 - \beta_{n})||x_{n} - T_{n}z_{n}||^{2}$$

$$= ||x_{n} - p||^{2} + \beta_{n} \gamma_{n} (\gamma_{n}^{2}L^{2} + 2\gamma_{n} - 1)||x_{n} - T_{n}x_{n}||^{2} + \beta_{n} (\beta_{n} - \gamma_{n})||x_{n} - T_{n}z_{n}||^{2}$$

$$\leq ||x_{n} - p||^{2} + \beta_{n} \gamma_{n} (\gamma_{n}^{2}L^{2} + 2\gamma_{n} - 1)||x_{n} - T_{n}x_{n}||^{2},$$

$$(3.6)$$

where the last inequality is based on the condition (i). Therefore, substituting (3.3) and (3.6) into (3.2), we get

$$||x_{n+1} - p||^{2} \leq (1 - \alpha_{n}) \Big(||x_{n} - p||^{2} + \gamma_{n}^{2} ||x_{n} - T_{n} x_{n}||^{2} \Big)$$

$$+ \alpha_{n} \Big(||x_{n} - p||^{2} + \beta_{n} \gamma_{n} (\gamma_{n}^{2} L^{2} + 2\gamma_{n} - 1) ||x_{n} - T_{n} x_{n}||^{2} \Big)$$

$$= ||x_{n} - p||^{2} + \Big((1 - \alpha_{n}) \gamma_{n}^{2} + \alpha_{n} \beta_{n} \gamma_{n} (\gamma_{n}^{2} L^{2} + 2\gamma_{n} - 1) \Big) ||x_{n} - T_{n} x_{n}||^{2}. (3.7)$$

According to the conditions and Lemma 2.2, inequality (3.7) implies that

$$||x_{n+1} - p||^2 \le ||x_n - p||^2.$$
(3.8)

It is obvious that $\lim_{n\to\infty} ||x_n - p||$ exists, then $\{||x_n - p||\}$ is bounded. This implies that $\{x_n\}$, $\{T_nx_n\}$, $\{z_n\}$, $\{T_nz_n\}$ and $\{y_n\}$ are also bounded.

Furthermore, we have that

$$||x_n - p||^2 = ||x_n - x_{n+1}||^2 + ||x_{n+1} - p||^2 + 2\langle x_{n+1} - p, x_n - x_{n+1} \rangle.$$

This implies

$$\langle x_{n+1} - p, x_n - x_{n+1} \rangle + \frac{1}{2} ||x_n - x_{n+1}||^2 = \frac{1}{2} (||x_n - p||^2 - ||x_{n+1} - p||^2).$$
 (3.9)

Moreover, since the interior of \mathcal{F} is nonempty, then there exists $p^* \in \mathcal{F}$ and r > 0 such that $p^* + rh \in \mathcal{F}$ whenever $||h|| \leq 1$. Thus, from (3.8), we have

$$0 \leq \langle x_{n+1} - (p^* + rh), x_n - x_{n+1} \rangle + \frac{1}{2} ||x_n - x_{n+1}||^2$$

$$= \frac{1}{2} (||x_n - (p^* + rh)||^2 - ||x_{n+1} - (p^* + rh)||^2). \tag{3.10}$$

From (3.9) and (3.10), we obtain that

$$r\langle h, x_n - x_{n+1} \rangle \leq \langle x_{n+1} - p^*, x_n - x_{n+1} \rangle + \frac{1}{2} ||x_n - x_{n+1}||^2$$

$$= \frac{1}{2} (||x_n - p^*||^2 - ||x_{n+1} - p^*||^2). \tag{3.11}$$

Since h with $||h|| \le 1$ is arbitrary, we can take $h = \frac{x_n - x_{n+1}}{||x_n - x_{n+1}||}$ with ||h|| = 1, then

$$||x_n - x_{n+1}|| \le \frac{1}{2r} (||x_n - p^*||^2 - ||x_{n+1} - p^*||^2).$$

So, for n > m, we can get

$$||x_{m} - x_{n}|| = ||(x_{m} - x_{m+1}) + (x_{m+1} - x_{m+2}) + \dots + (x_{n-1} - x_{n})||$$

$$\leq \sum_{i=m}^{n-1} ||x_{i} - x_{i+1}||$$

$$\leq \sum_{i=m}^{n-1} \frac{1}{2r} (||x_{i} - p^{*}||^{2} - ||x_{i+1} - p^{*}||^{2})$$

$$= \frac{1}{2r} (||x_{m} - p^{*}||^{2} - ||x_{n} - p^{*}||^{2}).$$

From (3.8), we know that $\{\|x_n - p^*\|^2\}$ converges. Therefore, $\{x_n\}$ is a Cauchy sequence. Since C is closed subset of Hilbert space H, then there exists $x^* \in C$ such that

$$x_n \to x^* \in C. \tag{3.12}$$

Furthermore, from the conditions and Lemma 2.2, we have

$$0 < \beta \Big((\alpha - 1)\gamma + \alpha \beta (1 - 2\gamma - \gamma^2 L^2) \Big)$$

$$\leq \gamma_n \left((\alpha_n - 1)\gamma_n + \alpha_n \beta_n (1 - 2\gamma_n - \gamma_n^2 L^2) \right)$$

$$= (\alpha_n - 1)\gamma_n^2 + \alpha_n \beta_n \gamma_n (1 - 2\gamma_n - \gamma_n^2 L^2). \tag{3.13}$$

Then, by (3.7) and (3.13), we conclude that

$$\left((\alpha - 1)\gamma \beta + \alpha \beta^{2} (1 - 2\gamma - \gamma^{2} L^{2}) \right) \sum_{n=1}^{\infty} \|x_{n} - T_{n} x_{n}\|^{2}$$

$$\leq \sum_{n=1}^{\infty} \left((\alpha_{n} - 1)\gamma_{n}^{2} + \alpha_{n} \beta_{n} \gamma_{n} (1 - 2\gamma_{n} - \gamma_{n}^{2} L^{2}) \right) \|x_{n} - T_{n} x_{n}\|^{2}$$

$$\leq \sum_{n=1}^{\infty} (\|x_{n} - p\|^{2} - \|x_{n+1} - p\|^{2}) < \infty,$$

from which it follows that

$$\lim_{n \to \infty} ||x_n - T_n x_n|| = 0. (3.14)$$

Since $\{T_n\}_{n=1}^{\infty}$ are uniformly closed mappings, then from (3.12) and (3.14), we can obtain

$$x^* \in \bigcap_{n=1}^{\infty} \mathcal{F}(T_n) = \mathcal{F}.$$

The proof is complete.

Remark 3.1 We now give an example of a countable family of uniformly closed and uniformly Lipschitz pseudo-contractive mappings with the interior of the common fixed points nonempty. This example comes from [30]. Suppose that H := R and $C := [-1, 1] \in H$. Let $\{T_n\}_{n=1}^{\infty} : C \to C$ be defined by

$$T_n x := \begin{cases} x, & x \in [-1, 0), \\ (\frac{1}{2^n} + \frac{1}{2})x, & x \in [0, 1]. \end{cases}$$

Then $\mathcal{F} := \bigcap_{n=1}^{\infty} \mathcal{F}(T_n) = [-1,0]$, and hence the interior of the common fixed points is nonempty. Moreover, it is easy to show that $\{T_n\}_{n=1}^{\infty}$ is a countable family of uniformly closed and uniformly Lipschitz pseudo-contractive mappings with Lipschitz constant $L := \sup_{n \geq 1} L_n = 2$.

For this example, we can let $\alpha_n = \frac{3}{4} + \frac{1}{n+4}$, $\beta_n = \frac{1}{10} + \frac{1}{n+40}$ and $\gamma_n = \frac{3}{20} - \frac{1}{n+40}$ for $n \ge 1$. Then $\{\alpha_n\}, \{\beta_n\}, \{\gamma_n\} \subset (0,1)$ and $\beta_n \le \gamma_n, \forall n \ge 1$. Furthermore, $\alpha = \liminf_{n \to \infty} \alpha_n = \frac{3}{4}$, $\beta = \liminf_{n \to \infty} \beta_n = \frac{1}{10}$, $\sup_{n \ge 1} \gamma_n \le \frac{3}{20}$, and

$$(1-\alpha)\gamma + \alpha\beta(\gamma^2L^2 + 2\gamma - 1) = (1-\frac{3}{4})\times\frac{3}{20} + \frac{3}{4}\times\frac{1}{10}\times\left((\frac{3}{20})^2\times2^2 + 2\times\frac{3}{20} - 1\right) = -\frac{33}{4000} < 0.$$

It satisfies all conditions in Theorem 3.1. Hence, from Theorem 3.1, we can obtain the sequence $\{x_n\}$ generated by (3.1) and staring with an arbitrary $x_1 \in C$ will converges strongly to a common fixed point of $\{T_n\}_{n=1}^{\infty}$.

4 Applications

If in Theorem 3.1, we consider a finite family of Lipschitz pseudo-contractive mappings, then we have the following result.

Theorem 4.1 Let C be a nonempty, closed convex subset of a real Hilbert space H, let $\{T_i\}_{i=1}^N$: $C \to C$ be a finite family of uniformly closed and Lipschitz pseudo-contractive mappings with Lipschitzian constants L_i , for $i = 1, 2, \dots, N$, respectively. Assume that the interior of $\mathcal{F} := \bigcap_{i=1}^N \mathcal{F}(T_i)$ is nonempty. Let $\{x_n\}$ be a sequence generated from an arbitrary $x_1 \in C$ by

$$\begin{cases} z_n = (1 - \gamma_n)x_n + \gamma_n T_n x_n, \\ y_n = (1 - \beta_n)x_n + \beta_n T_n z_n, \\ x_{n+1} = (1 - \alpha_n)z_n + \alpha_n y_n, \end{cases}$$
(4.1)

where $T_n := T_{n(mod\ N)}$ and $\{\alpha_n\}, \{\beta_n\}, \{\gamma_n\} \subset (0,1)$ satisfying the following conditions:

(i)
$$\beta_n \leq \gamma_n, \forall n \geq 1$$
,

(ii)
$$(1 - \alpha)\gamma + \alpha\beta(\gamma^2 L^2 + 2\gamma - 1) < 0$$
,

where $\alpha = \liminf_{n \to \infty} \alpha_n$, $\beta = \liminf_{n \to \infty} \beta_n$ and $\gamma \ge \sup_{n \ge 1} \gamma_n$, for $L := \max\{L_i : i = 1, 2, \dots, N\}$. Then, $\{x_n\}$ converges strongly to a common fixed point of $\{T_1, T_2, \dots, T_N\}$.

If in Theorem 3.1, we consider a single Lipschitz pseudo-contractive mapping, then we may add a condition that is $\sum_{n=1}^{\infty} \gamma_n = \infty$.

Theorem 4.2 Let C be a nonempty, closed convex subset of a real Hilbert space H, let $T: C \to C$ be a Lipschitz pseudo-contractive mapping with Lipschitzian constant L. Assume that the interior of $\mathcal{F}(T)$ is nonempty. Let $\{x_n\}$ be a sequence generated from an arbitrary $x_1 \in C$ by

$$\begin{cases}
z_n = (1 - \gamma_n)x_n + \gamma_n T x_n, \\
y_n = (1 - \beta_n)x_n + \beta_n T z_n, \\
x_{n+1} = (1 - \alpha_n)z_n + \alpha_n y_n,
\end{cases} (4.2)$$

where $\{\alpha_n\}, \{\beta_n\}, \{\gamma_n\} \subset (0,1)$ satisfying the following conditions:

- (i) $\beta_n \leq \gamma_n, \forall n \geq 1$,
- (ii) $\sum_{n=1}^{\infty} \gamma_n = \infty$,

(iii)
$$(1-\alpha)\gamma + \alpha\beta(\gamma^2L^2 + 2\gamma - 1) < 0$$
,

where $\alpha = \liminf_{n \to \infty} \alpha_n$, $\beta = \liminf_{n \to \infty} \beta_n$ and $\gamma \ge \sup_{n \ge 1} \gamma_n$. Then, $\{x_n\}$ converges strongly to a fixed point of T.

Proof. Following the method of the proof of Theorem 3.1, we also obtain that

$$||x_{n+1} - p||^2 \le ||x_n - p||^2 + \left((1 - \alpha_n)\gamma_n^2 + \alpha_n \beta_n \gamma_n (\gamma_n^2 L^2 + 2\gamma_n - 1) \right) ||x_n - Tx_n||^2,$$

and $x_n \to x^* \in C$. Now, from Lemma 2.2, we get

$$\left((\alpha - 1)\gamma + \alpha\beta(1 - 2\gamma - \gamma^{2}L^{2}) \right) \sum_{n=1}^{\infty} \gamma_{n} \|x_{n} - Tx_{n}\|^{2}$$

$$\leq \sum_{n=1}^{\infty} \gamma_{n} \left((\alpha_{n} - 1)\gamma_{n} + \alpha_{n}\beta_{n}(1 - 2\gamma_{n} - \gamma_{n}^{2}L^{2}) \right) \|x_{n} - Tx_{n}\|^{2}$$

$$= \sum_{n=1}^{\infty} \left((\alpha_{n} - 1)\gamma_{n}^{2} + \alpha_{n}\beta_{n}\gamma_{n}(1 - 2\gamma_{n} - \gamma_{n}^{2}L^{2}) \right) \|x_{n} - Tx_{n}\|^{2}$$

$$\leq \sum_{n=1}^{\infty} (\|x_{n} - p\|^{2} - \|x_{n+1} - p\|^{2}) < \infty,$$

from which it follows that

$$\liminf_{n \to \infty} ||x_n - Tx_n|| = 0,$$

and hence there exists a subsequence $\{x_{n_k}\}$ of $\{x_n\}$ such that

$$\lim_{n \to \infty} ||x_{n_k} - Tx_{n_k}|| = 0.$$

Thus, $x_{n_k} \to x^*$ and the continuity of T imply that $x^* = Tx^*$ and hence $x^* \in \mathcal{F}(T)$. \square Now, we prove a convergence theorem for a countable family of monotone mappings.

Theorem 4.3 Let H be a real Hilbert space, let $\{T_n\}_{n=1}^{\infty}: H \to H$ be a countable family of uniformly Lipschitz monotone mappings with Lipschitzian constants L_n , let $L := \sup_{n \geq 1} L_n$. And if $x_n \to x^*$ and $||T_n x_n|| \to 0$, then $x^* \in \bigcap_{n=1}^{\infty} \mathcal{N}(T_n)$. Assume that the interior of $\mathcal{N} := \bigcap_{n=1}^{\infty} \mathcal{N}(T_n)$ is nonempty. Let $\{x_n\}$ be a sequence generated from an arbitrary $x_1 \in C$ by

$$\begin{cases} z_n = x_n - \gamma_n T_n x_n, \\ y_n = x_n - \beta_n (x_n - z_n) - \beta_n T_n z_n, \\ x_{n+1} = (1 - \alpha_n) z_n + \alpha_n y_n, \end{cases}$$
(4.3)

where $\{\alpha_n\}, \{\beta_n\}, \{\gamma_n\} \subset (0,1)$ satisfying the following conditions:

- (i) $\beta_n \leq \gamma_n, \forall n \geq 1$,
- (ii) $(1-\alpha)\gamma + \alpha\beta(\gamma^2L^2 + 2\gamma 1) < 0$,

where $\alpha = \liminf_{n \to \infty} \alpha_n$, $\beta = \liminf_{n \to \infty} \beta_n$ and $\gamma \ge \sup_{n \ge 1} \gamma_n$. Then, $\{x_n\}$ converges strongly to $x^* \in \mathcal{N}$.

Proof. Since T_n is monotone if and only if $A_n := I - T_n$ is pseudo-contractive and $\bigcap_{n=1}^{\infty} \mathcal{F}(A_n) = \bigcap_{n=1}^{\infty} \mathcal{N}(T_n) \neq \emptyset$, then the conclusion follows from Theorem 3.1.

If in Theorem 4.3, we consider a finite family of monotone mappings and a single monotone mapping, respectively, then we get the following corollaries.

Corollary 4.1 Let H be a real Hilbert space, let $\{T_i\}_{i=1}^N: H \to H$ be a finite family of Lipschitz monotone mappings with Lipschitzian constants L_i , for $i=1,2,\cdots,N$, respectively. And if $x_n \to x^*$ and $||T_n x_n|| \to 0$, then $x^* \in \bigcap_{i=1}^N \mathcal{N}(T_i)$. Assume that the interior of $\mathcal{N} := \bigcap_{i=1}^N \mathcal{N}(T_i)$ is nonempty. Let $\{x_n\}$ be a sequence generated from an arbitrary $x_1 \in C$ by

$$\begin{cases}
z_n = x_n - \gamma_n T_n x_n, \\
y_n = x_n - \beta_n (x_n - z_n) - \beta_n T_n z_n, \\
x_{n+1} = (1 - \alpha_n) z_n + \alpha_n y_n,
\end{cases} (4.4)$$

where $T_n := T_{n(mod\ N)}$ and $\{\alpha_n\}, \{\beta_n\}, \{\gamma_n\} \subset (0,1)$ satisfying the following conditions:

- (i) $\beta_n \leq \gamma_n, \forall n \geq 1$,
- (ii) $(1-\alpha)\gamma + \alpha\beta(\gamma^2L^2 + 2\gamma 1) < 0$,

where $\alpha = \liminf_{n \to \infty} \alpha_n$, $\beta = \liminf_{n \to \infty} \beta_n$ and $\gamma \ge \sup_{n \ge 1} \gamma_n$. for $L := \max\{L_i : i = 1, 2, \dots, N\}$. Then, $\{x_n\}$ converges strongly to a common zero point of $\{T_1, T_2, \dots, T_N\}$.

Corollary 4.2 Let H be a real Hilbert space, let $T: H \to H$ be a Lipschitz monotone mapping with Lipschitzian constant L. Assume that the interior of $\mathcal{N}(T)$ is nonempty. Let $\{x_n\}$ be a sequence generated from an arbitrary $x_1 \in C$ by

$$\begin{cases} z_n = x_n - \gamma_n T x_n, \\ y_n = x_n - \beta_n (x_n - z_n) - \beta_n T z_n, \\ x_{n+1} = (1 - \alpha_n) z_n + \alpha_n y_n, \end{cases}$$
(4.5)

where $\{\alpha_n\}, \{\beta_n\}, \{\gamma_n\} \subset (0,1)$ satisfying the following conditions:

- (i) $\beta_n \leq \gamma_n, \forall n \geq 1$,
- (ii) $\sum_{n=1}^{\infty} \gamma_n = \infty$,
- (iii) $(1-\alpha)\gamma + \alpha\beta(\gamma^2L^2 + 2\gamma 1) < 0$,

where $\alpha = \liminf_{n \to \infty} \alpha_n$, $\beta = \liminf_{n \to \infty} \beta_n$ and $\gamma \ge \sup_{n \ge 1} \gamma_n$. Then, $\{x_n\}$ converges strongly to a zero point of T.

Competing interests

The authors declare that they have no competing interests regarding the publication of this article.

Authors' contributions

All authors contributed equally and significantly in writing this article. All authors read and approved the final manuscript.

References

- [1] D. Butnariu, Y. Censor, P. Gurfil, E. Hadar, On the behavior of subgradient projections methods for convex feasibility problem in Euclidean spaces, SIAM J. Optim. 19 (2) (2008) 786-807.
- [2] S. Maruster, C. Popirlan, On the Mann-type iteration and the convex feasibility problem,J. Comput. Appl. Math. 212 (2008) 390-396.
- [3] H.K. Xu, A variable Krasnosel'skii-Mann algorithm and the multiple-set split feasibility problem, Inverse Problems 22 (2006) 2021-2034.
- [4] D. Youla, Mathematical theory of image restoration by the method of convex projections, in: H. Stark (Ed.), Image Recovery Theory and Applications, Academic Press, Orlando, 1987, pp. 29-77.
- [5] O. Scherzer, Convergence criteria of iterative methods based on Landweber iteration for solving nonlinear problems, J. Math. Anal. Appl. 194 (1991) 911-933.
- [6] H. Bauschke, The approximation of fixed points of compositions of nonexpansive mappings in Hilbert spaces, J. Math. Anal. Appl. 202 (1996) 150-159.
- [7] D.P. Wu, S.S. Chang, G.X. Yuan, Approximation of common fixed points for a family of finite nonexpansive mappings in Banach space, Nonlinear Anal. 63 (2005) 987-999.
- [8] B. Halpern, Fixed points of nonexpanding maps, Bull. Amer. Math. Soc. 73 (1967) 957-961.
- [9] N. Shioji, W. Takahashi, Strong convergence of approximated sequences for nonexpansive mappings in Banach spaces, Proc. Amer. Math. Soc. 125 (1997) 3641-3645.
- [10] R. Wittmann, Approximation of fixed points of nonexpansive mappings, Arch. Math. 58 (1992) 486-491.
- [11] K. Aoyama, Y. Kimura, W. Takahashi, M. Toyoda, Approximation of common fixed points of a countable family of nonexpansive mappings in a Banach space, Nonlinear Anal. 67 (2007) 2350-2360.
- [12] S.Y. Matsushita, W. Takahashi, A strong convergence theorem for relatively nonexpansive mappings in a Banach space, J. Approx. Theory 134 (2005) 257-266.
- [13] S.S. Chang, Viscosity approximation methods for a finite family of nonexpansive mappings in Banach spaces, J. Math. Anal. Appl. 323 (2006) 1402-1416.

- [14] H. Zegeye, N. Shahzad, Viscosity approximation methods for a common fixed point of a family of quasi-nonexpansive mappings, Nonlinear Anal. 68 (7) (2008) 2005-2012.
- [15] C.E. Chidume, C.O. Chidume, Iterative approximation of fixed points of nonexpansive mappings, J. Math. Anal. Appl. 318 (2006) 288-295.
- [16] T. Suzuki, Strong convergence of approximated sequences for nonexpansive mappings in Banach spaces, Proc. Amer. Math. Soc. 135 (2007) 99-106.
- [17] W. Takahashi, Y. Takeuchi, R. Kubota, Strong convergence theorems by hybrid methods for families of nonexpansive mappings in Hilbert spaces, J. Math. Anal. Appl. 341 (1) (2008) 276-286.
- [18] W.R. Mann, Mean value methods in iteration, Proc. Amer. Math. Soc. 4 (1953) 506C510.
- [19] S. Reich, Weak convergence theorems for nonexpansive mappings in Banach spaces, J. Math. Anal. Appl. 67 (1979) 274C276.
- [20] C.E. Chidume, On approximation of fixed points of nonexpansive mappings, Houston J. Math. 7 (1981) 345-355.
- [21] W.A. Kirk, Locally nonexpansive mappings in Banach spaces, in: Lecture Notes in Math., vol. 886, Springer, Berlin, 1981, pp. 178-198.
- [22] F.E. Browder, W.V. Petryshyn, Construction of fixed points of nonlinear mappings in Hilbert spaces, J. Math. Anal. Appl. 20 (1967) 197-228.
- [23] G. Marino, H.K. Xu, Weak and strong convergence theorems for strict pseudo-contractions in Hilbert Spaces, J. Math. Anal. Appl. 329 (2007) 336C346.
- [24] S. Ishikawa, Fixed points by a new iteration method, Proc. Amer. Math. Soc. 44 (1) (1974) 147-150.
- [25] C.E. Chidume, S.A. Mutangadura, An example on the Mann iteration method for Lipschitz pseudocontractions, Proc. Amer. Math. Soc. 129 (8) (2001) 2359-2363.
- [26] H. Zhou, Convergence theorems of fixed points for Lipschitz pseudo-contractions in Hilbert spaces, J. Math. Anal. Appl. 343 (2008) 546-556.
- [27] Y.H. Yao, Y.C. Liou, G. Marino, A hybrid algorithm for pseudo-contractive mappings, Nonlinear Anal. 71 (2009) 4997C5002.
- [28] Y.C. Tang, J.G. Peng, L.W. Liu, Strong convergence theorem for pseudo-contractive mappings in Hilbert spaces, Nonlinear Anal. 74 (2011) 380-385.

- [29] H. Zegeye, N. Shahzad, M.A. Alghamdi, Convergence of Ishikawas iteration method for pseudocontractive mappings, Nonlinear Anal. 74 (2011) 7304-7311.
- [30] Q.Q. Cheng, Y.F. Su, J.L. Zhang, Convergence theorems of a three-step iteration method for a countable family of pseudocontractive mappings, Fixed Point Theory and Applications 2013, 2013: 100.
- [31] N. Huang, C. Ma, A new extragradient-like method for solving variational inequality problems, Fixed Point Theory and Applications 2012, 2012: 223.
- [32] Y. Ke, C. Ma, A new relaxed extragradient-like algorithm for approaching common solutions of generalized mixed equilibrium problems, a more general system of variational inequalities and a fixed point problem, Fixed Point Theory and Applications 2013, 2013: 126.
- [33] Y. Ke, C. Ma, The convergence analysis of the projection methods for a system of generalized relaxed cocoercive variational inequalities in Hilbert spaces, Fixed Point Theory and Applications 2013, 2013: 182.

Harmonic analysis in the product of commutative hypercomplex systems

Hossam A. Ghany

Department of mathematics, Helwan University, Sawah street (11282), Cairo, Egypt. Department of mathematics, Taif University, Hawea (888), Taif, KSA. h.abdelghany@yahoo.com

Abstract

The main aim of this paper is to give integral representations for strongly negative definite functions defined on the product hypercomplex systems. Harmonic properties for strongly negative definite functions are investigated. We construct a Lèvy measure on the product hypercomplex systems, then we study the conditions that guarantee the existence of some integrations having an integrand parts as a function of the constructed kernel. Finally, we give a Lèvy - Khinchin type formula for strongly negative definite functions defined on the product hypercomplex systems.

Keywords. Lèvy – Khinchin; Hypercomplex; Negative definite.

2010 Mathematics subject classification. 43A35; 43A65; 43A25.

1. Introduction.

The integral representation of negative definite functions is defined as Lèvy-Khinchin formula. This was established by Lèvy-Khinchin in1930's for $G = \mathbb{R}$. Many author's paid attention to generalize this result in different spaces. It had been extended by Hunt [4] to Lie groups, Parthasarathy et al [8] to locally compact commutative groups, Berg et al [3] to comutative semigroups with identical involution and by Lasser [6] for commutative hypergroups. The main aim of this paper is devoted to find the integral representations for strongly negative definite functions defined on the product dual hypercomplex system. Let Q be a commutative separable locally compact metric space of points p, q, r, ...; B(Q) is the σ -algebra of Borel subsets on Q and $B_0(Q)$ is the subring of B(Q), which consists of sets with compact closure. We denote by C(Q) the space of continuous functions on Q; $C_b(Q)$, $C_\infty(Q)$ and $C_0(Q)$ consists of bounded, tending to zero at infinity and compactly supported functions from C(Q), respectively. For a fixed $r \in Q$, $B \in B(Q)$, we will denote by c(A, B; r) a commutative Borel structure measure in $A \in B(Q)$. The hypercomplex system $L_1(Q, dm)$ is the Banach algebra of functions on Q with respect to the multiplicative measure m and convolution " * " defined for any $\phi * \psi \in L_1(Q, dm)$ by:

$$(\phi * \psi)(r) = \int_{Q} \phi(p) dp \int_{Q} \psi(q) dq \, c(E_p, E_q; r)$$

$$= \int_{Q} \int_{Q} \phi(p) \psi(q) \, c(p, q; r) \, dm(p) dm(q)$$

$$= \int_{Q} \int_{Q} \phi(p) \psi(q) \, dm_r(p, q)$$

The space $C_{\infty}(Q)$ is a Banach space with norm

$$||.||_{\infty} = \sup_{r \in \Omega} |(.)(r)|$$

We will denote by $\mathcal{M}(Q)$, the space of Radon measure on Q, i.e. the space of continuous linear functionals defined on $C_0(Q)$. Let $\mathcal{M}_b(Q) = (C_\infty(Q))'$ denote the space of bounded Radon measures with norm

$$||\mu||_{\infty} = \sup\{|\mu(f)|; f \in C_{\infty}, |f| \le 1\}$$

The topology of simple convergence on functions from in the space of Radon measures, is called vague topology.

2. Strongly Negative Definite Functions.

A hypercomplex system $L_1(Q, dm)$ may or may not have a unity. In this paper we will concern our efforts on hypercomplex system with unity. A normal hypercomplex system contain a basis unity if there exists $e \in Q$ such that $e^* = e$ and

$$c(A, B; e) = m(A^* \cap B), \quad A, B \in B(Q).$$

A nonzero measurable and bounded almost everywhere function $Q \ni r \to \chi(r) \in \mathbb{C}$ is said to be a character of the hypercomplex system $L_1(Q, dm)$ if for all $A, B \in B_0(Q)$ we have

$$\int_{O} c(A, B; r) \chi(r) dm(r) = \chi(A) \chi(B)$$

and

$$\int_C \chi(r) \, dm(r) = \chi(C), \ C \in B_0(Q).$$

We will denote by X_h the set of all bounded Hermitian characters, i.e.

$$X_h := \{ \chi \in C_b(Q); \int\limits_Q c(A, B; r) \chi(r) dm(r) = \chi(A) \chi(B), \ \overline{\chi(r)} = \chi(r^*) \}$$

A continuous bounded function $\psi: Q \to \mathbb{C}$ is called negative definite if for any $r_1, r_2, ..., r_n \in Q$; $c_1, c_2, ..., c_n \in \mathbb{C}$ and $n \in \mathbb{N}$ we have:

$$\sum_{i,j=1}^{n} [\psi(r_i) + \overline{\psi(r_j)} - (R_{r_i} \psi)(r_i)] c_i \overline{c_j} \ge 0,$$

and a continuous bounded function $\varphi: Q \to \mathbb{C}$ is called positive definite if for any $r_1, r_2, ..., r_n \in Q$; $c_1, c_2, ..., c_n \in \mathbb{C}$ and $n \in \mathbb{N}$ we have:

$$\sum_{i,j=1}^n (R_{r^*_i}\varphi)(r_i)\,c_i\overline{c_j}\geq 0,$$

where R_r ($r \in Q$), denote the generalized translation operators on $L_1(Q, dm)$.

As pointed out of [1], every positive definite function $\varphi \in P(Q)$ admits a unique representation in the integral form

(2.1)
$$\varphi(r) = \hat{\mu}(\chi) = \int_{X_h} \chi(r) d\mu(\chi), \quad \chi \in X_h,$$

where μ is a finite nonnegative regular measure on the space X_h . Conversely, each function have the integral form (1.1) belongs to the set of all positive definite function P(Q).

Let Q_1 and Q_2 be two commutative separable locally compact metric spaces, with identities e_1 and e_2 respectively, and suppose A be a non empty subset of $L_1(Q_1) \times L_1(Q_2)$, then the strongly positive definite function will be defined as follows:

Definition 2.1. A locally bounded continuous measurable function $\Phi \in A$ is called strongly positive definite, if there exists two positive definite functions $\varphi_1 \in P(Q_1)$ and $\varphi_2 \in P(Q_2)$ and a Radon measure $\mu \in \mathcal{M}_+(Q_1 \times Q_2)$, such that

(2.2)
$$\hat{\mu}(\chi,\tau) = \begin{cases} \varphi_1(\chi) + \varphi_2(\tau), & (\chi,\tau) \in A \\ 0, & (\chi,\tau) \notin A \end{cases}.$$

A locally bounded continuous measurable function $\Psi \in A$ is called strongly negative definite, if $\Psi(e_1, e_2) \ge 0$ and $\exp(-t\Psi)$ is strongly positive definite in A for each t > 0.

Clearly each strongly positive (negative) definite function is positive (negative) definite but the converse implication does not hold. Negative definiteness is an analogue of one half of Schoenberg's duality result, It is not known for which hypercomplex system, negative definiteness implies strong negative definiteness. The following Lemma is in fact, an adaption of

whatever done for hypergroups [7], we will not repeat the proof, wherever the proof for hypergroups can be applied to the hypercomplex with necessary modification.

Lemma 2.2. The sum and the point-wise limit of strongly negative definite functions on hypercomplex are also strongly negative definite.

Theorem 2.3. A function $\Psi: Q \to \mathbb{C}$ is strongly negative definite if and only if the following conditions are satisfied:

- $\frac{\Psi(e_1, e_2) \ge 0}{\Psi(\mathbf{r})} = \Psi(\mathbf{r}^*)$ for each $\mathbf{r} \in Q_1 \times Q_2$;
- (iii) if for any $r_1, r_2, ..., r_n \in Q_1 \times Q_2$ and $c_1, c_2, ..., c_n \in \mathbb{C}$ with $\sum_{i=1}^n c_i = 0$ and $r_i = (r_1^i, r_1^i) \in Q_1 \times Q_2$, we have

$$\sum_{i,j=1}^{n} (R_{\boldsymbol{r}^*_{i}} \Psi)(\boldsymbol{r}_{i}) c_{i} \overline{c_{j}} \leq 0.$$

Proof. Suppose that the function Ψ is strongly negative definite. From the above definition of strongly negative definite functions, it is clear that Ψ satisfies (i) and (ii). Let $r_1, r_2, ..., r_n \in$ $Q_1 \times Q_2$ and $c_1, c_2, \dots, c_n \in \mathbb{C}$ with $\sum_{i=1}^n c_i = 0$. Since, every strongly negative definite function is negative definite, so

$$0 \leq \sum_{i,j=1}^{n} [\Psi(\boldsymbol{r}_{i}) + \overline{\Psi(\boldsymbol{r}_{j})} - (R_{\boldsymbol{r}_{j}} \Psi)(\boldsymbol{r}_{i})] c_{i} \overline{c_{j}}$$

$$= \overline{(\sum_{j=1}^{n} c_{j})} \sum_{i=1}^{n} [\Psi(\boldsymbol{r}_{i})] c_{i} + (\sum_{i=1}^{n} c_{i}) \overline{\sum_{j=1}^{n} [\Psi(\boldsymbol{r}_{j})]}$$

$$- \sum_{i,j=1}^{n} [(R_{\boldsymbol{r}_{j}} \Psi)(\boldsymbol{r}_{i})] c_{i} \overline{c_{j}}$$

$$= - \sum_{i,j=1}^{n} [(R_{\boldsymbol{r}_{j}} \Psi)(\boldsymbol{r}_{i})] c_{i} \overline{c_{j}}$$

Conversely, suppose that Ψ satisfies the above conditions. Let $e, r_1, r_2, ..., r_n \in Q_1 \times Q_1$ Q_2 and $c_1, c_2, ..., c_n \in \mathbb{C}$ with $\sum_{i=1}^n c_i = 0$. From (iii) we have

$$0 \geq \sum_{i,j=0}^{n} \left[(R_{\boldsymbol{r}^{*}_{j}} \Psi)(\boldsymbol{r}_{i}) \right] c_{i} \overline{c_{j}}$$

$$= \sum_{i,j=1}^{n} \left[(R_{\boldsymbol{r}^{*}_{j}} \Psi)(\boldsymbol{r}_{i}) \right] c_{i} \overline{c_{j}} + \overline{c_{0}} \sum_{i=1}^{n} \left[\Psi(\boldsymbol{r}_{i}) \right] c_{i} + c_{0} \sum_{j=1}^{n} \left[\Psi(\boldsymbol{r}_{j}) \right] c_{j} + \Psi(\boldsymbol{e}) |c_{0}|^{2}$$

$$= \sum_{i,j=1}^{n} \left[\Psi(\boldsymbol{r}_{i}) + \overline{\Psi(\boldsymbol{r}_{j})} - (R_{\boldsymbol{r}^{*}_{j}} \Psi)(\boldsymbol{r}_{i}) \right] c_{i} \overline{c_{j}} + \Psi(\boldsymbol{e}) |c_{0}|^{2}$$

This implies

$$\sum_{i,j=1}^{n} \left[\Psi(\boldsymbol{r}_{i}) + \overline{\Psi(\boldsymbol{r}_{j})} - (R_{\boldsymbol{r}_{j}^{*}} \Psi)(\boldsymbol{r}_{i}) \right] c_{i} \overline{c}_{j} \geq \Psi(\boldsymbol{e}) |c_{0}|^{2} \geq 0$$

Corollary 2.4. For any functions Φ , Ψ on the product $Q_1 \times Q_2$ we have:

- (i) If Ψ belongs to the set of strongly negative definite function on $Q_1 \times Q_2$, then the function $\mathbf{r} \to \Psi(\mathbf{r}) \Psi(e_1, e_2)$ is also strongly negative definite function.
- (ii) If Φ belongs to the set of strongly positive definite function on $Q_1 \times Q_2$, then the function $r \to \Phi(r) \Phi(e_1, e_2)$ is also strongly positive definite function.

Proof. Let $r_1, r_2, ..., r_n \in Q_1 \times Q_2$ and $c_1, c_2, ..., c_n \in \mathbb{C}$ with $\sum_{i=1}^n c_i = 0$. Then we have

$$\sum_{i,j=0}^{n} [R_{r_{j}^{*}}(\Psi(r_{i}) - \Psi(e_{1}, e_{2}))] c_{i}\overline{c_{j}} = \sum_{i,j=0}^{n} (R_{r_{j}^{*}}\Psi)(r_{i})c_{i}\overline{c_{j}} - \Psi(e_{1}, e_{2}) | \sum_{i=1}^{n} c_{i} |^{2}$$

$$= \sum_{i,j=0}^{n} (R_{r_{j}^{*}}\Psi)(r_{i})c_{i}\overline{c_{j}} \leq 0$$

This proves the strongly negative definiteness of $\Psi(r) - \Psi(e_1, e_2)$. Similarly, let $r_1, r_2, ..., r_n \in Q_1 \times Q_2$ and $c_1, c_2, ..., c_n \in \mathbb{C}$ with $\sum_{i=1}^n c_i = 0$. Then we find

$$\sum_{i,j=0}^{n} [R_{r_{j}^{*}}(\Phi(e_{1}, e_{2}) - \Phi(r_{i}))] c_{i}\overline{c_{j}} = -\sum_{i,j=0}^{n} (R_{r_{j}^{*}}\Phi)(r_{i})c_{i}\overline{c_{j}} - \Phi(e_{1}, e_{2}) | \sum_{i=1}^{n} c_{i} |^{2}$$

$$= -\sum_{i,j=0}^{n} (R_{r_{j}^{*}}\Phi)(r_{i})c_{i}\overline{c_{j}} \leq 0$$

Because Φ belongs to the set of strongly positive definite functions, hence (ii).

Theorem 2.5. For every strongly negative definite function Ψ on the product $Q_1 \times Q_2$ with $\Psi(e_1, e_2) \geq 0$, the function $\frac{1}{\Psi}$ is strongly positive definite function on the product $Q_1 \times Q_2$.

Proof. Suppose Ψ strongly negative definite function on the product $Q_1 \times Q_2$, so $\exp(-t\Psi)$ is strongly positive definite on the product $Q_1 \times Q_2$. This implies

$$|\exp(-t\Psi)| \le |\exp(-t\Psi(e_1, e_2))|$$
 for all $t > 0$.

It follows, for all $(\chi, \tau) \in \widehat{Q_1 \times Q_2}$ we have

$$\frac{1}{\Psi(\chi,\tau)} = \int_{0}^{\infty} \exp(-t\Psi(\chi,\tau)) dt = \int_{0}^{\infty} \widehat{\mu_{t}}(\chi,\tau) dt$$

Where μ_t is the corresponding measure for $\exp(-t\Psi)$. Moreover, applying Lèvy continuity Theorem, there exists a measure $v \in \mathcal{M}_+(Q_1 \times Q_2)$ such that

$$\upsilon(\chi,\tau) \coloneqq \widehat{\upsilon}(\chi,\tau) = \int_{0}^{\infty} \widehat{\mu_{t}}(\chi,\tau)dt$$

and

$$\upsilon(e_1, e_2) = \frac{1}{\Psi(e_1, e_2)} < \infty$$

Consequently, $v \in \mathcal{M}_+^b(Q_1 \times Q_2)$. This implies the required to prove.

3. Construction of Lèvy measure.

Let $L_1(Q_1 \times Q_2)$ denote a commutative normal hypercomplex system with the product basis $Q_1 \times Q_2$ and basis unity $\mathbf{e} = (e_1, e_2)$. A family of bounded Radon measures $(\mu_t)_{t>0}$ will be called a convolution semigroup on $Q_1 \times Q_2$ if it satisfies the following items:

- (i) $\mu_t(Q_1 \times Q_2) \le 1$, for each t > 0;
- (ii) $\mu_{t_1} * \mu_{t_2} = \mu_{t_1+t_2}$ for each $t_1, t_2 > 0$;
- (iii) $\lim_{t\to 0} \mu_t = \epsilon_e$, with respect to the vague topology on $\mu \in \mathcal{M}^b(Q_1 \times Q_2)$.

Theorem 3.1. For any strongly negative definite function Ψ on $Q_1 \times Q_2$, there exists a unique convolution semigroup on $Q_1 \times Q_2$ such that Ψ is associated to $(\mu_t)_{t>0}$.

Proof. Firstly, we will prove that, for $(\chi, \tau) \in \widehat{Q_1 \times Q_2}$, the function $t \to \widehat{\mu}_t(\chi, \tau)$ is continuous. As pointed out of Ursohn's lemma [9], there exists $f \in C_c(Q_1 \times Q_2)$ that satisfies f(e) = 1 and $0 \le f < 1$. Applying the above conditions for the convolution semigroup on $Q_1 \times Q_2$, we have:

$$1 = f(\boldsymbol{e}) = \lim_{t \to 0} <\mu_t, f > \leq \liminf_{t \to 0} \mu_t(Q_1 \times Q_2) \leq \limsup_{t \to 0} \mu_t(Q_1 \times Q_2) \leq 1$$

and this shows that

$$\lim_{t\to 0} \mu_t = \epsilon_e \qquad \text{(in the Bernolli topology)}.$$

As pointed out of [2], for each t_1 , $t_2 > 0$, we have

$$|\hat{\mu}_t(\chi,\tau) - \hat{\mu}_{t_0}(\chi,\tau)| \leq |\hat{\mu}_{|t-t_0|}(\chi,\tau) - 1|$$

the right hand side tends to zero uniformally on compact subset of $\widehat{Q_1 \times Q_2}$, so

$$\lim_{t\to 0} \mu_t = \mu_{t_0} \qquad \text{(in the Bernolli topology)}.$$

Secondly, from the definition of strongly negative definite function, there exists a unique determined measures $\mu_t \in \mathcal{M}^b(Q_1 \times Q_2)$, t > 0, such that $\hat{\mu}_t(\chi) = \exp(-t\Psi)$ It is clear that,

the family $(\mu_t)_{t>0}$ satisfies conditions (i) and (ii). The boundedness of the function Ψ on compact subsets of $Q_1 \times Q_2$ implies that

$$\lim_{t\to 0} \hat{\mu}_t(\chi) = \lim_{t\to 0} \exp(-t\Psi) = 1.$$

From [5], there exists a multiplicative measure \widehat{m} on the dual $\widehat{Q_1 \times Q_2}$, such that for every $f \in C_0(Q_1 \times Q_2)$ and $\varepsilon > 0$, there exist $g \in C_0(\widehat{Q_1 \times Q_2})$ such that $\widehat{Q_1 \times Q_2} ||f - \widetilde{g}|| < \varepsilon$ and

$$|\mu_t(f) - \varepsilon_e(f)| \le 2\varepsilon + \int_{Q_1 \times Q_2} |g(\chi, \tau)| |\hat{\mu}_t(\chi, \tau) - 1| d\hat{m}(\chi, \tau)$$

this implies (iii).

Let S denote the set of probability and symmetric measures on $Q_1 \times Q_2$ with compact support, i.e.

$$S = \{\sigma; \ \sigma \in \mathcal{M}^1(Q_1 \times Q_2) \cap \mathcal{M}^c(Q_1 \times Q_2), \sigma(\chi, \tau) = \widetilde{\sigma}(\chi, \tau)\}$$

Let $(\mu_t)_{t>0}$ be a convolution semigroup on $Q_1 \times Q_2$ and $\Psi: Q_1 \times Q_2 \to \mathbb{C}$ the strongly negative definite function associated to $(\mu_t)_{t>0}$. Applying the same technique of [2] for the hypercomplex system instead of semigroups, we can see that, the net $(\frac{1}{t}\mu_t|Q_1\times Q_2\setminus \{\boldsymbol{e}\})_{t>0}$ of positive measures on $Q_1\times Q_2\setminus \{\boldsymbol{e}\}$ converges vaguely as $t\to 0$ to a measure μ on $Q_1\times Q_2\setminus \{\boldsymbol{e}\}$, and for every $\sigma\in S$, the function $\Psi*\sigma-\Psi$ is continuous strongly positive definite on $Q_1\times Q_2$ and the positive bounded measure μ_σ on $Q_1\times Q_2$ whose Fourier transform is $\Psi*\sigma-\Psi$ satisfies

$$(3.1) (1 - \widetilde{\sigma})\mu = \mu_{\sigma}|Q_1 \times Q_2 \setminus \{e\}.$$

The positive measure μ on $Q_1 \times Q_2 \setminus \{e\}$ defined by (3.1) is called the strong Lèvy measure for the convolution semigroup $(\mu_t)_{t>0}$ on $Q_1 \times Q_2$.

Theorem 3.2. Let μ denote the Lèvy measure for the convolution semigroup $(\mu_t)_{t>0}$ on $Q_1 \times Q_2$. Then

$$(3.2) \qquad \qquad \int_{Q_1 \times Q_2 \setminus \{e\}} (1 - \operatorname{Re}(\chi, \tau)(r)) d\,\mu(\chi, \tau) < \infty, \ (\chi, \tau) \in \widehat{Q_1 \times Q_2}.$$

Proof. For $(\chi, \tau) \in \widehat{Q_1 \times Q_2}$, let $\sigma = \frac{1}{2} (\epsilon_{(\chi, \tau)} + \epsilon_{\overline{(\chi, \tau)}}) \in S$; then $\widetilde{\sigma} = Re(\chi, \tau)(r)$, substituting in (3.2) we get

$$\int\limits_{Q_1\times Q_2\setminus \{\boldsymbol{e}\}} (1-R\boldsymbol{e}(\chi,\tau)(r))d\,\mu(\chi,\tau) = \int\limits_{Q_1\times Q_2\setminus \{\boldsymbol{e}\}} (1-\widetilde{\sigma}(r))d\,\mu(\chi,\tau) = \mu_{\sigma}|Q_1\times Q_2\setminus \{\boldsymbol{e}\} < \infty.$$

4. Integral representation theorem.

A continuous function $h: Q_1 \times Q_2 \to \mathbb{R}$ is called homomorphism if it satisfies $h(r^*) = -h(r)$ and $R_r h(s) = h(r) + h(s)$, $r, s \in Q_1 \times Q_2$. Clearly, if $h: Q_1 \times Q_2 \to \mathbb{R}$ is a homomorphism, then the function $\Psi = ih$ is strongly negative definite. A continuous function $q: Q_1 \times Q_2 \to \mathbb{R}$ is called a quadratic form, if it satisfies

(4.1)
$$R_{rq}(s) + R_{r*}q(s) = 2q(r) + 2q(s), r, s \in Q_1 \times Q_2.$$

Theorem 4.1. Let Ψ be a strongly negative definite function associated the convolution semigroup $(\mu_t)_{t>0}$ on $Q_1 \times Q_2$. If the Lèvy measure μ of $(\mu_t)_{t>0}$ is symmetric, then $Im\Psi$ is a homomorphism.

Proof. As remarked in [2], a continuous function $f: Q_1 \times \widehat{Q_2} \to \mathbb{R}$ which satisfies $f(e_1, e_2) = 0$ is a homomorphism if and only if f * v - f = 0 for all $v \in S$. Since, $\check{\mu} = \mu$ is equivalent to $\check{\mu}_{\sigma} = \mu_{\sigma}$ for each $\sigma \in S$. So, $Im\Psi * v - Im\Psi = 0$ for each $\sigma \in S$, hence, then $Im\Psi$ is a homomorphism. In particular, we have $i \ Im\Psi$ is strongly negative definite.

Lemma 4.2. For every positive definite symmetric measure μ on the product $Q_1 \times Q_2 \setminus \{e\}$ such that

$$(4.2) \qquad \int_{Q_1 \times Q_2 \setminus \{e\}} (1 - \operatorname{Re}(\chi, \tau)(r)) d\mu(r) < \infty, \ (\chi, \tau) \in \widehat{Q_1 \times Q_2}.$$

The function $\Psi_{\mu}: \widehat{Q_1} \times Q_2 \to \mathbb{C}$ defined by

$$\Psi_{\mu} := \int_{Q_1 \times Q_2 \setminus \{e\}} (1 - \operatorname{Re}(\chi, \tau)(r)) d\mu(r) < \infty, \ (\chi, \tau) \in \widehat{Q_1 \times Q_2},$$

is strongly negative definite function.

Proof. To prove the function Ψ_{μ} is strongly negative definite, we will sufficiently prove that the measure μ is strong Lèvy measure for Ψ_{μ} . For $f \in C_c^+(Q_1 \times Q_2)$ such that $f(\bar{\chi}) = f(\chi)$ and $\int f(\chi) dx = 1$, Applying Fubini's Theorem we get

$$(4.4) \qquad (\Psi_{\mu} * f)(\chi) = \int_{Q_{1} \times Q_{2}} (R_{\rho} f)(\chi) \Psi_{\mu}(\rho) d\rho$$

$$= \int_{Q_{1} \times Q_{2}} f(\rho) \int_{Q_{1} \times Q_{2} \setminus \{(e_{1}, e_{2})\}} [1 - Re\chi(r)\rho(r)] d\mu(r)$$

$$= \int_{Q_{1} \times Q_{2} \setminus \{e\}} [1 - Re\chi(r)\tilde{f}(r)] d\mu(r)$$

Specially, for $\chi = 1$, we have

$$\int_{Q_1 \times Q_2 \setminus \{e\}} \left[1 - \tilde{f}(r) \right] d\mu(r) = \int f(\rho) \, \Psi_{\mu}(\rho) d\rho$$

Clearly, $dv(r) = [1 - \tilde{f}(r)]d\mu(r)$ is positive definite measure on $Q_1 \times Q_2 \setminus \{e\}$, so can be considered as positive definite measure on $Q_1 \times Q_2$. This implies

$$\hat{v}(\chi) = Re\hat{v}(\chi) = \int_{O_1 \times O_2 \setminus \{e\}} Re\chi(r) [1 - \tilde{f}(r)] d\mu(r)$$
 for $\chi \in \widehat{Q_1 \times Q_2}$.

Putting $f = \sigma$ in (4.4) implies that

$$\Psi_{\mu} * \sigma(\chi) - \Psi_{\mu}(\chi) = \int_{Q_1 \times Q_2 \setminus \{e\}} Re\chi(r) [1 - \tilde{\sigma}(r)] d \mu(r)$$

So, $\Psi_{\mu} * \sigma - \Psi_{\mu}$ is the Fourier transform of the measure $[1 - \tilde{\sigma}(r)] | \mu$, this implies μ is the Lèvy measure of Ψ_{μ} .

Theorem 4.3.(*Main Result*) Let $\Psi: Q_1 \times Q_2 \to \mathbb{C}$ be a strongly negative definite function associated the convolution semigroup $(\mu_t)_{t>0}$ with a symmetric positive Lèvy measure μ such that

$$\int\limits_{Q_1\times Q_2\setminus \{e\}} (1-Re(\chi,\tau)(r))d\,\mu(r)<\infty,\ (\chi,\tau)\in\widehat{Q_1\times Q_2},$$

Then Ψ admits the integral representation

$$\Psi(\chi,\tau) = \Psi(e) + iIm\Psi + q(\chi,\tau)$$

$$+ \int\limits_{Q_1 \times Q_2 \setminus \{e\}} (1 - \operatorname{Re}(\chi, \tau)(r)) d \, \mu(r) < \infty, \ (\chi, \tau) \in \widehat{Q_1 \times Q_2},$$

where

$$q(\chi,\tau) = \lim_{n \to \infty} \left[\frac{(R_{(\chi,\tau)}^n \Psi)(\chi,\tau)}{4n^2} + \frac{(R_{(\chi,\tau)}^n \Psi)(\chi,\tau)}{2n} \right].$$

Proof. Regarding Theorem 4.1, the symmetries of the measure μ implies $h = Im\Psi$ is a homomorphism and ih belongs to the space of strongly negative definite functions on $Q_1 \times Q_2$. Hence, the function $\Psi - CI$ belongs to the space of strongly negative definite functions on $Q_1 \times Q_2$ associated Lèvy measure μ , where $C = \Psi(e)$. This implies the function $\Psi^{\#} = \Psi - CI - ih$ belongs to the space of strongly negative definite functions on $Q_1 \times Q_2$ associated Lèvy measure μ . By virtue of the argument of Theorem 3.2, the integral

$$\Psi_{\mu} \coloneqq \int_{Q_1 \times Q_2 \setminus \{e\}} (1 - Re(\chi, \tau)(r)) d \mu(r)$$

is finite for all $(\chi, \tau) \in \widehat{Q_1 \times Q_2}$. Observing Lemma 4.2, we get that, the function $q = \Psi^{\#} - \Psi_{\mu}$ is a real valued symmetric function with q(e) = 0. As remarked in [3], for $\sigma \in S$ we have

$$\Psi^{\#} * \sigma - \Psi^{\#} = \Psi * \sigma - \Psi$$

and

(4.5)
$$\Psi_{\mu} * \sigma - \Psi_{\mu} = \int_{Q_1 \times Q_2 \setminus \{e\}} Re\chi(r) [1 - \tilde{\sigma}(r)] d\mu(r)$$

Applying (3.1) and (4.5), we get

(4.6)
$$q * \sigma - q = (\Psi^{\#} - \Psi_{\mu}) * \sigma - (\Psi^{\#} - \Psi_{\mu}) = \hat{\mu}_{\sigma}(\{e\}) \ge 0$$

As pointed in [2], (4.6) implies that the function q is a nonnegative quadratic form on $\widehat{Q_1 \times Q_2}$. Recalling the integral

$$\Psi_{\mu} \coloneqq \int_{Q_1 \times Q_2 \setminus \{e\}} (1 - Re(\chi, \tau)(\mathbf{r})) d\mu(\mathbf{r})$$

By Lemma 4.2 the function Ψ_{μ} is strongly negative definite. Since every quadratic form satisfies the following relation[2]

$$\lim_{n\to\infty} \left[\frac{(R_{(\chi,\tau)}^n q)(\chi,\tau)}{4n^2} \right] = q(\chi,\tau) - \frac{1}{2} (R_{\overline{(\chi,\tau)}} q)(\chi,\tau)$$

So

$$(4.7) q(\chi,\tau) - \frac{1}{2} (R_{\overline{(\chi,\tau)}} q)(\chi,\tau)$$

$$= \lim_{n \to \infty} \left[\frac{(R_{(\chi,\tau)}^n \Psi)(\chi,\tau)}{4n^2} \right] - \lim_{n \to \infty} \left[\frac{(R_{(\chi,\tau)}^n \Psi_{\mu})(\chi,\tau)}{4n^2} \right]$$

$$= \lim_{n \to \infty} \left[\frac{(R_{(\chi,\tau)}^n \Psi)(\chi,\tau)}{4n^2} \right] - \lim_{n \to \infty} \frac{1}{4n^2} \int_{Q_1 \times Q_2 \setminus \{e\}} (1 - Re((\chi,\tau)(r))^{2n}) d\mu(r)$$

Since the product $Q_1 \times Q_2$ is locally compact, then for every compact K of $Q_1 \times Q_2$, there exists a constant $M_K \ge 0$, a nieghbourhood N_K of \mathbf{e} and a finite subset S_K of K such that for every element $r \in N_K$ we have

$$\sup_{\mathbf{r}} \{1 - Re(\chi, \tau)(\mathbf{r}); \ (\chi, \tau) \in K\} \le M_K \sup_{\mathbf{r}} \{1 - Re(\chi, \tau)(\mathbf{r}); \ (\chi, \tau) \in S_K\}.$$

If $(\chi, \tau)(r) \neq 0$, let $(\chi, \tau)(r) = \rho \exp(i\vartheta)$ for some $0 < \rho \le 1$ and $-\pi \le \vartheta \le \pi$. Then for

 $n \in \mathbb{N}$ the ratio $\frac{\sin(n\theta)}{n\theta}$ is bounded a way from $Q_1 \times Q_2$ on $[\frac{\pi}{2}, \pi]$, this implies the existence of a positive constant $C \ge 0$ such that

$$\frac{1}{4n^2}(1-\cos(2n\theta)) = \frac{1}{2} \left[\frac{\sin(n\theta)}{n\theta} \right]^2 \left[\frac{\theta}{\sin(n\theta)} \right]^2 \left[\frac{1-\cos(2\theta)}{2} \right]$$

$$\leq C(1-\cos(2\theta))$$

Also, we have

$$\frac{1 - \rho^{2n}}{4n^2} \le \frac{1 - \rho}{2n} \le \frac{1 - \rho^2}{2}$$

These gives

$$\frac{1}{4n^2} \Big(1 - Re \Big((\chi, \tau)(r) \Big)^{2n} \Big) = \frac{1}{4n^2} (1 - \rho^{2n}) + \frac{\rho^{2n}}{4n^2} (1 - \cos(2n\theta))$$

$$\leq \frac{1 - \rho^2}{2} + C\rho^{2n} (1 - \cos(2\theta))$$

$$\leq \frac{1 - \rho^2}{2} + C\rho^2 (1 - \cos(2\theta))$$

$$\leq \frac{1 - \rho^2}{2} + C(1 - Re((\chi, \tau)(r))^2)$$

Applying the dominated convergence theorem gives

$$\frac{1}{4n^2} \int\limits_{Q_1 \times Q_2 \setminus \{e\}} (1 - Re((\chi, \tau)(\boldsymbol{r}))^{2n}) d\,\mu(\boldsymbol{r}) = 0$$

Substituting in (4.7) gives

(4.8)
$$q(\chi,\tau) = \frac{1}{2} \left(R_{\overline{(\chi,\tau)}} q \right) (\chi,\tau) + \lim_{n \to \infty} \left[\frac{(R_{(\chi,\tau)}^n \Psi)(\chi,\tau)}{4n^2} \right]$$

Observing that

$$(R_{\overline{(\chi,\tau)}}q)(\chi,\tau) = \lim_{n\to\infty} \left[\frac{(R_{\overline{(\chi,\tau)}}^nq)(\chi,\tau)}{2n}\right]$$

$$= \lim_{n\to\infty} \left[\frac{(R_{(\chi,\tau)}^n \Psi)(\chi,\tau)}{2n} \right] - \lim_{n\to\infty} \frac{1}{2n} \int_{Q_1 \times Q_2 \setminus \{e\}} (1 - |(\chi,\tau)(r)|^{2n}) d\mu(r)$$

But

$$\frac{1}{2n}(1-|(\chi,\tau)(r)|^{2n}) \le 1-|(\chi,\tau)(r)|^2$$

Applying the dominated convergence theorem again gives

$$\lim_{n\to\infty}\frac{1}{2n}\int_{Q_1\times Q_2\setminus \{\boldsymbol{e}\}}(1-|(\chi,\tau)(\boldsymbol{r})|^{2n})d\,\mu(\boldsymbol{r})=0$$

and so

$$(R_{\overline{(\chi,\tau)}}q)(\chi,\tau) = \lim_{n \to \infty} \left[\frac{(R_{\overline{(\chi,\tau)}}^n \Psi)(\chi,\tau)}{2n} \right]$$

This complete the proof of the Theorem.

5. Conclusion

In this paper integral representations for strongly negative definite functions defined on the product hypercomplex systems is given. Harmonic properties for strongly negative definite functions are investigated. We construct a Lèvy measure on the product hypercomplex systems, then we study the conditions that guarantee the existence of some integrations having an integrand parts as a function of the constructed kernel. Finally, we give a Lèvy - Khinchin type formula for strongly negative definite functions defined on the product hypercomplex systems.

6. Competing Interests

"The authors declare that they have no competing interests."

7. Acknowledgements

I greatly thanks Prof. Dr. Ahmed Zable for his valuable discussion throughout the preparing of this paper.

References

[1] Ju. M. Berezanskii and A. A. Kalyuhnyi, *Harmonic analysis in hypercomplex systems*, Kive, Naukova Dumka, (1992).

- [2] C. Berg and G. Forst, *Potential theory on locally compact abelian groups*, Springer-Verlag, Berlin-Heidelberg-New York (1975).
- [3] C. Berg, J.P.R. Christensen and P. Ressel, *Harmonic analysis on semigroups. Theory of positive definite and related functions*, Graduated texts in Math., 100, Springer-Verlag, Berlin-Heidelberg-New-York (1984).
- [4] G. A. Hunt, Semigroups of measures on Lie groups, Trans. Amer. Math. Soc, 81(1956), 264-293.
- [5] R.I. Jewett, *Spaces with an abstract convolution of measures*, Adv. in Math., 18 (1975), 1-101.
- [6] R. Lasser, On the Lèvy Hincin formula for commutative hypergroups, Lecture notes in Math, 1064(1984), 298-308.
- [7] A. S. Okb El Bab and H. A. Ghany, *Harmonic analysis on hypergroups*, American Institute of Physics Conf. Proc. 1309(2010), 312.
- [8] K.R. Parthasarathy, *Probability measures on metric spaces*, Academic Press, New York-London, (1967).
- [9] W. Rudin, Real and complex analysis, McGraw-Hill Book Co, New York, (1974).

Nonlinear delay fractional difference equations with applications on discrete fractional Lotka-Volterra competition model

J. Alzabut a , T. Abdeljawad a , D. Baleanu b,c1

^aDepartment of Mathematics and Physical Sciences, Prince Sultan University
 P. O. Box 66833, 11586 Riyadh, Saudi Arabia
 ^bDepartment of Mathematics, Çankaya University
 06530 Ankara, Turkey

^cInstitute of Space Sciences, Magurele–Bucharest, Romania

Abstract. The existence and uniqueness of solutions for nonlinear delay fractional difference equations are investigated in this paper. We prove the main results by employing the theorems of Krasnoselskii's Fixed Point and Arzela–Ascoli. As an application of the main theorem, we provide an existence result on the discrete fractional Lotka–Volterra model.

Keywords. Existence and uniqueness; Fractional difference equations; Krasnoselskii Fixed Point Theorem; Arzela-Ascoli's Theorem; Discrete fractional Lotka-Volterra model.

AMS subject classification: 34A08, 34A12, 39A12.

1 Introduction

Fractional differential equations have received a special attention during the last decades since it has been found that these type of equations provide an excellent instruments for the description of memory and hereditary properties of various materials and processes [1, 2, 3]. The problem of the existence of solutions for fractional differential equations, in particular, has been considered in several recent papers; (see Refs. [4, 5, 6, 7, 8] and the references therein).

For the development of the theory of fractional difference equations, which is the discrete counterpart of fractional differential equations, still there exists less interest among researchers. In fact the progress of the theory of fractional difference equations is still in its early stages. Indeed, some mathematicians have recently taken the lead to develop the qualitative properties of fractional difference equations. We name here for instance Atici et. al. [9, 10, 11, 12, 13] who developed the transform methods, properties of initial value problems and studied applications of these equations on the tumor growth, Abdeljawad et. al. [14, 15, 16, 17, 18] who investigated the properties of Riemann and Caputo's fractional sum and difference operators, Anastassiou [19, 20] who defined a Caputo like discrete fractional difference and studied some discrete fractional inequalities, Goodrich [21, 22, 23] who established sufficient conditions for the existence of solutions for initial and boundary value problems of discrete fractional equations and Chen et. al. [24, 25, 26] who studied the stability of certain fractional difference equations. In [27, 28], Wu and Baleanu provided some applied results concerning with certain real life problems described by discrete fractional equations. For further details on these achievements, we recommend the reader to consult the new publications [29, 30].

 $^{^1\}mathrm{Corresponding}$ Author E-Mail Address: dumitru@cankaya.edu.tr

Obviously, the existence and uniqueness of solutions are essentially significant concept for differential equations. To the best of authors' knowledge, there are no results concerning with the existence and uniqueness of solutions for nonlinear delay fractional difference equations. The objective of this paper is to cover this gap and study the existence and uniqueness problem for equations of the form

$$\begin{cases} {}^{c}\nabla_{0}^{\alpha}x(t) = f(t, x(t), x(t-\tau)), \ t \in \mathbb{N}_{0} = \{0, 1, 2, \dots\}, \ \tau \ge 0, \\ x(t) = \phi(t), \ t \in [-\tau, -\tau + 1, \dots, 0], \end{cases}$$
(1)

where $f: \mathbb{N}_0 \times \mathbb{R} \times \mathbb{R} \to \mathbb{R}$ and ${}^c\nabla_0^{\alpha}$ denotes the Caputo's fractional difference of order $\alpha \in (0,1)$. To prove our main results, we employ the Krasnoselskii Fixed Point Theorem and the Arzela-Ascoli's Theorem. As an application of the main theorem, we provide an existence result on the discrete fractional Lotka–Volterra model.

2 Preliminaries

Throughout this paper, we will make use of the following notations, definitions and known results of discrete fractional calculus [29]. For any $\alpha, t \in \mathbb{R}$, the α rising function is defined by

$$t^{\overline{\alpha}} = \frac{\Gamma(t+\alpha)}{\Gamma(t)}, \ t \in \mathbb{R} \setminus \{\dots, -2, -1, 0\}, \ 0^{\overline{\alpha}} = 0,$$
 (2)

where Γ is the well known Gamma function satisfying $\Gamma(\alpha + 1) = \alpha \Gamma(\alpha)$.

Definition 1. Let $x : \mathbb{N}_0 \to \mathbb{R}$, $\rho(s) = s - 1$, $\alpha \in \mathbb{R}^+$ and $\mu > -1$. Then

1. The nabla difference of x is defined by

$$\nabla x(t) = x(t) - x(t-1), \ t \in \mathbb{N}_1 = \{1, 2, \ldots\}.$$

2. The Riemann-Liouville's sum operator of x of order $\alpha > 0$ is defined by

$$\nabla_0^{-\alpha} x(t) = \frac{1}{\Gamma(\alpha)} \sum_{s=1}^t (t - \rho(s))^{\overline{\alpha} - 1} x(s), \quad t \in \mathbb{N}_1.$$
 (3)

3. The Riemann-Liouville's difference operator of x of order $0 < \alpha < 1$ is defined by

$${}^{c}\nabla_{0}^{\alpha}x(t) = \nabla_{0}^{-(1-\alpha)}\nabla x(t) = \frac{1}{\Gamma(1-\alpha)}\sum_{s=1}^{t} (t-\rho(s))^{\overline{-\alpha}}\nabla x(s), \quad t \in \mathbb{N}_{1}.$$
 (4)

4. The power rule is defined by

$$\nabla_0^{-\alpha} t^{\overline{\mu}} = \frac{\Gamma(\mu+1)}{\Gamma(\mu+\alpha+1)} (t)^{\overline{\alpha+\mu}}, \quad t \in \mathbb{N}_0.$$
 (5)

Lemma 1. [40] x(t) denotes a solution of equation (1) if and only if it admits the following representation

$$x(t) = \phi(0) + \frac{1}{\Gamma(\alpha)} \sum_{s=1}^{t} (t - \rho(s))^{\overline{\alpha - 1}} f(s, x(s), x(s - \tau)), \quad t \in \mathbb{N}_0,$$
 (6)

and $x(t) = \phi(t), t \in [-\tau, -\tau + 1, \dots, 0].$

The space l_{∞} denotes the set of real bounded sequences with respect to the usual supremum norm. We recall that l_{∞} is a Banach space.

Definition 2. A set D of sequences in l_{∞} is uniformly Cauchy if for every $\varepsilon > 0$, there exists an integer N such that $|x(t) - x(s)| < \varepsilon$ whenever t, s > N for any $x = \{x(n)\}$ in D.

The following discrete version of Arzela–Ascoli's Theorem has a crucial role in the proof of our main theorem.

Theorem 1. (Arzela–Ascoli's Theorem) A bounded, uniformly Cauchy subset D of l_{∞} is relatively compact.

The proof of the main theorem is achieved by employing the following fixed point theorem.

Theorem 2. [31] (Krasnoselskii Fixed Point Theorem) Let D be a nonempty, closed, convex and bounded subset of a Banach space (X, ||x||). Suppose that $A: X \to X$ and $B: D \to X$ are two operators such that

- (i) A is a contraction.
- (ii) B is continuous and B(D) resides in a compact subset of X,
- (iii) for any $x, y \in D$, $Ax + By \in D$.

Then the operator equation Ax + Bx = x has a solution $x \in D$.

3 Main results

We prove our main results under the following assumptions:

- (I) $f(t, x(t), y(t)) = f_1(t, x(t)) + f_2(t, x(t), y(t))$, where f_i are Lipschitz functions with Lipschitz constants L_{f_i} , i = 1, 2.
- (II) $|f_1(t, x(t))| \le M_1|x(t)|$, $|f_2(t, x(t), y(t))| \le M_2|x(t)| \times |y(t)|$ for any positive numbers M_1 and M_2 .

Let $B(\mathbb{N}_{-\tau}, \mathbb{R})$ denote the set of all bounded functions (sequences). Define the set

$$D = \{x : x \in B(\mathbb{N}_{-\tau}, \mathbb{R}), |x| < r, t \in \mathbb{N}_0\},\$$

where r satisfies

$$|\phi(0)| + \frac{M_1 r + M_2 r^2}{\Gamma(\alpha)} \le r.$$

Define the operators F_1 and F_2 by

$$F_1 x(t) = \phi(0) + \frac{1}{\Gamma(\alpha)} \sum_{s=1}^{t} (t - \rho(s))^{\overline{\alpha-1}} f_1(s, x(s)),$$

and

$$F_2x(t) = \frac{1}{\Gamma(\alpha)} \sum_{s=1}^t (t - \rho(s))^{\overline{\alpha-1}} f_2(s, x(s), x(s-\tau)).$$

It is clear that x(t) is a solution of (1) it it is a fixed point of the operator $Fx = F_1x + F_2x$.

Theorem 3. Let conditions (I)–(II) hold. Then, equation (1) has a solution in the set D provided that $\frac{L_{f_1}C(\alpha)}{\Gamma(\alpha)} < 1$ and $|\phi(0)| + \frac{\left(M_1r + M_2r^2\right)C(\alpha)}{\Gamma(\alpha)} \leq r$.

Proof. From the assumptions on the set D, one can easily see that D is a nonempty, closed, convex and bounded set.

Step.1: We prove that F_1 is contractive. We can easily see that

$$|F_{1}x(t) - F_{1}y(t)| = \frac{1}{\Gamma(\alpha)} \sum_{s=1}^{t} (t - \rho(s))^{\overline{\alpha-1}} |f_{1}(s, x(s)) - f_{1}(s, y(s))|$$

$$\leq \frac{L_{f_{1}}}{\Gamma(\alpha)} \sum_{s=1}^{t} (t - \rho(s))^{\overline{\alpha-1}} |x(s) - y(s)|$$

$$\leq \frac{L_{f_{1}}}{\Gamma(\alpha)} ||x - y|| \sum_{s=1}^{t} (t - \rho(s))^{\overline{\alpha-1}}.$$
(7)

By virtue of (2), (3), (5) and since $(t-0)^{\overline{0}}=1$, one can see that

$$\sum_{s=1}^{t} (t - \rho(s))^{\overline{\alpha - 1}} (t - 0)^{\overline{0}} = \Gamma(\alpha) \nabla_0^{-\alpha} (t - 0)^{\overline{0}} = \frac{\Gamma(t + \alpha)}{\alpha \Gamma(t)}.$$

Therefore, (7) becomes

$$|F_1 x(t) - F_1 y(t)| \le \frac{L_{f_1} C(\alpha)}{\Gamma(\alpha)} ||x - y||, \ t < T_1,$$

where $C(\alpha) = \frac{\Gamma(T_1 + \alpha)}{\alpha \Gamma(T_1)}$ is a positive constant depending on the order α . By the assumption $\frac{L_{f_1}C(\alpha)}{\Gamma(\alpha)} < 1$, we conclude that F_1 is contractive. Furthermore, we obtain for $x \in D$

$$\begin{aligned}
|F_1 x(t) + F_2 x(t)| &\leq |\phi(0)| + \frac{1}{\Gamma(\alpha)} \sum_{s=1}^t (t - \rho(s))^{\overline{\alpha - 1}} |f_1(s, x(s)) + f_2(s, x(s), x(s - \tau))| \\
&\leq |\phi(0)| + \frac{M_1 ||x|| + M_2 ||x||^2}{\Gamma(\alpha)} \sum_{s=1}^t (t - \rho(s))^{\overline{\alpha - 1}} \\
&\leq |\phi(0)| + \frac{(M_1 r + M_2 r^2) C(\alpha)}{\Gamma(\alpha)},
\end{aligned}$$

which implies that $F_1x + F_2x \in D$. For $x \in D$, we also get

$$|F_2x(t)| \le \frac{1}{\Gamma(\alpha)} \sum_{s=1}^t (t - \rho(s))^{\overline{\alpha-1}} |f_2(s, x(s), x(s-\tau))| \le \frac{(M_2r^2)C(\alpha)}{\Gamma(\alpha)} \le r,$$

which implies that $F_2(D) \subset D$.

Step.2: We prove that F_2 is continuous. Let a sequence x_n converge to x. Taking the norm of $F_2x_n(t) - F_2x(t)$, we have

$$\begin{aligned}
|F_{2}x_{n}(t) - F_{2}x(t)| &\leq \frac{1}{\Gamma(\alpha)} \sum_{s=1}^{t} (t - \rho(s))^{\overline{\alpha - 1}} |f_{2}(s, x_{n}(s), x_{n}(s - \tau)) - f_{2}(s, x(s), x(s - \tau))| \\
&\leq \frac{L_{f_{2}}}{\Gamma(\alpha)} \sum_{s=1}^{t} (t - \rho(s))^{\overline{\alpha - 1}} \Big(|x_{n}(s) - x(s)| - |x_{n}(s - \tau)) - x(s - \tau)| \Big) \\
&\leq \frac{2L_{f_{2}}}{\Gamma(\alpha)} ||x_{n} - x|| \sum_{s=1}^{t} (t - \rho(s))^{\overline{\alpha - 1}} = \frac{(2L_{f_{2}})C(\alpha)}{\Gamma(\alpha)} ||x_{n} - x||.
\end{aligned}$$

From the above discussion, we conclude that whenever $x_n \to x$, $Fx_n \to Fx$. This proves the continuity of F_2 . To prove that $F_2(D)$ resides in a relatively compact subset of l_{∞} , we let $t_1 \le t_2 \le H$ to get

$$\begin{aligned}
|F_{2}x(t_{2}) - F_{2}x(t_{1})| &\leq \frac{1}{\Gamma(\alpha)} \left| \sum_{s=1}^{t_{2}} (t_{2} - \rho(s))^{\overline{\alpha-1}} f_{2}(s, x(s), x(s-\tau)) \right| \\
&- \sum_{s=1}^{t_{1}} (t_{1} - \rho(s))^{\overline{\alpha-1}} f_{2}(s, x(s), x(s-\tau)) \right| \\
&\leq \frac{1}{\Gamma(\alpha)} \sum_{s=1}^{t_{1}} \left| (t_{2} - \rho(s))^{\overline{\alpha-1}} - (t_{1} - \rho(s))^{\overline{\alpha-1}} \right| |f_{2}(s, x(s), x(s-\tau))| \\
&+ \frac{1}{\Gamma(\alpha)} \sum_{s=t_{1}+1}^{t_{2}} \left| (t_{2} - \rho(s))^{\overline{\alpha-1}} \right| |f_{2}(s, x(s), x(s-\tau))|.
\end{aligned}$$

Upon employing condition (II), we obtain

$$|F_{2}x(t_{2}) - F_{2}x(t_{1})| \leq M_{2}r^{2} \left[\frac{1}{\Gamma(\alpha)} \sum_{s=1}^{t_{1}} (t_{2} - \rho(s))^{\overline{\alpha-1}} - \frac{1}{\Gamma(\alpha)} \sum_{s=1}^{t_{1}} (t_{1} - \rho(s))^{\overline{\alpha-1}} + \frac{1}{\Gamma(\alpha)} \sum_{s=t_{1}+1}^{t_{2}} (t_{2} - \rho(s))^{\overline{\alpha-1}} \right].$$

By using (3), we get

$$\left| F_2 x(t_2) - F_2 x(t_1) \right| \le M_2 r^2 \left[\nabla_0^{-\alpha} (t_2 - 0)^{\overline{0}} - \nabla_0^{-\alpha} (t_1 - 0)^{\overline{0}} + \nabla_{t_1}^{-\alpha} (t_2 - t_1)^{\overline{0}} \right].$$

From (5), it follows that

$$|F_2x(t_2) - F_2x(t_1)| \le \frac{M_2r^2}{\Gamma(\alpha+1)} \left[t_2^{\overline{0}} - t_1^{\overline{0}} + (t_2 - t_1)^{\overline{0}}\right].$$

This implies that F_2 is bounded and uniformly subset of l^{∞} . Thus, by virtue of the Discrete Arzela Ascoli's Theorem 1, we conclude that F_2 is relatively compact.

Step.3: It remains to show that for any $x, y \in D$, we have $F_1x(t) + F_2y(t) \in D$. If $x = F_1x(t) + F_2y(t)$, then we have

$$|x(t)| \leq |F_1 x(t) + F_2 y(t)| \leq |\phi(0)| + \frac{1}{\Gamma(\alpha)} \sum_{s=1}^{t} (t - \rho(s))^{\overline{\alpha - 1}} |f_1(s, x(s)) + f_2(s, y(s), y(s - \tau))|$$

$$\leq |\phi(0)| + \frac{M_1 ||x|| + M_2 ||x||^2}{\Gamma(\alpha)} \sum_{s=1}^{t} (t - \rho(s))^{\overline{\alpha - 1}}$$

$$\leq |\phi(0)| + \frac{(M_1 r + M_2 r^2) C(\alpha)}{\Gamma(\alpha)},$$

which implies that $x(t) \in D$.

By employing the Krasnoselskii Fixed Point Theorem, we conclude that there exists $x \in D$ such that $x = Fx = F_1x + F_2x$ which is a fixed point of F. Hence, equation (1) has at least one solution in D.

4 Applications

The Lotka–Volterra model has been extensively investigated through different approaches [32, 33, 34, 35, 36, 37]. However, all the above mentioned papers studied the integer order Lotka–Volterra model. In spite of the fact that the study of population and medical models of fractional order has been initiated in [12, 38, 39], there is no literature achieved in the direction of discrete fractional Lotka–Volterra model. Therefore, in this section, we employ Theorem 3 to prove an existence and uniqueness result for the solutions of this model.

For a bounded sequence g on \mathbb{N} , we define g^+ and g^- as follows

$$g^+ = \sup_{t \in \mathbb{N}} g(t)$$
 and $g^- = \inf_{t \in \mathbb{N}} g(t)$.

Let $f(t, x(t), x(t - \tau)) = x(t)(\gamma(t) - \beta(t)x(t - \tau))$ in equation (1), then we have the following discrete fractional Lotka–Volterra model:

$$\begin{cases} {}^{c}\nabla_{0}^{\alpha}x(t) = x(t)(\gamma(t) - \beta(t)x(t-\tau)), \ t \in \mathbb{N}_{0} \\ x(t) = \phi(t), \ t \in [-\tau, -\tau + 1, \dots, 0], \ 0 < \alpha < 1, \end{cases}$$
(8)

where the coefficients γ and β satisfy the boundedness relations

$$\gamma^- \le \gamma(t) \le \gamma^+, \ \beta^- \le \beta(t) \le \beta^+,$$

which are medically and biologically feasible. Model (8) represents the interspecific competition in single species with τ denotes the maturity time period.

Denote

$$\overline{f}_1(t,x(t)) = x(t)\gamma(t), \quad \overline{f}_2(t,x(t),x(t-\tau)) = -\beta(t)x(t)x(t-\tau).$$

It follows that the functions \overline{f}_1 and \overline{f}_2 satisfy the conditions

(III)
$$|\overline{f}_1(t,x(t))| \leq \gamma^+|x(t)|$$
, $|\overline{f}_2(t,x(t),x(t-\tau))| \leq \beta^+|x(t)| \times |x(t-\tau)|$.

(IV) \overline{f}_i are Lipschitz functions with Lipschitz constants \overline{L}_{f_i} , i = 1, 2.

The solution of model (8) has the form

$$x(t) = \phi(0) + \frac{1}{\Gamma(\alpha)} \sum_{s=1}^{t} (t - \rho(s))^{\overline{\alpha - 1}} x(s) \Big(\gamma(s) - \beta(s) x(s - \tau) \Big), \quad t \in \mathbb{N}_0,$$
 (9)

and $x(t) = \phi(t), \ t \in [-\tau, -\tau + 1, \dots, 0].$ Define a function G by

$$Gx(t) = G_1x(t) + G_2x(t),$$

where

$$G_1x(t) = \phi(0) + \frac{1}{\Gamma(\alpha)} \sum_{s=1}^{t} (t - \rho(s))^{\overline{\alpha-1}} x(s) \gamma(s),$$

and

$$G_2x(t) = -\frac{1}{\Gamma(\alpha)} \sum_{s=1}^{t} (t - \rho(s))^{\overline{\alpha-1}} x(s)\beta(s)x(s - \tau).$$

One can easily employ the same arguments used in the proof of Theorem 3 to complete the proof of the following theorem for equation (8).

Theorem 4. Let conditions (III)–(IV) hold. Then, the model (8) has a solution in the set D provided that $\frac{L_{f_1}C(\alpha)}{\Gamma(\alpha)} < 1$ and $|\phi(0)| + \frac{(\gamma^+r+\beta^+r^2)C(\alpha)}{\Gamma(\alpha)} \le r$.

Remark 1. The above result can be extended to n species competitive Lotka–Volterra system of the form

$$\begin{cases}
\nabla_0^{\alpha} x_i(t) = x_i(t) \left(\gamma_i(t) - \sum_{j=1}^n \beta_{ij}(t) x_j(t - \tau_{ij}) \right), \ t \in \mathbb{N}_0, \ i = 1, 2, \dots, n. \\
x_i(t) = \phi_i(t), \ t \in [-\tau_i, -\tau_i + 1, \dots, 0], \ 0 < \alpha < 1, \ \tau_i = \max_{1 \le j \le n} \tau_{ij},
\end{cases}$$
(10)

where $\gamma^- \le \gamma_i(t) \le \gamma^+, \ \beta^- \le \beta_{ij}(t) \le \beta^+.$

Remark 2. Results of this paper can be carried out for the equation

$$\begin{cases}
\nabla_0^{\alpha} x(t) = f(t, x(t), x(t - \tau)), \ t \in \mathbb{N}_2 = \{2, 3, \ldots\}, \ \tau \ge 0, \\
x(t) = \phi(t), \ t \in [-\tau, -\tau + 1, \ldots, 1],
\end{cases}$$
(11)

where $f: \mathbb{N}_0 \times \mathbb{R} \times \mathbb{R} \to \mathbb{R}$ and ∇_0^{α} denotes the Riemann-Liouville's fractional difference of order $\alpha \in (0,1)$. The solution of equation (11) has the form

$$x(t) = \frac{t^{\overline{\alpha - 1}}}{\Gamma(\alpha)}\phi(1) + \frac{1}{\Gamma(\alpha)} \sum_{s=2}^{t} (t - \rho(s))^{\overline{\alpha - 1}} f(s, x(s), x(s - \tau)). \tag{12}$$

5 Conclusion

A comprehensive literature survey on the predator—prey type Lotka—Volterra model reveals that a considerable amount of work has already been done by many esteemed researchers during the last century. However the concept of the model related to fractional time derivatives is an original one.

The fractional Lotka–Volterra equation is obtained from the classical equations by replacing the first order time derivative by fractional derivative of order $\alpha \in (0,1)$. One of the most significant outcomes of this evolution equation is the generation of fractional Brownian motions.

It has been discernible that the discrete analogue of ordinary differential equations has tremendous applications in computational analysis and computer simulations. Motivated by this reality, the study of the discrete analogue of fractional differential equations has become pressing and compulsory.

In this paper, we studied the existence and uniqueness of solutions for nonlinear delay fractional difference equations. The main theorem is proved with the help the Krasnoselskii fixed point theorem and the Arzela–Ascoli's Theorem. Prior to the main result, we set forth some notations and definitions which enriched the knowledge of discrete fractional calculus. To demonstrate the applicability of the main theorem, we provide an existence result for the discrete fractional Lotka–Volterra model.

It is to be noted that the analysis carried out in this paper is based on the use of nabla rather than delta operators. Indeed, unlike the delta operator the range of nabla fractional sum and difference operators depends only of the starting point and independent of the order α . This provides exceptional ability to treat skilfully different circumstances throughout the proofs. The delta approach can be obtained from nabla operator through the implementation of the dual identities discussed in [41].

References

- [1] I. Podlubny: Fractional Differential Equations, vol. 198 of Mathematics in Science and Engineering, Academic Press, San Diego, Calif, USA, 1999.
- [2] A. A. Kilbas, H. M. Srivastava, J. J. Trujillo: Theory and Applications of Fractional Differential Equations, Elsevier, North Holland, 2006.
- [3] K. V. Miller, B. Ross: An Introduction to the Fractional Calculus and Fractional Differential Equations, Wiley–Interscience, New York, 1993.
- [4] A. B. Abdulla, M. Al-Refai, A. Al-Rawashdeh: On the existence and uniqueness of solutions for a class of non-linear fractional boundary value problems, J. King Saud Univ. 28 (1) (2016), 103–110.
- [5] Z-Dong Mei, J-Gen Peng, J-Huai Gao: Existence and uniqueness of solutions for nonlinear general fractional differential equations in Banach spaces, Indag. Math. 26 (4) (2015), 669–678.
- [6] B. Zhu, L. Liu, Y. Wu: Existence and uniqueness of global mild solutions for a class of nonlinear fractional reaction-diffusion equations with delay, Comput. Math. Appl. In Press, Corrected Proof, Available online 12 February 2016
- [7] Y. Zhou, F. Jiao, J. Li: Existence and uniqueness for fractional neutral differential equations with infinite delay, Nonlinear Anal. 71 (7–8) (2009), 3249–3256.
- [8] N. Li, C. Wang: New existence results of positive solution for a class of nonlinear fractional differential equations, Acta Math. Sinica 33 (3)(2013), 847–854.
- [9] F. M. Atici, P. W. Eloe: A transform method in discrete fractional calculus, Int. J. Difference Equ. 2 (2) (2007), 165–176.

- [10] F. M. Atici, P. W. Eloe: Initial value problems in discrete fractional calculus, Proc. Amer. Math. Soc. 137 (3) (2009), 981–989. 12 Advances in Difference Equations
- [11] F. M. Atici, P. W. Eloe: Discrete fractional calculus with the nabla operator, Electron. J. Qual. Theory Differ. Equ. vol. 2009, no. 3, pp. 1–12, 2009.
- [12] F. M. Atici, S. Şengül: Modeling with Factorial Difference Equations, J. Math. Anal. Appl. 369 (1) (2010), 1–9.
- [13] F. M. Atici, P. W. Eloe: Linear systems of fractional nabla difference equations, Rocky Mountain J. Math. 41 (2011), 353–370.
- [14] T. Abdeljawad: On Riemann and Caputo fractional differences, Comput. Math. Appl. 62 (2011), 1602–1611.
- [15] T. Abdeljawad, F. M. Atici: On the definitions of nabla fractional operators, Abstr. Appl. Anal. 2012, (2012), 13 pages.
- [16] T. Abdeljawad, D. Baleanu: Fractional differences and integration by Parts, J. Comput. Anal. Appl. 13(2011), no. 5, 574–582
- [17] T. Abdeljawad, D. Baleanu, F. Jarad, R. P. Agarwal: Fractional sums and differences with binomial coefficients, Discrete Dyn. Nat. Soc. Volume 2013, Article ID 104173, 6 pages.
- [18] T. Abdeljawad, J. O. Alzabut,: The q-fractional analogue for Gronwall-type inequality, J. Funct. Spaces Appl. 2013, Art. ID 543839.
- [19] G. A. Anastassiou: Discrete fractional calculus and inequalities, http://arxiv.org/abs/0911.3370.
- [20] G. A. Anastassiou: Nabla discrete fractional calculus and nabla inequalities, Math. Comput. Modell. 51 (2010), 562–571.
- [21] C. S. Goodrich: Existence of a positive solution to a system of discrete fractional boundary value problems, App. Math. Comput. 217 (9) (2011), 4740–4753.
- [22] C. S. Goodrich: Existence and uniqueness of solutions to a fractional difference equation with nonlocal conditions, Comput. Math. Appl. 61 (2) (2011), 191–202.
- [23] C. S. Goodrich: On a discrete fractional three-point boundary value problem, J. Differ. Equ. Appl. 18 (3) (2012), 397–415.
- [24] F. Chen: Fixed points and asymptotic stability of nonlinear fractional difference equations, Electron. J. Qual. Theory Differ. Equ. 39 (2011), 1-?18.
- [25] F. Chen, X. Luo, Y. Zhou: Existence results for nonlinear fractional order difference equation, Adv. Differ. Equ. 2011 (2011), Article ID 713201.
- [26] F. Chen, Y. Zhou: Existence and Ulam stability of solutions for discrete fractional boundary value problem, Discrete Dyn. Nat. Soc. Volume 2013 (2013), Article ID 459161.
- [27] G. C. Wu, D. Baleanu: Discrete fractional logistic map and its chaos, Nonlinear Dyn. 75 (2014) 283–287.
- [28] G. C. Wu, D. Baleanu: Chaos synchronization of the discrete fractional logistic map, Sign. Proc. 102 (2014) 96–99.
- [29] L. Erbe, C. S. Goodrich, B. Jia, A. Peterson: Survey of the qualitative properties of fractional difference operators: monotonicity, convexity, and asymptotic behavior of solutions, Adv. Differ. Equ. 2016 2016:43.
- [30] C. Goodrich, A. Peterson: Discrete Fractional Calculus, Springer 2015.
- [31] T. A. Burton: A fixed point theorem of Krasnoselskii fixed point theorem, Appl. Math. Lett. 11 (1998), 85–88.
- [32] T. Faria: Sharp conditions for global stability of Lotka-Volterra systems with distributed delays, J. Differ. Equ. 246 (11) (2009), 4391–4404.
- [33] F. Capone, R. D. Luca, S. Rionero: On the stability of non-autonomous perturbed Lotka-Volterra models, Appl. Math. Comp.219 (12) (2013), 6868-6881.
- [34] J. X. Li, J. R. Yan: Persistence for Lotka-volterra patch-system with time delay, Nonlinear Anal. RWA 9 (2) (2008), 490-499.

- [35] J. X. Li, J. R. Yan: Permanence and extinction for a non linear diffusive predator–prey system, Nonlinear Anal. 71 (1?2) (2009), 399–417.
- [36] S. S. Chen, J. P. Shi, J. J. Wei: A note on Hopf bifurcations in a delayed diffusive Lotka-Volterra predator-prey system, Comput. Math. Appl. 62 (5) (2011), 2240–2245.
- [37] Z. J. Liu, L. S. Chen: Periodic solution of neutral Lotka-volterra system with periodic delays, J. Math. Anal. Appl. 324 (1) (2006), 435-?451.
- [38] C. N. Angstmann, B. I. Henry, A.V. McGann: A fractional-order infectivity SIR model, Physica A, 452 (15) (2016), 86–93.
- [39] R. Khoshsiar Ghaziani, J. Alidousti, A. Bayati Eshkaftaki: Stability and dynamics of a fractional order Leslie–Gower prey–predator model, Appl. Math. Model. 40 (3) (2016), 2075–2086.
- [40] T. Abdeljawad: On delta and nabla Caputo fractional differences and dual identities, Discrete Dyn. Nat. Soc. Volume 2013 (2013), Article ID 406910, 12 page.
- [41] T. Abdeljawad: Dual identities in fractional difference calculus within Riemann, Adv. Differ. Equ. 2013: 36.

Some sharp results on NLC-operators in G_p -metric spaces

Huaping Huang¹, Ljiljana Gajić², Stojan Radenović³, Guantie Deng^{1,*}

- 1. School of Mathematical Sciences, Beijing Normal University, Laboratory of Mathematics and Complex Systems, Ministry of Education, Beijing 100875, PR China
- 2. Department of Mathematics and Informatics, Faculty of Science, University of Novi Sad, Serbia
 - 3. Faculty of Mechanical Engineering, University of Belgrade, Kraljice Marije 16, 11120, Beograd, Serbia

Abstract: In this paper we generalize, complement and improve some recent results on NLC-operators established in G_p -metric spaces. Several examples are given to support our theoretical approach.

Keywords: G_p -metric space, NLC-operator, supporting sequence, G_p -complete, fixed point

1 Introduction and preliminaries

Partial metric space and G-metric space are two different generalized metric spaces. In 1994 Matthews [13] introduced partial metric space as follows:

Definition 1.1. Let X be a nonempty set. A partial metric is a mapping $p: X^2 \to [0, +\infty)$ which satisfies that

- (p1) $x = y \Leftrightarrow p(x, x) = p(x, y) = p(y, y)$, for all $x, y \in X$;
- (p2) $p(x,x) \leq p(x,y)$, for all $x,y \in X$;
- (p3) p(x,y) = p(y,x), for all $x, y \in X$;
- (p4) $p(x,z) \le p(x,y) + p(y,z) p(y,y)$, for all $x, y, z \in X$.

Then the pair (X, p) is called a partial metric space.

It is clear that each (standard) metric space is a partial metric space, while on the contrary it does not hold, in general. In recent years, many authors have obtained lots of fixed point results in partial metric spaces, for example, see [12], [13], [15], [17], [21] and the references therein.

On the other hand, in 2006 Mustafa and Sims [14] introduced another kind of generalized metric space, so-called G-metric space as follows:

Definition 1.2. Let X be a nonempty set. A mapping $G: X^3 \to [0, +\infty)$ is called G-metric if it satisfies the following conditions:

^{*}Correspondence: denggt@bnu.edu.cn (G. Deng)

- (G1) $x = y = z \Leftrightarrow G(x, y, z) = 0$ for all $x, y, z \in X$;
- (G2) 0 < G(x, x, y), for all $x, y \in X$ with $x \neq y$;
- (G3) $G(x, x, y) \leq G(x, y, z)$, for all $x, y, z \in X$ with $z \neq y$;
- (G4) $G(x, y, z) = G(P\{x, y, z\})$, where P is a permutation of $x, y, z \in X$ (symmetry in all three variables);
- (G5) $G(x, y, z) \leq G(x, a, a) + G(a, y, z)$, for all $x, y, z, a \in X$ (rectangle inequality). Then the pair (X, G) is called a G-metric space.

Based on this notion, many fixed point results under different contractive conditions have been obtained (see [1], [7]-[10], [14], and the references therein).

In 2011 Zand and Nezhad [23] introduced a concept as a generalization of both partial metric space and G-metric space as follows:

Definition 1.3. Let X be a nonempty set. A mapping $G_p: X^3 \to [0, +\infty)$ is called a G_p -metric if the following conditions are satisfied:

(G_p1)
$$x = y = z$$
 if $G_p(x, y, z) = G_p(x, x, x) = G_p(y, y, y) = G_p(z, z, z)$ for all $x, y, z \in X$;

- $(G_p 2)$ $G_p(x, x, x) \le G_p(x, x, y) \le G_p(x, y, z)$ for all $x, y, z \in X$;
- (G_p3) $G_p(x, y, z) = G_p(P\{x, y, z\})$, where P is a permutation of $x, y, z \in X$ (symmetry in all three variables);
- $(G_p 4) G_p(x, y, z) \le G_p(x, a, a) + G_p(a, y, z) G_p(a, a, a)$, for all $x, y, z, a \in X$ (rectangle inequality).

Then the pair (X, G_p) is called a G_p -metric space.

Remark 1.4. It is worth mentioning that authors in [2], [3], [5], [19] and [23] used (G_p2) while in [6], [18] and [20] authors used the following condition:

$$(G_p 2')$$
 $G_p(x, x, x) \leq G_p(x, x, y) \leq G_p(x, y, z)$ for all $x, y, z \in X$ with $z \neq y$.

In the former case (X, G_p) is a symmetric G_p -metric space, that is., $G_p(x, x, y) = G_p(x, y, y)$ for all $x, y \in X$. However, in the latter case this does not hold.

Otherwise, each symmetric G-metric space is symmetric G_p -metric space, but the converse is not true (see Example 1 from [23]) as well as each G-metric space is G_p -metric space in the sense of [18]. However, the claim from [23] (page 87, lines 6-,7-) that each G-metric space is also G_p -metric space is false (see [18], page 79). In addition, It is noteworthy that Example 3 in [23] is symmetric G-metric space, and hence it is G_p -metric space. It is also clear that Definition 6 (because (G_p2)) in [23] is superfluous.

First our important result in this section is the following:

Proposition 1.5. Every G_p -metric space (X, G_p) in the sense of [18] defines a metric space (X, d_{G_p}) as follows:

$$d_{G_p}(x,y) = G_p(x,y,y) + G_p(x,x,y) - G_p(x,x,x) - G_p(y,y,y)$$
, for all $x,y \in X$.

Proof. Using $(G_p 2)$, we have $d_{G_p}(x, y) \geq 0$ for all $x, y \in X$. Also, if x = y, then $d_{G_p}(x, y) = 0$. Conversely, let $d_{G_p}(x, y) = 0$, then

$$G_p(x, y, y) + G_p(x, x, y) - G_p(x, x, x) - G_p(y, y, y) = 0,$$

that is.,

$$[G_p(x, x, y) - G_p(x, x, x)] + [G_p(x, y, y) - G_p(y, y, y)] = 0,$$

or equivalently, $G_p(x, x, y) = G_p(x, x, x)$ and $G_p(x, y, y) = G_p(y, y, y)$. Further, on account of $(G_p 4)$ it implies that $G_p(x, y, y) \le 2G_p(x, x, y) - G_p(x, x, x) = G_p(x, x, y)$. Similarly it follows that $G_p(x, x, y) \le G_p(x, y, y)$ for all $x, y \in X$. Then

$$G_{p}(x, y, x) = G_{p}(x, x, x) = G_{p}(y, y, y),$$

thus by (G_p1) it gives x = y.

It is obvious that $d_{G_p}(x,y) = d_{G_p}(y,x)$ for all $x,y \in X$.

Finally, we shall prove that

$$d_{G_p}(x,z) \le d_{G_p}(x,y) + d_{G_p}(y,z)$$
,

for all $x, y, z \in X$, or equivalently,

$$G_{p}(x, x, z) + G_{p}(x, z, z) - G_{p}(x, x, x) - G_{p}(z, z, z)$$

$$\leq G_{p}(x, x, y) + G_{p}(x, y, y) - G_{p}(x, x, x) - G_{p}(y, y, y)$$

$$+ G_{p}(y, y, z) + G_{p}(y, z, z) - G_{p}(y, y, y) - G_{p}(z, z, z),$$

that is.,

$$G_{p}(x, x, z) + G_{p}(x, z, z)$$

$$\leq G_{p}(x, x, y) + G_{p}(x, y, y) - G_{p}(y, y, y) + G_{p}(y, y, z) + G_{p}(y, z, z) - G_{p}(y, y, y).$$

Notice that

$$G_p(x, x, z) = G_p(z, x, x) \le G_p(z, y, y) + G_p(y, x, x) - G_p(y, y, y)$$

and

$$G_p(x, z, z) \le G_p(x, y, y) + G_p(y, z, z) - G_p(y, y, y),$$

so the proof is completed.

Remark 1.6. Our proof of this proposition is more detailed than one of [23].

Further, we announce the following definition with valid approaches which complements Definition 1.9 from [18].

Definition 1.7. Let (X, G_p) be a G_p -metric space and $\{x_n\}$ a sequence in X. Then

- (1) $\{x_n\}_{n\in\mathbb{N}}$ is called G_p -convergent to a point $x\in X$ if $\lim_{n,m\to\infty}G_p\left(x,x_n,x_m\right)=G_p\left(x,x,x\right)$. In this case, we write $x_n\to x$ as $n\to\infty$;
- (2) $\{x_n\}$ is called a G_p -Cauchy sequence if $\lim_{n,m\to\infty} G_p(x_n,x_m,x_m) = r \in \mathbb{R}$. Particularly, $\{x_n\}$ is called 0-Cauchy sequence if r=0;
- (3) (X, G_p) is called G_p -complete if for every G_p -Cauchy sequence $\{x_n\}$ in X is G_p -convergent to $x \in X$.

Now, we give the following conclusion which corrects Proposition 4 of [23]:

Proposition 1.8. Let (X, G_p) be a symmetric G_p -metric space. Then for a sequence $\{x_n\} \subseteq X$ and a point $x \in X$ the following are equivalent:

- (1) $\{x_n\}$ is G_p -convergent to x;
- (2) $G_p(x_n, x_n, x) \to G_p(x, x, x)$ as $n \to \infty$;
- (3) $G_p(x_n, x, x) \to G_p(x, x, x)$ as $n \to \infty$.

Proof. Since (X, G_p) is symmetric G_p -metric space, then (2) is equivalent to (3). Taking m = n in (1), we speculate that (1) implies (2), thus, (1) implies (3). For the converse we have that

$$G_{p}(x, x_{n}, x_{m}) - G_{p}(x, x, x)$$

$$= G_{p}(x_{n}, x_{m}, x) - G_{p}(x, x, x)$$

$$\leq G_{p}(x_{n}, x, x) + G_{p}(x, x_{m}, x) - G_{p}(x, x, x) - G_{p}(x, x, x)$$

$$= [G_{p}(x_{n}, x, x) - G_{p}(x, x, x)] + [G_{p}(x_{m}, x, x) - G_{p}(x, x, x)]$$

$$\to 0 + 0 = 0, \text{ as } n, m \to \infty,$$

then (3) implies (1). We complete the proof.

Next we generalize Lemma 1.10 from [2] (see also [3], [5], [6], [18], [20]), that is., we announce the following assertion:

Proposition 1.9. Let (X, G_p) be a G_p -metric space in the sense of [18]. Then

- (A) if $G_p(x, y, z) = 0$, then x = y = z;
- (B) if $x \neq y$, then $G_p(x, y, y) > 0$.

Proof. (A) If $x \neq y \neq z \neq x$, then (A) is an immediate consequence of $(G_p 2')$ and $(G_p 1)$. If for instance, $x \neq y = z$, then $G_p(x, y, z) = G_p(x, y, y) = 0$. In this case, we get $G_p(x, x, x) = G_p(x, x, y) = G_p(y, y, y) = 0$. Indeed, by $(G_p 4)$ it follows that

$$G_p(x, x, y) \le G_p(x, y, y) + G_p(y, x, y) - G_p(y, y, y) \le 2G_p(x, y, y) = 0.$$

Since $G_p(x, x, x) \leq G_p(x, x, y)$ and $G_p(y, y, y) \leq G_p(x, y, y)$ hold for all $x, y \in X$, then we arrive at

$$G_{p}(x, y, y) = G_{p}(x, x, y) = G_{p}(x, x, x) = G_{p}(y, y, y) = 0,$$

so by (G_p1) , we obtain the desired result.

(B) Let $G_p(x, y, y) = 0$. Now, based on the proof of (A) when $x \neq y = z$, we claim that x = y. A contradiction.

2 Auxiliary results

In the sequel, let (X, G_p) be a G_p -metric space in the sense of [18]. First of all, we introduce the following notion:

Definition 2.1. Let (X, G_p) be a G_p -metric space, $\alpha \in (0, 1)$ a constant and $T: X \to X$ a mapping. We say that T is an NLC-operator on X if for each $x \in X$ there is some

 $n(x) \in \mathbb{N}$ such that for each $y \in X$ it holds

$$G_p(T^{n(x)}x, T^{n(x)}x, T^{n(x)}y) \le \max\{\alpha G_p(x, x, y), G_p(x, x, x)\}.$$
 (2.1)

For an NLC-operator T and $x \in X$ we define supporting sequence at x as a sequence $\{s_k\}_{k \in \mathbb{N} \cup \{0\}}$ where $s_0 = 0$ and $s_{k+1} = s_k + n(T^{s_k}x), k \in \mathbb{N} \cup \{0\}$. Also set $J_T(X) = \{x \in X : T^m x = T^{m+1}x \text{ for some } m \in \mathbb{N}\}$.

Remark 2.2. (i) Condition (2.1) implies that for any $i \geq s_k$, it is valid that

$$G_p\left(T^{s_k}x, T^{s_k}x, T^{i}x\right) \le \max\left\{\alpha G_p\left(T^{s_{k-1}}x, T^{s_{k-1}}x, T^{j}x\right), G_p\left(T^{s_{k-1}}x, T^{s_{k-1}}x, T^{s_{k-1}}x\right)\right\},\tag{2.2}$$

where $j = i - s_k + s_{k-1} \ge s_{k-1}$, and specially that

$$G_n(T^{s_k}x, T^{s_k}x, T^{s_k}x) \le G_n(T^{s_{k-1}}x, T^{s_{k-1}}x, T^{s_{k-1}}x). \tag{2.3}$$

Now, fix $x \in X \setminus J_T(X)$. For $k \in \mathbb{N}$ and $i \geq s_k$ use (2.2), repeatedly fix integers $l_j \geq s_j$, $0 \leq j < k$ and $t_1, t_2, ..., t_k \in \{0, 1\}$ such that $l_k := i$, then

$$G_p(T^{s_j}x, T^{s_j}x, T^{l_j}x) \le \alpha^{t_j} \cdot G_p(T^{s_{j-1}}x, T^{s_{j-1}}x, T^{l_{j-1}}x)$$

for all $0 \le j \le k$, where

$$t_j = \begin{cases} 1, & \text{if } s_{j-1} < l_{j-1}, \\ 0, & \text{if } s_{j-1} = l_{j-1}. \end{cases}$$

Let us recall $(l_0, l_1, ..., l_{k-1})$ and $(t_1, t_2, ..., t_k)$ as the (k, l)-descent and (k, i)-signature at x, respectively.

Further put $r_{k,i} =: k - h_{k,i}$, where $h_{k,i}$ is a number of zeroes in (k,i)-signature at x.

We shall say that x is Type 1 if there are sequences of positive integers $\{k_m\}_{m\in\mathbb{N}\cup\{0\}}$ and $\{i_m\}_{m\in\mathbb{N}\cup\{0\}}$, one of them is strictly increasing such that for all $m\in\mathbb{N}\cup\{0\}$ we have that $i_m\geq s_m$ and $r_{k_m,i_m}< r_{k_{m+1},i_{m+1}}$.

We shall say that x is Type 2 if x is not Type 1, i.e., there are $k_0, B \in \mathbb{N}$ such that for all $k \geq k_0$ and $i \geq s_k$ it holds $r_{k,i} < B$.

(ii) In the framework of G-metric spaces, condition (2.1) becomes

$$G_p\left(T^{n(x)}x, T^{n(x)}x, T^{n(x)}y\right) \le \alpha G_p\left(x, x, y\right),\tag{2.3'}$$

hence, it is iterate contractive condition of Sehgal-Guseman type in this framework (see [11], [16]).

Lemma 2.3. Let T be an NLC-operator on G_p -metric space (X, G_p) , $x \notin J_T(X)$, and let $\{s_k\}_{k\in\mathbb{N}\cup\{0\}}$ be a supporting sequence at x. Then

(a) if $(l_0, l_1, ..., l_{k-1})$ is (k, i_0) -descent at x, then

$$G_p\left(T^{s_k}x, T^{s_k}x, T^{i_0}x\right) \le \alpha^{r_{k,i_0}} \cdot G_p\left(x, x, T^{l_0}x\right),$$

$$G_p\left(T^{s_k}x, T^{s_k}x, T^{i_0}x\right) \le G_p\left(T^{s_j}x, T^{s_j}x, T^{l_j}x\right)$$

for all $0 \le j \le k$, where $l_k := i_0$;

(b) if $P \subseteq \{0, 1, ..., k-1\}$ and $r_{k,i_0} < \text{card}P$ (card P is the number of elements of P), then for some $j_0 \in P$ it holds

$$G_p(T^{s_k}x, T^{s_k}x, T^{i_0}x) \le G_p(T^{s_{j_0}}x, T^{s_{j_0}}x, T^{s_{j_0}}x).$$

Proof. Using the definition of $r_{k,i}$, (a) is obvious. To prove (b), under the hypothesis, the set $\{j+1: j \in P\}$ is subset of $\{1,2,...,k\}$ with $\operatorname{card}(P) > r_{k,i_0}$, so there is some $j_0 \in P$ with $t_{j_0+1} = 0$. Then

$$G_{p}\left(T^{s_{j_{0}+1}}x, T^{s_{j_{0}+1}}x, T^{i_{0}}x\right) \leq G_{p}\left(T^{l_{j_{0}+1}}x, T^{l_{j_{0}+1}}x, T^{i_{0}+1}x\right)$$

$$\leq \alpha^{t_{j_{0}}+1}G_{p}\left(T^{s_{j_{0}}}x, T^{s_{j_{0}}}x, T^{l_{j_{0}}}x\right)$$

$$= G_{p}\left(T^{s_{j_{0}}}x, T^{s_{j_{0}}}x, T^{s_{j_{0}}}x\right),$$

whereof (a) and $s_{j_0} = l_{j_0}$ have been used.

Lemma 2.4. Let T be an NLC-operator on G_p -metric space (X, G_p) and $x \in X$, then there is some $M_x > 0$ such that for all $i \geq 0$ it satisfies that

$$G_p\left(x, x, T^i x\right) \le M_x,\tag{2.4}$$

and so $G_p(T^jx, T^jx, T^ix) \leq 3M_x$, for each $i, j \in \mathbb{N} \cup \{0\}$.

Proof. If $x \in J_T(X)$, then this is obvious. Thus, let $x \notin J_T(X)$ and set

$$b(x) = G_p(x, x, x) + G_p(x, x, Tx) + \dots + G_p(x, x, T^{n(x)}x).$$

Let us prove by induction that

$$G_p\left(x, x, T^i x\right) \leq \frac{1}{1-\alpha} b\left(x\right), \text{ for all } i \in \mathbb{N}.$$

Obviously (2.4) is true for $0 \le k \le n(x)$. Now assume that the same is valid for some $k \ge n(x)$. Then

$$G_{p}\left(x, x, T^{k+1}x\right) \leq G_{p}\left(x, x, T^{n(x)}x\right) + G_{p}\left(T^{n(x)}x, T^{n(x)}x, T^{k+1}x\right)$$

$$\leq G_{p}\left(x, x, T^{n(x)}x\right) + \max\left\{\alpha G_{p}\left(x, x, T^{k+1-n(x)}x\right), G_{p}\left(x, x, x\right)\right\}$$

$$\leq G_{p}\left(x, x, T^{n(x)}x\right) + G_{p}\left(x, x, x\right) + \frac{\alpha}{1-\alpha}b\left(x\right)$$

$$\leq b\left(x\right) + \frac{\alpha}{1-\alpha}b\left(x\right)$$

$$= \frac{1}{1-\alpha}b\left(x\right),$$

so (2.4) is proved with $M_x = \frac{1}{1-\alpha}b(x)$.

Further, we have

$$G_p(T^i x, T^j x, T^j x) \le G_p(T^i x, x, x) + 2G_p(T^j x, x, x) \le 3M_x,$$

for all $i, j \in \mathbb{N} \cup \{0\}$.

Lemma 2.5. Let T be an NLC-operator on G_p -metric space (X, G_p) and $x \in X \setminus J_T(X)$. If x is Type 1, then $\lim_{i,j\to\infty} G_p(T^ix, T^ix, T^jx) = 0$.

Proof. Fix $m \in \mathbb{N} \cup \{0\}$. If $(l_0, ..., l_{k_m-1})$ is (s_{k_m}, i_m) -descent, then by (a) of Lemma 2.3 we have

$$G_p\left(T^{s_{k_m}}x, T^{s_{k_m}}x, T^{i_m}x\right) \le \alpha^{r_{k_m}, i_m} \cdot G_p\left(x, x, T^{l_0}x\right) \le \alpha^{r_{k_m}, i_m} M_x.$$

In view of $\lim_{m\to\infty} r_{k_m,i_m} = \infty$, it follows that

$$\lim_{m \to \infty} G_p \left(T^{s_{k_m}} x, T^{s_{k_m}} x, T^{i_m} x \right) = \lim_{m \to \infty} G_p \left(T^{s_{k_m}} x, T^{s_{k_m}} x, T^{s_{k_m}} x \right) = 0.$$

For given $\varepsilon > 0$, choose $m_0 \in \mathbb{N}$ such that $\alpha^{m_0} M_x < \varepsilon$ and $G_p(T^{s_{k_m}} x, T^{s_{k_m}} x, T^{s_{k_m}} x) < \varepsilon$ for all $m \ge m_0$. Let $r_{k_{2m_0},i} \ge m_0$. Then

$$G_p(T^{s_{k_{2m_0}}}x, T^{s_{k_{2m_0}}}x, T^ix) \le \alpha^{r_{k_{2m_0},i}} \cdot M_x \le \alpha^{m_0}M_x < \varepsilon.$$

Now suppose that $r_{k_{2m_0},i} < m_0$. For $P_i = \{k_{m_0}, ..., k_{2m_0-1}\} \subseteq \{0, 1, ..., k_{2m_0} - 1\}$, we have card $(P) > r_{k_{2m_0},i}$, so by Lemma 2.3, there exists some $m_0 \le j \le 2m_0 - 1$ such that

$$G_p(T^{s_{k_2m_0}}x, T^{s_{k_2m_0}}x, T^ix) \le G_p(T^{s_{k_j}}x, T^{s_{k_j}}x, T^{s_{k_j}}x,) < \varepsilon$$

for each $i \geq s_{k_{2m_0}}$.

Accordingly, if $i, j \geq s_{k_{2m_0}}$, then

$$G_{p}\left(T^{i}x, T^{i}x, T^{j}x\right) \leq G_{p}\left(T^{s_{k_{2}m_{0}}}x, T^{s_{k_{2}m_{0}}}x, T^{j}x\right) + G_{p}\left(T^{i}x, T^{i}x, T^{s_{k_{2}m_{0}}}\right)$$

$$\leq G_{p}\left(T^{s_{k_{2}m_{0}}}x, T^{s_{k_{2}m_{0}}}x, T^{j}x\right) + 2G_{p}\left(T^{i}x, T^{s_{k_{2}m_{0}}}x, T^{s_{k_{2}m_{0}}}x\right)$$

$$< 3\varepsilon.$$

Therefore, we prove that $\lim_{i,j\to\infty} G_p\left(T^ix,T^ix,T^jx\right)=0$.

Lemma 2.6. Let T be an NLC-operator and $x \in X \setminus J_T(X)$. If x is Type 2, then the sequence $\{T^i x\}_{i \in \mathbb{N} \cup \{0\}}$ is G_p -Cauchy.

Proof. By (2.3), it is easy to see that $\{G_p(T^{s_k}x, T^{s_k}x, T^{s_k}x)\}_{k\in\mathbb{N}\cup\{0\}}$ is a nonincreasing sequence, where $\{s_k\}_{k\in\mathbb{N}\cup\{0\}}$ is a supporting sequence at x. Then there exists

$$r_x := \lim_{k} G_p\left(T^{s_k}x, T^{s_k}x, T^{s_k}x\right) = \inf_{k} \left\{ G_p\left(T^{s_k}x, T^{s_k}x, T^{s_k}x\right) \right\}$$

such that it is finite.

At first let us prove that for any $\varepsilon > 0$, there exists $m_0 \in \mathbb{N}$ such that for all $m \geq m_0$ and $i \geq s_m$, one has

$$G_p\left(T^{s_m}x, T^{s_m}x, T^ix\right) \in (r_x - \varepsilon, r_x + \varepsilon).$$
 (2.5)

Since x is Type 2 there are $k_0, B \in \mathbb{N}$ such that for all $k \geq k_0$ and all $i \geq s_k$, there holds $r_{k,i} < B$. Let $\varepsilon > 0$, take $m_1 \geq k_0$ such that for all $m \geq m_1$,

$$G_p(T^{s_m}x, T^{s_m}x, T^{s_m}x) \in (r_x - \varepsilon, r_x + \varepsilon). \tag{2.6}$$

Let $m \ge m_1 + B$ and $i \ge s_m$ be arbitrary. For $P = \{m_1, ..., m_1 + B - 1\} \subseteq \{0, 1, ..., m - 1\}$, we have $\operatorname{card} P \ge B > r_{m,i}$, then there exists $m_1 \le j \le m_1 + B - 1$ such that

$$r_x - \varepsilon < G_p\left(T^{s_m}x, T^{s_m}x, T^{s_m}x, T^{s_m}x\right) \le G_p\left(T^{s_m}x, T^{s_m}x, T^ix\right) \le G_p\left(T^{s_j}x, T^{s_j}x, T^{s_j}x\right) < r_x + \varepsilon.$$

So we get (2.5).

Now let us prove that for any $\varepsilon > 0$, there is $k^* \in \mathbb{N}$ such that for all $i, j \geq k^*$,

$$G_p\left(T^i x, T^i x, T^j x\right) < r_x + \varepsilon.$$
 (2.7)

Indeed, for any $\varepsilon > 0$, consider m_0 as in (2.5) and let $i, j \geq s_{m_0}$ be arbitrary. Then

$$G_{p}\left(T^{i}x, T^{i}x, T^{j}x\right) \leq G_{p}\left(T^{s_{m_{0}}}x, T^{s_{m_{0}}}x, T^{j}x\right) + G_{p}\left(T^{i}x, T^{i}x, T^{s_{m_{0}}}x\right) - G_{p}\left(T^{s_{m_{0}}}x, T^{s_{m_{0}}}x, T^{s_{m_{0}}}x\right) < r_{x} + \varepsilon + 2G_{p}\left(T^{s_{m_{0}}}x, T^{s_{m_{0}}}x, T^{i}x\right) - 2G_{p}\left(T^{s_{m_{0}}}x, T^{s_{m_{0}}}x, T^{s_{m_{0}}}x\right) < r_{x} + \varepsilon + 2\left(r_{x} + \varepsilon\right) - 2\left(r_{x} - \varepsilon\right) = r_{x} + 5\varepsilon.$$

To prove $\lim_{i,j\to\infty} G_p\left(T^ix,T^ix,T^jx\right)=r_x$, we only need to show that for any $\varepsilon>0$, there exists $\widetilde{k}\in\mathbb{N}$ such that for all $i\geq\widetilde{k}$, ones always have

$$r_x - \varepsilon < G_p \left(T^i x, T^i x, T^j x \right). \tag{2.8}$$

Suppose on the contrary, that for any k there is some $i_0 \geq k$ satisfying

$$G_p\left(T^{i_0}x, T^{i_0}x, T^{i_0}x\right) \le r_x - \varepsilon.$$

Put $z := T^{i_0}x$. Obviously, $x \notin J_T(X)$ implies that $z \notin J_T(X)$. If z is Type 1, then by Lemma 2.5 it follows that

$$0 = \lim_{i,j} G_p\left(T^i z, T^i z, T^j z\right) = \lim_{i,j} G_p\left(T^i x, T^i x, T^j x\right) = r_x,$$

so $\{T^ix\}_{i\in\mathbb{N}\cup\{0\}}$ is 0-Cauchy sequence.

Now suppose that z is Type 2, and let $\{q_m\}_{m\in\mathbb{N}\cup\{0\}}$ be a supporting sequence at z. Then, for each $m\in\mathbb{N}\cup\{0\}$,

$$G_p(T^{q_m}z, T^{q_m}z, T^{q_m}z) \le G_p(z, z, z) \le r_x - \varepsilon,$$

SO

$$r_z = \lim_{m} G_p\left(T^{q_m}z, T^{q_m}z, T^{q_m}z\right) \le r_x - \varepsilon.$$

Note that $r_z < \frac{r_x + r_z}{2}$, then for $j_0 \in \mathbb{N}$, one obtain that

$$G_p\left(T^jz, T^jz, T^jz\right) < \frac{r_x + r_z}{2}$$
, for all $j \ge j_0$.

As $\lim_{m\to\infty} G_p(T^{s_m}x,T^{s_m}x,T^{s_m}x)=r_x$, then there is some $m\geq i_0+j_0$ such that

$$G_p\left(T^jx, T^jx, T^jx\right) > \frac{r_x + r_z}{2},$$

which is impossible, so (2.8) is satisfied. Now, for $s_m - i_0 \ge m - i_0 \ge j_0$, we claim that

$$\frac{r_x + r_z}{2} < G_p\left(T^{s_m}x, T^{s_m}x, T^{s_m}x\right) = G_p\left(T^{s_m - i_0}x, T^{s_m - i_0}x, T^{s_m - i_0}x\right) < \frac{r_x + r_z}{2}.$$

In the end, from

$$r_x - \varepsilon < G_p\left(T^i x, T^i x, T^i x\right) \le G_p\left(T^i x, T^i x, T^j x\right),$$

it follows that $\{T^i x\}_{i \in \mathbb{N} \cup \{0\}}$ is a G_p -Cauchy sequence.

Lemma 2.7. Let $T: X \to X$ be an operator on G_p -metric space (X, G_p) . Suppose that $x \in X$ is a point such that $T^k x = x$ holds for some positive integer k, and there is $y \in X$ such that

$$G_p(y, y, y) = \lim_i G_p(y, T^i x, T^i x) = \lim_{i,j} G_p(T^i x, T^i x, T^j x),$$
 (2.9)

then Tx = x.

Proof. Since $T^{k \cdot i} x = x$, then for any $i \in \mathbb{N} \cup \{0\}$, we have that

$$G_p(y, y, y) = \lim_{i} G_p(y, T^{ki}x, T^{ki}x) = G_p(y, x, x)$$

and

$$G_{p}\left(y,y,y\right) = \lim_{i} G_{p}\left(T^{ki}x, T^{ki}x, T^{ki}x\right) = G_{p}\left(x, x, x\right),$$

so y = x. Now (2.9) implies that

$$G_p(x, x, x) = \lim_{i} G_p(x, T^{ki+1}x, T^{ki+1}x) = G_p(x, Tx, Tx)$$

and

$$G_p(x, x, x) = \lim_{i} G_p(T^{ki+1}x, T^{ki+1}x, T^{ki+1}x) = G_p(Tx, Tx, Tx).$$

Thus, Tx = x.

3 Main results

Both results in this section generalize many existing results in the literature (see [12, Theorem 3.1] and [4, Lemmas 3.-5, Theorems 1 and 2]). Firstly, we announce our first result for NLC-operator in G_p -complete G_p -metric space as follows.

Proposition 3.1. Let T be an NLC-operator on G_p -complete G_p -metric space (X, G_p) , then

- (1) for each $x \in X$, the sequence $\{T^i x\}_{i \in \mathbb{N} \cup \{0\}}$ G_p -converges to some $v_x \in X$;
- (2) for all $x, y \in X$, one has

$$G_p(v_y, v_y, v_x) = \max \{G_p(v_x, v_x, v_x), G_p(v_y, v_y, v_y)\}.$$

Proof. Since (X, G_p) is G_p -complete, then for each $x \in X$, the existence of v_x is assured by Lemma 2.5 and Lemma 2.6. Let us prove (2). Let $x, y \in X$ and $G_p(v_y, v_y, v_y) \ge G_p(v_x, v_x, v_x)$. If $G_p(v_y, v_y, v_y) = 0$, then $v_x = v_y$ and the claim is clear. Thus, assume that $G_p(v_y, v_y, v_y) > 0$.

For any $0 < \varepsilon < \frac{1-\alpha}{2(1+\alpha)}G_p(v_y, v_y, v_y)$, there is some $m_0 \in \mathbb{N}$ such that for all $i, j \geq m_0$, we have

$$\max\{G_p(T^iy, v_y, v_y) - G_p(T^iy, T^iy, T^iy), |G_p(T^iy, T^iy, T^iy) - G_p(v_y, v_y, v_y)|, G_p(T^iy, T^iy, v_y) - G_p(v_y, v_y, v_y)\} < \varepsilon$$

and

$$\max\left\{G_{p}\left(v_{x},v_{x},T^{j}x\right)-G_{p}\left(v_{x},v_{x},v_{x}\right),G_{p}\left(v_{x},T^{j}x,T^{j}x\right)-G_{p}\left(T^{j}x,T^{j}x,T^{j}x\right)\right\}<\varepsilon.$$

For $i, j \geq m_0$, we have

$$G_p\left(T^iy, T^iy, T^ix\right) \le G_p\left(T^iy, T^iy, v_y\right) - G_p\left(v_y, v_y, v_y\right)$$

$$+ G_p\left(v_y, v_y, v_x\right) + G_p\left(v_x, v_x, T^ix\right) - G_p\left(v_x, v_x, v_x\right)$$

$$< 2\varepsilon + G_p\left(v_y, v_y, v_x\right)$$

and

$$G_{p}(v_{y}, v_{y}, v_{x}) \leq G_{p}(v_{y}, v_{y}, T^{i}y) - G_{p}(T^{i}y, T^{i}y, T^{i}y) + G_{p}(v_{x}, T^{j}x, T^{j}x)$$
$$-G_{p}(T^{j}y, T^{j}y, T^{j}y) + G_{p}(T^{i}y, T^{i}y, T^{j}y)$$
$$< 2\varepsilon + G_{p}(T^{i}y, T^{i}y, T^{j}x).$$

For any $i_0 \geq m_0$ and $i_1 := n(T^{i_0}y)$, we get

$$\begin{split} G_{p}\left(v_{y}, v_{y}, v_{x}\right) - 2\varepsilon &\leq G_{p}\left(T^{i_{0}+i_{1}}y, T^{i_{0}+i_{1}}y, T^{i_{0}+i_{1}}x\right) \\ &\leq \max\left\{\alpha G_{p}\left(T^{i_{0}}y, T^{i_{0}}y, T^{i_{0}}x\right), G_{p}\left(T^{i_{0}}y, T^{i_{0}}y, T^{i_{0}}y\right)\right\} \\ &< \max\left\{\alpha \left(2\varepsilon + G_{p}\left(v_{y}, v_{y}, v_{x}\right), \varepsilon + G_{p}\left(v_{y}, v_{y}, v_{y}\right)\right)\right\}. \end{split}$$

If

$$G_p(v_y, v_y, v_x) - 2\varepsilon < 2\alpha\varepsilon + \alpha G_p(v_y, v_y, v_x),$$

then

$$G_p(v_y, v_y, v_x) < 2\varepsilon (1 + \alpha) < G_p(v_y, v_y, v_x)$$
.

This is a contradiction. As a consequence, we deduce that

$$G_p(v_y, v_y, v_x) < 3\varepsilon + G_p(v_y, v_y, v_y),$$

so

$$G_p(v_y, v_y, v_x) \leq G_p(v_y, v_y, v_y)$$
.

Finally, by (G_p2) , we speculate that

$$G_{p}\left(v_{y},v_{y},v_{x}\right)=G_{p}\left(v_{y},v_{y},v_{x}\right)=\max\left\{ G_{p}\left(v_{x},v_{x},v_{x}\right),G_{p}\left(v_{y},v_{y},v_{y}\right)\right\} .$$

Now, we announce our second result in the framework of G_p -complete G_p -metric spaces. **Theorem 3.2.** Let T be an NLC-opertor on G_p -complete G_p -metric space (X, G_p) , then there is a fixed point $z \in X$ of T such that $G_p(z, z, z) = \inf \{G_p(v_x, v_x, v_x) : x \in X\}$.

Proof. For $x \in X$, put $r_x := G_p(v_x, v_x, v_x) = \lim_{k \to \infty} G_p(T^{s_k}x, T^{s_k}x, T^{s_k}x)$ for $\{s_k\}_{k \in \mathbb{N} \cup \{0\}}$ which is the supporting sequence at x. Let $I := \inf\{r_x : x \in X\}$. For $m \ge 1$, take $x_m \in X$ such that for all $i, j \in \mathbb{N} \cup \{0\}$, it holds

$$G_p\left(Tx_m^i, Tx_m^i, Tx_m^j\right) \in \left(I - \frac{1}{m}, I + \frac{1}{m}\right). \tag{3.1}$$

At first we shall prove that $\lim_{m,k\to\infty} G_p(x_m,x_m,x_k)=I$. For $m,k\geq 2$, let $C_{m,k}>0$ and

$$G_p\left(T^jx_m, T^jx_m, T^ix_k\right) < C_{m,k}, \quad i, j \in \mathbb{N} \cup \{0\}.$$

Fix $m, k \geq 2$ and let $\{s_q\}_{q \in \mathbb{N} \cup \{0\}}$ be the supporting sequence at x_m and let $l \geq 1$ be an integer such that $\alpha^l \cdot C_{m,k} < \frac{1}{k+m}$. Then

$$G_{p}(x_{m}, x_{m}, x_{k})$$

$$\leq G_{p}(x_{m}, x_{m}, T^{s_{l}}x_{m}) - G_{p}(T^{s_{l}}x_{m}, T^{s_{l}}x_{m}, T^{s_{l}}x_{m}) + G_{p}(T^{s_{l}}x_{m}, T^{s_{l}}x_{m}, x_{k})$$

$$\leq G_{p}(x_{m}, x_{m}, T^{s_{l}}x_{m}) - G_{p}(T^{s_{l}}x_{m}, T^{s_{l}}x_{m}, T^{s_{l}}x_{m})$$

$$+ G_{p}(x_{k}, T^{s_{l}}x_{k}, T^{s_{l}}x_{k}) - G_{p}(T^{s_{l}}x_{k}, T^{s_{l}}x_{k}, T^{s_{l}}x_{k}) + G_{p}(T^{s_{l}}x_{m}, T^{s_{l}}x_{m}, T^{s_{l}}x_{k}).$$

Denote

$$A_{m,k} := G_p(x_m, x_m, T^{s_l}x_m) - G_p(T^{s_l}x_m, T^{s_l}x_m, T^{s_l}x_m) < \frac{2}{m},$$

$$D_{m,k} := G_p(x_k, T^{s_l}x_k, T^{s_l}x_k) - G_p(T^{s_l}x_k, T^{s_l}x_k, T^{s_l}x_k) < \frac{2}{k}.$$

At first, assume that

$$G_p(T^{s_l}x_m, T^{s_l}x_m, T^{s_l}x_k) > G_p(T^ix_m, T^ix_m, T^ix_m)$$
 for all $i \in \{0, 1, ..., s_l\}$.

Then by (1.2), it is clear that

$$G_{p}\left(T^{s_{j-1}}x_{m}, T^{s_{l-1}}x_{m}, T^{s_{l-1}}x_{k}\right) \leq \alpha G_{p}\left(T^{s_{l}}x_{m}, T^{s_{l}}x_{m}, T^{s_{l}}x_{k}\right)$$

$$\leq \alpha^{2} G_{p}\left(T^{s_{l-2}}x_{m}, T^{s_{l-2}}x_{m}, T^{s_{l-2}}x_{k}\right) \leq \dots$$

$$\leq \alpha^{l} G_{p}\left(x_{m}, x_{m}, x_{k}\right) \leq \alpha^{l} \cdot C_{m,k} < \frac{1}{k+n}.$$

If $G_p(T^{s_l}x_m, T^{s_l}x_m, T^{s_l}x_k) \leq G_p(T^ix_m, T^ix_m, T^ix_k)$ for some $i \in \{0, ..., s_l\}$, then by (3.1), $G_p(T^{s_l}x_m, T^{s_l}x_m, T^{s_l}x_k) < I + \frac{1}{m}$, so

$$G_p(x_m, x_m, x_k) \le A_{m,k} + D_{m,k} + G_p(T^{s_l}x_m, T^{s_l}x_m, T^{s_l}x_k)$$

 $< \frac{2}{m} + \frac{2}{k} + I + \frac{1}{m}.$

From the above consideration and

$$I - \frac{1}{m} < G_p(x_m, x_m, x_m) \le G_p(x_m, x_m, x_k),$$

it follows that

$$\lim_{m,k\to\infty} G_p\left(x_m,x_m,x_m\right) = I.$$

Now that (X, G_p) is G_p -complete, there is some $u \in X$ such that

$$I = \lim_{m,k \to \infty} G_p\left(x_m, x_m, x_k\right) = \lim_{m \to \infty} G_p\left(x_m, x_m, u\right) = \lim_{m \to \infty} G_p\left(x_m, u, u\right) = G_p\left(u, u, u\right).$$

It is easy to see that

$$G_{p}\left(T^{n(u)}u, T^{n(u)}u, T^{n(u)}u\right) = G_{p}\left(u, u, u\right) = I.$$

Now we shall prove that $T^{n(u)}u = u$.

From

$$I = G_{p}(u, u, u) \leq G_{p}(u, u, T^{j}x_{m})$$

$$\leq G_{p}(u, u, x_{m}) + G_{p}(x_{m}, x_{m}, T^{j}x_{m}) - G_{p}(x_{m}, x_{m}, x_{m})$$

$$\leq G_{p}(u, u, x_{m}) + I + \frac{1}{m} - \left(I - \frac{1}{m}\right)$$

$$= G_{p}(u, u, x_{m}) + \frac{2}{m},$$

it means that

$$\lim_{m \to \infty} G_p\left(u, u, T^j x_m\right) = I, \quad j \in \mathbb{N}.$$

On the other hand,

$$I = G_p \left(T^{n(u)} u, T^{n(u)} u, T^{n(u)} u \right) \le G_p \left(T^{n(u)} u, T^{n(u)} u, T^{n(u)} x_m \right)$$

$$< \max \left\{ \alpha G_p \left(u, u, x_m \right), G_p \left(u, u, u \right) \right\},$$

which implies that

$$\lim_{m \to \infty} G_p\left(T^{n(u)}u, T^{n(u)}u, T^{n(u)}x_m\right) = I.$$

Now that

$$I \leq G_{p}\left(u, T^{n(u)}u, T^{n(u)}u\right)$$

$$\leq G_{p}\left(u, T^{n(u)}x_{m}, T^{n(u)}x_{m}\right) + G_{p}\left(T^{n(u)}u, T^{n(u)}u, T^{n(u)}x_{m}\right)$$

$$- G_{p}\left(T^{n(u)}x_{m}, T^{n(u)}x_{m}, T^{n(u)}x_{m}\right)$$

$$\leq 2G_{p}\left(u, u, T^{n(u)}, x_{m}\right) - G_{p}\left(u, u, u\right) + G_{p}\left(T^{n(u)}u, T^{n(u)}u, T^{n(u)}x_{m}\right) - I + \frac{1}{m}$$

$$\to I, \text{ as } m \to \infty,$$

SO

$$G_p(u, T^{n(u)}u, T^{n(u)}u) = I = G_p(u, u, u) = G_p(T^{n(u)}u, T^{n(u)}u, T^{n(u)}u),$$

and $T^{n(u)}u = u$. Finally, by utilizing Lemma 2.7, the remaining proof is valid.

4 Some examples

Now, we give four examples to support our theoretical approach.

Example 4.1. Let $X = \{0, 1, 2\}$ be a set and $G_p: X^3 \to [0, +\infty)$ a mapping satisfying

$$G_{p}(x, x, x) = \frac{1}{2} \text{ for all } x \in X,$$

$$G_{p}(0, 0, 1) = G_{p}(0, 1, 0) = G_{p}(1, 0, 0) = 1,$$

$$G_{p}(0, 1, 1) = G_{p}(1, 0, 1) = G_{p}(1, 1, 0) = 1,$$

$$G_{p}(1, 2, 2) = G_{p}(2, 1, 2) = G_{p}(2, 2, 1) = 3,$$

$$G_{p}(0, 0, 2) = G_{p}(0, 2, 0) = G_{p}(2, 0, 0) = 3,$$

$$G_{p}(0, 2, 2) = G_{p}(2, 0, 2) = G_{p}(2, 2, 0) = 3,$$

$$G_{p}(1, 1, 2) = G_{p}(1, 2, 1) = G_{p}(2, 1, 1) = 3.1,$$

$$G_{p}(0, 1, 2) = G_{p}(0, 2, 1) = G_{p}(1, 0, 2) = 3.2.$$

Then G_p is an asymmetric G_p -metric as $G_p(1,2,2) \neq G_p(1,1,2)$. Further, (X,G_p) is a G_p -metric space in the sense of [18]. Let $T:X\to X$ be defined by T0=T1=0,T2=1. We shall prove that T is an NLC-operator where $\alpha=\frac{1}{2}$, while n(x)=1 for all $x\in X$. Indeed, we need to check

$$G_p(Tx, Tx, Ty) \le \max \left\{ \frac{1}{2} G_p(x, x, y), G_p(x, x, x) \right\}$$

$$(4.1)$$

for all $x, y \in X$ into nine cases as follows:

$$(1) \quad x = 0, \ y = 0 \Longrightarrow \frac{1}{2} = G_p(T0, T0, T0) \le \max \left\{ \frac{1}{2} G_p(0, 0, 0), G_p(0, 0, 0) \right\} = \frac{1}{2},$$

$$(2) \quad x = 0, \ y = 1 \Longrightarrow \frac{1}{2} = G_p(T0, T0, T1) \le \max \left\{ \frac{1}{2} G_p(0, 0, 1), G_p(0, 0, 0) \right\} = \frac{1}{2},$$

$$(3) \quad x = 0, \ y = 2 \Longrightarrow 1 = G_p(T0, T0, T2) \le \max \left\{ \frac{1}{2} G_p(0, 0, 2), G_p(0, 0, 0) \right\} = \frac{3}{2},$$

$$(4) \quad x = 1, \ y = 0 \Longrightarrow \frac{1}{2} = G_p(T1, T1, T0) \le \max \left\{ \frac{1}{2} G_p(1, 1, 0), G_p(1, 1, 1) \right\} = \frac{1}{2},$$

$$(5) \quad x = 1, \ y = 1 \Longrightarrow \frac{1}{2} = G_p(T1, T1, T1) \le \max \left\{ \frac{1}{2} G_p(1, 1, 1), G_p(1, 1, 1) \right\} = \frac{1}{2},$$

$$(6) \quad x = 1, \ y = 2 \Longrightarrow 1 = G_p(T1, T1, T2) \le \max \left\{ \frac{1}{2} G_p(1, 1, 2), G_p(1, 1, 1) \right\} = \frac{3.1}{2},$$

$$(7) \quad x = 2, \ y = 0 \Longrightarrow 1 = G_p(T2, T2, T0) \le \max \left\{ \frac{1}{2} G_p(2, 2, 0), G_p(2, 2, 2) \right\} = \frac{3}{2},$$

$$(8) \quad x = 2, \ y = 1 \Longrightarrow 1 = G_p(T2, T2, T1) \le \max \left\{ \frac{1}{2} G_p(2, 2, 1), G_p(2, 2, 2) \right\} = \frac{3}{2},$$

$$(9) \quad x = 2, \ y = 2 \Longrightarrow \frac{1}{2} = G_p(T2, T2, T2) \le \max \left\{ \frac{1}{2} G_p(2, 2, 2), G_p(2, 2, 2) \right\} = \frac{1}{2}.$$

Hence all cases show that (4.1) is satisfied and then both Proposition 3.1 and Theorem 3.2 are true.

Example 4.2. Let (X, G_p) be a G_p -metric space where $X = [0, +\infty)$ and $G_p(x, y, z) = \max\{x, y, x\}$. Define $T: X \to X$ by $Tx = \frac{x^2}{3(1+x)}$. We shall prove that T is an NLC-operator, that is, for each $x \in X$, there is n(x) such that for each $y \in X$,

$$G_p\left(T^{n(x)}x, T^{n(x)}x, T^{n(x)}y\right) \le \max\left\{\alpha G_p\left(x, x, y\right), G_p\left(x, x, x\right)\right\},$$

where $\alpha \in (0,1)$. Let $\alpha = \frac{1}{3}$. It is easy to see that n(x) = 1. Indeed, we shall check that

$$\max \left\{ \frac{x^2}{3(1+x)}, \frac{x^2}{3(1+x)}, \frac{y^2}{3(1+y)} \right\} \le \max \left\{ \frac{1}{3} \max \left\{ x, x, y \right\}, \max \left\{ x, x, x \right\} \right\}, \quad (4.2)$$

for all $x, y \in [0, +\infty)$.

Consider the following three possible cases.

(i) $y \le x$. In this case (4.2) becomes:

$$\frac{x^2}{3(1+x)} \le \max\left\{\frac{1}{3}x, x\right\} = x,\tag{4.3}$$

which is true for any $x \in [0, +\infty)$.

(ii) $\frac{y}{3} \le x \le y$. In this case (4.2) becomes:

$$\frac{y^2}{3(1+y)} \le \max\left\{\frac{1}{3}y, x\right\} = x. \tag{4.4}$$

By virtue of $\frac{y^2}{3(1+y)} = \frac{y}{1+y} \cdot \frac{y}{3} \le \frac{y}{3} \le x$, it follows that (4.4) holds.

(iii) $0 \le x \le \frac{y}{3}$. Because of $x \le y$, (4.2) becomes:

$$\frac{y^2}{3(1+y)} \le \max\left\{\frac{1}{3}y, x\right\} = \frac{1}{3}y. \tag{4.5}$$

Obviously, (4.5) holds for each $y \in [0, +\infty)$.

Hence, (4.2) holds for all $x, y \in [0, +\infty)$, that is., all the conditions of Proposition 3.1 and Theorem 3.2 are satisfied and T has a fixed point (which is x = 0).

Example 4.3. Let $X = \{a, b\}$ be a set with G_p -metric defined by

$$G_p(a, a, a) = 0$$
, $G_p(a, a, b) = G_p(a, b, a) = G_p(b, a, a) = 1$,
 $G_p(b, b, b) = G_p(a, b, b) = G_p(b, a, b) = G_p(b, b, a) = 2$.

Since $G_p(a, a, b) \neq G_p(a, b, b)$, we get that (X, G_p) is an asymmetric G_p -metric space. Also, we have that for all $x, y \in X$,

$$d_{G_p}(x,y) = G_p(x,x,y) + G_p(x,y,y) - G_p(x,x,x) - G_p(y,y,y) = \begin{cases} 1, & x \neq y, \\ 0, & x = y, \end{cases}$$

is a (standard) metric on X.

Example 4.4. Let $X = \{a, b\}$ be a set with G_p -metric defined by

$$G_p(a, a, a) = 0$$
, $G_p(a, a, b) = G_p(a, b, a) = G_p(b, a, a) = 1 = G_p(b, b, b)$,
 $G_p(a, b, b) = G_p(b, a, b) = G_p(b, b, a) = 2$.

It ensures us that the sequence $\{x_n = a\}$ converges to a. However, conditions (2) and (3) of Proposition 1.8 are not equivalent. Indeed,

$$G_p(x_n, x_n, b) = G_p(a, a, b) \rightarrow G_p(b, b, b) \quad (n \rightarrow \infty),$$

while

$$G_p(x_n, b, b) = G_p(a, b, b) \nrightarrow G_p(b, b, b) \quad (n \to \infty).$$

Thus, $G_p(\cdot,\cdot,\cdot)$ may not be continuous in the sense that $x_n \to x$, $y_n \to y$ and $z_n \to z$ implies $G_p(x_n,y_n,z_n) \to G_p(x,y,z)$. In fact, we take $x_n = y_n = a$ and $z_n = b$ for all $n \in \mathbb{N}$. Further, it is easy to check that $x_n \to b$, $y_n \to a$ and $z_n \to b$ but $G_p(x_n,y_n,z_n) \to G_p(b,a,b)$, this is because $G_p(x_n,y_n,z_n) = G_p(a,a,b) = 1 \neq 2 = G_p(b,a,b)$.

Acknowledgements

The research is partially supported by the National Natural Science Foundation of China (11271045). It is also supported by Ministry of Science and Technology Development Republic of Serbia for the second and third author.

References

- [1] M. Abbas, T. Nazir, P. Vetro, Common fixed point results for three maps in G-metric spaces, Filomat, 25(4) (2011), 1-7.
- [2] H. Aydi, E. Karapinar, P. Salimi, Some fixed point results in G_p -metric spaces, J. Appl. Math., Vol. 2012, Article ID 891713, 16 pages.
- [3] M. A. Barakat, A. M. Zidan, A common fixed point theorem for weak contractive maps in G_p -metric spaces, J. Egyptian Math. Soc., 23 (2014), 309-314.
- [4] C. Di Bari, Common fixed points for self-mappings on partial metric spaces, Fixed Point Theory Appl., 2012, 2012: 140.
- [5] N. Bilgili, E. Karapinar, P. Salimi, Fixed point theorems for generalized contractions on G_p-metric spaces, J. Inequal. Appl., 2013, 2013: 39.
- [6] Lj. Ćirić, S. M. Alsulami, V. Parvaneh, R. Roshan, Some fixed point results in ordered G_p -metric spaces, Fixed Point Theory Appl., **2013**, 2013: 317.
- [7] Lj. Gajić, M. Stojaković, On fixed point results for Matkowski type of mappings in G-metric spaces, Filomat, **29**(10) (2015), 2301-2309.
- [8] Lj. Gajić, Z. Lozanov-Crvenković, On mappings with contractive iterate at point in generalized metric spaces, Fixed Point Theory Appl., Volume 2010, Article ID 458086, 16 pages.

- [9] Lj. Gajić, Z. Lozanov-Crvenković, A fixed point result for mappings with contractive iterate at a point in G-metric spaces, Filomat, 25(2) (2011), 53-58.
- [10] Lj. Gajić, M. Stojaković, On mappings with φ -contractive iterate at a point on generalized metric spaces, Fixed Point Theory Appl., **2014**, 2014: 46.
- [11] L. F. Guseman, Fixed point mappings with a contractive iterate at a point, Proc. Amer. Math. Soc., 26 (1970), 615-618
- [12] D. Ilić, V. Pavlović, V. Rakočević, Fixed points of mappings with contractive iterate at a point in partial metric spaces, Fixed Point Theory Appl., **2013**, 2013: 335.
- [13] S. G. Matthews, Partial metric topology, Proc. 8th Summer Conference on General Topology and Applications, Ann New York Acad Sci, 728 (1994), 183-197.
- [14] Z. Mustafa, B. Sims, A new approach to generalized metric spaces, J. Nonlinear Conv. Anal., 7(2) (2006), 289-297.
- [15] S. Oltra, O. Valero, Banach fixed point theorem for partial metric spaces, Rendinconti dell'Istituto di Matematica dell'Universitá di Trieste, **36**(1-2) (2004), 17-26.
- [16] V. M. Sehgal, A fixed point theorem for mappings with a contractive iterate, Proc. Amer. Math. Soc., 23 (1969), 631-634.
- [17] O. Valero, On Banach fixed point theorems for partial metric spaces, Appl. General. Topol., **6**(2) (2005), 229-240.
- [18] V. Paravneh, J. R. Roshan, Z. Kadelburg, On generalized weakly G_p -contractive mappings in ordered G_p -metric spaces, Gulf J. Math., 1 (2013), 78-97.
- [19] V. Paravneh, P. Salimi, P. Vetro, A. D. Nezhad, S. Radenović, Fixed point results for $GP(\Lambda, \Theta)$ -contractive mappings, J. Nonlinear Sci. Appl., 7 (2014), 150-159.
- [20] V. Popa, A. M. Patriciu, Two general fixed point theorems for a sequence of mappings satisfying implicit relations in G_p -metric spaces, Appl. General. Topol., $\mathbf{16}(2)$ (2015), 225-231.
- [21] S. Romaguera, A Kirk type characterizations of a completeness for partial metric spaces, Fixed Point Theory Appl., 2011, 2011: 4.
- [22] P. Salimi, P. Vetro, A result of Suzuki type in partial G-metric spaces, Acta Mathematica Scientia, **34B**(2) (2014), 274-284.
- [23] M. R. A. Zand, A. D. Nezhad, A generalization of partial metric spaces, J. Contemporary Appl. Math., 1(1) (2011), 86-93.

Most general Self Adjoint Operator Chebyshev-Grüss Inequalities

George A. Anastassiou
Department of Mathematical Sciences
University of Memphis
Memphis, TN 38152, U.S.A.
ganastss@memphis.edu

Abstract

We demonstrate here most general self adjoint operator Chebyshev-Grüss type inequalities to all cases. We finish with applications.

2010 AMS Subject Classification: 26D10, 26D20, 47A60, 47A67. Key Words and Phrases: Self adjoint operator, Hilbert space, Chebyshev-Grüss inequalities.

1 Motivation

Here we mention the following interesting and motivating results.

Theorem 1 (Čebyšev, 1882, [2]). Let $f, g : [a, b] \to \mathbb{R}$ absolutely continuous functions. If $f', g' \in L_{\infty}([a, b])$, then

$$\left| \frac{1}{b-a} \int_{a}^{b} f(x) g(x) dx - \left(\frac{1}{b-a} \int_{a}^{b} f(x) dx \right) \left(\frac{1}{b-a} \int_{a}^{b} g(x) dx \right) \right|$$

$$\leq \frac{1}{12} (b-a)^{2} \|f'\|_{\infty} \|g'\|_{\infty}.$$
(1)

Also we mention

Theorem 2 (Grüss, 1935, [6]). Let f, g integrable functions from [a, b] into \mathbb{R} , such that $m \leq f(x) \leq M$, $\rho \leq g(x) \leq \sigma$, for all $x \in [a, b]$, where $m, M, \rho, \sigma \in \mathbb{R}$. Then

$$\left| \frac{1}{b-a} \int_{a}^{b} f(x) g(x) dx - \left(\frac{1}{b-a} \int_{a}^{b} f(x) dx \right) \left(\frac{1}{b-a} \int_{a}^{b} g(x) dx \right) \right|$$

$$\leq \frac{1}{4} \left(M - m \right) \left(\sigma - \rho \right).$$

$$(2)$$

2 Background

Let A be a selfadjoint linear operator on a complex Hilbert space $(H; \langle \cdot, \cdot \rangle)$. The Gelfand map establishes a *-isometrically isomorphism Φ between the set C(Sp(A)) of all continuous functions defind on the spectrum of A, denoted Sp(A), and the C^* -algebra $C^*(A)$ generated by A and the identity operator 1_H on H as follows (see e.g. [5, p. 3]):

For any $f, g \in C(Sp(A))$ and any $\alpha, \beta \in \mathbb{C}$ we have

- (i) $\Phi(\alpha f + \beta g) = \alpha \Phi(f) + \beta \Phi(g)$;
- (ii) $\Phi(fg) = \Phi(f)\Phi(g)$ (the operation composition is on the right) and $\Phi(\overline{f}) = (\Phi(f))^*$;
 - $(\mathrm{iii})\ \|\Phi\left(f\right)\| = \|f\| := \sup_{t \in Sp(A)} |f\left(t\right)|;$
- (iv) $\Phi(f_0) = 1_H$ and $\Phi(f_1) = A$, where $f_0(t) = 1$ and $f_1(t) = t$, for $t \in Sp(A)$.

With this notation we define

$$f(A) := \Phi(f)$$
, for all $f \in C(Sp(A))$,

and we call it the continuous functional calculus for a selfadjoint operator A.

If A is a selfadjoint operator and f is a real valued continuous function on Sp(A) then $f(t) \geq 0$ for any $t \in Sp(A)$ implies that $f(A) \geq 0$, i.e. f(A) is a positive operator on H. Moreover, if both f and g are real valued functions on Sp(A) then the following important property holds:

(P) $f(t) \ge g(t)$ for any $t \in Sp(A)$, implies that $f(A) \ge g(A)$ in the operator order of B(H).

Equivalently, we use (see [4], pp. 7-8):

Let U be a selfadjoint operator on the complex Hilbert space $(H, \langle \cdot, \cdot \rangle)$ with the spectrum Sp(U) included in the interval [m, M] for some real numbers m < M and $\{E_{\lambda}\}_{\lambda}$ be its spectral family.

Then for any continuous function $f:[m,M]\to\mathbb{C}$, it is well known that we have the following spectral representation in terms of the Riemann-Stieljes integral:

$$\langle f(U) x, y \rangle = \int_{m-0}^{M} f(\lambda) d(\langle E_{\lambda} x, y \rangle),$$
 (3)

for any $x, y \in H$. The function $g_{x,y}(\lambda) := \langle E_{\lambda}x, y \rangle$ is of bounded variation on the interval [m, M], and

$$g_{x,y}(m-0) = 0$$
 and $g_{x,y}(M) = \langle x, y \rangle$,

for any $x, y \in H$. Furthermore, it is known that $g_x(\lambda) := \langle E_{\lambda} x, x \rangle$ is increasing and right continuous on [m, M].

In this article we will be using a lot the formula

$$\langle f(U) x, x \rangle = \int_{m-0}^{M} f(\lambda) d(\langle E_{\lambda} x, x \rangle), \quad \forall \ x \in H.$$
 (4)

As a symbol we can write

$$f(U) = \int_{m-0}^{M} f(\lambda) dE_{\lambda}.$$
 (5)

Above, $m = \min \{\lambda | \lambda \in Sp(U)\} := \min Sp(U), M = \max \{\lambda | \lambda \in Sp(U)\} := \max Sp(U)$. The projections $\{E_{\lambda}\}_{{\lambda} \in \mathbb{R}}$, are called the spectral family of A, with the properties:

- (a) $E_{\lambda} \leq E_{\lambda'}$ for $\lambda \leq \lambda'$;
- (b) $E_{m-0} = 0_H$ (zero operator), $E_M = 1_H$ (identity operator) and $E_{\lambda+0} = E_{\lambda}$ for all $\lambda \in \mathbb{R}$.

Furthermore

$$E_{\lambda} := \varphi_{\lambda} (U), \ \forall \ \lambda \in \mathbb{R}, \tag{6}$$

is a projection which reduces U, with

$$\varphi_{\lambda}\left(s\right) := \begin{cases} 1, & \text{for } -\infty < s \leq \lambda, \\ 0, & \text{for } \lambda < s < +\infty. \end{cases}$$

The spectral family $\{E_{\lambda}\}_{{\lambda}\in\mathbb{R}}$ determines uniquely the self-adjoint operator U and vice versa.

For more on the topic see [7], pp. 256-266, and for more details see there pp. 157-266. See also [3].

Some more basics are given (we follow [4], pp. 1-5):

Let $(H; \langle \cdot, \cdot \rangle)$ be a Hilbert space over \mathbb{C} . A bounded linear operator A defined on H is selfjoint, i.e., $A = A^*$, iff $\langle Ax, x \rangle \in \mathbb{R}$, $\forall x \in H$, and if A is selfadjoint, then

$$||A|| = \sup_{x \in H: ||x|| = 1} |\langle Ax, x \rangle|. \tag{7}$$

Let A, B be selfadjoint operators on H. Then $A \leq B$ iff $\langle Ax, x \rangle \leq \langle Bx, x \rangle$, $\forall x \in H$.

In particular, A is called positive if $A \geq 0$.

Denote by

$$\mathcal{P} := \left\{ \varphi\left(s\right) := \sum_{k=0}^{n} \alpha_k s^k | n \ge 0, \ \alpha_k \in \mathbb{C}, \ 0 \le k \le n \right\}. \tag{8}$$

If $A \in \mathcal{B}(H)$ (the Banach algebra of all bounded linear operators defined on H, i.e. from H into itself) is selfadjoint, and $\varphi(s) \in \mathcal{P}$ has real coefficients, then $\varphi(A)$ is selfadjoint, and

$$\|\varphi(A)\| = \max\{|\varphi(\lambda)|, \lambda \in Sp(A)\}. \tag{9}$$

If φ is any function defined on \mathbb{R} we define

$$\|\varphi\|_{\Lambda} := \sup\left\{ |\varphi\left(\lambda\right)|, \lambda \in Sp\left(A\right) \right\}. \tag{10}$$

If A is selfadjoint operator on Hilbert space H and φ is continuous and given that $\varphi(A)$ is selfadjoint, then $\|\varphi(A)\| = \|\varphi\|_A$. And if φ is a continuous real valued function so it is $|\varphi|$, then $\varphi(A)$ and $|\varphi|(A) = |\varphi(A)|$ are selfadjoint operators (by [4], p. 4, Theorem 7).

Hence it holds

$$\begin{aligned} & \left\| \left| \varphi \left(A \right) \right| \right\| = \left\| \left| \varphi \right| \right\|_{A} = \sup \left\{ \left| \left| \varphi \left(\lambda \right) \right| \right|, \lambda \in Sp\left(A \right) \right\} \\ & = \sup \left\{ \left| \varphi \left(\lambda \right) \right|, \lambda \in Sp\left(A \right) \right\} = \left\| \varphi \right\|_{A} = \left\| \varphi \left(A \right) \right\|, \end{aligned}$$

that is

$$\||\varphi(A)|\| = \|\varphi(A)\|. \tag{11}$$

For a selfadjoint operator $A \in \mathcal{B}(H)$ which is positive, there exists a unique positive selfadjoint operator $B := \sqrt{A} \in \mathcal{B}(H)$ such that $B^2 = A$, that is $\left(\sqrt{A}\right)^2 = A$. We call B the square root of A.

Let $A \in \mathcal{B}(H)$, then A^*A is selfadjoint and positive. Define the "operator absolute value" $|A| := \sqrt{A^*A}$. If $A = A^*$, then $|A| = \sqrt{A^2}$.

For a continuous real valued function φ we observe the following:

$$|\varphi\left(A\right)|$$
 (the functional absolute value) $=\int_{m=0}^{M}|\varphi\left(\lambda\right)|dE_{\lambda}=$

$$\int_{m-0}^{M} \sqrt{\left(\varphi\left(\lambda\right)\right)^{2}} dE_{\lambda} = \sqrt{\left(\varphi\left(A\right)\right)^{2}} = \left|\varphi\left(A\right)\right| \text{ (operator absolute value)},$$

where A is a selfadjoint operator.

That is we have

 $|\varphi(A)|$ (functional absolute value) = $|\varphi(A)|$ (operator absolute value). (12)

Let $A, B \in \mathcal{B}(H)$, then

$$||AB|| < ||A|| \, ||B|| \,, \tag{13}$$

by Banach algebra property.

3 Main Results

Next we present most general Chebyshev-Grüss type operator inequalities based on Theorem 26.9 of [1], p. 404.

Then we specialize them for n = 1.

We give

Theorem 3 Let $n \in \mathbb{N}$ and $f_1, f_2 \in C^n([a,b])$ with $[m,M] \subset (a,b)$, m < M; $g \in C^1([a,b])$ and $g^{-1} \in C^n([a,b])$. Here A is a selfadjoint linear operator on the Hilbert space H with spectrum $Sp(A) \subseteq [m,M]$. We consider any $x \in H$: ||x|| = 1.

Then

$$\langle (\Delta(f_{1}, f_{2}; g)) (A) x, x \rangle := \left| \langle f_{1}(A) f_{2}(A) x, x \rangle - \langle f_{1}(A) x, x \rangle \cdot \langle f_{2}(A) x, x \rangle - \frac{1}{2(M-m)} \left\{ \sum_{k=1}^{n-1} \frac{1}{k!} \cdot \left\{ \left[\left\langle \left(f_{2}(A) \int_{m-0}^{M} \left(\int_{m}^{M} (f_{1} \circ g^{-1})^{(k)} (g(t)) (g(\lambda) - g(t))^{k} dt \right) dE_{\lambda} \right) x, x \right\rangle - \left\{ \langle f_{2}(A) x, x \rangle \int_{m-0}^{M} \left(\int_{m}^{M} (f_{1} \circ g^{-1})^{(k)} (g(t)) (g(\lambda) - g(t))^{k} dt \right) d\langle E_{\lambda} x, x \rangle \right] + \left[\left\langle \left(f_{1}(A) \int_{m-0}^{M} \left(\int_{m}^{M} (f_{2} \circ g^{-1})^{(k)} (g(t)) (g(\lambda) - g(t))^{k} dt \right) dE_{\lambda} \right) x, x \right\rangle - \left\langle f_{1}(A) x, x \rangle \int_{m-0}^{M} \left(\int_{m}^{M} (f_{2} \circ g^{-1})^{(k)} (g(t)) (g(\lambda) - g(t))^{k} dt \right) d\langle E_{\lambda} x, x \rangle \right] \right\} \right\} \right|$$

$$\leq \frac{\|g\|_{\infty,[m,M]}^{n-1} \|g'\|_{\infty,[m,M]}}{(n+1)! (M-m)} \left[\|f_{2}(A)\| \left\| (f_{1} \circ g^{-1})^{(n)} \circ g \right\|_{\infty,[m,M]} + \left\| f_{1}(A)\| \left\| (f_{2} \circ g^{-1})^{(n)} \circ g \right\|_{\infty,[m,M]} \right\| \right].$$

$$\|f_{1}(A)\| \left\| (f_{2} \circ g^{-1})^{(n)} \circ g \right\|_{\infty,[m,M]} \right] \left[\left\| (M1_{H} - A)^{n+1} \right\| + \left\| (A - m1_{H})^{n+1} \right\| \right].$$

$$(14)$$

Proof. Call $l_i = f_i \circ g^{-1}$, i = 1, 2. Then $l_i, l'_i, ..., l_i^{(n)}$ are continuous from g([a, b]) into $f_i([a, b])$, i = 1, 2. Hence $(f_i \circ g^{-1})^{(n)} \circ g \in C([a, b])$, i = 1, 2. Here $\{E_{\lambda}\}_{\lambda}$ is the spectral family of A.

Next we use Theorem 26.9 of [1], p. 404. We have that (i = 1, 2)

$$f_{i}(\lambda) = \frac{1}{M-m} \int_{m}^{M} f_{i}(t) dt + \frac{1}{(M-m)} \left\{ \sum_{k=1}^{n-1} \frac{1}{k!} \int_{m}^{M} \left(f_{i} \circ g^{-1} \right)^{(k)} (g(t)) (g(\lambda) - g(t))^{k} dt \right\} + \frac{1}{(n-1)! (M-m)} \int_{m}^{M} (g(\lambda) - g(t))^{n-1} \left(f_{i} \circ g^{-1} \right)^{(n)} (g(t)) g'(t) K(t, \lambda) dt,$$

$$\forall \lambda \in [m, M],$$
(15)

where

$$K(t,\lambda) := \begin{cases} t - m, & m \le t \le \lambda \le M, \\ t - M, & m < \lambda < t < M. \end{cases}$$
(16)

By applying the spectral representation theorem on (15), i.e. integrating against E_{λ} over [m, M], see (4), we obtain:

$$f_{i}(A) = \left(\frac{1}{M-m} \int_{m}^{M} f_{i}(t) dt\right) 1_{H} + \frac{1}{(M-m)} \left\{ \sum_{k=1}^{n-1} \frac{1}{k!} \int_{m-0}^{M} \left(\int_{m}^{M} \left(f_{i} \circ g^{-1} \right)^{(k)} (g(t)) (g(\lambda) - g(t))^{k} dt \right) dE_{\lambda} \right\} + \frac{1}{(n-1)! (M-m)} \cdot \int_{m-0}^{M} \left(\int_{m}^{M} (g(\lambda) - g(t))^{n-1} \left(f_{i} \circ g^{-1} \right)^{(n)} (g(t)) g'(t) K(t, \lambda) dt \right) dE_{\lambda}, \quad (17)$$

$$= 1, 2.$$

We notice that

$$f_1(A) f_2(A) = f_2(A) f_1(A),$$
 (18)

to be used next.

Hence it holds

$$f_2(A) f_1(A) = \left(\frac{1}{M-m} \int_m^M f_1(t) dt\right) f_2(A) +$$
 (19)

$$\frac{1}{(M-m)} \left\{ \sum_{k=1}^{n-1} \frac{1}{k!} f_2(A) \int_{m-0}^{M} \left(\int_{m}^{M} \left(f_1 \circ g^{-1} \right)^{(k)} (g(t)) (g(\lambda) - g(t))^k dt \right) dE_{\lambda} \right\} + \frac{1}{(n-1)! (M-m)} f_2(A).$$

$$\int_{m-0}^{M} \left(\int_{m}^{M} \left(g\left(\lambda \right) - g\left(t \right) \right)^{n-1} \left(f_{1} \circ g^{-1} \right)^{(n)} \left(g\left(t \right) \right) g'\left(t \right) K\left(t, \lambda \right) dt \right) dE_{\lambda},$$

and

$$f_{1}(A) f_{2}(A) = \left(\frac{1}{M-m} \int_{m}^{M} f_{2}(t) dt\right) f_{1}(A) + \frac{1}{(M-m)} \left\{ \sum_{k=1}^{n-1} \frac{1}{k!} f_{1}(A) \int_{m-0}^{M} \left(\int_{m}^{M} \left(f_{2} \circ g^{-1} \right)^{(k)} (g(t)) (g(\lambda) - g(t))^{k} dt \right) dE_{\lambda} \right\} + \frac{1}{(n-1)! (M-m)} f_{1}(A) .$$

$$\int_{m-0}^{M} \left(\int_{m}^{M} (g(\lambda) - g(t))^{n-1} (f_2 \circ g^{-1})^{(n)} (g(t)) g'(t) K(t, \lambda) dt \right) dE_{\lambda}.$$
 (20)

Here from now on we consider $x \in H: ||x|| = 1$; immediately we get

$$\int_{m-0}^{M} d\langle E_{\lambda} x, x \rangle = 1.$$

Then it holds (i = 1, 2)

$$\langle f_i(A) x, x \rangle = \left(\frac{1}{M-m} \int_m^M f_i(t) dt\right) +$$
 (21)

$$\frac{1}{(M-m)} \left\{ \sum_{k=1}^{n-1} \frac{1}{k!} \int_{m-0}^{M} \left(\int_{m}^{M} \left(f_{i} \circ g^{-1} \right)^{(k)} (g(t)) (g(\lambda) - g(t))^{k} dt \right) d \langle E_{\lambda} x, x \rangle \right\} + \frac{1}{(n-1)! (M-m)}.$$

$$\int_{m-0}^{M} \left(\int_{m}^{M} \left(g\left(\lambda \right) - g\left(t \right) \right)^{n-1} \left(f_{i} \circ g^{-1} \right)^{(n)} \left(g\left(t \right) \right) g'\left(t \right) K\left(t, \lambda \right) dt \right) d \left\langle E_{\lambda} x, x \right\rangle.$$

It follows that

$$\langle f_2(A) x, x \rangle \langle f_1(A) x, x \rangle = \left(\frac{1}{M-m} \int_m^M f_1(t) dt\right) \langle f_2(A) x, x \rangle + \frac{1}{(M-m)}$$

$$\left\{ \sum_{k=1}^{n-1} \frac{1}{k!} \left\langle f_{2}(A) x, x \right\rangle \int_{m-0}^{M} \left(\int_{m}^{M} \left(f_{1} \circ g^{-1} \right)^{(k)} (g(t)) (g(\lambda) - g(t))^{k} dt \right) d \left\langle E_{\lambda} x, x \right\rangle \right\} + \frac{1}{(n-1)! (M-m)} \left\langle f_{2}(A) x, x \right\rangle . \tag{22}$$

$$\int_{m-0}^{M} \left(\int_{m}^{M} \left(g\left(\lambda \right) - g\left(t \right) \right)^{n-1} \left(f_{1} \circ g^{-1} \right)^{(n)} \left(g\left(t \right) \right) g'\left(t \right) K\left(t, \lambda \right) dt \right) d \left\langle E_{\lambda} x, x \right\rangle,$$

and

$$\langle f_1(A) x, x \rangle \langle f_2(A) x, x \rangle = \left(\frac{1}{M-m} \int_m^M f_2(t) dt\right) \langle f_1(A) x, x \rangle + \frac{1}{(M-m)}.$$

$$\left\{ \sum_{k=1}^{n-1} \frac{1}{k!} \left\langle f_{1}(A) x, x \right\rangle \int_{m-0}^{M} \left(\int_{m}^{M} \left(f_{2} \circ g^{-1} \right)^{(k)} (g(t)) (g(\lambda) - g(t))^{k} dt \right) d \left\langle E_{\lambda} x, x \right\rangle \right\} + \frac{1}{(n-1)! (M-m)} \left\langle f_{1}(A) x, x \right\rangle.$$
(23)

$$\int_{m-0}^{M} \left(\int_{m}^{M} \left(g\left(\lambda \right) - g\left(t \right) \right)^{n-1} \left(f_{2} \circ g^{-1} \right)^{(n)} \left(g\left(t \right) \right) g'\left(t \right) K\left(t, \lambda \right) dt \right) d\left\langle E_{\lambda} x, x \right\rangle.$$

Furthermore we obtain

$$\langle f_{1}(A) f_{2}(A) x, x \rangle = \left(\frac{1}{M-m} \int_{m}^{M} f_{1}(t) dt \right) \langle f_{2}(A) x, x \rangle + \frac{1}{(M-m)} \cdot \left\{ \sum_{k=1}^{n-1} \frac{1}{k!} \left\langle \left(f_{2}(A) \int_{m-0}^{M} \left(\int_{m}^{M} \left(f_{1} \circ g^{-1} \right)^{(k)} (g(t)) (g(\lambda) - g(t))^{k} dt \right) dE_{\lambda} \right) x, x \right\rangle \right\} + \frac{1}{(n-1)! (M-m)} \cdot \left(\left(f_{2}(A) \int_{m-0}^{M} \left(\int_{m}^{M} (g(\lambda) - g(t))^{n-1} (f_{1} \circ g^{-1})^{(n)} (g(t)) g'(t) K(t, \lambda) dt \right) dE_{\lambda} \right) x, x \right\rangle,$$

and

$$\langle f_{1}(A) f_{2}(A) x, x \rangle = \left(\frac{1}{M-m} \int_{m}^{M} f_{2}(t) dt \right) \langle f_{1}(A) x, x \rangle + \frac{1}{(M-m)} \cdot \left\{ \sum_{k=1}^{n-1} \frac{1}{k!} \left\langle \left(f_{1}(A) \int_{m-0}^{M} \left(\int_{m}^{M} \left(f_{2} \circ g^{-1} \right)^{(k)} (g(t)) (g(\lambda) - g(t))^{k} dt \right) dE_{\lambda} \right) x, x \right\rangle \right\} + \frac{1}{(n-1)! (M-m)} \cdot (25)$$

$$\left\langle \left(f_{1}(A) \int_{m-0}^{M} \left(\int_{m}^{M} (g(\lambda) - g(t))^{n-1} (f_{2} \circ g^{-1})^{(n)} (g(t)) g'(t) K(t, \lambda) dt \right) dE_{\lambda} \right) x, x \right\rangle.$$

By (24)-(22) we obtain

$$E := \langle f_{1}(A) f_{2}(A) x, x \rangle - \langle f_{1}(A) x, x \rangle \langle f_{2}(A) x, x \rangle = \frac{1}{(M - m)}.$$

$$\left\{ \sum_{k=1}^{n-1} \frac{1}{k!} \left[\left\langle \left(f_{2}(A) \int_{m-0}^{M} \left(\int_{m}^{M} \left(f_{1} \circ g^{-1} \right)^{(k)} (g(t)) (g(\lambda) - g(t))^{k} dt \right) dE_{\lambda} \right) x, x \right\rangle - \langle f_{2}(A) x, x \rangle \int_{m-0}^{M} \left(\int_{m}^{M} \left(f_{1} \circ g^{-1} \right)^{(k)} (g(t)) (g(\lambda) - g(t))^{k} dt \right) d\langle E_{\lambda} x, x \rangle \right] \right\} + \frac{1}{(n-1)! (M-m)}.$$

$$\left[\left\langle \left(f_{2}(A) \int_{m-0}^{M} \left(\int_{m}^{M} (g(\lambda) - g(t))^{n-1} (f_{1} \circ g^{-1})^{(n)} (g(t)) g'(t) K(t, \lambda) dt \right) dE_{\lambda} \right) x, x \right\rangle$$
(26)

$$-\langle f_2(A) x, x \rangle \cdot$$

$$\int_{m-0}^{M} \left(\int_{m}^{M} (g(\lambda) - g(t))^{n-1} \left(f_1 \circ g^{-1} \right)^{(n)} (g(t)) g'(t) K(t, \lambda) dt \right) d\langle E_{\lambda} x, x \rangle \right],$$
and by (25)-(23) we have
$$E = \frac{1}{(M-m)} \cdot$$

$$\left\{ \sum_{k=1}^{n-1} \frac{1}{k!} \left[\left\langle \left(f_1(A) \int_{m-0}^{M} \left(\int_{m}^{M} \left(f_2 \circ g^{-1} \right)^{(k)} (g(t)) (g(\lambda) - g(t))^k dt \right) dE_{\lambda} \right) x, x \right\rangle \right.$$

$$\left. - \langle f_1(A) x, x \rangle \int_{m-0}^{M} \left(\int_{m}^{M} \left(f_2 \circ g^{-1} \right)^{(k)} (g(t)) (g(\lambda) - g(t))^k dt \right) d\langle E_{\lambda} x, x \rangle \right] \right\}$$

$$\left. + \frac{1}{(n-1)! (M-m)} \cdot$$

$$\left[\left\langle \left(f_1(A) \int_{m-0}^{M} \left(\int_{m}^{M} (g(\lambda) - g(t))^{n-1} \left(f_2 \circ g^{-1} \right)^{(n)} (g(t)) g'(t) K(t, \lambda) dt \right) dE_{\lambda} \right) x, x \right\rangle$$

$$\left. - \langle f_1(A) x, x \rangle \cdot$$

$$\int_{m-0}^{M} \left(\int_{m}^{M} (g(\lambda) - g(t))^{n-1} \left(f_2 \circ g^{-1} \right)^{(n)} (g(t)) g'(t) K(t, \lambda) dt \right) d\langle E_{\lambda} x, x \rangle \right].$$

$$(27)$$

Consequently, by adding (26) and (27), we get that

$$2E = \frac{1}{(M-m)}.$$

$$\left\{ \sum_{k=1}^{n-1} \frac{1}{k!} \left\{ \left[\left\langle \left(f_{2}(A) \int_{m-0}^{M} \left(\int_{m}^{M} (f_{1} \circ g^{-1})^{(k)} (g(t)) (g(\lambda) - g(t))^{k} dt \right) dE_{\lambda} \right) x, x \right\rangle \right.$$

$$\left. - \left\langle f_{2}(A) x, x \right\rangle \int_{m-0}^{M} \left(\int_{m}^{M} (f_{1} \circ g^{-1})^{(k)} (g(t)) (g(\lambda) - g(t))^{k} dt \right) d\left\langle E_{\lambda} x, x \right\rangle \right] +$$

$$\left[\left\langle \left(f_{1}(A) \int_{m-0}^{M} \left(\int_{m}^{M} (f_{2} \circ g^{-1})^{(k)} (g(t)) (g(\lambda) - g(t))^{k} dt \right) dE_{\lambda} \right) x, x \right\rangle \right.$$

$$\left. - \left\langle f_{1}(A) x, x \right\rangle \int_{m-0}^{M} \left(\int_{m}^{M} (f_{2} \circ g^{-1})^{(k)} (g(t)) (g(\lambda) - g(t))^{k} dt \right) d\left\langle E_{\lambda} x, x \right\rangle \right] \right\} \right\}$$

$$\left. + \frac{1}{(n-1)! (M-m)}.$$

$$\left\{ \left[\left\langle \left(f_{2}(A) \int_{m-0}^{M} \left(\int_{m}^{M} (g(\lambda) - g(t))^{n-1} (f_{1} \circ g^{-1})^{(n)} (g(t)) g'(t) K(t, \lambda) dt \right) dE_{\lambda} \right) x, x \right\rangle \right.$$

$$-\langle f_2(A)x,x\rangle \cdot$$

$$\int_{m-0}^M \left(\int_m^M (g(\lambda) - g(t))^{n-1} \left(f_1 \circ g^{-1} \right)^{(n)} (g(t)) g'(t) K(t,\lambda) dt \right) d\langle E_\lambda x,x\rangle \right] +$$

$$\left[\left\langle \left(f_1(A) \int_{m-0}^M \left(\int_m^M (g(\lambda) - g(t))^{n-1} \left(f_2 \circ g^{-1} \right)^{(n)} (g(t)) g'(t) K(t,\lambda) dt \right) dE_\lambda \right) x,x \right\rangle - \langle f_1(A)x,x\rangle \cdot$$

$$\int_{m-0}^M \left(\int_m^M (g(\lambda) - g(t))^{n-1} \left(f_2 \circ g^{-1} \right)^{(n)} (g(t)) g'(t) K(t,\lambda) dt \right) d\langle E_\lambda x,x\rangle \right] \right\}.$$
We find that
$$\langle f_1(A) f_2(A)x,x \rangle - \langle f_1(A)x,x \rangle \langle f_2(A)x,x \rangle - \frac{1}{2(M-m)} \cdot$$

$$\left\{ \sum_{k=1}^{n-1} \frac{1}{k!} \left\{ \left[\left\langle \left(f_2(A) \int_{m-0}^M \left(\int_m^M \left(f_1 \circ g^{-1} \right)^{(k)} (g(t)) \left(g(\lambda) - g(t) \right)^k dt \right) dE_\lambda \right) x,x \right\rangle - \langle f_2(A)x,x \rangle \int_{m-0}^M \left(\int_m^M \left(f_2 \circ g^{-1} \right)^{(k)} (g(t)) \left(g(\lambda) - g(t) \right)^k dt \right) d\langle E_\lambda x,x \rangle \right] +$$

$$\left[\left\langle \left(f_1(A) \int_{m-0}^M \left(\int_m^M \left(f_2 \circ g^{-1} \right)^{(k)} (g(t)) \left(g(\lambda) - g(t) \right)^k dt \right) d\langle E_\lambda x,x \rangle \right] \right\} \right\}$$

$$= \frac{1}{2(n-1)!(M-m)} \cdot$$

$$\left\{ \left[\left\langle \left(f_2(A) \int_{m-0}^M \left(\int_m^M \left(g(\lambda) - g(t) \right)^{n-1} \left(f_1 \circ g^{-1} \right)^{(n)} (g(t)) g'(t) K(t,\lambda) dt \right) dE_\lambda \right) x,x \right\rangle - \langle f_2(A)x,x \rangle \cdot$$

$$\int_{m-0}^M \left(\int_m^M \left(g(\lambda) - g(t) \right)^{n-1} \left(f_1 \circ g^{-1} \right)^{(n)} \left(g(t) \right) g'(t) K(t,\lambda) dt \right) d\langle E_\lambda x,x \rangle \right] +$$

$$\left[\left\langle \left(f_1(A) \int_{m-0}^M \left(\int_m^M \left(g(\lambda) - g(t) \right)^{n-1} \left(f_2 \circ g^{-1} \right)^{(n)} \left(g(t) \right) g'(t) K(t,\lambda) dt \right) d\langle E_\lambda x,x \rangle \right] +$$

$$\left[\left\langle \left(f_1(A) \int_{m-0}^M \left(\int_m^M \left(g(\lambda) - g(t) \right)^{n-1} \left(f_2 \circ g^{-1} \right)^{(n)} \left(g(t) \right) g'(t) K(t,\lambda) dt \right) d\langle E_\lambda x,x \rangle \right] +$$

$$\left[\left\langle \left(f_1(A) \int_{m-0}^M \left(\int_m^M \left(g(\lambda) - g(t) \right)^{n-1} \left(f_2 \circ g^{-1} \right)^{(n)} \left(g(t) \right) g'(t) K(t,\lambda) dt \right) d\langle E_\lambda x,x \rangle \right] +$$

$$\left[\left\langle \left(f_1(A) \int_{m-0}^M \left(\int_m^M \left(g(\lambda) - g(t) \right)^{n-1} \left(f_2 \circ g^{-1} \right)^{(n)} \left(g(t) \right) g'(t) K(t,\lambda) dt \right) d\langle E_\lambda x,x \rangle \right] \right\} =$$

$$= R.$$

Hence we have

$$\left\{ \left[\left| \left\langle \left(f_{2}(A) \int_{m-0}^{M} \left(\int_{m}^{M} (g(\lambda) - g(t))^{n-1} \left(f_{1} \circ g^{-1} \right)^{(n)} (g(t)) g'(t) K(t, \lambda) dt \right) dE_{\lambda} \right) x, x \right\rangle \right| \\
+ \left| \left\langle f_{2}(A) x, x \right\rangle \right| \\
\left| \int_{m-0}^{M} \left(\int_{m}^{M} (g(\lambda) - g(t))^{n-1} \left(f_{1} \circ g^{-1} \right)^{(n)} (g(t)) g'(t) K(t, \lambda) dt \right) d\left\langle E_{\lambda} x, x \right\rangle \right| \right\} \\
\left[\left| \left\langle \left(f_{1}(A) \int_{m-0}^{M} \left(\int_{m}^{M} (g(\lambda) - g(t))^{n-1} \left(f_{2} \circ g^{-1} \right)^{(n)} (g(t)) g'(t) K(t, \lambda) dt \right) dE_{\lambda} \right) x, x \right\rangle \right| \\
+ \left| \left\langle f_{1}(A) x, x \right\rangle \right| \cdot \\
\left| \int_{m-0}^{M} \left(\int_{m}^{M} (g(\lambda) - g(t))^{n-1} \left(f_{2} \circ g^{-1} \right)^{(n)} (g(t)) g'(t) K(t, \lambda) dt \right) d\left\langle E_{\lambda} x, x \right\rangle \right| \right\}$$
(30)

(here notice that

$$\left| \int_{m}^{M} (g(\lambda) - g(t))^{n-1} (f_{1} \circ g^{-1})^{(n)} (g(t)) g'(t) K(t, \lambda) dt \right| \leq$$

$$\int_{m}^{M} |g(\lambda) - g(t)|^{n-1} \left| (f_{1} \circ g^{-1})^{(n)} (g(t)) \right| |g'(t)| |K(t, \lambda)| dt \leq$$

$$\left(\int_{m}^{M} |\lambda - t|^{n-1} |K(t, \lambda)| dt \right) \|g\|_{\infty}^{n-1} \|(f_{1} \circ g^{-1})^{(n)} \circ g\|_{\infty} \|g'\|_{\infty} =$$

$$\frac{\|g\|_{\infty}^{n-1} \|g'\|_{\infty} \|(f_{1} \circ g^{-1})^{(n)} \circ g\|_{\infty}}{n(n+1)} \left[(M - \lambda)^{n+1} + (\lambda - m)^{n+1} \right])$$

$$\leq \frac{1}{2(n-1)! (M-m)} \cdot$$

$$\left\{ \left[\left\| f_{2}(A) \int_{m-0}^{M} \left(\int_{m}^{M} (g(\lambda) - g(t))^{n-1} (f_{1} \circ g^{-1})^{(n)} (g(t)) g'(t) K(t, \lambda) dt \right) dE_{\lambda} \right\| \right.$$

$$+ \left\| f_{1}(A) \int_{m-0}^{M} \left(\int_{m}^{M} (g(\lambda) - g(t))^{n-1} (f_{2} \circ g^{-1})^{(n)} (g(t)) g'(t) K(t, \lambda) dt \right) dE_{\lambda} \right\|$$

$$+ \left\| \|f_{2}(A) \| \frac{\|g\|_{\infty}^{n-1} \|g'\|_{\infty} \|(f_{1} \circ g^{-1})^{(n)} \circ g\|_{\infty}}{n(n+1)} \cdot$$

$$\left[\left\langle (M1_{H} - A)^{n+1} x, x \right\rangle + \left\langle (A - m1_{H})^{n+1} x, x \right\rangle \right] + \left\| f_{1}(A) \right\| \frac{\|g\|_{\infty}^{n-1} \|g'\|_{\infty} \| (f_{2} \circ g^{-1})^{(n)} \circ g \|_{\infty}}{n (n+1)} \cdot \left[\left\langle (M1_{H} - A)^{n+1} x, x \right\rangle + \left\langle (A - m1_{H})^{n+1} x, x \right\rangle \right] \right\}$$
(32)
$$\leq \frac{1}{2 (n-1)! (M-m)} \cdot \left\{ \|f_{2}(A)\| \left\| \int_{m-0}^{M} \left(\int_{m}^{M} (g(\lambda) - g(t))^{n-1} \left(f_{1} \circ g^{-1} \right)^{(n)} (g(t)) g'(t) K(t, \lambda) dt \right) dE_{\lambda} \right\| + \left\| f_{1}(A)\| \left\| \int_{m-0}^{M} \left(\int_{m}^{M} (g(\lambda) - g(t))^{n-1} \left(f_{2} \circ g^{-1} \right)^{(n)} (g(t)) g'(t) K(t, \lambda) dt \right) dE_{\lambda} \right\| \right\}$$

$$+ \left[\frac{\|f_{2}(A)\| \|g\|_{\infty}^{n-1} \|g'\|_{\infty} \| (f_{1} \circ g^{-1})^{(n)} \circ g \|_{\infty}}{n (n+1)} + \frac{\|f_{1}(A)\| \|g\|_{\infty}^{n-1} \|g'\|_{\infty} \| (f_{2} \circ g^{-1})^{(n)} \circ g \|_{\infty}}{n (n+1)} \right] \cdot \left[\left\langle (M1_{H} - A)^{n+1} x, x \right\rangle + \left\langle (A - m1_{H})^{n+1} x, x \right\rangle \right] \right\} =: (\xi) . \tag{33}$$

Notice here that

$$\left\| \int_{m-0}^{M} \left(\int_{m}^{M} (g(\lambda) - g(t))^{n-1} \left(f_{1} \circ g^{-1} \right)^{(n)} (g(t)) g'(t) K(t, \lambda) dt \right) dE_{\lambda} \right\| =$$

$$\sup_{\|x\|=1} \left| \int_{m-0}^{M} \left(\int_{m}^{M} (g(\lambda) - g(t))^{n-1} \left(f_{1} \circ g^{-1} \right)^{(n)} (g(t)) g'(t) K(t, \lambda) dt \right) d\langle E_{\lambda} x, x \rangle \right|$$

$$\leq \frac{\|g\|_{\infty}^{n-1} \|g'\|_{\infty} \left\| \left(f_{1} \circ g^{-1} \right)^{(n)} \circ g \right\|_{\infty}}{n(n+1)} .$$

$$\left[\left\| (M1_{H} - A)^{n+1} \right\| + \left\| (A - m1_{H})^{n+1} \right\| \right] .$$
 (34)

A similar estimate to (34) holds for f_2 .

Hence we obtain by (33), (34) that

$$(\xi) \le \frac{1}{(n-1)! (M-m)} \left[\|f_2(A)\| \frac{\|g\|_{\infty}^{n-1} \|g'\|_{\infty} \|(f_1 \circ g^{-1})^{(n)} \circ g\|_{\infty}}{n (n+1)} \right]$$

$$+ \|f_{1}(A)\| \frac{\|g\|_{\infty}^{n-1} \|g'\|_{\infty} \| (f_{2} \circ g^{-1})^{(n)} \circ g \|_{\infty}}{n (n+1)}$$

$$\left[\| (M1_{H} - A)^{n+1} \| + \| (A - m1_{H})^{n+1} \| \right] =$$

$$\frac{\|g\|_{\infty}^{n-1} \|g'\|_{\infty}}{(n+1)! (M-m)}$$

$$\left[\|f_{2}(A)\| \| (f_{1} \circ g^{-1})^{(n)} \circ g \|_{\infty} + \|f_{1}(A)\| \| (f_{2} \circ g^{-1})^{(n)} \circ g \|_{\infty} \right]$$

$$\left[\| (M1_{H} - A)^{n+1} \| + \| (A - m1_{H})^{n+1} \| \right]$$
(35)

We have proved that

$$|R| \leq \frac{\|g\|_{\infty}^{n-1} \|g'\|_{\infty}}{(n+1)! (M-m)} \cdot \left[\|f_{2}(A)\| \left\| (f_{1} \circ g^{-1})^{(n)} \circ g \right\|_{\infty} + \|f_{1}(A)\| \left\| (f_{2} \circ g^{-1})^{(n)} \circ g \right\|_{\infty} \right] \cdot$$

$$\left[\left\| (M1_{H} - A)^{n+1} \right\| + \left\| (A - m1_{H})^{n+1} \right\| \right],$$
(36)

that is proving the claim.

Above it is
$$\|\cdot\|_{\infty} = \|\cdot\|_{\infty,[m,M]}$$
. \blacksquare We give

Corollary 4 (n = 1 case of Theorem 3) For every $x \in H : ||x|| = 1$, we obtain that

$$\left| \left\langle f_{1}\left(A\right) f_{2}\left(A\right) x, x \right\rangle - \left\langle f_{1}\left(A\right) x, x \right\rangle \left\langle f_{2}\left(A\right) x, x \right\rangle \right| \leq \frac{\|g'\|_{\infty, [m, M]}}{2\left(M - m\right)}.$$

$$\left[\|f_{2}\left(A\right)\| \left\| \left(f_{1} \circ g^{-1}\right)' \circ g \right\|_{\infty, [m, M]} + \|f_{1}\left(A\right)\| \left\| \left(f_{2} \circ g^{-1}\right)' \circ g \right\|_{\infty, [m, M]} \right].$$

$$\left[\left\| \left(M1_{H} - A\right)^{2} \right\| + \left\| \left(A - m1_{H}\right)^{2} \right\| \right]. \tag{37}$$

We present

Theorem 5 Here all as in Theorem 3. Let $p, q > 1 : \frac{1}{p} + \frac{1}{q} = 1$. Then

$$\frac{\|g\|_{\infty,[m,M]}^{n-1} \|g'\|_{\infty,[m,M]}}{(n-1)! (M-m)} \left(\frac{\Gamma(p(n-1)+1)\Gamma(p+1)}{\Gamma(pn+2)} \right)^{\frac{1}{p}} \cdot \left[\|f_2(A)\| \left\| \left(f_1 \circ g^{-1} \right)^{(n)} \circ g \right\|_{q,[m,M]} + \|f_1(A)\| \left\| \left(f_2 \circ g^{-1} \right)^{(n)} \circ g \right\|_{q,[m,M]} \right] \cdot \left[\left\| \left(M1_H - A \right)^{n+\frac{1}{p}} \right\| + \left\| \left(A - m1_H \right)^{n+\frac{1}{p}} \right\| \right], \tag{38}$$

 $\langle (\Delta(f_1, f_2; g))(A) x, x \rangle \leq$

where Γ is the gamma function.

Proof. We observe that

$$\left| \int_{m}^{M} (g(\lambda) - g(t))^{n-1} (f_{1} \circ g^{-1})^{(n)} (g(t)) g'(t) K(t, \lambda) dt \right| \leq$$

$$\int_{m}^{M} |g(\lambda) - g(t)|^{n-1} \left| (f_{1} \circ g^{-1})^{(n)} (g(t)) \right| |g'(t)| |K(t, \lambda)| dt \leq$$

$$\|g\|_{\infty, [m, M]}^{n-1} \|g'\|_{\infty, [m, M]} \int_{m}^{M} |\lambda - t|^{n-1} \left| (f_{1} \circ g^{-1})^{(n)} (g(t)) \right| |K(t, \lambda)| dt =$$

$$\|g\|_{\infty, [m, M]}^{n-1} \|g'\|_{\infty, [m, M]} \left[\int_{m}^{\lambda} (\lambda - t)^{n-1} (t - m) \left| (f_{1} \circ g^{-1})^{(n)} (g(t)) \right| dt +$$

$$\int_{\lambda}^{M} (M - t) (t - \lambda)^{n-1} \left| (f_{1} \circ g^{-1})^{(n)} (g(t)) \right| dt \right] \leq$$

$$\|g\|_{\infty, [m, M]}^{n-1} \|g'\|_{\infty, [m, M]} \left[\left(\int_{m}^{\lambda} (\lambda - t)^{(p(n-1)+1)-1} (t - m)^{(p+1)-1} dt \right)^{\frac{1}{p}} +$$

$$\left(\int_{\lambda}^{M} (M - t)^{(p+1)-1} (t - \lambda)^{(p(n-1)+1)-1} dt \right)^{\frac{1}{p}} \left\| (f_{1} \circ g^{-1})^{(n)} \circ g \right\|_{q, [m, M]} =$$

$$\|g\|_{\infty, [m, M]}^{n-1} \|g'\|_{\infty, [m, M]} \left\| (f_{1} \circ g^{-1})^{(n)} \circ g \right\|_{q, [m, M]}.$$

$$\left(\frac{\Gamma(p(n-1)+1)\Gamma(p+1)}{\Gamma(pn+2)} \right)^{\frac{1}{p}} \left[(\lambda - m)^{n+\frac{1}{p}} + (M - \lambda)^{n+\frac{1}{p}} \right],$$

$$(40)$$

 $\forall \lambda \in [m, M]$.

So we got so far

$$\left| \int_{m}^{M} (g(\lambda) - g(t))^{n-1} (f_{1} \circ g^{-1})^{(n)} (g(t)) g'(t) K(t, \lambda) dt \right| \leq \|g\|_{\infty, [m, M]}^{n-1} \|g'\|_{\infty, [m, M]} \|(f_{1} \circ g^{-1})^{(n)} \circ g\|_{q, [m, M]}.$$

$$\left(\frac{\Gamma(p(n-1)+1) \Gamma(p+1)}{\Gamma(pn+2)} \right)^{\frac{1}{p}} \left[(M-\lambda)^{n+\frac{1}{p}} + (\lambda-m)^{n+\frac{1}{p}} \right], \tag{41}$$

 $\forall \lambda \in [m, M]$.

Hence it holds

$$\left| \int_{m-0}^{M} \left(\int_{m}^{M} \left(g\left(\lambda \right) - g\left(t \right) \right)^{n-1} \left(f_{i} \circ g^{-1} \right)^{(n)} \left(g\left(t \right) \right) g'\left(t \right) K\left(t, \lambda \right) dt \right) d\left\langle E_{\lambda} x, x \right\rangle \right| \leq$$

$$\|g\|_{\infty,[m,M]}^{n-1} \|g'\|_{\infty,[m,M]} \|(f_i \circ g^{-1})^{(n)} \circ g\|_{q,[m,M]}.$$

$$\left(\frac{\Gamma(p(n-1)+1)\Gamma(p+1)}{\Gamma(pn+2)}\right)^{\frac{1}{p}} \left[\|(M1_H - A)^{n+\frac{1}{p}}\| + \|(A - m1_H)^{n+\frac{1}{p}}\|\right],$$
(42)

for i = 1, 2.

Thus we derive

$$\left\| \int_{m-0}^{M} \left(\int_{m}^{M} (g(\lambda) - g(t))^{n-1} \left(f_{i} \circ g^{-1} \right)^{(n)} (g(t)) g'(t) K(t, \lambda) dt \right) dE_{\lambda} \right\| \leq \|g\|_{\infty, [m, M]}^{n-1} \|g'\|_{\infty, [m, M]} \left\| \left(f_{i} \circ g^{-1} \right)^{(n)} \circ g \right\|_{q, [m, M]} \cdot \left(\frac{\Gamma(p(n-1)+1) \Gamma(p+1)}{\Gamma(pn+2)} \right)^{\frac{1}{p}} \left[\left\| (M1_{H} - A)^{n+\frac{1}{p}} \right\| + \left\| (A - m1_{H})^{n+\frac{1}{p}} \right\| \right],$$

$$(43)$$

for i = 1, 2.

Next we use (42) and (43).

Acting as in the proof of Theorem 3 we find that

$$|R| \stackrel{(30)}{\leq} \frac{1}{2(n-1)!(M-m)} \cdot \left\{ 2 \left[\|f_{2}(A)\| \|g\|_{\infty,[m,M]}^{n-1} \|g'\|_{\infty,[m,M]} \| (f_{1} \circ g^{-1})^{(n)} \circ g \|_{q,[m,M]} \cdot \left(\frac{\Gamma(p(n-1)+1)\Gamma(p+1)}{\Gamma(pn+2)} \right)^{\frac{1}{p}} \left[\|(M1_{H}-A)^{n+\frac{1}{p}}\| + \|(A-m1_{H})^{n+\frac{1}{p}}\| \right] \right] + (44)$$

$$2 \left[\|f_{1}(A)\| \|g\|_{\infty,[m,M]}^{n-1} \|g'\|_{\infty,[m,M]} \| (f_{2} \circ g^{-1})^{(n)} \circ g \|_{q,[m,M]} \cdot \left(\frac{\Gamma(p(n-1)+1)\Gamma(p+1)}{\Gamma(pn+2)} \right)^{\frac{1}{p}} \left[\|(M1_{H}-A)^{n+\frac{1}{p}}\| + \|(A-m1_{H})^{n+\frac{1}{p}}\| \right] \right] \right\} = \frac{1}{(n-1)!(M-m)} \left\{ \|g\|_{\infty,[m,M]}^{n-1} \|g'\|_{\infty,[m,M]} \left(\frac{\Gamma(p(n-1)+1)\Gamma(p+1)}{\Gamma(pn+2)} \right)^{\frac{1}{p}} \cdot \left[\|f_{2}(A)\| \|(f_{1} \circ g^{-1})^{(n)} \circ g \|_{q,[m,M]} + \|f_{1}(A)\| \|(f_{2} \circ g^{-1})^{(n)} \circ g \|_{q,[m,M]} \right] \cdot \left[\|(M1_{H}-A)^{n+\frac{1}{p}}\| + \|(A-m1_{H})^{n+\frac{1}{p}}\| \right] \right\}, \tag{45}$$

proving the claim.

We give for n = 1:

Corollary 6 (to Theorem 5) It holds

$$\left| \left\langle f_{1}\left(A\right) f_{2}\left(A\right) x, x \right\rangle - \left\langle f_{1}\left(A\right) x, x \right\rangle \left\langle f_{2}\left(A\right) x, x \right\rangle \right| \leq \frac{\|g'\|_{\infty, [m, M]}}{\left(M - m\right) \left(p + 1\right)^{\frac{1}{p}}} \cdot \left[\|f_{2}\left(A\right)\| \left\| \left(f_{1} \circ g^{-1}\right)' \circ g \right\|_{q, [m, M]} + \|f_{1}\left(A\right)\| \left\| \left(f_{2} \circ g^{-1}\right)' \circ g \right\|_{q, [m, M]} \right] \cdot \left[\left\| \left(M1_{H} - A\right)^{1 + \frac{1}{p}} \right\| + \left\| \left(A - m1_{H}\right)^{1 + \frac{1}{p}} \right\| \right].$$

$$(46)$$

We continue with

Theorem 7 All as in Theorem 3. Then

$$\langle (\Delta (f_{1}, f_{2}; g)) (A) x, x \rangle \leq \frac{(M - m)^{n-1}}{(n-1)!} \|g\|_{\infty, [m, M]}^{n-1} \|g'\|_{\infty, [m, M]} \cdot \left[\|f_{1} (A)\| \|(f_{2} \circ g^{-1})^{(n)} \circ g\|_{1, [m, M]} + \|f_{2} (A)\| \|(f_{1} \circ g^{-1})^{(n)} \circ g\|_{1, [m, M]} \right].$$

$$(47)$$

Proof. We observe that

$$\left| \int_{m}^{M} (g(\lambda) - g(t))^{n-1} (f_{i} \circ g^{-1})^{(n)} (g(t)) g'(t) K(t, \lambda) dt \right| \leq$$

$$\int_{m}^{M} |g(\lambda) - g(t)|^{n-1} |g'(t)| |K(t, \lambda)| \left| (f_{i} \circ g^{-1})^{(n)} (g(t)) \right| dt \leq$$

$$\|g\|_{\infty, [m, M]}^{n-1} \|g'\|_{\infty, [m, M]} (M - m)^{n} \left(\int_{m}^{M} \left| (f_{i} \circ g^{-1})^{(n)} (g(t)) \right| dt \right) =$$

$$\|g\|_{\infty, [m, M]}^{n-1} \|g'\|_{\infty, [m, M]} (M - m)^{n} \left\| (f_{i} \circ g^{-1})^{(n)} \circ g \right\|_{1, [m, M]}, \quad i = 1, 2. \quad (48)$$

Hence it holds (i = 1, 2)

$$\left| \int_{m-0}^{M} \left(\int_{m}^{M} (g(\lambda) - g(t))^{n-1} (f_{i} \circ g^{-1})^{(n)} (g(t)) g'(t) K(t, \lambda) dt \right) d \langle E_{\lambda} x, x \rangle \right| \leq \|g\|_{\infty, [m, M]}^{n-1} \|g'\|_{\infty, [m, M]} (M - m)^{n} \| (f_{i} \circ g^{-1})^{(n)} \circ g \|_{1, [m, M]},$$
(49)

the last is valid since

$$\int_{m-0}^{M} d\langle E_{\lambda} x, x \rangle = 1, \text{ for } x \in H : ||x|| = 1.$$
 (50)

Therefore it holds

$$\left\| \int_{m-0}^{M} \left(\int_{m}^{M} (g(\lambda) - g(t))^{n-1} \left(f_{i} \circ g^{-1} \right)^{(n)} (g(t)) g'(t) K(t, \lambda) dt \right) dE_{\lambda} \right\| \leq \|g\|_{\infty, [m, M]}^{n-1} \|g'\|_{\infty, [m, M]} (M - m)^{n} \left\| \left(f_{i} \circ g^{-1} \right)^{(n)} \circ g \right\|_{1, [m, M]}, \tag{51}$$

for i = 1, 2.

Acting as in the proof of Theorem 3 we find that

$$|R| \stackrel{\text{(by (30), (49), (51))}}{\leq} \frac{1}{2(n-1)!(M-m)} \cdot \left\{ 2 \|f_{2}(A)\| \|g\|_{\infty,[m,M]}^{n-1} \|g'\|_{\infty,[m,M]} (M-m)^{n} \| (f_{1} \circ g^{-1})^{(n)} \circ g \|_{1,[m,M]} + 2 \|f_{1}(A)\| \|g\|_{\infty,[m,M]}^{n-1} \|g'\|_{\infty,[m,M]} (M-m)^{n} \| (f_{2} \circ g^{-1})^{(n)} \circ g \|_{1,[m,M]} \right\} = \frac{(M-m)^{n-1}}{(n-1)!} \|g\|_{\infty,[m,M]}^{n-1} \|g'\|_{\infty,[m,M]} \cdot \left[\|f_{2}(A)\| \| (f_{1} \circ g^{-1})^{(n)} \circ g \|_{1,[m,M]} + \|f_{1}(A)\| \| (f_{2} \circ g^{-1})^{(n)} \circ g \|_{1,[m,M]} \right],$$

proving the claim.

We finish this section with

Corollary 8 (to Theorem 7, n = 1) It holds

$$\left| \left\langle f_{1}\left(A\right) f_{2}\left(A\right) x, x \right\rangle - \left\langle f_{1}\left(A\right) x, x \right\rangle \left\langle f_{2}\left(A\right) x, x \right\rangle \right| \leq \|g'\|_{\infty, [m, M]} \cdot \left[\|f_{1}\left(A\right)\| \left\| \left(f_{2} \circ g^{-1}\right)' \circ g \right\|_{1, [m, M]} + \|f_{2}\left(A\right)\| \left\| \left(f_{1} \circ g^{-1}\right)' \circ g \right\|_{1, [m, M]} \right]. \tag{53}$$

4 Applications

We give

Theorem 9 Let $f_1, f_2 \in C'([a,b])$ with $[m,M] \subset (a,b), m < M$. Here A is a selfadjoint linear operator on the Hilbert space H with spectrum $Sp(A) \subseteq [m,M]$. We consider any $x \in H : ||x|| = 1$, and $\rho > 0 : M < \ln \rho$.

Then

$$\left|\left\langle f_{1}\left(A\right)f_{2}\left(A\right)x,x\right\rangle -\left\langle f_{1}\left(A\right)x,x\right\rangle \left\langle f_{2}\left(A\right)x,x\right\rangle \right|\leq\frac{e^{M}}{2\left(M-m\right)\rho}$$

$$\left[\|f_{2}(A)\| \|(f_{1} \circ \ln \rho t)' \circ \frac{e^{t}}{\rho} \|_{\infty,[m,M]} + \|f_{1}(A)\| \|(f_{2} \circ \ln \rho t)' \circ \frac{e^{t}}{\rho} \|_{\infty,[m,M]} \right] \\
\left[\|(M1_{H} - A)^{2}\| + \|(A - m1_{H})^{2}\| \right].$$
(54)

Proof. Apply Corollary 4 for $g(t) = \frac{e^t}{\rho}$. \blacksquare We continue with

Theorem 10 All as in Theorem 9. Let $p, q > 1 : \frac{1}{p} + \frac{1}{q} = 1$. Then

$$\left|\left\langle f_{1}\left(A\right)f_{2}\left(A\right)x,x\right\rangle -\left\langle f_{1}\left(A\right)x,x\right\rangle \left\langle f_{2}\left(A\right)x,x\right\rangle \right|\leq\frac{e^{M}}{\left(M-m\right)\left(p+1\right)^{\frac{1}{p}}\rho}$$

$$\left[\|f_{2}(A)\| \left\| (f_{1} \circ \ln \rho t)' \circ \frac{e^{t}}{\rho} \right\|_{q,[m,M]} + \|f_{1}(A)\| \left\| (f_{2} \circ \ln \rho t)' \circ \frac{e^{t}}{\rho} \right\|_{q,[m,M]} \right] \\
\left[\left\| (M1_{H} - A)^{1 + \frac{1}{p}} \right\| + \left\| (A - m1_{H})^{1 + \frac{1}{p}} \right\| \right].$$
(55)

Proof. Use of Corollary 6 and $g(t) = \frac{e^t}{\rho}$; $\rho > 0$, $M < \ln \rho$. \blacksquare We finish article with

Theorem 11 Here all as in Theorem 9. Then

$$\left|\left\langle f_{1}\left(A\right)f_{2}\left(A\right)x,x\right\rangle -\left\langle f_{1}\left(A\right)x,x\right\rangle \left\langle f_{2}\left(A\right)x,x\right\rangle \right|\leq\frac{e^{M}}{\rho}\tag{56}$$

$$\left[\left\|f_{1}\left(A\right)\right\|\left\|\left(f_{2}\circ\ln\rho t\right)'\circ\frac{e^{t}}{\rho}\right\|_{1,\left[m,M\right]}+\left\|f_{2}\left(A\right)\right\|\left\|\left(f_{1}\circ\ln\rho t\right)'\circ\frac{e^{t}}{\rho}\right\|_{1,\left[m,M\right]}\right].$$

Proof. Use of Corollary 8. ■

References

- [1] G.A. Anastassiou, *Intelligent Mathematics: Computational Analysis*, Springer, New York, Heidelberg, 2011.
- [2] P.L. Čebyšev, Sur les expressions approximatives des intégrales définies par les autres proses entre les mêmes limites, Proc. Math. Soc. Charkov, 2 (1882), 93-98.
- [3] S.S. Dragomir, Inequalities for functions of selfadjoint operators on Hilbert Spaces, a jmaa.org/RGMIA/monographs/InFuncOp.pdf, 2011.
- [4] S. Dragomir, Operator inequalities of Ostrowski and Trapezoidal type, Springer, New York, 2012.

- [5] T. Furuta, J. Mićić Hot, J. Pečarić and Y. Seo, Mond-Pečarić Method in Operator Inequalities. Inequalities for Bounded Selfadjoint Operators on a Hilbert Space, Element, Zagreb, 2005.
- [6] G. Grüss, Über das Maximum des absoluten Betrages von $\left[\left(\frac{1}{b-a}\right)\int_a^b f\left(x\right)g\left(x\right)dx \left(\frac{1}{(b-a)^2}\int_a^b f\left(x\right)dx\int_a^b g\left(x\right)dx\right)\right], \quad \text{Math.} \quad \text{Z.,} \\ 39 \ (1935), \ 215-226.$
- [7] G. Helmberg, Introduction to Spectral Theory in Hilbert Space, John Wiley & Sons, Inc., New York, 1969.

FOURIER SERIES OF SUMS OF PRODUCTS OF POLY-BERNOULLI AND GENOCCHI FUNCTIONS AND THEIR APPLICATIONS

TAEKYUN KIM, DAE SAN KIM, LEE CHAE JANG, AND GWAN-WOO JANG

ABSTRACT. We derive Fourier series expansions of three types of sums of products of poly-Bernoulli and Genocchi functions. In addition, we express each of them in terms of Bernoulli functions.

1. Introduction

For any integer r, the poly-Bernoulli polynomials $\mathbb{B}_m^{(r)}(x)$ of index r are given by the generating function

$$\frac{Li_r(1-e^{-t})}{e^t-1}e^{xt} = \sum_{m=0}^{\infty} \mathbb{B}_m^{(r)}(x)\frac{t^m}{m!}, \quad (\text{see } [1-4,7-10,12,13,17,18]), \tag{1.1}$$

where $Li_r(x) = \sum_{m=0}^{\infty} \frac{x^m}{m^r}$ is the r-th polylogarithmic function for $r \ge 1$ and a rational function for $r \le 0$. We observe here that

$$\frac{d}{dx}(Li_{r+1}(x)) = \frac{1}{x}Li_r(x). \tag{1.2}$$

As to poly-Bernoulli polynomials, we note the following:

$$\frac{d}{dx} \left(\mathbb{B}_{m}^{(r)}(x) \right) = m \mathbb{B}_{m-1}^{(r)}(x), \quad (m \ge 1).$$

$$\mathbb{B}_{m}^{(1)}(x) = B_{m}(x), \quad \mathbb{B}_{0}^{(r)}(x) = 1, \quad \mathbb{B}_{m}^{(0)}(x) = x^{m},$$

$$\mathbb{B}_{m}^{(0)} = \delta_{m,0}, \quad \mathbb{B}_{m}^{(r+1)}(1) - \mathbb{B}_{m}^{(r+1)}(0) = \mathbb{B}_{m-1}^{(r)}, \quad (m \ge 1).$$
(1.3)

The Genocchi polynomials $G_m(x)$ are given by the generating function

$$\frac{2t}{e^t + 1}e^{xt} = \sum_{m=0}^{\infty} G_m(x)\frac{t^m}{m!}, \quad (\text{see } [14 - 16]). \tag{1.4}$$

The first few Genocchi polynomials are as follows:

$$G_0(x) = 0, G_1(x) = 1, G_2(x) = 2x - 1,$$

$$G_3(x) = 3x^2 - 3x, G_4(x) = 4x^3 - 6x^2 + 1,$$

$$G_5(x) = 5x^4 - 10x^3 + 5x, G_6(x) = 6x^5 - 15x^4 + 15x^2 - 3,$$

$$G_7(x) = 7x^6 - 21x^5 + 35x^3 - 21x.$$
(1.5)

From the relation $G_m(x) = mE_{m-1}(x) (m \ge 1)$, we have

$$\deg G_m(x) = m - 1 \ (m \ge 1), \ G_m = mE_{m-1} \ (m \ge 1),$$

$$G_0 = 0, \ G_1 = 1, \ G_{2m+1} = 0 \ (m \ge 1), \ \text{and} \ G_{2m} \ne 0 \ (m \ge 1).$$

$$(1.6)$$

²⁰¹⁰ Mathematics Subject Classification. 11B83, 42A16.

 $Key\ words\ and\ phrases.$ Fourier series, poly-Bernoulli polynomials, poly-Bernoulli functions, Genocchi polynomials, Genocchi functions.

In addition,

2

$$\frac{d}{dx}G_m(x) = mG_{m-1}(x) \ (m \ge 1),
G_m(x+1) + G_m(x) = 2mx^{m-1} \ (m \ge 0).$$
(1.7)

From these, we also have

$$G_m(1) + G_m(0) = 2\delta_{m,1}, \quad (m \ge 0).$$
 (1.8)

$$\int_{0}^{1} G_{m}(x)dx = \frac{1}{m+1} (G_{m+1}(1) - G_{m+1}(0))$$

$$= \frac{2}{m+1} (-G_{m+1}(0) + \delta_{m,0})$$

$$= \begin{cases} 0, & \text{if } m \text{ is even,} \\ -\frac{2}{m+1} G_{m+1}, & \text{if } m \text{ is odd.} \end{cases}$$
(1.9)

For any real number x, let $\langle x \rangle = x - [x] \in [0,1)$ denote the fractional part of x. In this paper, we will study the Fourier series of the following three types of sums of products of poly-Bernoulli and Genocchi functions:

(1)
$$\alpha_m(\langle x \rangle) = \sum_{k=0}^{m-1} \mathbb{B}_k^{(r+1)}(\langle x \rangle) G_{m-k}(\langle x \rangle), (m \ge 2);$$

(2)
$$\beta_m(\langle x \rangle) = \sum_{k=0}^{m-1} \frac{1}{k!(m-k)!} \mathbb{B}_k^{(r+1)}(\langle x \rangle) G_{m-k}(\langle x \rangle), (m \ge 2)$$

(1)
$$\alpha_m(\langle x \rangle) = \sum_{k=0}^{m-1} \mathbb{B}_k^{(r+1)}(\langle x \rangle) G_{m-k}(\langle x \rangle), (m \ge 2);$$

(2) $\beta_m(\langle x \rangle) = \sum_{k=0}^{m-1} \frac{1}{k!(m-k)!} \mathbb{B}_k^{(r+1)}(\langle x \rangle) G_{m-k}(\langle x \rangle), (m \ge 2);$
(3) $\gamma_m(\langle x \rangle) = \sum_{k=1}^{m-1} \frac{1}{k(m-k)} \mathbb{B}_k^{(r+1)}(\langle x \rangle) G_{m-k}(\langle x \rangle), (m \ge 2).$

For some elementary facts about Fourier analysis, the reader may refer to [20,22]. As to $\gamma_m(\langle x \rangle)$, we note that the polynomial identity (1.10) follows immediately from (4.21) and (4.25), which is derived in turn from the Fourier series expansion of $\gamma_m(\langle x \rangle)$.

$$\sum_{k=1}^{m-1} \frac{1}{k(m-k)} \mathbb{B}_{k}^{(r+1)}(x) G_{m-k}(x)
= \frac{1}{m} \left(\Lambda_{m+1} + \frac{2G_{m+1}}{m(m+1)} \right)
+ \frac{1}{m} \sum_{s=1}^{m-1} {m \choose s} \left(\Lambda_{m-s+1} - \frac{2G_{m-s+1}}{m-s+1} (H_{m-1} - H_{m-s}) \right) B_{s}(x).$$
(1.10)

The obvious polynomial identities can be derived also for $\alpha_m(\langle x \rangle)$ and $\beta_m(\langle x \rangle)$ from (2.19) and (2.23), and (3.16) and (3.20), respectively. It is worth noting that from the Fourier series expansion of the function $\sum_{k=1}^{m-1} \frac{1}{k(m-k)} B_k(\langle x \rangle) B_{m-k}(\langle x \rangle)$ we can derive the following polynomial identity:

$$\sum_{k=1}^{m-1} \frac{1}{k(m-k)} B_k(x) B_{m-k}(x)$$

$$= \frac{2}{m^2} \left(B_m + \frac{1}{2} \right) + \frac{2}{m} \sum_{k=1}^{m-2} \frac{1}{m-k} {m \choose k} B_{m-k} B_k(x) + \frac{2}{m} H_{m-1} B_m(x), \quad (m \ge 2).$$
(1.11)

From (1.11), we can derive the following slightly different version of the well-known Miki's identity (see [5,21])

$$\sum_{k=1}^{m-1} \frac{1}{2k (2m-2k)} B_{2k} B_{2m-2k}$$

$$= \frac{1}{m} \sum_{k=1}^{m} \frac{1}{2k} {2m \choose 2k} B_{2k} B_{2m-2k} + \frac{1}{m} H_{2m-1} B_{2m}, \quad (m \ge 2).$$

$$(1.12)$$

Also, from (1.11) and with $\overline{B}_m = \left(\frac{1-2^{m-1}}{2^{m-1}}\right) B_m = \left(2^{1-m} - 1\right) B_m = B_m\left(\frac{1}{2}\right)$, we have

$$\sum_{k=1}^{m-1} \frac{1}{2k (2m-2k)} \overline{B}_{2k} \overline{B}_{2m-2k}$$

$$= \frac{1}{m} \sum_{k=1}^{m} \frac{1}{2k} {2m \choose 2k} B_{2k} \overline{B}_{2m-2k} + \frac{1}{m} H_{2m-1} \overline{B}_{2m}, \quad (m \ge 2),$$
(1.13)

which is the Faber-Pandharipande-Zagier identity (see [6]). Some related works can be found in [11,19].

2. Fourier series of functions of the first type

In this section, we will study the Fourier series of first type of sums of products of poly-Bernoulli and Genocchi functions.

$$\alpha_m(x) = \sum_{k=0}^{m-1} \mathbb{B}_k^{(r+1)}(x) G_{m-k}(x), \quad (m \ge 2).$$
 (2.1)

Note here that deg $\alpha_m(x) = m - 1$. We now consider the function

$$\alpha_m(\langle x \rangle) = \sum_{k=0}^{m-1} \mathbb{B}_k^{(r+1)}(\langle x \rangle) G_{m-k}(\langle x \rangle), \quad (m \ge 2), \tag{2.2}$$

defined on $(-\infty, -\infty)$, which is periodic of period 1. The Fourier series of $\alpha_m(\langle x \rangle)$ is

$$\sum_{n=-\infty}^{\infty} A_n^{(m)} e^{2\pi i n x},\tag{2.3}$$

where

$$A_n^{(m)} = \int_0^1 \alpha_m(\langle x \rangle) e^{-2\pi i n x} dx$$

$$= \int_0^1 \alpha_m(x) e^{-2\pi i n x} dx.$$
(2.4)

Before proceeding further, we need to observe the following.

$$\alpha'_{m}(x) = \sum_{k=0}^{m-1} (k \mathbb{B}_{k-1}^{(r+1)}(x) G_{m-k}(x) + (m-k) \mathbb{B}_{k}^{(r+1)}(x) G_{m-k-1}(x))$$

$$= \sum_{k=1}^{m-1} k \mathbb{B}_{k-1}^{(r+1)}(x) G_{m-k}(x) + \sum_{k=0}^{m-2} (m-k) \mathbb{B}_{k}^{(r+1)}(x) G_{m-k-1}(x)$$

$$= \sum_{k=0}^{m-2} (k+1) \mathbb{B}_{k}^{(r+1)}(x) G_{m-1-k}(x) + \sum_{k=0}^{m-2} (m-k) \mathbb{B}_{k}^{(r+1)}(x) G_{m-1-k}(x)$$

$$= (m+1) \sum_{k=0}^{m-2} \mathbb{B}_{k}^{(r+1)}(x) G_{m-1-k}(x)$$

$$= (m+1)\alpha_{m-1}(x).$$
(2.5)

So, $\alpha'_m(x) = (m+1)\alpha_{m-1}(x)$, and hence

$$\left(\frac{\alpha_{m+1}(x)}{m+2}\right)' = \alpha_m(x),$$
(2.6)

and

4

$$\int_{0}^{1} \alpha_{m}(x)dx = \frac{1}{m+2}(\alpha_{m+1}(1) - \alpha_{m+1}(0)). \tag{2.7}$$

For $m \geq 2$,

$$\Delta_{m} = \alpha_{m}(1) - \alpha_{m}(0)
= \sum_{k=0}^{m-1} \left(\mathbb{B}_{k}^{(r+1)}(1)G_{m-k}(1) - \mathbb{B}_{k}^{(r+1)}G_{m-k} \right)
= \mathbb{B}_{0}^{(r+1)}(1)G_{m}(1) - \mathbb{B}_{0}^{(r+1)}G_{m} + \sum_{k=1}^{m-1} \left(\mathbb{B}_{k}^{(r+1)}(1)G_{m-k}(1) - \mathbb{B}_{k}^{(r+1)}G_{m-k} \right)
= -2G_{m} + 2\delta_{m,1} + \sum_{k=1}^{m-1} \left(\left(\mathbb{B}_{k}^{(r+1)} + \mathbb{B}_{k-1}^{(r)} \right) \left(-G_{m-k} + 2\delta_{m-1,k} \right) - \mathbb{B}_{k}^{(r+1)}G_{m-k} \right)
= -2G_{m} + \sum_{k=1}^{m-1} \left(-2\mathbb{B}_{k}^{(r+1)}G_{m-k} + 2\mathbb{B}_{k}^{(r+1)}\delta_{m-1,k} - \mathbb{B}_{k-1}^{(r)}G_{m-k} + 2\mathbb{B}_{k-1}^{(r)}\delta_{m-1,k} \right)
= -2G_{m} - 2\sum_{k=1}^{m-1} \mathbb{B}_{k}^{(r+1)}G_{m-k} + 2\mathbb{B}_{m-1}^{(r+1)} - \sum_{k=1}^{m-1} \mathbb{B}_{k-1}^{(r)}G_{m-k} + 2\mathbb{B}_{m-2}^{(r)}
= -2\sum_{k=0}^{m-2} \mathbb{B}_{k}^{(r+1)}G_{m-k} - \sum_{k=0}^{m-2} \mathbb{B}_{k}^{(r)}G_{m-k-1} + 2\mathbb{B}_{m-2}^{(r)}
= -2\sum_{k=0}^{m-2} \mathbb{B}_{k}^{(r+1)}G_{m-k} - \sum_{k=0}^{m-2} \mathbb{B}_{k}^{(r)}G_{m-k-1} + 2\mathbb{B}_{m-2}^{(r)}
= \alpha_{m}(0) = \alpha_{m}(1) \iff \Delta_{m} = 0.$$
(2.9)
$$\int_{0}^{1} \alpha_{m}(x)dx = \frac{1}{m+2}\Delta_{m+1}.$$
(2.10)

Now, we are going to determine the Fourier coefficients $A_n^{(m)}$. Case $1: n \neq 0$.

$$\begin{split} A_n^{(m)} &= \int_0^1 \alpha_m(x) e^{-2\pi i n x} dx \\ &= -\frac{1}{2\pi i n} \left[\alpha_m(x) e^{-2\pi i n x} \right]_0^1 + \frac{1}{2\pi i n} \int_0^1 \alpha_m'(x) e^{-2\pi i n x} dx \\ &= -\frac{1}{2\pi i n} (\alpha_m(1) - \alpha_m(0)) + \frac{m+1}{2\pi i n} \int_0^1 \alpha_{m-1}(x) e^{-2\pi i n x} dx \\ &= \frac{m+1}{2\pi i n} A_n^{(m-1)} - \frac{1}{2\pi i n} \Delta_m \\ &= \frac{m+1}{2\pi i n} \left(\frac{m}{2\pi i n} A_n^{(m-2)} - \frac{1}{2\pi i n} \Delta_{m-1} \right) - \frac{1}{2\pi i n} \Delta_m \\ &= \frac{(m+1)m}{(2\pi i n)^2} A_n^{(m-2)} - \frac{m+1}{(2\pi i n)^2} \Delta_{m-1} - \frac{1}{2\pi i n} \Delta_m \\ &= \cdots \\ &= \frac{(m+1)_{m-1}}{(2\pi i n)^{m-1}} A_n^{(1)} - \sum_{j=1}^{m-1} \frac{(m+1)_{j-1}}{(2\pi i n)^j} \Delta_{m-j+1} \\ &= - \sum_{j=1}^{m-1} \frac{(m+1)_{j-1}}{(2\pi i n)^j} \Delta_{m-j+1}, \end{split}$$

where

$$A_n^{(1)} = \int_0^1 \alpha_1(x)e^{-2\pi i nx} dx = \int_0^1 e^{-2\pi i nx} dx = 0.$$
 (2.12)

Case 2: n = 0.

$$A_0^{(m)} = \int_0^1 \alpha_m(x)dx = \frac{1}{m+2} \Delta_{m+1}.$$
 (2.13)

Here we recall the following facts about Bernoulli functions $B_m(\langle x \rangle)$:

(a) for $m \geq 2$,

$$B_m(\langle x \rangle) = -m! \sum_{n=-\infty, n\neq 0}^{\infty} \frac{e^{2\pi i n x}}{(2\pi i n)^m}.$$
 (2.14)

(b) for m = 1,

$$-\sum_{n=-\infty}^{\infty} \frac{e^{2\pi i n x}}{2\pi i n} = \begin{cases} B_1(\langle x \rangle), & \text{for } x \in \mathbb{Z}^c, \\ 0, & \text{for } x \in \mathbb{Z}, \end{cases}$$
 (2.15)

where $\mathbb{Z}^c = \mathbb{R} - \mathbb{Z}$. $\alpha_m(\langle x \rangle)$, $(m \geq 2)$ is piecewise C^{∞} . Moreover, $\alpha_m(\langle x \rangle)$ is continuous for those integers $m \geq 2$ with $\Delta_m = 0$ and discontinuous with jump discontinuities at integers for those integers $m \geq 2$ with $\Delta_m \neq 0$. Assume first that m is an integer ≥ 2 with $\Delta_m = 0$. Then $\alpha_m(0) = \alpha_m(1)$. $\alpha_m(\langle x \rangle)$ is piecewise C^{∞} , and continuous. Thus, the Fourier series of $\alpha_m(\langle x \rangle)$ converges uniformly

to $\alpha_m(\langle x \rangle)$, and

6

$$\alpha_{m}(\langle x \rangle) = \frac{1}{m+2} \Delta_{m+1} + \sum_{n=-\infty, n\neq 0}^{\infty} \left(-\frac{1}{m+2} \sum_{j=1}^{m-1} \frac{(m+2)_{j}}{(2\pi i n)^{j}} \Delta_{m-j+1} \right) e^{2\pi i n x}$$

$$= \frac{1}{m+2} \Delta_{m+1} + \frac{1}{m+2} \sum_{j=1}^{m-1} {m+2 \choose j} \Delta_{m-j+1} \left(-j! \sum_{n=-\infty, n\neq 0}^{\infty} \frac{e^{2\pi i n}}{(2\pi i n)^{j}} \right)$$

$$= \frac{1}{m+2} \Delta_{m+1} + \frac{1}{m+2} \sum_{j=2}^{m-1} {m+2 \choose j} \Delta_{m-j+1} B_{j}(\langle x \rangle)$$

$$+ \frac{1}{m+2} {m+2 \choose 1} \Delta_{m} \times \begin{cases} B_{1}(\langle x \rangle), & \text{for } x \in \mathbb{Z}^{c}, \\ 0, & \text{for } x \in \mathbb{Z}. \end{cases}$$

$$(2.16)$$

Now, we can state our first theorem.

Theorem 2.1. For each integer $l \geq 2$, let

$$\Delta_{l} = -2\sum_{k=0}^{l-2} \mathbb{B}_{k}^{(r+1)} G_{l-k} - \sum_{k=0}^{l-2} \mathbb{B}_{k}^{(r)} G_{l-k-1} + 2\mathbb{B}_{l-2}^{(r)}.$$
(2.17)

Assume that $\Delta_m = 0$, for an integer $m \ge 2$. Then we have the following. (a) $\sum_{k=0}^{m-1} \mathbb{B}_k^{(r+1)}(\langle x \rangle) G_{m-k}(\langle x \rangle)$ has the Fourier series expansion

$$\sum_{k=0}^{m-1} \mathbb{B}_{k}^{(r+1)}(\langle x \rangle) G_{m-k}(\langle x \rangle)
= \frac{1}{m+2} \Delta_{m+1} + \sum_{n=-\infty, n \neq 0}^{\infty} \left(-\frac{1}{m+2} \sum_{j=1}^{m-1} \frac{(m+2)_{j}}{(2\pi i n)^{j}} \Delta_{m-j+1} \right) e^{2\pi i n x},$$
(2.18)

for all $x \in (-\infty, \infty)$, where the convergence is uniform.

$$\sum_{k=0}^{m-1} \mathbb{B}_{k}^{(r+1)}(\langle x \rangle) G_{m-k}(\langle x \rangle)$$

$$= \frac{1}{m+2} \Delta_{m+1} + \frac{1}{m+2} \sum_{j=2}^{m-1} {m+2 \choose j} \Delta_{m-j+1} B_{j}(\langle x \rangle),$$
(2.19)

for all $x \in (-\infty, \infty)$. Here $B_i(\langle x \rangle)$ is the Bernoulli function.

Assume next that $m \geq 2$ is an integer with $\Delta_m \neq 0$. Then $\alpha_m(0) \neq \alpha_m(1)$. So $\alpha_m(\langle x \rangle)$ is piecewise C^{∞} and discontinuous with jump discontinuities at integers. The Fourier series of $\alpha_m(\langle x \rangle)$ converges pointwise to $\alpha_m(\langle x \rangle)$, for $x \in \mathbb{Z}^c$, and converges to

$$\frac{1}{2}(\alpha_m(0) + \alpha_m(1)) = \alpha_m(0) + \frac{1}{2}\Delta_m, \tag{2.20}$$

for $x \in \mathbb{Z}$. Next, we can state our second theorem.

Theorem 2.2. For each integer l > 2, let

$$\Delta_{l} = -2\sum_{k=0}^{l-2} \mathbb{B}_{k}^{(r+1)} G_{l-k} - \sum_{k=0}^{l-2} \mathbb{B}_{k}^{(r)} G_{l-k-1} + 2\mathbb{B}_{l-2}^{(r)}.$$
(2.21)

Assume that $\Delta_m \neq 0$, for an integer ≥ 2 . Then we have the following.

$$\frac{1}{m+2}\Delta_{m+1} + \sum_{n=-\infty, n\neq 0}^{\infty} \left(-\frac{1}{m+2} \sum_{j=1}^{m-1} \frac{(m+2)_j}{(2\pi i n)^j} \Delta_{m-j+1} \right) e^{2\pi i n x}$$

$$= \begin{cases}
\sum_{k=0}^{m-1} \mathbb{B}_k^{(r+1)} (\langle x \rangle) G_{m-k} (\langle x \rangle), & \text{for } x \in \mathbb{Z}^c, \\
\sum_{k=0}^{m-1} \mathbb{B}_k^{(r+1)} G_{m-k} + \frac{1}{2} \Delta_m, & \text{for } x \in \mathbb{Z}.
\end{cases}$$
(2.22)

(b)

$$\frac{1}{m+2} \Delta_{m+1} + \frac{1}{m+2} \sum_{j=1}^{m-1} {m+2 \choose j} \Delta_{m-j+1} B_j(\langle x \rangle)$$

$$= \sum_{k=0}^{m-1} \mathbb{B}_k^{(r+1)} (\langle x \rangle) G_{m-k}(\langle x \rangle), \text{ for } x \in \mathbb{Z}^c;$$
(2.23)

$$\frac{1}{m+2}\Delta_{m+1} + \frac{1}{m+2} \sum_{j=1}^{m-1} {m+2 \choose j} \Delta_{m-j+1} B_j(\langle x \rangle)$$

$$\sum_{k=0}^{m-1} \mathbb{B}_k^{(r+1)} G_{m-k} + \frac{1}{2} \Delta_m, \ x \in \mathbb{Z}.$$
(2.24)

3. Fourier series of functions of the second type

Let $\beta_m(x) = \sum_{k=0}^{m-1} \frac{1}{k!(m-k)!} \mathbb{B}_k^{(r+1)}(x) G_{m-k}(x)$, $(m \ge 2)$. Observe that

$$\beta'_{m}(x) = \sum_{k=0}^{m-1} \left\{ \frac{k}{k!(m-k)!} \mathbb{B}_{k-1}^{(r+1)}(x) G_{m-k}(x) + \frac{m-k}{k!(m-k)!} \mathbb{B}_{k}^{(r+1)}(x) G_{m-k-1}(x) \right\}$$

$$= \sum_{k=1}^{m-1} \frac{1}{(k-1)!(m-k)!} \mathbb{B}_{k-1}^{(r+1)}(x) G_{m-k}(x) + \sum_{k=0}^{m-2} \frac{1}{k!(m-k-1)!} \mathbb{B}_{k}^{(r+1)}(x) G_{m-k-1}(x)$$

$$= 2 \sum_{k=0}^{m-2} \frac{1}{k!(m-1-k)!} \mathbb{B}_{k}^{(r+1)}(x) G_{m-1-k}(x)$$

$$= 2\beta_{m-1}(x).$$
(3.1)

From this, we have

$$\left(\frac{\beta_{m+1}(x)}{2}\right)' = \beta_m(x),$$
(3.2)

and

$$\int_0^1 \beta_m(x)dx = \frac{1}{2}(\beta_{m+1}(1) - \beta_{m+1}(0)). \tag{3.3}$$

For $m \geq 2$, we have

$$\begin{split} &\Omega_{m} = \Omega_{m}(r) = \beta_{m}(1) - \beta_{m}(0) \\ &= \sum_{k=0}^{m-1} \frac{1}{k!(m-k)!} \left(\mathbb{B}_{k}^{(r+1)}(1) G_{m-k}(1) - \mathbb{B}_{k}^{(r+1)} G_{m-k} \right) \\ &= \frac{1}{m!} \left(\mathbb{B}_{0}^{(r+1)}(1) G_{m}(1) - \mathbb{B}_{0}^{(r+1)} G_{m} \right) + \sum_{k=1}^{m-1} \frac{1}{k!(m-k)!} \left(\mathbb{B}_{k}^{(r+1)}(1) G_{m-k}(1) - \mathbb{B}_{k}^{(r+1)} G_{m-k} \right) \\ &= \frac{1}{m!} \left(-2G_{m} + 2\delta_{m,1} \right) + \sum_{k=1}^{m-1} \frac{1}{k!(m-k)!} \left(\left(\mathbb{B}_{k}^{(r+1)} + \mathbb{B}_{k-1}^{(r)} \right) \left(-G_{m-k} + 2\delta_{m-1,k} \right) - \mathbb{B}_{k}^{(r+1)} G_{m-k} \right) \\ &= -\frac{2}{m!} G_{m} + \sum_{k=1}^{m-1} \frac{1}{k!(m-k)!} \left(-2\mathbb{B}_{k}^{(r+1)} G_{m-k} + 2\mathbb{B}_{k}^{(r+1)} \delta_{m-1,k} - \mathbb{B}_{k-1}^{(r)} G_{m-k} + 2\mathbb{B}_{k-1}^{(r)} \delta_{m-1,k} \right) \\ &= -\frac{2}{m!} G_{m} - 2 \sum_{k=1}^{m-1} \frac{\mathbb{B}_{k}^{(r+1)} G_{m-k}}{k!(m-k)!} + 2 \frac{\mathbb{B}_{m-1}^{(r)}}{(m-1)!} - \sum_{k=1}^{m-1} \frac{\mathbb{B}_{k-1}^{(r)} G_{m-k}}{k!(m-k)!} + 2 \frac{\mathbb{B}_{m-2}^{(r)}}{(m-1)!} \\ &= -2 \sum_{k=1}^{m-2} \frac{\mathbb{B}_{k}^{(r+1)} G_{m-k}}{k!(m-k)!} - \sum_{k=1}^{m-1} \frac{\mathbb{B}_{k-1}^{(r)} G_{m-k}}{k!(m-k)!} + 2 \frac{\mathbb{B}_{m-2}^{(r)}}{(m-1)!} . \end{split}$$

Then

$$\beta_m(0) = \beta_m(1) \Longleftrightarrow \Omega_m = 0. \tag{3.5}$$

Also.

$$\int_{0}^{1} \beta_{m}(x)dx = \frac{1}{2}\Omega_{m+1}.$$
(3.6)

Now, we are going to consider the function

$$\beta_m(\langle x \rangle) = \sum_{k=0}^{m-1} \frac{1}{k!(m-k)!} \mathbb{B}_k^{(r+1)}(\langle x \rangle) G_{m-k}(\langle x \rangle), \ (m \ge 2), \tag{3.7}$$

defined on $(-\infty, \infty)$, which is periodic with period 1. The Fourier series of $\beta_m(\langle x \rangle)$ is

$$\sum_{k=-\infty}^{\infty} B_n^{(m)} e^{2\pi i n x},\tag{3.8}$$

where

$$B_n^{(m)} = \int_0^1 \beta_m(\langle x \rangle) e^{-2\pi i n x} dx$$

$$= \int_0^1 \beta_m(x) e^{-2\pi i n x} dx.$$
(3.9)

We are now going to determine the Fourier coefficients $B_n^{(m)}$.

Case 1: $n \neq 0$.

$$\begin{split} B_{n}^{(m)} &= \int_{0}^{1} \beta_{m}(x) e^{-2\pi i n x} dx \\ &= -\frac{1}{2\pi i n} \left[\beta_{m}(x) e^{-2\pi i n x} \right]_{0}^{1} + \frac{1}{2\pi i n} \int_{0}^{1} \beta'_{m}(x) e^{-2\pi i n x} dx \\ &= -\frac{1}{2\pi i n} (\beta_{m}(1) - \beta_{m}(0)) + \frac{2}{2\pi i n} \int_{0}^{1} \beta_{m-1}(x) e^{-2\pi i n x} dx \\ &= \frac{2}{2\pi i n} B_{n}^{(m-1)} - \frac{1}{2\pi i n} \Omega_{m} \\ &= \frac{2}{2\pi i n} \left(\frac{2}{2\pi i n} B_{n}^{(m-2)} - \frac{1}{2\pi i n} \Omega_{m-1} \right) - \frac{1}{2\pi i n} \Omega_{m} \\ &= \left(\frac{2}{2\pi i n} \right)^{2} B_{n}^{(m-2)} - \frac{2}{(2\pi i n)^{2}} \Omega_{m-1} - \frac{1}{2\pi i n} \Omega_{m} \\ &= \cdots \\ &= \left(\frac{2}{2\pi i n} \right)^{m-1} B_{n}^{(1)} - \sum_{j=1}^{m-1} \frac{2^{j-1}}{(2\pi i n)^{j}} \Omega_{m-j+1} \\ &= - \sum_{j=1}^{m-1} \frac{2^{j-1}}{(2\pi i n)^{j}} \Omega_{m-j+1}, \end{split}$$

where

$$B_n^{(1)} = \int_0^1 \beta_1(x)e^{-2\pi i nx} dx = \int_0^1 e^{-2\pi i nx} dx = 0.$$
 (3.11)

Case 2: n = 0.

$$B_0^{(m)} = \int_0^1 \beta_m(x) dx = \frac{1}{2} \Omega_{m+1}.$$
 (3.12)

 $\beta_m(< x>), (m \ge 2)$ is piecewise C^∞ . Moreover, $\beta_m(< x>)$ is continuous for those integers $m \ge 2$ with $\Omega_m = 0$ and discontinuous with jump discontinuities at integers for those integers $m \ge 2$ with $\Omega_m \ne 0$. Assume first that $\Omega_m = 0$, for an integer $m \ge 2$. Then $\beta_m(0) = \beta_m(1)$. $\beta_m(< x>)$ is piecewise C^∞ , and continuous. Thus the Fourier series of $\beta_m(< x>)$ converges uniformly to $\beta_m(< x>)$, and

$$\beta_{m}(\langle x \rangle) = \frac{1}{2}\Omega_{m+1} + \sum_{n=-\infty, n\neq 0}^{\infty} \left(-\sum_{j=1}^{m-1} \frac{2^{j-1}}{(2\pi i n)^{j}} \Omega_{m-j+1} \right) e^{2\pi i n x}$$

$$= \frac{1}{2}\Omega_{m+1} + \sum_{j=1}^{m-1} \frac{2^{j-1}}{j!} \Omega_{m-j+1} \left(-j! \sum_{n=-\infty, n\neq 0}^{\infty} \frac{e^{2\pi i n x}}{(2\pi i n)^{j}} \right)$$

$$= \frac{1}{2}\Omega_{m+1} + \sum_{j=2}^{m-1} \frac{2^{j-1}}{j!} \Omega_{m-j+1} B_{j}(\langle x \rangle) + \Omega_{m} \times \begin{cases} B_{1}(\langle x \rangle), & \text{for } x \in \mathbb{Z}^{c}, \\ 0, & \text{for } x \in \mathbb{Z}. \end{cases}$$

$$(3.13)$$

Now, we are ready to state our first theorem.

Theorem 3.1. For each integer l > 2, let

10

$$\Omega_{l} = -2\sum_{k=0}^{l-2} \frac{\mathbb{B}_{k}^{(r+1)} G_{l-k}}{k!(l-k)!} - \sum_{k=1}^{l-1} \frac{\mathbb{B}_{k-1}^{(r)} G_{l-k}}{k!(l-k)!} + 2\frac{\mathbb{B}_{l-2}^{(r)}}{(l-1)!}.$$
(3.14)

Assume that $\Omega_m = 0$, for an integer $m \ge 2$. Then we have the following. (a) $\sum_{k=0}^{m-1} \frac{1}{k!(m-k)!} \mathbb{B}_k^{(r+1)}(\langle x \rangle) G_{m-k}(\langle x \rangle)$ has the Fourier series expansion

$$\sum_{k=0}^{m-1} \frac{1}{k!(m-k)!} \mathbb{B}_{k}^{(r+1)}(\langle x \rangle) G_{m-k}(\langle x \rangle)
= \frac{1}{2} \Omega_{m+1} + \sum_{n=-\infty, n\neq 0}^{\infty} \left(-\sum_{j=1}^{m-1} \frac{2^{j-1}}{(2\pi i n)^{j}} \Omega_{m-j+1} \right) e^{2\pi i n x},$$
(3.15)

for all $x \in (-\infty, \infty)$, where the convergence is uniform.

$$\sum_{k=0}^{m-1} \frac{1}{k!(m-k)!} \mathbb{B}_{k}^{(r+1)}(\langle x \rangle) G_{m-k}(\langle x \rangle)$$

$$= \frac{1}{2} \Omega_{m+1} + \sum_{j=2}^{m-1} \frac{2^{j-1}}{j!} \Omega_{m-j+1} B_{j}(\langle x \rangle),$$
(3.16)

for all $x \in (-\infty, \infty)$, where $B_i(\langle x \rangle)$ is the Bernoulli function.

Assume next that $\Omega_m \neq 0$, for an integer $m \geq 2$. Then $\beta_m(0) \neq \beta_m(1)$. Thus $\beta_m(\langle x \rangle)$ is piecewise C^{∞} and discontinuous with jump discontinuities at integers. The Fourier series of $\beta_m(\langle x \rangle)$ converges pointwise to $\beta_m(\langle x \rangle)$, for $x \in \mathbb{Z}^c$, and converges to

$$\frac{1}{2}(\beta_m(0) + \beta_m(1)) = \beta_m(0) + \frac{1}{2}\Omega_m$$

$$\sum_{k=0}^{m-1} \frac{1}{k!(m-k)!} \mathbb{B}_k^{(r+1)} G_{m-k} + \frac{1}{2}\Omega_m,$$
(3.17)

for $x \in \mathbb{Z}$. We can now state our second theorem.

Theorem 3.2. For each integer $l \geq 2$, let

$$\Omega_{l} = -2\sum_{k=0}^{l-2} \frac{\mathbb{B}_{k}^{(r+1)} G_{l-k}}{k!(l-k)!} - \sum_{k=1}^{l-1} \frac{\mathbb{B}_{k-1}^{(r)} G_{l-k}}{k!(l-k)!} + 2\frac{\mathbb{B}_{l-2}^{(r)}}{(l-1)!}.$$
(3.18)

Assume that $\Omega_m \neq 0$, for an integer $m \geq 2$. Then we have the following.

$$\frac{1}{2}\Omega_{m+1} + \sum_{n=-\infty, n\neq 0}^{\infty} \left(-\sum_{j=1}^{m-1} \frac{2^{j-1}}{(2\pi i n)^{j}} \Omega_{m-j+1} \right) e^{2\pi i n x}$$

$$= \begin{cases}
\sum_{k=0}^{m-1} \frac{1}{k!(m-k)!} \mathbb{B}_{k}^{(r+1)}(\langle x \rangle) G_{m-k}(\langle x \rangle), & \text{for } x \in \mathbb{Z}^{c}, \\
\sum_{k=0}^{m-1} \frac{1}{k!(m-k)!} \mathbb{B}_{k}^{(r+1)} G_{m-k} + \frac{1}{2}\Omega_{m}, & \text{for } x \in \mathbb{Z}.
\end{cases}$$
(3.19)

Here the convergence is pointwise.

(b)

$$\frac{1}{2}\Omega_{m+1} + \sum_{j=1}^{m-1} \frac{2^{j-1}}{j!} \Omega_{m-j+1} B_j(\langle x \rangle)$$

$$= \sum_{k=0}^{m-1} \frac{1}{k!(m-k)!} \mathbb{B}_k^{(r+1)}(\langle x \rangle) G_{m-k}(\langle x \rangle), \tag{3.20}$$

for $x \in \mathbb{Z}^c$;

$$\frac{1}{2}\Omega_{m+1} + \sum_{j=2}^{m-1} \frac{2^{j-1}}{j!} \Omega_{m-j+1} B_j(\langle x \rangle)$$

$$= \sum_{k=0}^{m-1} \frac{1}{k!(m-k)!} \mathbb{B}_k^{(r+1)} G_{m-k} + \frac{1}{2} \Omega_m, \tag{3.21}$$

for $x \in \mathbb{Z}$. Here $B_j(\langle x \rangle)$ is the Bernoulli function.

4. Fourier series of functions of the third type

Let $\gamma_m(x) = \sum_{k=1}^{m-1} \frac{1}{k(m-k)} \mathbb{B}_k^{(r+1)}(x) G_{m-k}(x)$, $(m \ge 2)$. We observe the following.

$$\gamma'_{m}(x) = \sum_{k=1}^{m-1} \frac{1}{k(m-k)} \left\{ k \mathbb{B}_{k-1}^{(r+1)}(x) G_{m-k}(x) + (m-k) \mathbb{B}_{k}^{(r+1)}(x) G_{m-k-1}(x) \right\}
= \sum_{k=0}^{m-2} \frac{1}{m-k-1} \mathbb{B}_{k}^{(r+1)}(x) G_{m-k-1}(x) + \sum_{k=1}^{m-1} \frac{1}{k} \mathbb{B}_{k}^{(r+1)}(x) G_{m-k-1}(x)
= \frac{1}{m-1} G_{m-1}(x) + \sum_{k=1}^{m-2} \frac{1}{m-1-k} \mathbb{B}_{k}^{(r+1)}(x) G_{m-1-k}(x) + \sum_{k=1}^{m-2} \frac{1}{k} \mathbb{B}_{k}^{(r+1)}(x) G_{m-1-k}(x)
= \frac{1}{m-1} G_{m-1}(x) + (m-1) \sum_{k=1}^{m-2} \frac{1}{k(m-1-k)} \mathbb{B}_{k}^{(r+1)}(x) G_{m-1-k}(x)
= \frac{1}{m-1} G_{m-1}(x) + (m-1) \gamma_{m-1}(x).$$
(4.1)

From this, we see that

$$\left(\frac{1}{m}(\gamma_{m+1}(x) - \frac{1}{m(m+1)}G_{m+1}(x))\right)' = \gamma_m(x)$$
(4.2)

and

12

$$\int_{0}^{1} \gamma_{m}(x)dx$$

$$= \frac{1}{m} \left[\gamma_{m+1}(x) - \frac{1}{m(m+1)} G_{m+1}(x) \right]_{0}^{1}$$

$$= \frac{1}{m} \left(\gamma_{m+1}(1) - \gamma_{m+1}(0) - \frac{1}{m(m+1)} (G_{m+1}(1) - G_{m+1}(0)) \right)$$

$$= \frac{1}{m} \left(\gamma_{m+1}(1) - \gamma_{m+1}(0) - \frac{1}{m(m+1)} (-2G_{m+1}(0) + 2\delta_{m,0}) \right)$$

$$= \frac{1}{m} \left(\gamma_{m+1}(1) - \gamma_{m+1}(0) + \frac{2G_{m+1}}{m(m+1)} \right).$$
(4.3)

For $m \geq 2$, we let

$$\Lambda_{m} = \Lambda_{m}(r) = \gamma_{m}(1) - \gamma_{m}(0)
= \sum_{k=1}^{m-1} \frac{1}{k(m-k)} \left(\mathbb{B}_{k}^{(r+1)}(1) G_{m-k}(1) - \mathbb{B}_{k}^{(r+1)} G_{m-k} \right)
= \sum_{k=1}^{m-1} \frac{1}{k(m-k)} \left(\left(\mathbb{B}_{k}^{(r+1)} + \mathbb{B}_{k-1}^{(r)} \right) (-G_{m-k} + 2\delta_{m-1,k}) - \mathbb{B}_{k}^{(r+1)} G_{m-k} \right)
= \sum_{k=1}^{m-1} \frac{1}{k(m-k)} \left(-2\mathbb{B}_{k}^{(r+1)} G_{m-k} + 2\mathbb{B}_{k}^{(r+1)} \delta_{m-1,k} - \mathbb{B}_{k-1}^{(r)} G_{m-k} + 2\mathbb{B}_{k-1}^{(r)} \delta_{m-1,k} \right)$$
(4.4)

$$=-2\sum_{k=1}^{m-1}\frac{1}{k(m-k)}\mathbb{B}_{k}^{(r+1)}G_{m-k}+\frac{2}{m-1}\mathbb{B}_{m-1}^{(r+1)}-\sum_{k=1}^{m-1}\frac{1}{k(m-k)}\mathbb{B}_{k-1}^{(r)}G_{m-k}+\frac{2}{m-1}\mathbb{B}_{m-2}^{(r)}.$$

So,

$$\gamma_m(1) = \gamma_m(0) \Longleftrightarrow \Lambda_m = 0. \tag{4.5}$$

Also,

$$\int_0^1 \gamma_m(x)dx = \frac{1}{m} \left(\Lambda_{m+1} + \frac{2}{m(m+1)} G_{m+1} \right). \tag{4.6}$$

We are now going to consider

$$\gamma_m(\langle x \rangle) = \sum_{k=1}^{m-1} \frac{1}{k(m-k)} \mathbb{B}_k^{(r+1)}(\langle x \rangle) G_{m-k}(\langle x \rangle), \tag{4.7}$$

defined on $(-\infty, \infty)$, which is periodic with period 1. The Fourier series of $\gamma_m(< x >)$ is

$$\sum_{n=-\infty}^{\infty} C_n^{(m)} e^{2\pi i n x},\tag{4.8}$$

where

$$C_n^{(m)} = \int_0^1 \gamma_m(\langle x \rangle) e^{-2\pi i n x} dx = \int_0^1 \gamma_m(x) e^{-2\pi i n x} dx.$$
 (4.9)

Now, we want to determine the Fourier coefficients $C_n^{(m)}$.

Case 1: $n \neq 0$.

$$C_{n}^{(m)} = \int_{0}^{1} \gamma_{m}(x)e^{-2\pi i nx} dx$$

$$= -\frac{1}{2\pi i n} [\gamma_{m}(x)e^{-2\pi i nx}]_{0}^{1} + \frac{1}{2\pi i n} \int_{0}^{1} \gamma'_{m}(x)e^{-2\pi i nx} dx$$

$$= -\frac{1}{2\pi i n} (\gamma_{m}(1) - \gamma_{m}(0)) + \frac{1}{2\pi i n} \int_{0}^{1} \left(\frac{1}{m-1} G_{m-1}(x) + (m-1)\gamma_{m-1}(x)\right) e^{-2\pi i nx} dx \qquad (4.10)$$

$$= -\frac{1}{2\pi i n} \Lambda_{m} + \frac{m-1}{2\pi i n} C_{n}^{(m-1)} + \frac{1}{2\pi i n (m-1)} \int_{0}^{1} G_{m-1}(x)e^{-2\pi i nx} dx$$

$$= -\frac{1}{2\pi i n} \Lambda_{m} + \frac{m-1}{2\pi i n} C_{n}^{(m-1)} + \frac{1}{2\pi i n (m-1)} \Phi_{m},$$

where

$$\Phi_m = \sum_{k=1}^{m-2} \frac{(m-1)_{k-1}}{(2\pi i n)^k} G_{m-k},\tag{4.11}$$

and one can show

$$\int_{0}^{1} G_{l}(x)e^{-2\pi i nx} dx = \begin{cases}
\sum_{k=1}^{l-1} \frac{2(l)_{k-1}}{(2\pi i n)^{k}} G_{l-k+1}, & \text{for } n \neq 0, \\
-\frac{2G_{l+1}}{l+1}, & \text{for } n = 0.
\end{cases}$$
(4.12)

We observe that

$$\begin{split} C_n^{(m)} &= \frac{m-1}{2\pi i n} C_n^{(m-1)} - \frac{1}{2\pi i n} \Lambda_m + \frac{2}{2\pi i n (m-1)} \Phi_m \\ &= \frac{m-1}{2\pi i n} \left(\frac{m-2}{2\pi i n} C_n^{(m-2)} - \frac{1}{2\pi i n} \Lambda_{m-1} + \frac{2}{2\pi i n (m-2)} \Phi_{m-1} \right) \\ &- \frac{1}{2\pi i n} \Lambda_m + \frac{2}{2\pi i n (m-1)} \Phi_m \\ &= \frac{(m-1)(m-2)}{(2\pi i n)^2} C_n^{(m-2)} - \frac{m-1}{(2\pi i n)^2} \Lambda_{m-1} - \frac{1}{2\pi i n} \Lambda_m \\ &+ \frac{2(m-1)}{(2\pi i n)^2 (m-2)} \Phi_{m-1} + \frac{2}{2\pi i n (m-1)} \Phi_m \\ &= \cdots \\ &= \frac{(m-1)_{m-2}}{(2\pi i n)^{m-2}} C_n^{(2)} - \sum_{j=1}^{m-2} \frac{(m-1)_{j-1}}{(2\pi i n)^j} \Lambda_{m-j+1} + \sum_{j=1}^{m-2} \frac{2(m-1)_{j-1}}{(2\pi i n)^j (m-j)} \Phi_{m-j+1} \\ &= -\frac{(m-1)!}{(2\pi i n)^{m-1}} \Lambda_2 - \sum_{j=1}^{m-2} \frac{(m-1)_{j-1}}{(2\pi i n)^j} \Lambda_{m-j+1} + \sum_{j=1}^{m-2} \frac{2(m-1)_{j-1}}{(2\pi i n)^j (m-j)} \Phi_{m-j+1} \\ &= -\frac{1}{m} \sum_{j=1}^{m-1} \frac{(m)_j}{(2\pi i n)^j} \Lambda_{m-j+1} + \frac{1}{m} \sum_{j=1}^{m-2} \frac{2(m)_j}{(2\pi i n)^j (m-j)} \Phi_{m-j+1}, \end{split}$$

where

14

$$C_n^{(2)} = \int_0^1 \gamma_2(x)e^{-2\pi i n x} dx$$

$$= -\frac{1}{2\pi i n} \left[\gamma_2(x)e^{-2\pi i n x} \right]_0^1 + \frac{1}{2\pi i n} \int_0^1 \gamma_2'(x)e^{-2\pi i n x} dx$$

$$= -\frac{1}{2\pi i n} (\gamma_2(1) - \gamma_2(0)) = -\frac{1}{2\pi i n} \Lambda_2.$$
(4.14)

In order to get a final expression for $C_n^{(m)}$, we observe the following.

$$\sum_{j=1}^{m-2} \frac{2(m)_j}{(2\pi i n)^j (m-j)} \Phi_{m-j+1}$$

$$= \sum_{j=1}^{m-2} \frac{2(m)_j}{(2\pi i n)^j (m-j)} \sum_{k=1}^{m-j-1} \frac{(m-j)_{k-1}}{(2\pi i n)^k} G_{m-j-k+1}$$

$$= \sum_{j=1}^{m-2} \sum_{k=1}^{m-j-1} \frac{2(m)_{j+k-1}}{(2\pi i n)^{j+k} (m-j)} G_{m-j-k+1}$$

$$= 2 \sum_{j=1}^{m-2} \frac{1}{m-j} \sum_{s=j+1}^{m-1} \frac{(m)_{s-1}}{(2\pi i n)^s} G_{m-s+1}$$

$$= 2 \sum_{s=2}^{m-1} \frac{(m)_{s-1}}{(2\pi i n)^s} G_{m-s+1} \sum_{j=1}^{s-1} \frac{1}{m-j}$$

$$= 2 \sum_{s=1}^{m-1} \frac{(m)_s}{(2\pi i n)^s} \frac{G_{m-s+1}}{m-s+1} (H_{m-1} - H_{m-s}).$$
(4.15)

Putting everything altogether, we have

$$C_{n}^{(m)} = -\frac{1}{m} \sum_{s=1}^{m-1} \frac{(m)_{s}}{(2\pi i n)^{s}} \Lambda_{m-s+1} + \frac{2}{m} \sum_{s=1}^{m-1} \frac{(m)_{s}}{(2\pi i n)^{s}} \frac{G_{m-s+1}}{m-s+1} (H_{m-1} - H_{m-s})$$

$$= -\frac{1}{m} \sum_{s=1}^{m-1} \frac{(m)_{s}}{(2\pi i n)^{s}} \left\{ \Lambda_{m-s+1} - \frac{2G_{m-s+1}}{m-s+1} (H_{m-1} - H_{m-s}) \right\}.$$
(4.16)

Case 2: n = 0.

$$C_0^{(m)} = \int_0^1 \gamma_m(x)dx = \frac{1}{m} \left(\Lambda_{m+1} + \frac{2G_{m+1}}{m(m+1)} \right). \tag{4.17}$$

 $\gamma_m(< x>), (m \ge 2)$ is piecewise C^{∞} . In addition, $\gamma_m(< x>)$ is continuous for those integers $m \ge 2$ with $\Lambda_m = 0$, and discontinuous with jump discontinuities at integers for those integers $\Lambda_m \ne 0$.

Assume first that $\Lambda_m = 0$. Then $\gamma_m(0) = \gamma_m(1)$. $\gamma_m(\langle x \rangle)$ is piecewise C^{∞} , and continuous. So the Fourier series of $\gamma_m(\langle x \rangle)$ converges uniformly to $\gamma_m(\langle x \rangle)$, and

$$\gamma_{m}(< x >) = \frac{1}{m} \left(\Lambda_{m+1} + \frac{2G_{m+1}}{m(m+1)} \right) \\
- \frac{1}{m} \sum_{n=-\infty, n \neq 0}^{\infty} \left\{ \sum_{s=1}^{m-1} \frac{(m)_{s}}{(2\pi i n)^{s}} \left(\Lambda_{m-s+1} - \frac{2G_{m-s+1}}{m-s+1} (H_{m-1} - H_{m-s}) \right) \right\} e^{2\pi i n x} \\
= \frac{1}{m} \left(\Lambda_{m+1} + \frac{2G_{m+1}}{m(m+1)} \right) \\
+ \frac{1}{m} \sum_{s=1}^{m-1} {m \choose s} \left(\Lambda_{m-s+1} - \frac{2G_{m-s+1}}{m-s+1} (H_{m-1} - H_{m-s}) \right) \\
\times \left(-s! \sum_{n=-\infty, n \neq 0}^{\infty} \frac{e^{2\pi i n x}}{(2\pi i n)^{s}} \right) \\
= \frac{1}{m} \left(\Lambda_{m+1} + \frac{2G_{m+1}}{m(m+1)} \right) \\
+ \frac{1}{m} \sum_{s=2}^{m-1} {m \choose s} \left(\Lambda_{m-s+1} - \frac{2G_{m-s+1}}{m-s+1} (H_{m-1} - H_{m-s}) \right) B_{s}(< x >) \\
+ \Lambda_{m} \times \begin{cases} B_{1}(< x >), & \text{for } x \in \mathbb{Z}^{c}, \\ 0, & \text{for } x \in \mathbb{Z}. \end{cases}$$

Now, we can state our first result.

Theorem 4.1. For each integer $l \geq 2$, let

$$\Lambda_{l} = -2 \sum_{k=1}^{l-1} \frac{1}{k(l-k)} \mathbb{B}_{k}^{(r+1)} G_{l-k} + \frac{2}{l-1} \mathbb{B}_{l-1}^{(r+1)}
- \sum_{k=1}^{l-1} \frac{1}{k(l-k)} \mathbb{B}_{k-1}^{(r)} G_{l-k} + \frac{2}{l-1} \mathbb{B}_{l-2}^{(r)}.$$
(4.19)

Assume that $\Lambda_m = 0$, for an integer $m \ge 2$. Then we have the following. (a) $\sum_{k=1}^{m-1} \frac{1}{k(m-k)} \mathbb{B}_k^{(r+1)}(\langle x \rangle) G_{m-k}(\langle x \rangle)$ has the Fourier series expansion

$$\sum_{k=1}^{m-1} \frac{1}{k(m-k)} \mathbb{B}_{k}^{(r+1)}(\langle x \rangle) G_{m-k}(\langle x \rangle)
= \frac{1}{m} \left(\Lambda_{m+1} + \frac{2G_{m+1}}{m(m+1)} \right)
- \frac{1}{m} \sum_{n=-\infty, n\neq 0}^{\infty} \left\{ \sum_{s=1}^{m-1} \frac{(m)_{s}}{(2\pi i n)^{s}} \left(\Lambda_{m-s+1} - \frac{2G_{m-s+1}}{m-s+1} (H_{m-1} - H_{m-s}) \right) \right\} e^{2\pi i n x},$$
(4.20)

for all $x \in (-\infty, \infty)$. Here the convergence is uniform.

948

(b)
$$\sum_{k=1}^{m-1} \frac{1}{k(m-k)} \mathbb{B}_{k}^{(r+1)}(\langle x \rangle) G_{m-k}(\langle x \rangle)$$

$$= \frac{1}{m} \left(\Lambda_{m+1} + \frac{2}{m(m+1)} G_{m+1} \right)$$

$$+ \frac{1}{m} \sum_{s=2}^{m-1} {m \choose s} \left(\Lambda_{m-s+1} - \frac{2G_{m-s+1}}{m-s+1} (H_{m-1} - H_{m-s}) \right) B_{s}(\langle x \rangle)$$
(4.21)

for all $x \in (-\infty, \infty)$. Here $B_s(\langle x \rangle)$ is the Bernoulli function.

Assume next that $m \geq 2$ is an integer with $\Lambda_m \neq 0$. Then $\gamma_m(0) \neq \gamma_m(1)$. $\gamma_m(< x >)$ is piecewise C^{∞} and discontinuous with jump discontinuities at integers. Thus the Fourier series of $\gamma_m(< x >)$ converges pointwise to $\gamma_m(< x >)$, for $x \in \mathbb{Z}^c$, and converges to

$$\frac{1}{2}(\gamma_m(0) + \gamma_m(1)) = \gamma_m(0) + \frac{1}{2}\Lambda_m$$

$$= \sum_{k=1}^{m-1} \frac{1}{k(m-k)} \mathbb{B}_k^{(r+1)} G_{m-k} + \frac{1}{2}\Lambda_m,$$
(4.22)

for $x \in \mathbb{Z}$. Next, we can state our second result.

Theorem 4.2. For each integer $l \geq 2$, let

$$\Lambda_{l} = -2\sum_{k=1}^{l-1} \frac{1}{k(l-k)} \mathbb{B}_{k}^{(r+1)} G_{l-k} + \frac{2}{l-1} \mathbb{B}_{l-1}^{(r+1)} - \sum_{k=1}^{l-1} \frac{1}{k(l-k)} \mathbb{B}_{k-1}^{(r)} G_{l-k} + \frac{2}{l-1} \mathbb{B}_{l-2}^{(r)}.$$
(4.23)

Assume that $\Lambda_m \neq 0$, for an integer $m \geq 2$. Then we have the following (a)

$$\frac{1}{m} \left(\Lambda_{m+1} + \frac{2G_{m+1}}{m(m+1)} \right) \\
- \frac{1}{m} \sum_{n=-\infty, n\neq 0}^{\infty} \left(\sum_{s=1}^{m-1} \frac{(m)_s}{(2\pi i n)^s} \left(\Lambda_{m-s+1} - \frac{2G_{m-s+1}}{m-s+1} (H_{m-1} - H_{m-s}) \right) \right) e^{2\pi i n x} \\
= \begin{cases}
\sum_{k=1}^{m-1} \frac{1}{k(m-k)} \mathbb{B}_k^{(r+1)} (\langle x \rangle) G_{m-k} (\langle x \rangle), & \text{for } x \in \mathbb{Z}^c, \\
\sum_{k=1}^{m-1} \frac{1}{k(m-k)} \mathbb{B}_k^{(r+1)} G_{m-k} + \frac{1}{2} \Lambda_m, & \text{for } x \in \mathbb{Z}.
\end{cases} \tag{4.24}$$

Here the convergence is pointwise.

(b)

$$\frac{1}{m} \left(\Lambda_{m+1} + \frac{2G_{m+1}}{m(m+1)} \right)
+ \frac{1}{m} \sum_{s=1}^{m-1} {m \choose s} \left(\Lambda_{m-s+1} - \frac{2G_{m-s+1}}{m-s+1} (H_{m-1} - H_{m-s}) \right) B_s(\langle x \rangle)
= \sum_{k=1}^{m-1} \frac{1}{k(m-k)} \mathbb{B}_k^{(r+1)} (\langle x \rangle) G_{m-k}(\langle x \rangle),$$
(4.25)

for $x \in \mathbb{Z}^c$ and

$$\frac{1}{m} \left(\Lambda_{m+1} + \frac{2G_{m+1}}{m(m+1)} \right) + \frac{1}{m} \sum_{s=2}^{m-1} {m \choose s} \left(\Lambda_{m-s+1} - \frac{2G_{m-s+1}}{m-s+1} (H_{m-1} - H_{m-s}) \right) B_s(\langle x \rangle)$$

$$\sum_{s=1}^{m-1} \frac{1}{k(m-k)} \mathbb{B}_k^{(r+1)} G_{m-k} + \frac{1}{2} \Lambda_m, \tag{4.26}$$

for $x \in \mathbb{Z}$.

References

- 1. T. Arakawa, M. Kaneko, On poly-Bernoulli numbers, Comment. Math. Univ. St. Paul. 48(1999), no. 2, 159-167.
- A. Bayad, Y. Hamahata, Multiple polylogarithms and multi-poly-Bernoulli polynomials, Funct. Approx. Comment. Math. 46(2012), part 1, 45–61.
- D. V. Dolgy, D. S. Kim, T. Kim, T. Mansour, Degenerate poly-Bernoulli polynomials of the second kind, J. Comput. Anal. Appl. 21(2016), no.5, 954–966.
- D. V. Dolgy, D. S. Kim, T. Kim, T. Mansour, Degenerate poly-Cauchy polynomials, Appl. Math. Comput. 269(2015), 637–646.
- 5. G. V. Dunne, C. Schubert, Bernoulli number identities from quantum field theory and topological string theory, Commun. Number Theory Phys. 7(2)(2013), 225-249.
- 6. C. Faber, R. Pandharipande, Hodge integrals and Gromov-Witten theory, Invent. Math. 139(1)(2000), 173-199.
- 7. M. Kaneko, Poly-Bernoulli numbers, J. Theor. Nombres Bordeaux 9(1997), no. 1, 221-228.
- 8. D. S. Kim, T. Kim, A note on degenerate poly-Bernoulli numbers and polynomials, Adv. Difference Equ. 2015, 2015:258, 8 pp.
- 9. D. S. Kim, T. Kim, A note on poly-Bernoulli and higher-order poly-Bernoulli polynomials, Russ. J. Math. Phys., 22(1) (2015), 26-33.
- D. S. Kim, T. Kim, T. Mansour, J.-J. Seo, Fully degenerate poly-Bernoulli polynomials with a q parameter, Filomat 30(2016), no.4, 1029–1035.
- 11. D.S. Kim, T. Kim, A note on higher-order Bernoulli polynomials, J. Inequal. Appl. 2013, 2013:111.
- D. S. Kim, T. Kim, Higher-order Bernoulli and poly-Bernoulli mixed type polynomials, Georgian Math. J. 22(2015), no. 2, 265–272.
- D. S. Kim, T. Kim, H. I. Kwon, T. Mansour, Degenerate poly-Bernoulli polynomials with umbral calculus viewpoint, J. Inequal. Appl. 2015, 2015:228, 13 pp.
- 14. T. Kim, On the Multiple q-Genocchi and Euler Numbers, Russ. J. Math. Phys. 15(2008), 481-486.
- T. Kim, A note on the q-Genocchi Numbers and polynomials, J. Inequalities and applications, 2007 Article ID 71452, 8pages, (2007).
- T. Kim, Some identities for the Bernoulli, the Euler and Genocchi numbers and polynomials, Adv. Stud. Contemp. Math. 20(2015), no.1, 23-28.
- 17. T. Kim, D. S. Kim, Fully degenerate poly-Bernoulli numbers and polynomials, Open Math. 14(2016), 545-556.
- T. Kim, D. S. Kim, T. Komatsu, S.-H. Lee, Higher-order Daehee of the second kind and poly-Cauchy of the second kind mixed-type polynomials, J. Nonlinear Convex Anal. 16(2015), no. 10, 1993–2015.
- T. Kim, D.S. Kim, S.-H. Rim, D.-V. Dolgy, Fourier series of higher-order Bernoulli functions and their applications,
 J. Inequalities and Applications 2017 (2017), 2017:8 Pages.
- 20. J. E. Marsden, Elementary classical analysis, W. H. Freeman and Company, 1974.
- K. Shiratani, S. Yokoyama, An application of p-adic convolutions, Mem. Fac. Sci. Kyushu Univ. Ser. A 36(1)(1982), 7382
- 22. D. G. Zill, M. R. Cullen, Advanced Engineering Mathematics, Jones and Bartlett Publishers 2006.

DEPARTMENT OF MATHEMATICS, KWANGWOON UNIVERSITY, SEOUL 139-701, REPUBLIC OF KOREA *E-mail address*: tkkim@kw.ac.kr

Department of Mathematics, Sogang University, Seoul 121-742, Republic of Korea $E\text{-}mail\ address$: dskim@sogang.ac.kr

18

Graduate School of Education, Konkuk University, Seoul 143-701, Republic of Korea $E\text{-}mail\ address$: lcjang@konkuk.ac.kr

DEPARTMENT OF MATHEMATICS, KWANGWOON UNIVERSITY, SEOUL 139-701, REPUBLIC OF KOREA *E-mail address*: jgw5687@naver.com

Convergence of the Newton-HSS Method under the Lipschitz Condition with the L-average

Hong-Xiu Zhong¹, Guo-Liang Chen², Xue-Ping Guo³

Abstract: Under the hypothesis that the Jacobian matrix satisfies the center Lipschitz condition with the L-average, we prove the local convergence of the Newton-HSS method, which is used to solve large sparse systems of nonlinear equations with positive definite Jacobian matrices at the solution points. Numerical results are given to examine its feasibility and effectiveness.

Keywords: Large sparse systems; Nonlinear equations; Newton-HSS method; Center Lipschtiz condition with the L-average.

AMS classifications: 65F10, 65F50, 65W05,

1 Introduction

In this paper, we consider the following system of nonlinear equations

$$F(x) = 0, (1.1)$$

where $F: \mathbb{D} \subset \mathbb{C}^n \to \mathbb{C}^n$ is nonlinear and continuously differentiable, \mathbb{D} is an open convex subset of the n-dimensional complex linear space \mathbb{C}^n . The Jacobian matrix $F'(x) \in \mathbb{C}^{n \times n}$ is sparse, nonsymmetric and positive definite. This kind of nonlinear equations can be derived in many areas of scientific computing and engineering applications [1, 2, 3].

The most classic and important iterative method for the system of nonlinear equations (1.1) is Newton's method [14, 15], which can be formulated as

$$x_{k+1} = x_k - F'(x_k)^{-1}F(x_k), \quad k = 0, 1, \dots,$$

where $x_0 \in \mathbb{D}$ is a given initial vector. Obviously, at the k-th iteration step, it is necessary to solve the so-called Newton equation

$$F'(x_k)s_k = -F(x_k), (1.2)$$

which is the dominant task in implementations of the Newton method, then get the k+1-th iterative vector $x_{k+1} = x_k + s_k$. Bai and Guo [5], Guo and Duff [10], first used the HSS iteration [4] to solve approximately the Newton equation (1.2), and used inexact Newton method [8] as the outer solver, presented the Newton-HSS method for solving

¹School of Science, Jiangnan University, Wuxi 214122, P. R. China (zhonghongxiu@126.com).

²Corresponding author. Department of Mathematics, Shanghai Key Laboratory of PMMP, East China Normal University, Shanghai 200241, P. R. China (glchen@math.ecnu.edu.cn).

³Department of Mathematics, Shanghai Key Laboratory of PMMP, East China Normal University, Shanghai 200241, P. R. China (xpguo@math.ecnu.edu.cn).

the system of nonlinear equations (1.1), and gave the convergence theorems under the Lipschtiz continuous conditions. The following is HSS iterative method, which is used to solve non-Hermitian positive-definite linear system Ax = b [4].

Algorithm 1.1. HSS

- **1.** Given an initial guess $x_0 \in \mathbb{C}^n$, and positive constant α .
- 2. Split the linear matrix A into its Hermitian part H and skew-Hermitian part S

$$H = \frac{1}{2}(A + A^*)$$
 and $S = \frac{1}{2}(A - A^*).$

3. For $k = 0, 1, 2, \dots$, compute x_{k+1} using the following iteration scheme until $\{x_k\}$ satisfies the stopping criterion:

$$\begin{cases} (\alpha I + H)x_{k+\frac{1}{2}} = (\alpha I - S)x_k + b, \\ (\alpha I + S)x_{k+1} = (\alpha I - H)x_{k+\frac{1}{2}} + b, \end{cases}$$
(1.3)

where I denotes the identity matrix.

Recently, using HSS method as the inner solver for solving Newton equations (1.2), and the modified Newton method as the outer solver, Chen et al. have proposed the modified Newton-HSS method for the system of nonlinear equations (1.1). They have proved the convergence theorems under Hölder continuous condition, which is weaker than the usual Lipschtiz condition. When using Newton's method to solve equations (1.1), Guo [11] studied its semi-local convergence property, which is as brief as Newton-Kantorovich theorem [9, 12], under the hypothese that the derivative satisfies center Lipschtiz condition with the L-average, which is weaker than Hölder condition and Lipschtiz condition, and has gotten a lot of attention and been extensively studied [13, 17, 18].

The following conditions were introduced by Wang in [13], named the center Lipschitz condition with the L-average.

Definition 1.1. Let Y be a Banach space and let $x_* \in \mathbb{C}^n$. Let G be a mapping from \mathbb{C}^n to Y. Then G is said to satisfy the center Lipschitz condition with the L-average on $B(x_*, r)$ if

$$||G(x) - G(x_*)|| \le \int_0^{||x - x_*||} L(u) du$$
 for each $x \in B(x_*, r)$;

In this paper, motivated by the idea of [11], the main work is to study the local convergence theorem of the Newton-HSS method under the hypothese that the derivative satisfies the center Lipschitz condition with the L-average. The organization of the paper is as follows. In Section 2, we introduce the Newton-HSS iterative method. In Section 3, we first give some lemmas which are useful for our main result, then present the new local convergence theorems under the hypothese that the derivative satisfies the center Lipschitz condition with the L-average. An numerical example is given to illustrate the applications of the results in our paper in Section 4. Finally, in Section 5, some conclusions are given.

2 Newton-HSS iteration

For Jacobian matrix F'(x), let

$$H(x) = \frac{1}{2}(F'(x) + F'(x)^*)$$

be its Hermitian part,

$$S(x) = \frac{1}{2}(F'(x) - F'(x)^*)$$

be the skew-Hermitian part, the following is the Newton-HSS method [5, 10].

Algorithm 2.1. Newton-HSS

- **1.** Given an initial guess x_0 , positive constants α and tol, and positive integer sequence $\{l_k\}_{k=0}^{\infty}$;
- **2.** for $k = 0, 1, \dots$ until $||F(x_k)|| \le tol ||F(x_0)||$ do:
 - **2.1.** Set $d_{k,0} = 0$;
 - **2.2.** for $l = 0, 1, \dots, l_k 1$, apply Algorithm HSS to the linear system (1.2):

$$\begin{cases} (\alpha I + H(x_k))d_{k,l+\frac{1}{2}} = (\alpha I - S(x_k))d_{k,l} - F(x_k), \\ (\alpha I + S(x_k))d_{k,l+1} = (\alpha I - H(x_k))d_{k,l+\frac{1}{2}} - F(x_k), \end{cases}$$

and obtain d_{k,l_k} such that

$$||F(x_k) + F'(x_k)d_{k,l_k}|| \le \eta_k ||F(x_k)|| \qquad \eta_k \in [0,1).$$
(2.1)

2.3. Set $x_{k+1} = x_k + d_{k,l_k}$.

Denote

$$B(\alpha; x) = \frac{1}{2\alpha} (\alpha I + H(x))(\alpha I + S(x)),$$

$$C(\alpha; x) = \frac{1}{2\alpha} (\alpha I - H(x))(\alpha I - S(x)),$$

$$T(\alpha; x) = (\alpha I + S(x))^{-1} (\alpha I - H(x))(\alpha I + H(x))^{-1} (\alpha I - S(x)).$$

$$(2.2)$$

Thus we have the following formulas

$$T(\alpha; x) = B(\alpha; x)^{-1}C(\alpha; x),$$

$$F'(x) = B(\alpha; x) - C(\alpha; x),$$

$$F'(x)^{-1} = (I - T(\alpha; x))^{-1}B(\alpha; x)^{-1}.$$
(2.3)

From the Newton-HSS method we can get [10]

$$x_{k+1} = x_k - (I - T_k^{l_k})F'(x_k)^{-1}F(x_k),$$
(2.4)

here $T_k := T(\alpha; x_k)$.

3 Local convergence theorem under the center Lipschitz condition with the L-average

In this section, we establish a new local convergence theorem for the Newton-HSS method under the assumption that the derivative satisfies the center Lipschitz condition with the L-average, which is weaker than Hölder condition and Lipschitz condition. Firstly, we give the assumption.

Assumption 3.1. Let $F : \mathbb{D} \subset \mathbb{C}^n \to \mathbb{C}^n$ be G-differentiable on an open neighborhood $\mathbb{N}_0 \subset \mathbb{D}$ of a point $x_* \in \mathbb{D}$ at which F'(x) is continuous, positive definite, and $F(x_*) = 0$. Assume the following conditions hold for all $x \in B(x_*, r) \subset \mathbb{N}_0$, where $B(x_*, r)$ denotes an open ball centered at x_* with radius r:

(A1) (The Bounded Condition) there exist positive constants β , γ and δ such that

$$max\{||H(x_*)||, ||S(x_*)||\} \le \beta, ||F'(x_*)^{-1}|| \le \gamma.$$

(A2) (The Center Lipschitz Condition with the L-average) there exist positive integrable functions $L_h(u)$ and $L_s(u)$ such that,

$$||H(x) - H(x_*)|| \le \int_0^{\rho(x)} L_h(u) du,$$

$$||S(x) - S(x_*)|| \le \int_0^{\rho(x)} L_s(u) du,$$

here $\rho(x) = ||x - x_*||$.

Let $L(u) = L_h(u) + L_s(u)$, thus L(u) is a positive valued integrable function on $[0, +\infty)$. Before giving the main theorem, we list a series of useful lemmas as follows for our purpose. Lemma 3.1 is taken from [8], and we will give a proof of Lemma 3.2.

Lemma 3.1. Define $\chi(t) = \frac{1}{t} \int_0^t L(u)(t-u)du$, $t \ge 0$, Then χ is increasing on $[0, +\infty)$.

Lemma 3.2. Under Assumption 3.1, if $\gamma \int_0^r L(u)du < 1$, then for $x \in B(x_*, r) \subset \mathbb{N}_0$, $F'(x)^{-1}$ exists, and

(1)
$$||F'(x) - F'(x_*)|| \le \int_0^{\rho(x)} L(u) du$$
,

(2)
$$||F'(x)^{-1}|| \le \frac{\gamma}{1 - \gamma \int_0^{\rho(x)} L(u) du},$$

(3)
$$||F(x)|| \le \left(\frac{1}{\rho(x)} \int_0^{\rho(x)} L(u)(\rho(x) - u) du + 2\beta\right) ||x - x_*||,$$

(4)
$$||x - x_* - F'(x)^{-1}F(x)||$$

$$\leq \frac{\gamma}{1 - \gamma \int_{0}^{\rho(x)} L(u) du} \left(\frac{1}{\rho(x)} \int_{0}^{\rho(x)} L(u) (\rho(x) - u) du + \int_{0}^{\rho(x)} L(u) du \right) \|x - x_*\|.$$

Proof. By Assumption 3.1, F'(x) = H(x) + S(x), perturbation lemma [14], and condition $\gamma \int_0^r L(u) du < 1$, it is easy to get (1) and (2).

For (3), from integral mean-value theorem and Assumption 3.1, we first have

$$||F(x) - F(x_*) - F'(x_*)(x - x_*)||$$

$$= ||\int_0^1 (F'(x + t(x - x_*)) - F'(x_*))dt(x - x_*)||$$

$$\leq \int_0^1 \int_0^{t\rho(x)} L(u)dudt||x - x_*||$$

$$= \frac{1}{\rho(x)} \int_0^{\rho(x)} L(u)(\rho(x) - u)du||x - x_*||,$$
(3.5)

thus, together with $||F'(x_*)|| = ||H(x_*) + S(x_*)|| \le 2\beta$, we have

$$||F(x)|| \le ||F(x) - F(x_*) - F'(x_*)(x - x_*)|| + ||F'(x_*)(x - x_*)||$$

$$\le \left(\frac{1}{\rho(x)} \int_0^{\rho(x)} L(u)(\rho(x) - u) du + 2\beta\right) ||x - x_*||.$$

For (4), by integral mean-value theorem, Assumption 3.1, and (3.5), we can get

$$||x - x_* - F'(x)^{-1}F(x)||$$

$$= || - F'(x)^{-1}(F(x) - F(x_*) - F'(x_*)(x - x_*) + F'(x_*)(x - x_*) - F'(x)(x - x_*))||$$

$$\leq ||F'(x)^{-1}||(||F(x) - F(x_*) - F'(x_*)(x - x_*)|| + ||F'(x_*) - F'(x)||||x - x_*||)$$

$$\leq \frac{\gamma}{1 - \gamma \int_0^{\rho(x)} L(u) du} (\frac{1}{\rho(x)} \int_0^{\rho(x)} L(u)(\rho(x) - u) du + \int_0^{\rho(x)} L(u) du) ||x - x_*||.$$

Then we can give the following local convergence theorem of the Newton-HSS method under the center Lipschtiz condition with the L-average .

Theorem 3.1. Assume that Assumption 3.1 holds with $r \in (0, r_*)$, here r_* is defined by $r_* := \min\{r_1, r_2\}$, where r_1 and r_2 satisfy

$$\int_0^{r_1} L(u)du = 2(\alpha + \beta) \left(\sqrt{\frac{\alpha \tau \theta}{(2 + \tau \theta)\gamma(\alpha + \beta)^2} + 1} - 1 \right), \tag{3.6}$$

$$\frac{1}{r_2} \int_0^{r_2} L(u)(2r_2 - u) du = \frac{1 - 2\beta\gamma((\tau + 1)\theta)^{l_*}}{2\gamma},$$
(3.7)

and with $l_* = \liminf_{k \to \infty} l_k$ satisfying

$$l_* > \lfloor \frac{\ln 2\beta \gamma}{\ln((\tau+1)\theta)} \rfloor,$$
 (3.8)

5

where the symbol $\lfloor \cdot \rfloor$ is used to denote the smallest integer no less than the corresponding real number, $\tau \in (0, (1-\theta)/\theta)$, and

$$\theta \equiv \theta(\alpha; x_*) = ||T(\alpha; x_*)|| \le \max_{\lambda \in \sigma(H(x_*))} \frac{|\alpha - \lambda|}{\alpha + \lambda} \equiv \sigma(\alpha; x_*) < 1.$$

Then, for any $x_0 \in B(x_*, r)$, and any sequence $\{l_k\}_{k=0}^{\infty}$, the iteration sequence $\{x_k\}_{k=0}^{\infty}$ generated by Algorithm Newton-HSS is well defined and converges to x_* . Moreover, it holds that

$$\limsup_{k \to \infty} ||x_k - x_*||^{\frac{1}{k}} \le g(r_*; l_*),$$

here,

$$g(t,l) := \frac{\gamma}{1 - \gamma \int_0^t L(u) du} (\frac{2}{t} \int_0^t L(u)(t - u) du + \int_0^t L(u) du + 2\beta \gamma ((\tau + 1)\theta)^l).$$

Proof. First of all, we will show the following estimate about the iterative matrix $T(\alpha; x)$ of the linear solver: if $x \in B(x_*, r)$, then

$$||T(\alpha; x)|| < (\tau + 1)\theta < 1.$$

In fact, from the definition of $B(\alpha; x)$ in (2.2) and Assumption 3.1, denote $\rho(x) = ||x - x_*||$, we can get

$$||B(\alpha; x) - B(\alpha; x_*)|| \le \frac{1}{2} ||H(x) - H(x_*) + S(x) - S(x_*)|| + \frac{1}{2\alpha} ||H(x)S(x) - H(x_*)S(x_*)|| \le \frac{1}{2} \int_0^{\rho(x)} L(u) du + \frac{1}{2\alpha} ||(H(x) - H(x_*) + H(x_*))(S(x) - S(x_*)) + (H(x) - H(x_*))S(x_*)|| \le \frac{1}{2} \int_0^{\rho(x)} L(u) du + \frac{1}{2\alpha} [(\int_0^{\rho(x)} L_h(u) du + \beta) \int_0^{\rho(x)} L_s(u) du + \beta \int_0^{\rho(x)} L_h(u) du] \le \frac{1}{2} \int_0^{\rho(x)} L(u) du + \frac{1}{2\alpha} (\frac{(\int_0^{\rho(x)} L(u) du)^2}{4} + \beta \int_0^{\rho(x)} L(u) du) \le \frac{1}{8\alpha} (\int_0^{\rho(x)} L(u) du)^2 + \frac{\alpha + \beta}{2\alpha} \int_0^{\rho(x)} L(u) du.$$
(3.9)

Similarly, we have

$$||C(\alpha; x) - C(\alpha; x_*)|| \le \frac{1}{8\alpha} \left(\int_0^{\rho(x)} L(u) du \right)^2 + \frac{\alpha + \beta}{2\alpha} \int_0^{\rho(x)} L(u) du.$$
 (3.10)

Then from (2.3), it follows that

$$||B(\alpha; x_*)^{-1}|| = ||(I - T(\alpha; x_*))F'(x_*)^{-1}|| \le (1 + \theta)\gamma < 2\gamma.$$

Therefore from (3.6), we obtain

$$||I - B(\alpha; x_*)^{-1} B(\alpha; x)||$$

$$\leq ||B(\alpha; x_*)^{-1}|| \cdot ||B(\alpha; x) - B(\alpha; x_*)||$$

$$\leq \gamma \frac{(\int_0^{\rho(x)} L(u) du)^2 + 4(\alpha + \beta) \int_0^{\rho(x)} L(u) du}{4\alpha}$$

$$< 1.$$

Hence using the perturbation lemma, we get $B(\alpha; x)^{-1}$ exists, and

$$||B(\alpha; x)^{-1}|| \le \frac{||B(\alpha; x_*)^{-1}||}{1 - ||I - B(\alpha; x_*)^{-1}B(\alpha; x)||} \le \frac{8\alpha\gamma}{4\alpha - \gamma[(\int_0^{\rho(x)} L(u)du)^2 + 4(\alpha + \beta) \int_0^{\rho(x)} L(u)du]}.$$
(3.11)

Hence, together with (3.6), (3.9)-(3.11), the estimate about the gap between inner iterative matrix $T(\alpha; x)$ and $T(\alpha; x_0)$ is obtained as follows:

$$||T(\alpha; x) - T(\alpha; x_*)||$$

$$= ||B(\alpha; x)^{-1}(C(\alpha; x) - C(\alpha; x_*)) - B(\alpha; x)^{-1}(B(\alpha; x) - B(\alpha; x_*))B(\alpha; x_*)^{-1}C(\alpha; x_*)||$$

$$\leq \frac{2\gamma[(\int_0^{\rho(x)} L(u)du)^2 + 4(\alpha + \beta)\int_0^{\rho(x)} L(u)du]}{4\alpha - \gamma[(\int_0^{\rho(x)} L(u)du)^2 + 4(\alpha + \beta)\int_0^{\rho(x)} L(u)du]}$$

$$< \tau \theta.$$

Consequently,

$$||T(\alpha;x)|| \le ||T(\alpha;x) - T(\alpha;x_*)|| + ||T(\alpha;x_*)|| < (\tau+1)\theta < 1.$$
(3.12)

Next, we turn to estimate the error about the Newton-HSS iteration sequence $\{x_k\}$ defined by (2.4). Clearly, from $\int_0^{\rho(x)} L(u) du < \frac{1}{\rho(x)} \int_0^{\rho(x)} L(u) (2\rho(x) - u) du$ and Lemma 3.2, it holds that $\gamma \int_0^{\rho(x)} L(u) du < 1$, hence, using Lemma 3.1, Lemma 3.2, (3.7), (3.8)

and (3.12), we obtain

$$\begin{aligned} &\|x_{k+1} - x_*\| \\ &= \|x_k - x_* - F'(x_k)^{-1} F(x_k) + T_k^{l_k} F(x_k)^{-1} F(x_k)\| \\ &\leq \|x_k - x_* - F'(x_k)^{-1} F(x_k)\| + \|T_k^{l_k}\| \|F(x_k)^{-1}\| \|F(x_k)\| \\ &\leq \frac{\gamma}{1 - \gamma \int_0^{\rho(x_k)} L(u) du} (\frac{1}{\rho(x_k)} \int_0^{\rho(x_k)} L(u) (\rho(x_k) - u) du + \int_0^{\rho(x_k)} L(u) du) \|x_k - x_*\| \\ &+ \frac{((\tau + 1)\theta)^{l_k} \gamma}{1 - \gamma \int_0^{\rho(x_k)} L(u) du} (\frac{1}{\rho(x_k)} \int_0^{\rho(x_k)} L(u) (\rho(x_k) - u) du + 2\beta) \|x_k - x_*\| \\ &\leq \frac{\gamma}{1 - \gamma \int_0^{\rho(x_k)} L(u) du} (\frac{2}{\rho(x_k)} \int_0^{\rho(x_k)} L(u) (\rho(x_k) - u) du + \int_0^{\rho(x_k)} L(u) du \\ &+ 2\beta \gamma ((\tau + 1)\theta)^{l_k}) \|x_k - x_*\| \\ &\leq g(r_*, l_*) \|x_k - x_*\| \\ &\leq g(r_*, l_*) \|x_k - x_*\| \\ &\leq g(r_2, l_*) \|x_k - x_*\| \\ &\leq g(r_2, l_*) \|x_k - x_*\| \\ &\leq g(r_2, l_*) \|x_k - x_*\| \end{aligned}$$

when $x_k \in B(x_*, r_*)$, here, we have used the notation

$$g(t,l) := \frac{\gamma}{1 - \gamma \int_0^t L(u) du} (\frac{2}{t} \int_0^t L(u)(t - u) du + \int_0^t L(u) du + 2\beta \gamma ((\tau + 1)\theta)^l).$$

Thus, we can further prove that $\{x_k\} \subset B(x_*,r)$ with the estimates

$$||x_{k+1} - x_*|| \le g(r_*, l_*) ||x_k - x_*||, \quad k = 0, 1, 2, \cdots.$$
 (3.13)

In fact, for k = 0 we have $||x_0 - x_*|| < r$, as $x_0 \in B(x_*, r)$. Together with $g(r_*, l_*) < 1$, it follows from (3.13) that

$$||x_1 - x_*|| \le g(r_*, l_*) ||x_0 - x_*|| < r,$$

hence, $x_1 \in B(x_*, r)$. Suppose that $x_k \in B(x_*, r)$, then using (3.13) again, we have

$$||x_{k+1} - x_*|| < q(r_*, l_*) ||x_k - x_*|| < r$$

hence, $x_{k+1} \in B(x_*, r)$. Moreover, we have

$$||x_k - x_*|| \le g(r_*, l_*) ||x_k - x_*|| \le g(r_*, l_*)^{k+1} ||x_0 - x_*||.$$

Now the proof is complete.

959

Remark 1. If we assume the integrable functions $L_h(u)$ and $L_s(u)$ in (A2) are positive constants L_h and L_s , respectively, then the center Lipschtiz condition with the L-average becomes usual Lipschtiz condition. If both integrable functions are $\frac{L}{p}u^{p-1}$, where 0 , <math>L is a positive constant, then the center Lipschtiz condition with the L-average becomes usual Hölder condition. Therefore, Theorem 3.1 is an extension of Theorem 3.2 in [10]. If the outer solver, Newton method, is changed to the modified Newton method, then 3.1 is an extension of Theorem 3.1 in [7].

4 Application

In this section, we apply the main result on a two-demensional nonlinear convectiondiffusion equation.

Example 1. Consider the following two-dimensional nonlinear convection-diffusion equation

$$\begin{cases} -(u_{xx} + u_{yy}) + q_1 u_x + q_2 u_y = u^c, & (x, y) \in \Omega, \\ u(x, y) = 0, & on (x, y) \in \partial \Omega, \end{cases}$$
(4.14)

where c is a rational number, $\Omega = (0,1) \times (0,1)$, $\partial \Omega$ is the boundary. q_1 and q_2 are positive constants used to measure magnitudes of the convective terms. By applying the centered finite difference scheme on the equidistant discretization grid with the stepsize h = 1/(N+1), the system of nonlinear equations (1.1) is obtained with the following form

$$F(x) = Mx + h^2\phi(x) = 0,$$

where N is a prescribed positive integer,

$$M = (T_x \otimes I + I \otimes T_y),$$

$$\phi(x) = (x_1^c, x_2^c, \cdots, x_n^c)^T,$$

with $T_x = tridiag(-1 - Re_1, 2, -1 + Re_1)$, $T_y = tridiag(-1 - Re_2, 2, -1 + Re_2)$, here, $Re_j = \frac{1}{2}q_jh$, j = 1, 2, $Re = \max\{Re_1, Re_2\}$ is the mesh Reynolds number, \otimes is the Kronecker product, and $n = N \times N$.

Obviously, $x_*=0$ is a solution of (4.14), and it is easy to get $F'(x)=M+ch^2diag(x_1^{c-1},x_2^{c-1},\cdots,x_n^{c-1})$. Hence $F'(x_*)=M$. Moreover, we have

$$||F'(x) - F'(x_*)|| \le ch^2 ||x - x_*||^{c-1} = \int_0^{\rho(x)} L(u) du, \quad x \in B(x_*, r) \subset \Omega,$$

where $\|\cdot\|$ denotes the 2-norm, $L(u)=c(c-1)h^2u^{c-2}$. Hence, the center Lipschtiz condition with the L average is satisfied.

Thus we can obtain the convergence result of nonlinear equation (4.14).

Corollary 4.1. Consider (4.14), define $r_* := \min\{r_1, r_2\}$, where r_1 and r_2 satisfy

$$r_1^{c-1} = \frac{2(\alpha+\beta)}{ch^2} \left(\sqrt{\frac{\alpha\tau\theta}{(2+\tau\theta)\gamma(\alpha+\beta)^2} + 1} - 1 \right),$$

$$r_2^{c-1} = \frac{1 - 2\beta\gamma((\tau+1)\theta)^{l_*}}{2(c+1)\gamma h^2},$$

and $l_* = \liminf_{k \to \infty} l_k$ satisfies

$$l_* > \lfloor \frac{\ln 2\beta \gamma}{\ln((\tau+1)\theta)} \rfloor,$$

where the symbol $\lfloor \cdot \rfloor$ is used to denote the smallest integer no less than the corresponding real number, $\tau \in (0, (1-\theta)/\theta)$, and

$$\theta \equiv \theta(\alpha; x_*) = ||T(\alpha; x_*)|| \le \max_{\lambda \in \sigma(H(x_*))} \frac{|\alpha - \lambda|}{\alpha + \lambda} \equiv \sigma(\alpha; x_*) < 1.$$

Then, for any $x_0 \in B(x_*, r)$, and any sequence $\{l_k\}_{k=0}^{\infty}$, the iteration sequence $\{x_k\}_{k=0}^{\infty}$ generated by Algorithm Newton-HSS is well defined and converges to x_* . Moreover, it holds that

$$\limsup_{k \to \infty} \|x_k - x_*\|^{\frac{1}{k}} \le g(r_*; l_*),$$

here,

$$g(t,l) := \frac{\gamma}{1 - c\gamma h^2 t^{c-1}} ((c+2)h^2 t^{c-1} + 2\beta\gamma((\tau+1)\theta)^l).$$

Remark 2. For equation (4.14), if c = 4/3 or c = 3/2, then equation (4.14) becomes the equation studied in [6] and [7], respectively, hence satisfies Hölder condition. If c = 2, thus $L(u) = 2h^2$ is a positive constant, hence equation (4.14) satisfies Lipschtiz condition.

Now we consider the numerical results of the corollary. We choose c=2. In the following computation, the stopping criterion for the outer Newton method is set to be

$$\frac{\|F(x_k)\|_2}{\|F(x_0)\|_2} \le 10^{-10},$$

and the prescribed tolerance for controlling the accuracy of the HSS iteration is set to be $\eta_k = \eta$. Let the initial guess $x_0 = 1$, then parameters β , γ , can be estimated from Assumption 3.1. Take positive constants $q_1 = q$, $q_2 = 1/h$, and adopt experimentally optimal parameter α , which yields the smallest value of $||x_{k+1} - x_*||$, then θ and τ can be estimated from the definition of $||T(\alpha; x_0)||$ and the estimation of $||T(\alpha; x)||$, respectively, and the Newton-HSS method is examined for different problem size $n = N \times N$, different quantity $q = q_1$ and different tolerance η , from the values of $||x_{k+1} - x_*||$, $\frac{||x_{k+1} - x_*||}{||x_k - x_*||}$. We list the numerical results in Tables 4.2 and 4.3.

Table 4.1. The optimal value α for the Newton-HSS method

N	VI	q=600			q=800			q=1000			
	` [$\eta = 0.1$	$\eta = 0.2$	$\eta = 0.4$	$\eta = 0.1$	$\eta = 0.2$	$\eta = 0.4$	$\eta = 0.1$	$\eta = 0.2$	$\eta = 0.4$	
3	0	0.9	3.1	1.8	1.3	3.3	1	0.6	0.6	1.1	
4	0	1	3.3	2.1	1	0.7	1.5	1	3.9	0.6	
5	0	3.7	2.1	4.9	0.7	3.1	3.4	0.7	0.5	2.9	

Table 4.2. Values of $||x_{k+1} - x_*||$ for different N and q ($\eta = 0.1$)

k	N=30			N=40			N=50		
K	q=600	q=800	q=1000	q=600	q=800	q=1000	q=600	q=800	q=1000
1	1.5115	1.8882	3.1749	2.1595	1.1569	3.1537	1.6414	2.1067	2.0363
2	0.1171	0.2152	0.2880	0.1665	0.1154	0.2779	0.0877	0.1133	0.1477
3	0.0087	0.0156	0.0268	0.0116	0.0085	0.0219	0.0075	0.0079	0.0121
4	6.49e-04	0.0011	0.0026	8.30e-04	8.90e-04	0.0021	5.03e-04	7.05e-04	9.03e-04
5	6.05e-05	9.33e-05	2.61e-04	5.97e-05	7.90e-05	1.83e-04	4.16e-05	5.63e-05	7.18e-05
6	5.80e-06	7.70e-06	2.21e-05	4.11e-06	5.98e-06	1.30e-05	3.55e-06	5.03e-06	6.28e-06
7	5.26e-07	5.21e-07	1.53e-06	3.12e-07	4.52e-07	7.06e-07	2.73e-07	3.32e-07	6.01e-07
8	3.23e-08	3.86e-08	1.58e-07	2.35e-08	3.14e-08	4.35e-08	1.96e-08	2.54e-08	5.40e-08
9	2.51e-09	3.36e-09	1.32e-08	1.80e-09	2.64e-09	3.81e-09	1.34e-09	2.10e-09	4.50e-09
10	1.46e-10	2.14e-10	9.05e-10	1.73e-10	2.51e-10	3.10e-10	8.91e-11	1.81e-10	3.59e-10

In Table 4.2, we present the values of $||x_{k+1} - x_*||$, corresponding to the problem size N = 30, 40 and 50, and parameter q = 600, 800 and 1000, respectively, for the inner tolerance $\eta = 0.1$. From the table, we can see that the sequence $\{x_k\}$ generated by the Newton-HSS method converges to the solution x_* in all these situations.

Table 4.3. Values of $\frac{\|x_{k+1}-x_*\|}{\|x_k-x_*\|}$ for different N and q $(\eta=0.1)$

k	N=30			N=40			N=50		
ı K	q=600	q=800	q=1000	q=600	q=800	q=1000	q=600	q=800	q=1000
1	0.0504	0.0629	0.1058	0.0540	0.0392	0.0788	0.0328	0.0421	0.0407
2	0.0775	0.0114	0.0907	0.0771	0.0736	0.0881	0.0534	0.0538	0.0725
3	0.0741	0.0726	0.0931	0.0699	0.0736	0.0788	0.0858	0.0693	0.0819
4	0.0742	0.0729	0.0957	0.0713	0.1048	0.0966	0.0669	0.0898	0.0747
5	0.0933	0.0820	0.1017	0.0720	0.0888	0.0863	0.0827	0.0799	0.0795
6	0.0959	0.0825	0.0848	0.0688	0.0756	0.0712	0.0854	0.0893	0.0874
7	0.0906	0.0676	0.0689	0.0759	0.0757	0.0542	0.0768	0.0659	0.0958
8	0.0614	0.0742	0.1037	0.0752	0.0694	0.0616	0.0718	0.0767	0.0898
9	0.0778	0.0869	0.0835	0.0766	0.0840	0.0876	0.0686	0.0826	0.0833
10	0.0582	0.0636	0.0686	0.0961	0.0953	0.0815	0.0663	0.0860	0.0799

In Table 4.3, we present the values of $\frac{\|x_{k+1}-x_*\|}{\|x_k-x_*\|}$ corresponding to the problem size $N=30,\ 40$ and 50, and parameter $q=600,\ 800$ and 1000, respectively, for the inner tolerance $\eta=0.1$. From the table, we can observe that all the values of $g(r_*,l_*)$ are smaller than 0.11.

5 Conclusion

The Newton-HSS method is a considerable method for solving large sparse nonlinear systems with non-Hermitian positive definite Jacobian matrices. In this paper, Under the hypothesis that the Jacobian matrix satisfies the center Lipschtiz condition with the L-average, which is weaker than Hölder condition and Lipschtiz condition, we establish the local convergence theorem for the Newton-HSS method. Finally, a numerical example is given to confirm the concrete applications of the results of our paper.

6 Acknowledgement

This second author is supported by the National Natural Science Foundation of China (No. 11471122). The third author is partly supported by the National Natural Science Foundation of China (No. 44107310, No. 11471122), Science and Technology Commission of Shanghai Municipality (STCSM) (No. 13dz2260400).

References

- [1] O. Axelsson, G. F. Carey, On the numerical solution of two-point singularly perturbed boundary value problems, *Comput. Methods Appl. Mech. Eng.*, 50, 217–229(1985).
- [2] O. Axelsson, M. Nikolova, Avoiding slave points in an adaptive refinement procedure for convection-diffusion problems in 2D, *Computing*, 61, 331–357(1998).
- [3] Z.-Z. Bai, A class of two-stage iterative methods for systems of weakly nonlinear equations, *Numer. Algor.*, 14, 295–319(1997).
- [4] Z.-Z. Bai, G. H. Golub, M. K. Ng, Hermitian and skew-Hermitian splitting methods for non-Hermitian positive definite linear systems, *SIAM J. Matrix Anal. Appl.*, 24, 603–626(2003).
- [5] Z.-Z. Bai, X.-P. Guo, On Newton-HSS method for systems of nonlinear equations with positive-definite Jacobian matrices, *J. Comput. Math.*, 28, 235–260(2010).
- [6] M.-H. Chen, R.-F. Lin, Q.-B. Wu, Convergence analysis of the modified Newton-HSS method under the Hölder continuous condition, *J. Comput. Appl. Math.*, 264, 115–130(2014).
- [7] M.-H. Chen, Q.-B. Wu, R.-F. Lin, Semilocal convergence analysis for the Modified Newton-HSS method under the Hölder condition, *Numer. Algor.*, 3, 1-19(2016).
- [8] R. S. Dembo, S. C. Eisenstat, T. Steihaug, Inexact Newton methods, SIAM J. Numer. Anal., 19, 400–408(1982).
- [9] O. P. Ferreira, B. F. Svaiter, Kantorovich's majorants principle for Newton's method, *Comput. Optim. Appl.*, 42, 213–229(2009).
- [10] X.-P. Guo, I. S. Duff, Semilocal and global convergence of the Newton-HSS method for systems of nonlinear equations, *Numer. Linear Algebra Appl.*, 18, 299–315(2011).
- [11] X.-P. Guo, On the convergence of Newton's method in Banach space, *Journal of Zhejiang University(Sciences Edition)*, 27(5), 484–492(2000).
- [12] L. V. Kantorovich, G. P. Akilov, Functional Analysis in Normed Spaces, Oxford, Pergamon, 1964.

- [13] C. Li, K. F. NG, Majorizing functions and convergence of the Gauss-Newton method for convex composite optimation, SIAM J. OPTIM., 18(2), 613–642(2007).
- [14] J. M. Ortega, W. C. Rheinbolt, *Iterative Solution of Nonlinear Equations in Several Variables*, Academic Press, NewYork, 1970.
- [15] W. C. Rheinboldt, Methods of solving systems of nonlinear equations (2nd edn), SIAM, Philadelphia, 1998.
- [16] W.-P. Shen, C. Li, Kantorovich-type convergence criterion for inexact Newton methods, *Appl. Numer. Math.*, 59, 1599–1611(2009).
- [17] X.-H. Wang, Convergence of Newton's method and inverse function theorem in Banach space, *Math. Comput.*, 68, 169–185(1999).
- [18] X.-H. Wang, Convergence of Newton's method and uniqueness of the solution of equations in Banach space, *IMA J. Numer. Anal.*, 20, 123–134(2000).

Oscillation for Fractional Neutral Functional Differential Systems*

Yong Zhou^{1,2}, Ahmed Alsaedi² and Bashir Ahmad²

E-mail: yzhou@xtu.edu.cn (Y. Zhou), aalsaedi@hotmail.com (A. Alsaedi), bashirahmad_qau@yahoo.com (B. Ahmad)

Abstract

In this paper, we discuss the linear autonomous system of neutral delay differential equations with Riemann–Liouville fractional derivative

$$D^{\alpha} \left[x(t) + \sum_{i=1}^{l} P_{j} x(t - \tau_{j}) \right] + \sum_{i=1}^{n} Q_{i} x(t - \delta_{i}) = 0$$

where $D^{\alpha}x(t) = [D^{\alpha_1}x_1(t), D^{\alpha_2}x_2(t), ..., D^{\alpha_m}x_m(t)]^T$ is Riemann–Liouville fractional derivative, the coefficients $P_j(j=1,2,...,l)$ and $Q_i(i=1,2,...,n)$ are real $m\times m$ matrices and the delays $\tau_j(j=1,2,...,l)$ and $\delta_i(i-1,2,...,n)$ are non-negative real numbers. Sufficient conditions for all solutions of the given equation to be oscillatory are obtained by using fractional calculus and Laplace transform.

Key words and phrases: Fractional neutral differential equations; Riemann–Liouville derivative; Oscillation; Laplace transform.

AMS (MOS) Subject Classifications: 15A60; 26A33; 34A30; 34K11; 44A10.

1 Introduction

Fractional differential equations have gained considerable importance due to their application in various disciplines, such as physics, mechanics, chemistry, engineering, etc. In the recent years, there has been a significant development in ordinary and partial differential equations involving fractional derivatives, see the monographs of Podlubny[1], Kilbas et al.[2], Diethelm[3], Zhou[4, 5], the recent papers[6, 7, 8, 9] and the references therein.

On the other hand, the objective of oscillation theory is to acquire as much information as possible about the qualitative properties of solutions of differential equations. Oscillation theory of functional differential equations with integer derivative has been developed in the past thirty years. The several monographs by Ladde et al.[10], Györi and Ladas[11], Gopalsamy[12], Erbe et al.[13], Agarwal et al.[14] summarize a lot of important works in this area.

However, to the best of our knowledge, there are few results on oscillation for fractional differential equations. Recently, Grace, Agarwal and Wong, et al.[15], Bolat[16], Duan, Wang and Fu[17], Harikrishnan, Prakash and Nieto[18] investigated oscillation and forced oscillation of fractional-order delay differential equations.

¹ Faculty of Mathematics and Computational Science, Xiangtan University, Hunan 411105, P.R. China

² Nonlinear Analysis and Applied Mathematics (NAAM) Research Group, Faculty of Science, King Abdulaziz University, Jeddah 21589, Saudi Arabia

^{*}Project supported by National Natural Science Foundation of China (11671339).

Y. ZHOU, A. ALSAEDI and B. AHMAD

In this paper, we discuss the neutral functional differential equations with Riemann–Liouville fractional derivative

$$D^{\alpha} \left[x(t) + \sum_{j=1}^{l} P_j x(t - \tau_j) \right] + \sum_{i=1}^{n} Q_i x(t - \delta_i) = 0,$$
 (E)

where $x(t) = [x_1(t), x_2(t), ..., x_m(t)]^T$, $D^{\alpha}x(t) = [D^{\alpha_1}x_1(t), D^{\alpha_2}x_2(t), ..., D^{\alpha_m}x_m(t)]^T$ is Riemann–Liouville fractional derivative of order $0 < \alpha, \alpha_r < 1, \alpha_r = p_r/q_r, p_r, q_r$ are co-prime, for r = 1, 2, ..., m, and $P_j, Q_i \in \mathbb{R}^{m \times m}, j = 1, 2, ..., l, i = 1, 2, ..., n$, the delays $\tau_j(j = 1, 2, ..., l)$ and $\delta_i(i - 1, 2, ..., n)$ are non-negative real numbers.

Our aim is to establish sufficient conditions for oscillation of the system (E). In the next section, we introduce some useful preliminaries. In section 3, we obtain various sufficient conditions for oscillation of all solutions to the system (E) by using fractional calculus and Laplace transform.

2 Preliminaries

In this section, we introduce preliminary facts which are used throughout this paper.

Definition 2.1 [2] Let $[a,b](-\infty < a < b < \infty)$ be a finite interval and let AC[a,b] be the space of functions f which are absolutely continuous on [a,b]. It is known [see Kolmogorov and Fomin ([16], p.338) that AC[a,b] coincides with the space of primitives of Lebesgue summable functions:

$$f(x) \in AC[a,b] \Rightarrow f(x) = c + \int_a^x \psi(t)dt \ (\psi(t) \in L(a,b)).$$

Definition 2.2 [2] The fractional integral of order α with the lower limit zero for a function f is defined as

$$(I^{\alpha}f)(t) = \frac{1}{\Gamma(\alpha)} \int_0^t \frac{f(s)}{(t-s)^{1-\alpha}} ds, \ t > 0, \ 0 < \alpha < 1,$$

provided the right side is point-wise defined on [0,b], where $\Gamma(\cdot)$ is the gamma function.

Definition 2.3 [2] Riemann-Liouville derivative of order α with the lower limit zero for a function f can be written as

$$(D^{\alpha}f)(t) = \frac{1}{\Gamma(1-\alpha)} \frac{d}{dt} \int_0^t \frac{f(s)}{(t-s)^{\alpha}} ds, \ t > 0, \ 0 < \alpha < 1.$$

Firstly, we consider the fractional delay differential systems

$$D^{\alpha}x(t) + \sum_{i=1}^{n} P_{i}x(t - \tau_{i}) = 0, \quad t \ge 0,$$
(1)

where $x(t) = [x_1(t), x_2(t), ..., x_m(t)]^T$, $D^{\alpha}x(t) = [D^{\alpha_1}x_1(t), D^{\alpha_2}x_2(t), ..., D^{\alpha_m}x_m(t)]^T$ is Riemann–Liouville fractional derivative of order $0 < \alpha, \alpha_i < 1$, $\alpha_j = p_j/q_j$, p_j, q_j are odd numbers, for i = 1, 2, ..., m, and $P_i \in \mathbb{R}^{m \times m}$, $\tau_i \in [0, \infty)$ for i = 1, 2, ..., n.

Without loss of generality we will assume the coefficients of P_i of (1) are all nonzero and that $\tau_1 = \max\{\tau_1, ..., \tau_n\}$.

Definition 2.4 By a solution of (1) in $[0, \infty)$ with initial function $\varphi \in AC[-\tau_1, 0]$ we mean a function $x \in AC[-\tau_1, \infty)$ such that $x(t) = \varphi(t)$, $t \in [-\tau_1, 0]$, $(D^{\alpha}x)(t)$ exists and x(t) satisfies (1) in $[0, \infty)$. A solution $x(t) = [x_1(t), ..., x_m(t)]^T$ of system (1) is said to oscillate if every component $x_i(t)$ of the solution has arbitrarily large zeros. Otherwise the solution is called non-oscillatory.

We recall some facts about Laplace transforms. If X(s) is the Laplace transform of x(t),

$$X(s) = (Lx)(s) = \int_0^\infty e^{-st} x(t)dt,$$

Oscillation for Fractional Neutral Functional Differential Systems

then the abscissa of convergence of X(s) is defined by

$$b = \inf\{\delta \in \mathbb{R} : X(\delta) \ exists\}.$$

Then X(s) is analytic for Re(s) > b.

We call a function x(t) to be eventually positive if there exists a $c \ge 0$ such that $x_c(t) > 0$ for all t > 0, where $x_c(t) = x(t+c)$.

For any m-dimensional vector $x = (x_1, x_2, ..., x_m)^T \in \mathbb{R}^m$, ||x|| denotes its norm. For any $m \times m$ real matrix A, the associated matrix norm is then defined by $||A|| = \max_{||x||=1} ||Ax||$. Denote $\mu(P_i)$ is the logarithmic norm with $\mu(P_i) = \max_{||u||=1} (P_i u, u)$.

Lemma 2.5 [2] Let $(LD^{\alpha}x)(s)$ is the Laplace transform of the Riemann–Liouville fractional derivative of order α with the lower limit 0 for a function x, and X(s) is the Laplace transform of $x(t) \in AC[0,b]$, for any b > 0, and the following estimate

$$|x(t)| \le Ae^{p_0 t} \quad (t > b > 0)$$

holds for constants A > 0 and $p_0 > 0$. Then the relation

$$(LD^{\alpha}x)(s) = s^{\alpha}BX(s) - (I^{1-\alpha}x)(0), \ 0 < \alpha < 1$$

is valid for $Re(s) > p_0$, where

$$X(s) = [X_1(s), X_2(s), ..., X_m(s)]^T, \quad s^{\alpha} = [s^{\alpha_1}, s^{\alpha_2}, ..., s^{\alpha_m}]$$

$$(I^{1-\alpha}x)(0) = \left((I^{1-\alpha_1}x_1)(0), (I^{1-\alpha_2}x_2)(0)], ..., (I^{1-\alpha_m}x_m)(0) \right)^T,$$

$$B = [B_1, B_2, ..., B_m]^T \ B_i = (b_{ij})_{m \times m}$$

$$b_{ij} = \begin{cases} 1, & i = j, \\ 0, & i \neq j. \end{cases}$$

Lemma 2.6 [19] If X(s) is the Laplace transform of a non-negative function x(t) and has abscissa of convergence $b > -\infty$, then X(s) has a singularity at the point s = b.

Lemma 2.7 [20] Let $v, w : [0, \infty) \to [0, \infty)$ be continuous functions. If $w(\cdot)$ is nondecreasing and there are constants a > 0 and $0 < \beta < 1$ such that

$$v(t) \le w(t) + a \int_0^t \frac{v(s)}{(t-s)^{\beta}} ds,$$

then there exists a constant $k = k(\beta)$ such that

$$v(t) \le w(t) + ka \int_0^t \frac{w(s)}{(t-s)^{\beta}} ds$$

for every $t \in [0, \infty)$.

3 Main Results

In this section, we present our main results.

Lemma 3.1 For any $c \in \mathbb{R}$, the Laplace transform $X_c(s)$ of $x_c(t)$ exists and has the same abscissa of convergence as X(s).

Y. ZHOU, A. ALSAEDI and B. AHMAD

Proof. Given that

$$X_{c}(s) = \int_{0}^{\infty} e^{-st} x_{c}(t) dt = \int_{0}^{\infty} e^{-st} x(t+c) dt = e^{sc} \int_{c}^{\infty} e^{-st} x(t) dt$$
$$= e^{sc} [X(s) - \int_{0}^{c} e^{-st} x(t) dt].$$

Since the last integral defines an entire function of the complex variable s, therefore X(s) and $X_c(s)$ converge or diverge for the same values of s, and have their singularities at the same points. This completes the proof.

Lemma 3.2 The solution of equation (1) has an exponent estimate

$$x(t) = o(e^{q_0 t})$$
 $(t > b > 0)$

for constant $q_0 > 0$.

Proof. Taking Riemann-Liouville integral of equation (1), we get

$$x(t) = \frac{t^{\alpha-1}}{\Gamma(\alpha)} Bx_0 - \sum_{i=1}^n P_i \int_0^t \frac{1}{\Gamma(\alpha)} (t-s)^{\alpha-1} Bx(s-\tau_i) ds$$
$$= \frac{t^{\alpha-1}}{\Gamma(\alpha)} Bx_0 - \sum_{i=1}^n P_i F_i(t), \tag{2}$$

where

$$x_0 = (I^{1-\alpha}x)(0),$$

$$F_i(t) = \int_0^t \frac{1}{\Gamma(\alpha)} (t-s)^{\alpha-1} Bx(s-\tau_i) ds, \quad \frac{t^{\alpha-1}}{\Gamma(\alpha)} = \left[\frac{t^{\alpha_1-1}}{\Gamma(\alpha_1)}, \frac{t^{\alpha_2-1}}{\Gamma(\alpha_2)}, ..., \frac{t^{\alpha_m-1}}{\Gamma(\alpha_m)}\right].$$

As $AC[-\tau_1, 0]$ is the Banach space with the norm $\|\varphi\|_{AC} = [\|\varphi_1\|_{AC}, \|\varphi_2\|_{AC}, ..., \|\varphi_m\|_{AC}]^T$. Then we have

$$||F_{i}(t)|| \leq \int_{0}^{t} \frac{1}{\Gamma(\alpha)} (t-s)^{\alpha-1} B ||x(s-\tau_{i})|| ds$$

$$\leq \frac{1}{\Gamma(\alpha)} \int_{0}^{t} (t-s)^{\alpha-1} B \max_{s-\tau_{i} \leq \eta \leq s} ||x(\eta)|| ds$$

$$\leq \frac{1}{\Gamma(\alpha)} \int_{0}^{t} (t-s)^{\alpha-1} B \max_{s-\tau_{i} \leq \eta \leq s} ||x(\eta)|| ds,$$

or

$$||F_i(t)|| \leq \frac{1}{\Gamma(\alpha)} \int_0^t (t-s)^{\alpha-1} B\left(\max_{s-\tau_1 \leq \eta \leq s} ||x(\eta)|| + ||\varphi||_{AC}\right) ds.$$
 (3)

From (3), it follows that

$$||x(t)|| \leq \frac{b^{\alpha-1}}{\Gamma(\alpha)}B|x_0| + \sum_{i=1}^n \frac{||P_i||}{\Gamma(\alpha)} \left[\int_0^t (t-s)^{\alpha-1}B\left(\max_{s-\tau_1 \leq \eta \leq s} ||x(\eta)|| + ||\varphi||_{AC}\right) ds \right]$$

$$\leq \frac{b^{\alpha-1}}{\Gamma(\alpha)}B|x_0| + \frac{np}{\Gamma(\alpha)} \frac{t^{\alpha}}{\alpha}B||\varphi||_{AC} + \frac{np}{\Gamma(\alpha)} \int_0^t (t-s)^{\alpha-1}B\max_{s-\tau_1 \leq \eta \leq s} ||x(\eta)|| ds,$$

where $p = \max\{||P_i||\}$, for i = 1, 2, ..., n.

Next we introduce a nondecreasing function m(t) as

$$m(t) = \frac{b^{\alpha - 1}}{\Gamma(\alpha)} B|x_0| + \frac{np}{\Gamma(\alpha)} \frac{t^{\alpha}}{\alpha} B|||\varphi||_{AC}||.$$

Oscillation for Fractional Neutral Functional Differential Systems

By Lemma 2.7, there exists a number α_0 in $\{\alpha_i\}$ such that

$$||x(t)|| \le \max_{t - \tau_1 \le s \le t} ||x(s)|| \le m(t) + \frac{knp}{\Gamma(\alpha_0)} \int_0^t (t - s)^{\alpha_0 - 1} m(s) ds \le m(t) \left(1 + \frac{knp}{\alpha_0 \Gamma(\alpha_0)} t^{\alpha_0} \right). \tag{4}$$

Obviously, from (4) we infer that x(t) has an exponent estimate. The proof is complete.

Theorem 3.3 If the characteristic equation

$$\det\left(\lambda^{\alpha}B + \sum_{i=1}^{n} P_{i}e^{-\lambda\tau_{i}}\right) = 0 \tag{5}$$

has no real roots, then every solution of (1) is oscillatory, where $\lambda^{\alpha} = [\lambda^{\alpha_1}, \lambda^{\alpha_2}, ..., \lambda^{\alpha_m}]$.

Proof. For the sake of contradiction, let us assume that (5) has no real roots and that (1) has a non-oscillatory solution $x(t) = [x_1(t), ..., x_m(t)]^T$. This means that one of the components of x(t) is non-oscillatory. Without loss of generality we assume that the component $x_1(t)$ is eventually positive, such that for some $c \ge 0$, $x_c(t) > 0$ for $t \ge 0$. As (1) is autonomous, it follows by Lemma 3.1 that $X_1(s)$ and $X_c(s)$ have the same convergence. Then we assume that $x_1(t) > 0$ for $t \ge -\tau_1$. Taking Laplace transform of both sides of (1), we obtain

$$s^{\alpha}BX(s) - (I^{1-\alpha}x)(0) + \sum_{i=1}^{n} P_{i} \int_{0}^{\infty} e^{-st}x(t-\tau_{i})dt = 0,$$

i.e.

$$s^{\alpha}BX(s) - (I^{1-\alpha}x)(0) + \sum_{i=1}^{n} P_i e^{-s\tau_i}X(s) + \sum_{i=1}^{n} P_i e^{-s\tau_i} \int_{-\tau_i}^{0} e^{-st}x(t)dt = 0.$$

Hence

$$(s^{\alpha}B + \sum_{i=1}^{n} P_{i}e^{-s\tau_{i}})X(s) = (I^{1-\alpha}x)(0) - \sum_{i=1}^{n} P_{i}e^{-s\tau_{i}} \int_{-\tau_{i}}^{0} e^{-st}x(t)dt.$$
 (6)

Let

$$F(s) = s^{\alpha}B + \sum_{i=1}^{n} P_i e^{-s\tau_i}, \ x_0 = (I^{1-\alpha}x)(0),$$

$$\Phi(s) = x_0 - \sum_{i=1}^{n} P_i e^{-s\tau_i} \int_{-\tau_i}^{0} e^{-st} x(t) dt.$$

Then, from (6) we get

$$F(s)X(s) = \Phi(s), Re(s) > b.$$
(7)

Since det[F(s)] = 0 has no real roots, det[F(s)] > 0, $s \in \mathbb{R}$. By Cramer's rule, we have

$$X_1(s) = \frac{\det[D(s)]}{\det[F(s)]}, \ Re(s) > b, \tag{8}$$

where

$$D(s) = \begin{pmatrix} \Phi_1(s) & F_{12}(s) & \cdots & F_{1m}(s) \\ \vdots & \vdots & & \vdots \\ \Phi_m(s) & F_{m2}(s) & \cdots & F_{mm}(s) \end{pmatrix},$$

 $\Phi_i(s)$ is the *i*th component of the vector $\Phi(s)$ and $F_{ij}(s)$ is the (i,j)th component of the matrix F(s). Clearly, for all i,j=1,2,...,m the functions $\Phi_i(s)$ and $F_{ij}(s)$ are entire and hence $\det[D(s)]$ and $\det[F(s)]$ are also entire functions.

Since $\det[F(s)] > 0$ for $s \in \mathbb{R}$, so $\det[D(s)]/\det[F(s)]$ holds for $s \in \mathbb{R}$ and thus (8) becomes

$$X_1(s) = \frac{\det[D(s)]}{\det[F(s)]}, \ s \in \mathbb{R}.$$
 (9)

Y. ZHOU, A. ALSAEDI and B. AHMAD

As $x_1(t) > 0$, it follows that $X_1(s) > 0$ for all $s \in \mathbb{R}$ and, by $\det[F(s)] > 0$ $s \in \mathbb{R}$ and (9), $\det[D(s)] > 0$ $s \in \mathbb{R}$. Now one can see from the definitions of D(s), F(s) and $\Phi(s)$ that there exist positive constants M, β , and s_0 such that

$$\det[D(s)] \le Me^{-\beta s} \quad for \ s \le -s_0. \tag{10}$$

Since $\det[F(s)]$ is a continuous function in the variables $s, e^{-s\tau_1}, ..., e^{-s\tau_n}$, and $\det[F(s)] > 0$, $s \in \mathbb{R}$, it follows that there exists a positive number m_0 such that

$$\det[F(s)] \ge m_0 \quad for \ s \in \mathbb{R}. \tag{11}$$

From (9), (10) and (11), it follows that

$$X_1(s) = \int_0^\infty e^{-st} x_1(t) dt \ge \int_T^\infty e^{-st} x_1(t) dt \ge e^{-sT} \int_T^\infty x_1(t) dt > 0$$

and so

$$0 < \int_T^\infty x_1(t)dt \le \frac{M}{m_0} e^{s(T-\beta)} \to 0 \quad \text{as } s \to -\infty.$$

This implies that $x_1(t) \equiv 0$ for $t \geq T$, which is a contradiction. The proof is complete.

In Theorem 3.3, the characteristic equation (5) plays an important role in the investigation of the oscillation of equation (1). However, to determine whether (5) has a real root, is quite an issue in itself. In the following we derive some sufficient conditions for the oscillation of equation (1) which can easily be applied.

Before proceeding for it, we need the following lemma which is interesting in its own right.

Lemma 3.4 Assume that

 $P_i \in \mathbb{R}^{m \times m}$, $\tau_i \geq 0$ for i = 1, 2, ..., n, and $\bar{\alpha} = \min\{\alpha_j\}$, for j = 1, 2, ..., m with

$$\sum_{i=1}^{n} \mu(-P_i)e^{-\lambda \tau_i} < 0 \quad \text{for } \lambda \in \mathbb{R}$$
 (12)

and

$$\inf_{\lambda < 0} \left[\frac{1}{\lambda^{\bar{\alpha}}} \sum_{i=1}^{n} \mu(-P_i) e^{-\lambda \tau_i} \right] > 1. \tag{13}$$

Then every solution of (1) oscillates.

Proof. Assume, for the sake of contraction, that (1) has a non-oscillatory solution. Then, by Theorem 3.3, the characteristic equation (5) has a real root λ_0 . In consequence, there exists a vector $u \in \mathbb{R}^n$ with ||u|| = 1 such that

$$\left(\lambda_0^{\alpha} B + \sum_{i=1}^n P_i e^{-\lambda_0 \tau_i}\right) u = 0,$$

i.e.

$$\lambda_0^{\alpha} B u = -\sum_{i=1}^n P_i e^{-\lambda_0 \tau_i} u.$$

Hence

$$\lambda_0^{\bar{\alpha}} = (\lambda_0^{\bar{\alpha}} u, u) \le (\lambda_0^{\alpha} B u, u) = (-\sum_{i=1}^n P_i e^{-\lambda_0 \tau_i} u, u)$$
$$= (-\sum_{i=1}^n P_i u, u) e^{-\lambda_0 \tau_i} \le \sum_{i=1}^n \mu(-P_i) e^{-\lambda_0 \tau_i}.$$

Then by (12), $\lambda_0 < 0$ such that

$$\left[\frac{1}{\lambda_0^{\overline{\alpha}}} \sum_{i=1}^n \mu(-P_i) e^{-\lambda_0 \tau_i}\right] \le 1 \quad \text{or} \quad -\lambda_0 \ge \left[\sum_{i=1}^n -\mu(-P_i)\right]^{\frac{1}{\overline{\alpha}}}.$$
 (14)

This contradicts (13) and completes the proof.

Oscillation for Fractional Neutral Functional Differential Systems

Theorem 3.5 Assume that for each i = 1, 2, ..., n,

$$P_i \in \mathbb{R}^{m \times m}, \quad \tau_i > 0 \quad and \quad \mu(-P_i) < 0.$$

Then each of the following two conditions is sufficient for the oscillation of all solutions of (1):

(i)
$$\sum_{i=1}^{n} -\mu(-P_i)\tau_i \left[\sum_{i=1}^{n} -\mu(-P_i)\right]^{\frac{1-\bar{\alpha}}{\bar{\alpha}}} > \frac{1}{e};$$

(ii)
$$\left[\prod_{i=1}^{n}(-\mu(-P_i))\right]^{\frac{1}{n}}\sum_{i=1}^{n}\tau_i\left[\sum_{i=1}^{n}-\mu(-P_i)\right]^{\frac{1-\bar{\alpha}}{\bar{\alpha}}} > \frac{1}{e}.$$

Proof. We employ Lemma 3.4. As $\mu(-P_i) \le 0$, (12) is satisfied and so it suffices to establish (13). First, assume that (i) holds. Then, by using the inequality $e^x \ge ex$, we see that for all $\lambda < 0$,

$$\frac{1}{\lambda^{\bar{\alpha}}} \sum_{i=1}^{n} \mu(-P_i) e^{-\lambda \tau_i} \geq \frac{1}{\lambda^{\bar{\alpha}}} \sum_{i=1}^{n} \mu(-P_i) e(-\lambda \tau_i)$$

$$= -e \frac{1}{\lambda^{\bar{\alpha}}} \sum_{i=1}^{n} \mu(-P_i) \tau_i \lambda^{\bar{\alpha}} (-\lambda)^{1-\bar{\alpha}}$$

$$\geq e \sum_{i=1}^{n} -\mu(-P_i) \tau_i \left[\sum_{i=1}^{n} -\mu(-P_i) \right]^{\frac{1-\bar{\alpha}}{\bar{\alpha}}},$$

which, together with (i), implies that (13) holds. Next, assume that (ii) holds. Then, by using the arithmetic mean–geometric mean inequality we find that for all $\lambda < 0$,

$$\frac{1}{\lambda^{\overline{\alpha}}} \sum_{i=1}^{n} \mu(-P_i) e^{-\lambda \tau_i} = -\frac{1}{\lambda^{\overline{\alpha}}} \sum_{i=1}^{n} -\mu(-P_i) e^{-\lambda \tau_i} \\
\geq -\frac{1}{\lambda^{\overline{\alpha}}} n \left[\prod_{i=1}^{n} -\mu(-P_i) e^{-\lambda \tau_i} \right]^{\frac{1}{n}} \\
= -\frac{1}{\lambda^{\overline{\alpha}}} n \left[\prod_{i=1}^{n} -\mu(-P_i) \right]^{\frac{1}{n}} \exp\left(-\frac{1}{n} \lambda \sum_{i=1}^{n} \tau_i \right) \\
\geq -\frac{1}{\lambda^{\overline{\alpha}}} \left[\prod_{i=1}^{n} -\mu(-P_i) \right]^{\frac{1}{n}} e\left(-\lambda \sum_{i=1}^{n} \tau_i \right) \\
= \left[\prod_{i=1}^{n} -\mu(-P_i) \right]^{\frac{1}{n}} e(-\lambda)^{1-\overline{\alpha}} \sum_{i=1}^{n} \tau_i \\
\geq e \left[\prod_{i=1}^{n} (-\mu(-P_i)) \right]^{\frac{1}{n}} \sum_{i=1}^{n} \tau_i \left[\sum_{i=1}^{n} -\mu(-P_i) \right]^{\frac{1-\overline{\alpha}}{\overline{\alpha}}}.$$

From this and (ii) it follows that (13) holds. The proof is complete. As a special case of the delay differential system with one delay,

$$(D^{\alpha}x)(t) + Px(t-\tau) = 0, \tag{15}$$

where

$$P \in \mathbb{R}^{m \times m}$$
 and $\tau \ge 0$,

the conditions (i) and (ii) coincide and each reduces to

$$[-\mu(-P)]^{\frac{1}{\bar{\alpha}}}\tau > \frac{1}{e}.\tag{16}$$

Y. ZHOU, A. ALSAEDI and B. AHMAD

Note that (16) is sharp in the sense that the lower bound 1/e cannot be improved. Moreover, when P is a scalar, (16) is a sufficient condition for the oscillation of all solutions to equation (15).

For the delay differential system (15), we also have the following explicit sufficient condition for the oscillation of all solutions.

Theorem 3.6 Assume that

$$P \in \mathbb{R}^{m \times m}$$
 and $\tau \ge 0$.

If P has no real eigenvalues in the interval $(-\infty, 1/(e\tau)^{\bar{\alpha}}]$ (when $\tau = 0$, replace $1/(e\tau)^{\bar{\alpha}}$ by $+\infty$), then every solution of (15) oscillates.

Proof. For $\tau = 0$, this result follows immediately from Theorem 3.1. So assume $\tau > 0$. Note that the characteristic equation $\det(\lambda^{\alpha}B + Pe^{-\lambda\tau}) = 0$ has a real root λ_0 , that is, $\det(\lambda_0^{\alpha}e^{\lambda_0\tau}B + P) = 0$ if and only if $\mu_0^{\alpha} = -\lambda_0^{\alpha}e^{\lambda_0\tau}$ is a real eigenvalue of P. For convenience, we take one element $\lambda_0^{\alpha_i}$ of $\lambda_0^{\alpha_i}$:

$$\mu_0^{\alpha_i} = -\lambda_0^{\alpha_i} e^{\lambda_0 \tau}. \tag{17}$$

Observe that (17) holds if $\lambda_0^{\alpha_i} + \mu_0^{\alpha_i} e^{-\lambda_0 \tau} = 0$, that is, the equation $\lambda^{\alpha_i} + \mu_0^{\alpha_i} e^{-\lambda \tau} = 0$ has a real root. If $\mu_0 \leq 1/e\tau$, then the eigenvalue μ_0^{α} of P should lie in the interval $(-\infty, 1/(e\tau)^{\bar{\alpha}}]$. The proof is complete.

Definition 3.7 ([13]) We say that (1) is oscillatory, globally in the delays, if for all $\tau_i \geq 0$ for i = 1, 2, ..., n, every solution of (1) oscillates.

The following corollary is an immediate consequence of Theorem 3.6.

Corollary 3.8 Equation (15) is oscillatory globally in the delay τ if P has no real eigenvalues.

Next, we consider the linear autonomous system of neutral delay differential equations

$$D^{\alpha} \left[x(t) + \sum_{j=1}^{l} P_j x(t - \tau_j) \right] + \sum_{i=1}^{n} Q_i x(t - \delta_i) = 0,$$
 (18)

where the coefficients P_j and Q_i are real $m \times m$ matrices and the delays τ_j and δ_i are non-negative real numbers. Associated with (18), the characteristic equation is

$$det\left(\lambda^{\alpha}B + \lambda^{\alpha}\sum_{i=1}^{l}P_{j}e^{-\lambda\tau_{j}} + \sum_{i=1}^{n}Q_{i}e^{-\lambda\delta_{i}}\right) = 0.$$

$$(19)$$

Lemma 3.9 If lp < 1, then the solution of equation (18) has an exponent estimate

$$||x(t)|| \le A_0 e^{b_0 t}$$
 $(t > b > 0)$

for constants $A_0 > 0$ and $b_0 > 0$.

Proof. Let $\delta = \max\{\delta_i\}, \ j = 1, 2, ..., l, \ \bar{\delta} = \max\{\tau_1, \ \delta\}, \ q = \max\{\|Q_i\|\} \ i = 1, 2, ..., n, \text{ and take } x_0 = (I^{1-\alpha}x)(0) + \sum_{j=1}^l P_j(I^{1-\alpha}x)(-\tau_j) \text{ with } x(t) \in AC[0, b].$ Then there exists a constant M such that $\|x(t)\| \leq M$. Then, for t > b,

$$\begin{split} \|x(t)\| & \leq c \|x_0\| + lp \|x(t-\tau_j)\| + \frac{nq}{\Gamma(\alpha_0)} \int_0^t (t-s)^{\alpha_0-1} \|x(s-\delta_i)\| ds \\ & \leq c \|x_0\| + lp \max_{t-\tau_i \leq s \leq t} \|x(s)\| + \frac{nq}{\Gamma(\alpha_0)} \int_0^t (t-s)^{\alpha_0-1} \max_{s-\delta_i \leq \eta \leq s} \|x(\eta)\| ds \\ & \leq c \|x_0\| + lp (M + \|\varphi\|_{AC} + \max_{b \leq s \leq t} \|x(s)\|) \\ & + \frac{nq}{\Gamma(\alpha_0)} \int_0^b (t-s)^{\alpha_0-1} \max_{s-\bar{\delta} \leq \eta \leq b} \|x(\eta)\| ds + \frac{nq}{\Gamma(\alpha_0)} \int_b^t (t-s)^{\alpha_0-1} \max_{b \leq \eta \leq s} \|x(\eta)\| ds \end{split}$$

Oscillation for Fractional Neutral Functional Differential Systems

$$\leq c\|x_0\| + (M + \|\varphi\|_{AC}) \left(lp + \frac{nq}{\Gamma(\alpha_0)} \frac{t^{\alpha_0}}{\alpha_0} \right) + lp \max_{b \leq s \leq t} \|x(s)\|$$
$$+ \frac{nq}{\Gamma(\alpha_0)} \int_b^t (t-s)^{\alpha_0 - 1} \max_{b \leq \eta \leq s} \|x(\eta)\| ds.$$

Set

$$a = c||x_0|| + (M + ||\varphi||_{AC}) \left(lp + \frac{nq}{\Gamma(\alpha_0)} \frac{t^{\alpha_0}}{\alpha_0}\right),$$

which yields

$$\max_{b \le s \le t} \|x(s)\| \le \frac{1}{1 - lp} \left(a + \frac{nq}{\Gamma(\alpha_0)} \int_b^t (t - s)^{\alpha_0 - 1} \max_{b \le \eta \le s} \|x(\eta)\| ds \right),$$

Consequently, by Lemma 3.2, we obtain

$$||x(t)|| \leq \max_{b \leq s \leq t} ||x(s)|| \leq \frac{a(t)}{1 - lp} + \frac{1}{(1 - lp)^2} \frac{knq}{\Gamma(\alpha_0)} \int_0^t (t - s)^{\alpha_0 - 1} a(s) ds$$
$$\leq \frac{a(t)}{1 - lp} \left(1 + \frac{1}{1 - lp} \frac{knq}{\alpha_0 \Gamma(\alpha_0)} t^{\alpha_0} \right).$$

The proof is complete.

A slight modification in the proof of Theorem 3.3 shows that the following result is also true.

Theorem 3.10 Assume that for j = 1, 2, ..., l and i = 1, 2, ..., n,

$$P_i, Q_i \in \mathbb{R}^{m \times m}, \quad \tau_i \in (0, \infty) \quad and \quad \delta_i \in [0, \infty).$$

If the characteristic equation (19) has no real roots, then every solution of (18) oscillates.

Proof. If we modify the functions F(s) and $\Phi(s)$, defined in Theorem 3.3, as

$$F(s) = s^{\alpha}B + s^{\alpha}B\sum_{j=1}^{l} P_{j}e^{-s\tau_{j}} + \sum_{i=1}^{n} Q_{i}e^{-s\delta_{i}},$$

$$\Phi(s) = x_0 - \sum_{i=1}^n Q_i e^{-s\delta_i} \int_{-\delta_i}^0 e^{-st} x(t) dt - s^{\alpha} B \sum_{j=1}^l P_j e^{-s\tau_j} \int_{\tau_j}^0 e^{-st} x(t) dt + \sum_{j=1}^l P_j (I^{1-\alpha} x) (-\tau_j).$$

Then, following the method of proof for Theorem 3.3, one can complete the proof.

References

- [1] I. Podlubny, Fractional Differential Equations, Academic Press, San Diego, 1999.
- [2] A. A. Kilbas, H. M. Srivastava, J. J. Trujillo, *Theory and Applications of Fractional Differential Equations*, Elsevier Science B.V., Amsterdam, 2006.
- [3] K. Diethelm, The Analysis of Fractional Differential Equations, Springer-Verlag, Berlin, 2010.
- [4] Y. Zhou, Basic Theory of Fractional Differential Equations, World Scientific, Singapore, 2014.
- [5] Y. Zhou, Fractional Evolution Equations and Inclusions: Analysis and Control, Academic Press, 2016.
- [6] Y. Zhou, L. Peng, On the time-fractional Navier-Stokes equations, Comput. Math. Appl. 73 (2017) 874-891.

П

Y. ZHOU, A. ALSAEDI and B. AHMAD

- [7] Y. Zhou, L. Peng, Weak solutions of the time-fractional Navier-Stokes equations and optimal control, *Comput. Math. Appl.* **73** (2017) 1016-1027.
- [8] Y. Zhou, L. Zhang, Existence and multiplicity results of homoclinic solutions for fractional Hamiltonian systems, *Comput. Math. Appl.* **73** (2017) 1325-1345.
- [9] Y. Zhou, V. Vijayakumar, R. Murugesu, Controllability for fractional evolution inclusions without compactness, *Evol. Equ. Control The.* 4 (2015) 507-524.
- [10] G.S. Ladde, V. Lakshmikantham, B.G. Zhang, Oscillation Theory of Differential Equations with Deviation Arguments, Dekker, New York, 1989.
- [11] I. Györi, G. Ladas, Oscillation Theory of Delay Differential Equations with Applications, Clarendon, Oxford, 1991.
- [12] K. Gopalsamy, Stability and Oscillation in Delay Differential Equations of Population Dynamics, Kluwer Academic, Boston, 1992.
- [13] L.H. Erbe, Q.K. Kong, B.G. Zhang, Oscillation Theory for Functional Differential Equations, Marcel Dekker Inc., New York, 1995.
- [14] R.P. Agarwal, M. Bohner, W.T. Li, Nonoscillation and Oscillation: Theory for Functional Differential Equations, Marcel Dekker Inc., 2004.
- [15] S. Grace, R. Agarwal, P. Wong, et al., On the oscillation of fractional differential equations, Fract. Calc. Appl. Anal. 15 (2012) 222-231.
- [16] Y. Bolat, On the oscillation of fractional-order delay differential equations with constant coefficients, Commun. Nonlinear Sci. Numer. Simul. 19 (2014) 3988-3993.
- [17] J.S. Duan, Z. Wang, S.Z. Fu, The zeros of the solutions of the fractional oscillation equation, *Fract. Calc. Appl. Anal.* **17** (2014) 10-22.
- [18] S. Harikrishnan, P. Prakash, J.J. Nieto, Forced oscillation of solutions of a nonlinear fractional partial differential equation, *Appl. Math. Comput.* **254** (2015) 14-19.
- [19] V. S. Vladimirov, Equations of Mathematical Physics, Nauka, Moscow, 1981.
- [20] D. Henry, Geometric Theory of Semilinear Parabolic Partial Differential Equations, Springer, Berlin, Germany, 1989.

FIXED POINT RESULTS FOR A PAIR OF MULTI DOMINATED MAPPINGS ON A SMALLEST SUBSET IN K-SEQUENTIALLY DISLOCATED QUASI METRIC SPACE WITH AN APPLICATION

TAHAIR RASHAM, ABDULLAH SHOAIB, CHOONKIL PARK*, AND MUHAMMAD ARSHAD

ABSTRACT. The aim of this paper is to establish fixed point results for semi α_* -dominated multivalued pair of mappings satisfying generalized locally α_* - ψ -type contractive conditions for a pair of multivalued dominated mappings in complete dislocated quasi metric space. Applications have been given and an example has been constructed to demonstrate the novelty of our results.

1. Introduction and preliminaries

Let $H: Z \to Z$ be a mapping. A point $x \in Z$ is said to be a fixed point of Z if x = Zx. Fixed point results are a tool to estimate the unique solution of nonlinear functional equations. Many results appeared in literature related to the fixed point of mappings which are contractive on the whole domain. It may happen that $H: Z \to Z$ is not a contraction but is a contraction on a subset of Z. It is possible for one to get fixed point for such mappings if they satisfy certain conditions. It has been shown the existence of fixed point for such mappings that fulfill certain conditions on a closed ball by Beg et al. [8] (see also [3, 4, 5, 14, 24, 25, 26, 27]).

Many authors established fixed point theorems in complete dislocated metric spaces. The idea of dislocated topologies has useful applications in the context of logic programming semantics (see [11]). Dislocated metric space (metric-like space) (see [17]) is a generalization of partial metric space (see [16]). Furthermore, dislocated quasi metric space (quasi-metric-like space) (see [8, 21, 30, 31]) generalized the idea of dislocated metric space and quasi-partial metric space (see [18, 25]).

Nadler [20] initiated the study of fixed point theorems for the multivalued mappings (see also [7]). Several results on multivalued mappings have been observed [1, 10, 19, 29]. Asl et al. [6] gave the idea of α_* - ψ contractive multifunctions, α_* -admissible mapping and got some fixed point conclusions for these multifunctions (see also [2, 12]).

In this paper, we evaluate some fixed point results for α_* - ψ -contractive type multivalued α_* -dominated mappings in a closed ball in left(right) K-sequentially complete dislocated quasi metric space. Moreover, we give examples of multivalued mappings which are α_* -dominated but not α_* -admissible. We give the following definitions and results which will be needed in the sequel

Definition 1.1. [30] Let X be a nonempty set and let $d_q: X \times X \to [0, \infty)$ be a function, called a dislocated quasi metric (or simply d_q -metric) if the following conditions hold for any $x, y, z \in X$:

- (i) If $d_q(x, y) = d_q(y, x) = 0$, then x = y;
- (ii) $d_q(x, y) \le d_q(x, z) + d_q(z, y)$.

The pair (X, d_q) is called a dislocated quasi metric space.

²⁰¹⁰ Mathematics Subject Classification. Primary: 46S40, 47H10, 54H25.

Key words and phrases. fixed point; p left(right) K-sequentially complete dislocated quasi metric space; pair of mappings; closed ball; semi α_* -dominated multivalued mapping; graphic contraction..

*Corresponding author.

It is clear that if $d_q(x,y) = d_q(y,x) = 0$, then from (i), x = y. But if x = y, $d_q(x,y)$ may not be 0. It is observed that if $d_q(x,y) = d_q(y,x)$ for all $x,y \in X$, then (X,d_q) becomes a dislocated metric space (metric-like space) (X,d_l) . For $x \in X$ and $\varepsilon > 0$, $B_{d_q}(x,\varepsilon) = \{y \in X : d_q(x,y) < \varepsilon$ and $d_q(y,x) < \varepsilon\}$ and $\overline{B_{d_q}(x,\varepsilon)} = \{y \in X : d_q(x,y) \le \varepsilon$ and $d_q(y,x) \le \varepsilon\}$ are an open ball and a closed ball in (X,d_q) , respectively. Also $B_{d_l}(x,\varepsilon) = \{y \in X : d_q(x,y) \le \varepsilon\}$ is a closed ball in (X,d_l) .

Example 1.2. [8] Let $X = R^+ \cup \{0\}$ and $d_q(x, y) = x + \max\{x, y\}$ for any $x, y \in X$.

- (i) If $d_q(x,y) = d_q(y,x) = 0$, then $x + \max\{x,y\} = y + \max\{y,x\} = 0$, which implies that x = y = 0.
- (ii) Case 1: If $x \ge y$, then $d_q(x,y) = x + \max\{x,y\} = 2x$. Let $z \in X$. If $z \le x$, then

$$d_q(x,z) + d_q(z,y) = x + \max\{x,z\} + z + \max\{z,y\}$$

= $x + x + z + \max\{z,y\} \ge 2x = d_q(x,y).$

If z > x, then $d_q(x, z) + d_q(z, y) = x + z + z + z \ge 2x = d_q(x, y)$.

Case 2: If x < y, then $d_q(x, y) = x + y$. If $z \ge y$, then $d_q(x, z) + d_q(z, y) = x + z + z + z \ge x + y = d_q(x, y)$. If z < y, then $d_q(x, z) + d_q(z, y) = x + \max\{x, z\} + z + y \ge x + y = d_q(x, y)$.

Hence both the conditions of Definition 1.1 hold and so $d_q(x, y) = x + \max\{x, y\}$ defines a dislocated quasi metric on X.

Definition 1.3. [8] Let (X, d_q) be a dislocated quasi metric space.

- (a) A sequence $\{x_n\}$ in (X, d_q) is called left (resp., right) K-Cauchy if for all $\varepsilon > 0$, there exists $n_0 \in N$ such that for all $n > m \ge n_0$ (resp., for all $m > n \ge n_0$), $d_q(x_m, x_n) < \varepsilon$.
- (b) A sequence $\{x_n\}$ is called dislocated quasi-converges (for short, d_q -converges) to x if $\lim_{n\to\infty} d_q(x_n,x) = \lim_{n\to\infty} d_q(x,x_n) = 0$ or for any $\varepsilon > 0$, there exists $n_0 \in N$ such that for all $n > n_0$, $d_q(x,x_n) < \varepsilon$ and $d_q(x_n,x) < \varepsilon$. In this case, x is called a d_q -limit of $\{x_n\}$.
- (c) (X, d_q) is called left (resp., right) K-sequentially complete if every left (resp., right) K-Cauchy sequence in X converges to a point $x \in X$ such that $d_q(x, x) = 0$.

Definition 1.4. Let (X, d_q) be a dislocated quasi metric space. Let K be a nonempty subset of X and $x \in X$. An element $y_0 \in K$ is called a best approximation in K if

$$\begin{array}{rcl} d_q(x,K) & = & d_q(x,y_0), \text{ where } d_q(x,K) = \inf_{y \in K} d_q(x,y), \\ d_q(K,x) & = & d_q(y_0,x), \text{ where } d_q(K,x) = \inf_{y \in K} d_q(y,x). \end{array}$$

If each $x \in X$ has at least one best approximation in K, then K is called a proximinal set.

We denote by P(X) the set of all proximinal subsets of X.

Definition 1.5. [22] Let $(S,T): X \to P(X)$ and $\beta: X \times X \to [0,+\infty)$ be a function. We say that the pair (S,T) is β_{\star} -admissible if for all $x,y \in X$,

$$\beta(x,y) \geq 1$$
 implies $\beta_{\star}(Tx,Sy) \geq 1$ and $\beta_{\star}(Tx,Sy) \geq 1$.

Again the pair (S,T) is said to be β -admissible if $\beta(x,y) \geq 1$ implies $\beta(a,b) \geq 1$ for all $a \in Sx$ and $b \in Ty$.

Let Ψ denote the family of all nondecreasing functions $\psi : [0, +\infty) \to [0, +\infty)$ such that $\sum_{n=1}^{+\infty} \psi^n(t) < +\infty$ for all t > 0, where ψ^n is the n^{th} iterate of ψ . If $\psi \in \Psi$, then $\psi(t) < t$ for all t > 0.

Definition 1.6. [22] Let (X, d) be a complete metric space and $\beta: X \times X \to [0, +\infty)$ be a mapping. Let $(S, T): X \to P(X)$ be a multifunction and $\psi \in \Psi$. We say that the pair (S, T) is a β_{\star} - ψ contractive multifunction whenever

$$\beta_{\star}(Tx, Sy)H(Tx, Sy) \leq \psi(d(x, y)) \ \forall \ x, y \in X,$$

 $\beta_{\star}(Sx, Ty)H(Sx, Ty) \leq \psi(d(x, y)) \ \forall \ x, y \in X,$

where $\beta_{\star}(Tx, Sy) = \inf\{\beta(a, b) : a \in Tx, b \in Sy\}.$

Definition 1.7. [27] Let (X, d_l) be a dislocated metric space, $S: X \to P(X)$ be a multivalued mapping and $\alpha: X \times X \to [0, +\infty)$. Let $A \subseteq X$. Then we say that S is semi α_* -admissible on A, whenever $\alpha(x, y) \ge 1$ implies $\alpha_*(Sx, Sy) \ge 1$ for all $x \in A$, where $\alpha_*(Sx, Sy) = \inf\{\alpha(a, b) : a \in Sx, b \in Sx\}$. If A = X, then we say that S is α_* -admissible on X.

Definition 1.8. Let (X, d_l) be a dislocated metric space, $S, T : X \to P(X)$ be multivalued mappings and $\alpha : X \times X \to [0, +\infty)$. Let $A \subseteq X$. Then we say that S is semi α_* -dominated on A, whenever $\alpha_*(x, Sx) \ge 1$ for all $x \in A$, where $\alpha_*(x, Sx) = \inf\{\alpha(x, b) : b \in Sx\}$. If A = X, then we say that S is α_* -dominated on X.

Definition 1.9. [23] The function $H_{d_q}: P(X) \times P(X) \to X$, defined by

$$H_{d_q}(A, B) = \max\{\sup_{a \in A} d_q(a, B), \sup_{b \in B} d_q(A, b)\},\$$

is called a dislocated quasi Hausdorff metric on P(X). Also $(P(X), H_{d_q})$ is known as a dislocated quasi Hausdorff metric space.

Lemma 1.10. [23] Let (X, d_q) be a dislocated quasi metric space. Let $(P(X), H_{d_q})$ be a dislocated quasi Hausdorff metric space on P(X). Then, for all $A, B \in P(X)$ and for each $a \in A$, there exists $b_a \in B$ such that $H_{d_q}(A, B) \ge d_q(a, b_a)$ and $H_{d_q}(B, A) \ge d_q(b_a, a)$, where $d_q(a, B) = d_q(a, b_a)$ and $d_q(B, a) = d_q(b_a, a)$.

Example 1.11. Let $X = \mathbb{R}$. Define the mapping $\alpha: X \times X \to [0, \infty)$ by

$$\alpha(x,y) = \begin{cases} 1 \text{ if } x > y \\ \frac{1}{2} \text{ otherwise.} \end{cases}$$

Define the multivalued mappings $S, T: X \to P(X)$ by

$$Sx = \{[x-4, x-3] \text{ if } x \in X\},\$$

$$Ty = \{[y-2, y-1] \text{ if } y \in X\}.$$

Suppose x=3 and y=2. Since 3>2, $\alpha(3,2)\geq 1$. Now $\alpha_{\star}(S3,T2)=\inf\{\alpha(a,b):a\in S3,b\in T2\}=\frac{1}{2}\not\geq 1$, which means that $\alpha_{\star}(S3,T2)<1$, that is, the pair (S,T) is not α_{\star} -admissible. Also $\alpha_{\star}(S3,S2)\not\geq 1$ and $\alpha_{\star}(T3,T2)\not\geq 1$. This implies that S and T are not α_{\star} -admissible individually. Since $\alpha_{\star}(x,Sx)=\inf\{\alpha(x,b):b\in Sx\}\geq 1$ for all $x\in X,S$ is an α_{\star} -dominated mapping. Similarly, $\alpha_{\star}(y,Ty)=\inf\{\alpha(y,b):b\in Ty\}\geq 1$. Hence it is clear that S and T are α_{\star} -dominated but not α_{\star} -admissible.

Lemma 1.12. [23] Every closed ball Y in a left (right) K-sequentially complete dislocated quasi metric space X is left (right) K-sequentially complete.

2. Main results

Let (X, d_q) be a dislocated quasi metric space, $x_0 \in X$ and $S, T : X \to P(X)$ be multifunctions on X. Let $x_1 \in Sx_0$ be an element such that $d_q(x_0, Sx_0) = d_q(x_0, x_1)$. Let $x_2 \in Tx_1$ be such that $d_q(x_1, Tx_1) = d_q(x_1, x_2)$. Let $x_3 \in Sx_2$ be such that $d_q(x_2, Sx_2) = d_q(x_2, x_3)$. Continuing this process, we construct a sequence $\{x_n\}$ of points in X such that $x_{2n+1} \in Sx_{2n}$ and $x_{2n+2} \in Tx_{2n+1}$, where $n = 0, 1, 2, \ldots$ Also $d_q(x_{2n}, Sx_{2n}) = d_q(x_{2n}, x_{2n+1})$ and $d_q(x_{2n+1}, Tx_{2n+1}) = d_q(x_{2n+1}, x_{2n+2})$. We denote this iterative sequence by $\{TS(x_n)\}$. We say that $\{TS(x_n)\}$ is a sequence in X generated by x_0 .

Theorem 2.1. Let (X, d_q) be a left (right) K-sequentially complete dislocated quasi metric space. Suppose there exists a function $\alpha: X \times X \to [0, \infty)$. Let r > 0, $x_0 \in \overline{B_{d_q}(x_0, r)}$ and $S, T: X \to P(X)$ be semi α_* -dominated mappings on $\overline{B_{d_q}(x_0, r)}$. Assume that, for some $\psi \in \Psi$ and $D_q(x, y) = \max\{d_q(x, y), d_q(x, Sx), d_q(y, Ty)\}$, the following hold:

$$\max\{\alpha_*(x, Sx)H_{dq}(Sx, Ty), \alpha_*(y, Ty)H_{dq}(Ty, Sx)\} \le \min\{\psi(D_q(x, y)), \psi(D_q(y, x))\}$$
(2.1)

for all $x, y \in \overline{B_{d_q}(x_0, r)} \cap \{TS(x_n)\}$ with either $\alpha(x, y) \ge 1$ or $\alpha(y, x) \ge 1$ whenever $x \in Sy$, and

$$\sum_{i=0}^{n} \max\{\psi^{i}(d_{q}(x_{1}, x_{0}), \psi^{i}(d_{q}(x_{0}, x_{1}))\} \le r \text{ for all } n \in \mathbb{N} \cup \{0\}.$$
(2.2)

Then $\{TS(x_n)\}\$ is a sequence in $\overline{B_{d_q}(x_0,r)}$ and $\{TS(x_n)\} \to x^* \in \overline{B_{d_q}(x_0,r)}$. Also if the inequality (2.1) holds for x^* and either $\alpha(x_n,x^*) \ge 1$ or $\alpha(x^*,x_n) \ge 1$ for all $n \in \mathbb{N} \cup \{0\}$, then S and T have a common fixed point x^* in $\overline{B_{d_q}(x_0,r)}$ and $d_q(x^*,x^*)=0$.

Proof. Consider a sequence $\{TS(x_n)\}$ generated by x_0 . Then, we have $x_{2n+1} \in Sx_{2n}$ and $x_{2n+2} \in Tx_{2n+1}$, where n = 0, 1, 2, Also $d_q(x_{2n}, Sx_{2n}) = d_q(x_{2n}, x_{2n+1}), d_q(x_{2n+1}, Tx_{2n+1}) = d_q(x_{2n+1}, x_{2n+2}).$ By Lemma 1.10, we have

$$d_q(x_{2n}, x_{2n+1}) \leq H_{d_q}(Tx_{2n-1}, Sx_{2n}), \tag{2.3}$$

$$d_q(x_{2n+1}, x_{2n+2}) \leq H_{d_q}(Sx_{2n}, Tx_{2n+1}) \tag{2.4}$$

for all $n = 1, 2, \dots$ From (2.2), we have

$$\max\{d_q(x_1, x_0), d_q(x_0, x_1)\} \le \sum_{i=0}^{j} \max\{\psi^i(d_q(x_1, x_0), \psi^i(d_q(x_0, x_1))\} \le r.$$

It follows that, $d_q(x_1, x_0) \leq r$ and $d_q(x_0, x_1) \leq r$. Hence we have

$$x_1 \in \overline{B_{d_q}(x_0, r)}$$
.

Let $x_2, \dots, x_j \in \overline{B_{d_q}(x_0, r)}$ for some $j \in \mathbb{N}$. Since $S, T : X \to P(X)$ are semi α_* -dominated mappings on $\overline{B_{d_q}(x_0, r)}$, $\alpha_*(x_{2i}, Sx_{2i}) \ge 1$ and $\alpha_*(x_{2i+1}, Tx_{2i+1}) \ge 1$. Since $\alpha_*(x_{2i}, Sx_{2i}) \ge 1$, $\inf\{\alpha(x_{2i}, b) : b \in Sx_{2i}\} \ge 1$. Also $x_{2i+1} \in Sx_{2i}$ and so $\alpha(x_{2i}, x_{2i+1}) \ge 1$. Now by (2.3), we obtain

$$\begin{array}{ll} d_q(x_{2i+1},x_{2i+2}) & \leq & H_{d_q}(Sx_{2i},Tx_{2i+1}) \leq \max\{\alpha_*(x_{2i},Sx_{2i})H_{d_q}(Sx_{2i},Tx_{2i+1}),\\ & & \alpha_*(x_{2i+1},Tx_{2i+1})H_{d_q}(Tx_{2i+1},Sx_{2i})\} \\ & \leq & \min\{\psi(D_q(x_{2i},x_{2i+1})),\psi(D_q(x_{2i+1},x_{2i}))\} \leq \psi(D_q(x_{2i},x_{2i+1}))\\ & \leq & \psi(\max\{d_q(x_{2i},x_{2i+1}),d_q(x_{2i},Sx_{2i}),d_q(x_{2i+1},Tx_{2i+1})\})\\ & \leq & \psi(\max\{d_q(x_{2i},x_{2i+1}),d_q(x_{2i},x_{2i+1}),d_q(x_{2i+1},x_{2i+2})\})\\ & \leq & \psi(\max\{d_q(x_{2i},x_{2i+1}),d_q(x_{2i+1},x_{2i+2})\}). \end{array}$$

If $\max\{d_q(x_{2i}, x_{2i+1}), d_q(x_{2i+1}, x_{2i+2})\} = d_q(x_{2i+1}, x_{2i+2})$, then $d_q(x_{2i+1}, x_{2i+2}) \le \psi(d_q(x_{2i+1}, x_{2i+2}))$, which contradicts to the fact that $\psi(t) < t$ for all t > 0. So $\max\{d_q(x_{2i}, x_{2i+1}), d_q(x_{2i+1}, x_{2i+2})\} = d_q(x_{2i}, x_{2i+1})$. Hence we obtain

$$d_q(x_{2i+1}, x_{2i+2}) \le \psi(d_q(x_{2i}, x_{2i+1})). \tag{2.5}$$

Since $\alpha_*(x_{2i-1}, Tx_{2i-1}) \ge 1$ and $x_{2i} \in Tx_{2i-1}, \alpha(x_{2i-1}, x_{2i}) \ge 1$. Now by (2.4), we have

$$\begin{aligned} d_q(x_{2i}, x_{2i+1}) & \leq & H_{d_q}(Tx_{2i-1}, Sx_{2i}) \leq \max\{\alpha_*(x_{2i}, Sx_{2i}) H_{d_q}(Sx_{2i}, Tx_{2i-1}), \\ & & \alpha_*(x_{2i-1}, Tx_{2i-1}) H_{d_q}(Tx_{2i-1}, Sx_{2i})\} \\ & \leq & \min\{\psi(D_q(x_{2i}, x_{2i-1})), \psi(D_q(x_{2i-1}, x_{2i}))\} \leq \psi(D_q(x_{2i}, x_{2i-1})) \\ & \leq & \psi(\max\{d_q(x_{2i}, x_{2i-1}), d_q(x_{2i}, Sx_{2i}), d_q(x_{2i-1}, Tx_{2i-1})\}) \\ & \leq & \psi(\max\{d_q(x_{2i}, x_{2i-1}), d_q(x_{2i}, x_{2i+1}), d_q(x_{2i-1}, x_{2i})\}) \\ & \leq & \psi(\max\{d_q(x_{2i}, x_{2i-1}), d_q(x_{2i}, x_{2i+1}), d_q(x_{2i-1}, x_{2i})\}). \end{aligned}$$

If $\max\{d_q(x_{2i}, x_{2i-1}), d_q(x_{2i}, x_{2i+1}), d_q(x_{2i-1}, x_{2i})\} = d_q(x_{2i}, x_{2i+1})$, then $d_q(x_{2i}, x_{2i+1}) \le \psi(d_q(x_{2i}, x_{2i+1}))$, which contradicts to the fact that $\psi(t) < t$ for all t > 0. Hence we obtain

$$d_q(x_{2i}, x_{2i+1}) \le \psi(\max\{d_q(x_{2i}, x_{2i-1}), d_q(x_{2i-1}, x_{2i})\}).$$

If $\max\{d_q(x_{2i}, x_{2i-1}), d_q(x_{2i-1}, x_{2i})\} = d_q(x_{2i-1}, x_{2i})$, then

$$d_q(x_{2i}, x_{2i+1})) \le \psi(d_q(x_{2i-1}, x_{2i})).$$

Since ψ is a nondecreasing function,

$$\psi(d_q(x_{2i}, x_{2i+1})) \le \psi^2(d_q(x_{2i-1}, x_{2i})).$$

By (2.5), we obtain

$$d_q(x_{2i+1}, x_{2i+2}) \le \psi^2(d_q(x_{2i-1}, x_{2i})). \tag{2.6}$$

If $\max\{d_q(x_{2i}, x_{2i-1}), d_q(x_{2i-1}, x_{2i})\} = d_q(x_{2i}, x_{2i-1})$, then

$$d_q(x_{2i+1}, x_{2i+2}) \le \psi^2(d_q(x_{2i}, x_{2i-1})) \tag{2.7}$$

By (2.6) and (2.7), we obtain

$$d_q(x_{2i+1}, x_{2i+2}) \le \max\{\psi^2(d_q(x_{2i}, x_{2i-1})), \psi^2(d_q(x_{2i-1}, x_{2i}))\}.$$

Continuing in this way, we obtain

$$d_q(x_{2i+1}, x_{2i+2}) \le \max\{\psi^{2i+1}(d_q(x_1, x_0)), \psi^{2i+1}(d_q(x_0, x_1))\}$$
(2.8)

Similarly, we have

$$d_q(x_{2i}, x_{2i+1}) \le \max\{\psi^{2i}(d_q(x_1, x_0)), \psi^{2i}(d_q(x_0, x_1))\}.$$
(2.9)

By (2.8) and (2.9), we obtain

$$d_q(x_j, x_{j+1}) \le \max\{\psi^j(d_q(x_1, x_0)), \psi^j(d_q(x_0, x_1))\} \text{ for some } j \in \mathbb{N}.$$
(2.10)

By Lemma 1.10 and (2.1), we have

$$d_{q}(x_{2i+2}, x_{2i+1}) \leq H_{d_{q}}(Tx_{2i+1}, Sx_{2i}) \leq \max\{\alpha_{*}(x_{2i}, Sx_{2i})H_{d_{q}}(Sx_{2i}, Tx_{2i+1}), \alpha_{*}(x_{2i+1}, Tx_{2i+1})H_{d_{q}}(Tx_{2i+1}, Sx_{2i})\}$$

$$\leq \min\{\psi(D_{q}(x_{2i}, x_{2i+1})), \psi(D_{q}(x_{2i+1}, x_{2i}))\}.$$

By the same reasoning as in the proof of (??), we have

$$d_q(x_{j+1}, x_j) \le \max\{\psi^j(d_q(x_1, x_0)), \psi^j(d_q(x_0, x_1))\} \text{ for some } j \in \mathbb{N}.$$
 (2.10)

Now

$$d_{q}(x_{0}, x_{j+1}) \leq d_{q}(x_{0}, x_{1}) + \dots + d_{q}(x_{j}, x_{j+1})$$

$$\leq d_{q}(x_{0}, x_{1}) + \dots + \max\{\psi^{j}(d_{q}(x_{1}, x_{0})), \psi^{j}(d_{q}(x_{0}, x_{1}))\}$$

$$\leq \sum_{i=0}^{j} \max\{\psi^{i}(d_{q}(x_{1}, x_{0}), \psi^{i}(d_{q}(x_{0}, x_{1}))\} \leq r.$$
(2.11)

Also

$$d_{q}(x_{j+1}, x_{0}) \leq d_{q}(x_{j+1}, x_{j}) + \dots + d_{q}(x_{1}, x_{0})$$

$$\leq \max\{\psi^{j}(d_{q}(x_{1}, x_{0})), \psi^{j}(d_{q}(x_{0}, x_{1}))\} + \dots + d_{q}(x_{1}, x_{0})$$

$$\leq \sum_{i=0}^{j} \max\{\psi^{i}(d_{q}(x_{1}, x_{0}), \psi^{i}(d_{q}(x_{0}, x_{1}))\} \leq r.$$

$$(2.12)$$

By (2.11) and (2.12), we have $x_{j+1} \in \overline{B_{dq}(x_0, r)}$. Hence by mathematical induction $x_n \in \overline{B_{dq}(x_0, r)}$ for all $n \in \mathbb{N}$. Therefore, $\{TS(x_n)\}$ is a sequence in $\overline{B_{dq}(x_0, r)}$. Since $S, T: X \to P(X)$ are semi α_* -dominated mappings on $\overline{B_{dq}(x_0, r)}$, $\alpha_*(x_n, Sx_n) \ge 1$ and $\alpha_*(x_n, Tx_n) \ge 1$ for all $n \in \mathbb{N}$. Now (2.8) and (2.9) can be written as

$$d_q(x_n, x_{n+1}) \le \max\{\psi^n(d_q(x_1, x_0)), \psi^n(d_q(x_0, x_1))\} \text{ for all } n \in \mathbb{N}.$$
(2.13)

$$d_q(x_{n+1}, x_n) \le \max\{\psi^n(d_q(x_1, x_0)), \psi^n(d_q(x_0, x_1))\} \text{ for all } n \in \mathbb{N}.$$
(2.14)

Fix $\varepsilon > 0$ and let $k_1(\varepsilon) \in \mathbb{N}$ such that $\sum_{k \geq k_1(\varepsilon)} \max\{\psi^k(d_q(x_1, x_0)), \psi^k(d_q(x_0, x_1))\} < \varepsilon$. Let $n, m \in \mathbb{N}$

with $m > n > k_1(\varepsilon)$. Then we obtain

$$d_{q}(x_{n}, x_{m}) \leq \sum_{k=n}^{m-1} d_{q}(x_{k}, x_{k+1})$$

$$\leq \sum_{k=n}^{m-1} \max\{\psi^{k}(d_{q}(x_{1}, x_{0})), \psi^{k}(d_{q}(x_{0}, x_{1}))\} \text{ by } (2.13),$$

$$d_{q}(x_{n}, x_{m}) \leq \sum_{k \geq k_{1}(\varepsilon)} \max\{\psi^{n}(d_{q}(x_{1}, x_{0})), \psi^{n}(d_{q}(x_{0}, x_{1}))\} < \varepsilon.$$

Thus we obtain that $\{TS(x_n)\}\$ is a left K-Cauchy sequence in $(\overline{B_{d_q}(x_0,r)},d_q)$. Similarly, by (2.14), we have

$$d_q(x_m, x_n) \le \sum_{k=n}^{m-1} d_q(x_{k+1}, x_k) < \varepsilon.$$

Hence $\{TS(x_n)\}$ is a right K-Cauchy sequence in $(B_{d_q}(x_0, r), d_q)$. Since every closed ball in left(right) K-sequentially complete dislocated quasi metric space is left(right) K-sequentially complete, there exists $x^* \in \overline{B_{dq}(x_0, r)}$ such that $\{TS(x_n)\} \to x^*$, that is,

$$\lim_{n \to \infty} d_q(x_n, x^*) = \lim_{n \to \infty} d_q(x^*, x_n) = 0.$$
 (2.15)

Now

$$d_q(x^*, Tx^*) \leq d_q(x^*, x_{2n+1}) + d_q(x_{2n+1}, Tx^*)$$

$$\leq d_q(x^*, x_{2n+1}) + H_{d_q}(Sx_{2n}, Tx^*) \text{ by Lemma 1.10.}$$
 (2.16)

Since $\alpha_*(x^*, Tx^*) \geq 1$, $\alpha_*(x_{2n}, Sx_{2n}) \geq 1$ and $\alpha(x_{2n}, x^*) \geq 1$, we obtain

$$H_{d_q}(Sx_{2n}, Tx^*) \leq \max\{\alpha_*(x_{2n}, Sx_{2n})H_{d_q}(Sx_{2n}, Tx^*), \alpha_*(x^*, Tx^*)H_{d_q}(Tx^*, Sx_{2n})\}$$

$$\leq \min\{\psi(D_q(x_{2n}, x^*)), \psi(D_q(x^*, x_{2n}))\}$$

$$\leq \psi(\max\{d_q(x_{2n}, x^*), d_q(x_{2n}, x_{2n+1}), d_q(x^*, Tx^*)\})$$

$$\leq \psi(\max\{d_q(x_{2n}, x^*), d_q(x_{2n}, x^*) + d_q(x^*, x_{2n+1}), d_q(x^*, Tx^*)\}). \tag{2.17}$$

By (2.16) and (2.17), we have

$$d_{q}(x^{*}, Tx^{*}) \leq d_{q}(x^{*}, x_{2n+1}) + \psi(\max\{d_{q}(x_{2n}, x^{*}), d_{q}(x_{2n}, x^{*}) + d_{q}(x^{*}, x_{2n+1}), d_{q}(x^{*}, Tx^{*})\}).$$

Letting $n \to \infty$, and by (2.15), we obtain $d_q(x^*, Tx^*) \le \psi(d_q(x^*, Tx^*))$ and hence $d_q(x^*, Tx^*) = 0$. Now

$$d_q(Tx^*, x^*) \le d_q(Tx^*, x_{2n+1}) + d_q(x_{2n+1}, x^*)$$

 $\le H_{d_q}(Tx^*, Sx_{2n}) + d_q(x_{2n+1}, x^*), \text{ by Lemma 1.10.}$

By using a similar argument, we obtain $d_q(Tx^*, x^*) = 0$ or $x^* \in Tx^*$.

Similarly, by Lemma 1.10, (2.15) and

$$d_q(x^*, Sx^*) \le d_q(x^*, x_{2n+2}) + d_q(x_{2n+2}, Sx^*),$$

we can show that $d_q(x^*, Sx^*) = 0$ and $x^* \in Sx^*$.

Similarly, $d_q(Sx^*, x^*) = 0$. Hence S and T have a common fixed point x^* in $\overline{B_{d_q}(x_0, r)}$. Now

$$d_q(x^*, x^*) \le d_q(x^*, Tx^*) + d_q(Tx^*, x^*) \le 0.$$

This implies that $d_q(x^*, x^*) = 0$.

Corollary 2.2. Let (X, d_q) be a left (right) K-sequentially complete dislocated quasi metric space. Suppose that there exists a function $\alpha: X \times X \to [0, \infty)$. Let r > 0, $x_0 \in \overline{B_{d_q}(x_0, r)}$ and $S: X \to P(X)$ be a semi α_* -dominated mapping on $\overline{B_{d_q}(x_0, r)}$. Assume that, for some $\psi \in \Psi$ and $D_q(x, y) = \max\{d_q(x, y), d_q(x, Sx), d_q(y, Sy)\}$, the following hold:

$$\max\{\alpha_*(x,Sx)H_{dq}(Sx,Sy), \ \alpha_*(y,Sy)H_{dq}(Sy,Sx)\} \le \min\{\psi(D_q(x,y)),\psi(D_q(y,x))\}$$
 (2.18)

for all $x, y \in \overline{B_{d_q}(x_0, r)} \cap \{S(x_n)\}\$ with either $\alpha(x, y) \ge 1$ or $\alpha(y, x) \ge 1$, and

$$\sum_{i=0}^{n} \max\{\psi^{i}(d_{q}(x_{1}, x_{0}), \psi^{i}(d_{q}(x_{0}, x_{1}))\} \leq r \text{ for all } n \in \mathbb{N} \cup \{0\}.$$

Then $\{S(x_n)\}$ is a sequence in $\overline{B_{d_q}(x_0,r)}$ and $\{S(x_n)\} \to x^* \in \overline{B_{d_q}(x_0,r)}$. Also, if (2.18) holds for x^* and either $\alpha(x_n,x^*) \ge 1$ or $\alpha(x^*,x_n) \ge 1$ for all $n \in \mathbb{N} \cup \{0\}$, then S has a fixed point x^* in $\overline{B_{d_q}(x_0,r)}$ and $d_q(x^*,x^*)=0$.

Corollary 2.3. Let (X, d_l) be a complete dislocated metric space. Suppose that there exists a function $\alpha: X \times X \to [0, \infty)$. Let r > 0, $x_0 \in \overline{B_{d_l}(x_0, r)}$ and $S, T: X \to P(X)$ be semi α_* -dominated mappings on $\overline{B_{d_l}(x_0, r)}$. Assume that, for some $\psi \in \Psi$ and $D_l(x, y) = \max\{d_l(x, y), d_l(x, Sx), d_l(y, Ty)\}$, the following hold:

$$\max\{\alpha_*(x, Sx)H_{d_l}(Sx, Ty), \ \alpha_*(y, Ty)H_{d_l}(Sx, Ty)\} \le \psi(D_l(x, y))$$
(2.19)

for all $x, y \in \overline{B_{d_l}(x_0, r)} \cap \{TS(x_n)\}$ with either $\alpha(x, y) \ge 1$ or $\alpha(y, x) \ge 1$, and

$$\sum_{i=0}^{n} \psi^{i}(d_{l}(x_{0}, x_{1})) \leq r \text{ for all } n \in \mathbb{N} \cup \{0\}.$$

Then $\{TS(x_n)\}\$ is a sequence in $\overline{B_{d_l}(x_0,r)}$ and $\{TS(x_n)\}\$ $\to x^* \in \overline{B_{d_l}(x_0,r)}$. Also if (2.19) holds for x^* and either $\alpha(x_n,x^*) \ge 1$ or $\alpha(x^*,x_n) \ge 1$ for all $n \in \mathbb{N} \cup \{0\}$, then S and T have a common fixed point x^* in $\overline{B_{d_l}(x_0,r)}$ and $d_g(x^*,x^*)=0$.

Corollary 2.4. Let (X, d_l) be a complete dislocated metric space. Suppose that there exists a function $\alpha: X \times X \to [0, \infty)$. Let r > 0, $x_0 \in \overline{B_{d_l}(x_0, r)}$ and $S: X \to P(X)$ be a semi α_* -dominated mapping on $\overline{B_{d_l}(x_0, r)}$. Assume that, for some $\psi \in \Psi$ and $D_l(x, y) = \max\{d_l(x, y), d_l(x, Sx), d_l(y, Sy)\}$, the following hold:

$$\max\{\alpha_*(x, Sx)H_{d_l}(Sx, Sy), \ \alpha_*(y, Sy)H_{d_l}(Sx, Sy)\} \le \psi(D_l(x, y))$$
(2.20)

for all $x, y \in \overline{B_{d_l}(x_0, r)} \cap \{S(x_n)\}\$ with either $\alpha(x, y) \ge 1$ or $\alpha(y, x) \ge 1$, and

$$\sum_{i=0}^{n} \psi^{i}(d_{l}(x_{0}, x_{1})) \leq r \text{ for all } n \in \mathbb{N} \cup \{0\}.$$

Then $\{S(x_n)\}\$ is a sequence in $\overline{B_{d_l}(x_0,r)}$ and $\{S(x_n)\}\to x^*\in \overline{B_{d_l}(x_0,r)}$. Also, if (2.20) holds for x^* and either $\alpha(x_n,x^*)\geq 1$ or $\alpha(x^*,x_n)\geq 1$ for all $n\in\mathbb{N}\cup\{0\}$, then S has a fixed point x^* in $\overline{B_{d_l}(x_0,r)}$ and $d_q(x^*,x^*)=0$.

Let X be a nonempty set, \leq a partial order on X and $A \subseteq X$. We say that $a \leq B$ whenever for all $b \in B$, we have $a \leq b$. A mapping $S: X \to P(X)$ is said to be semi-dominated on A if $a \leq Sa$ for each $a \in A \subseteq X$. If A = X, then $S: X \to P(X)$ is said to be dominated.

Corollary 2.5. Let (X, \leq, d_q) be a left (right) K-sequentially ordered complete dislocated quasi metric space. Let r > 0, $x_0 \in \overline{B_{d_q}(x_0, r)}$ and $S, T : X \to P(X)$ be semi-dominated mappings on $\overline{B_{d_q}(x_0, r)}$. Assume that, for some $\psi \in \Psi$ and $D_q(x, y) = \max\{d_q(x, y), d_q(x, Sx), d_q(y, Ty)\}$, the following hold:

$$\max\{H_{dq}(Sx, Ty), H_{dq}(Ty, Sx)\} \le \min\{\psi(D_q(x, y)), \psi(D_q(y, x))\}$$
(2.21)

for all $x, y \in \overline{B_{d_q}(x_0, r)} \cap \{TS(x_n)\}$ with either $x \leq y$ or $y \leq x$, and

$$\sum_{i=0}^{n} \max\{\psi^{i}(d_{q}(x_{1}, x_{0}), \psi^{i}(d_{q}(x_{0}, x_{1}))\} \le r \text{ for all } n \in \mathbb{N} \cup \{0\}.$$
(2.22)

Then $\{TS(x_n)\}\$ is a sequence in $\overline{B_{d_q}(x_0,r)}$ and $\{TS(x_n)\}\to x^*\in \overline{B_{d_q}(x_0,r)}$. Also if (2.21) holds for x^* and either $x_n \leq x^*$ or $x^* \leq x_n$ for all $n \in \mathbb{N} \cup \{0\}$, then S and T have a common fixed point x^* in $\overline{B_{d_q}(x_0,r)}$ and $d_q(x^*,x^*)=0$.

Proof. Let $\alpha: X \times X \to [0, +\infty)$ be a function defined by $\alpha(x,y) = 1$ for all $x \in \overline{B_{d_q}(x_0, r)}$ with either $x \preceq y$ or $y \preceq x$, and $\alpha(x,y) = 0$ for all other elements $x,y \in X$. Since S and T are the semi dominated mappings on $\overline{B_{d_q}(x_0, r)}$, $x \preceq Sx$ and $x \preceq Tx$ for all $x \in \overline{B_{d_q}(x_0, r)}$. This implies that $x \preceq b$ for all $b \in Sx$ and $x \preceq c$ for all $c \in Tx$. So $\alpha(x,b) = 1$ for all $b \in Sx$ and $\alpha(x,c) = 1$ for all $c \in Tx$. This implies that $\inf\{\alpha(x,y): y \in Sx\} = 1$ and $\inf\{\alpha(x,y): y \in Tx\} = 1$. Hence $\alpha_*(x,Sx) = 1$ and $\alpha_*(x,Tx) = 1$ for all $x \in \overline{B_{d_q}(x_0,r)}$. So $S,T:X\to P(X)$ are semi α_* -dominated mappings on $\overline{B_{d_q}(x_0,r)}$. Moreover, (2.21) can be written as

$$\max\{\alpha_*(x, Sx)H_{dq}(Sx, Ty), \ \alpha_*(y, Ty)H_{dq}(Ty, Sx)\} \le \min\{\psi(D_q(x, y)), \psi(D_q(y, x))\}$$

for all x, y in $\overline{B_{d_q}(x_0, r)} \cap \{TS(x_n)\}$ with either $\alpha(x, y) \geq 1$ or $\alpha(y, x) \geq 1$. Also, (2.22) holds. Then by Theorem 2.1, $\{TS(x_n)\}$ is a sequence in $\overline{B_{d_q}(x_0, r)}$ and $\{TS(x_n)\} \rightarrow x^* \in \overline{B_{d_q}(x_0, r)}$. Now, $x_n, x^* \in \overline{B_{d_q}(x_0, r)}$ and either $x_n \leq x^*$ or $x^* \leq x_n$ implies that either $\alpha(x_n, x^*) \geq 1$ or $\alpha(x^*, x_n) \geq 1$.

So all the conditions of Theorem 2.1 are satisfied. Hence by Theorem 2.1, S and T have a common fixed point x^* in $\overline{B_{d_q}(x_0,r)}$ and $d_q(x^*,x^*)=0$.

Example 2.6. Let $X = Q^+ \cup \{0\}$ and let $d_l : X \times X \to X$ be a complete dislocated quasi metric on X defined by

$$d_q(x,y) = x + y$$
 for all $x, y \in X$.

Define multivalued mappings $S, T: X \times X \to P(X)$ by,

$$Sx = \begin{cases} \left[\frac{x}{3}, \frac{2}{3}x\right] & \text{if } x \in [0, 1] \cap X \\ [x, x + 1] & \text{if } x \in (1, \infty) \cap X \end{cases}$$

and

$$Tx = \begin{cases} \left[\frac{x}{4}, \frac{3}{4}x\right] & \text{if } x \in [0, 1] \cap X \\ [x+1, x+3] & \text{if } x \in (1, \infty) \cap X. \end{cases}$$

Considering $x_0 = 1$, r = 8, we get $\overline{B_{d_q}(x_0, r)} = [0, 7] \cap X$. Now $d_q(x_0, Sx_0) = d_q(1, S1) = d_q(1, \frac{1}{3}) = \frac{4}{3}$. So we obtain a sequence $\{TS(x_n)\} = \{1, \frac{1}{12}, \frac{1}{144}, \frac{1}{1728}, \ldots\}$ in X generated by x_0 . Also $\overline{B_{d_q}(x_0, r)} \cap \{TS(x_n)\} = \{1, \frac{1}{12}, \frac{1}{144}, \ldots\}$. Let $\psi(t) = \frac{4t}{5}$ and

$$\alpha(x,y) = \begin{cases} 1 \text{ if } x,y \in [0,1] \\ \frac{3}{2} \text{ otherwise.} \end{cases}$$

Now if $x, y \notin \overline{B_{d_q}(x_0, r)} \cap \{TS(x_n)\}$, then we have the following cases.

Case 1. If $\max\{\alpha_*(x,Sx)H_{d_q}(Sx,Ty), \alpha_*(y,Ty)H_{d_q}(Ty,Sx)\} = \alpha_*(x,Sx)H_{d_q}(Sx,Ty)$, then for x=2 and y=3, we have

$$\alpha_*(2, S2)Hd_q(S2, T3) = \frac{3}{2}(8) > \psi(D_q(x, y)) = \frac{28}{5}.$$

Case 2. If $\max\{\alpha_*(x,Sx)H_{d_q}(Sx,Ty), \alpha_*(y,Ty)H_{d_q}(Ty,Sx)\} = \alpha_*(y,Ty)H_{d_q}(Ty,Sx)$, then for x=2 and y=3, we have

$$\alpha_*(3, T3)Hd_q(T3, S2) = \frac{3}{2}(8) > \psi(D_q(y, x)) = \frac{28}{5}.$$

So the contractive condition does not hold on the whole space X.

Now, for all $x, y \in \overline{B_{d_q}(x_0, r)} \cap \{TS(x_n)\}$, we have the following.

Case 3. If $\max\{\alpha_*(x,Sx)H_{d_q}(Sx,Ty), \alpha_*(y,Ty)H_{d_q}(Ty,Sx)\} = \alpha_*(x,Sx)H_{d_q}(Sx,Ty)$, then we have

$$\begin{split} \alpha_*(x,Sx)H_{d_q}(Sx,Ty) &=& 1[\max\{\sup_{a\in Sx}d_q(a,Ty),\sup_{b\in Ty}d_q(Sx,b)\}] \\ &=& \max\{\sup_{a\in Sx}d_q(a,[\frac{y}{4},\frac{3y}{4}]),\sup_{b\in Ty}d_q([\frac{x}{3},\frac{2x}{3}],b)\} \\ &=& \max\{d_q(\frac{2x}{3},[\frac{y}{4},\frac{3y}{4}]),d_q([\frac{x}{3},\frac{2x}{3}],\frac{3y}{4})\} \\ &=& \max\{d_q(\frac{2x}{3},\frac{y}{4}),d_q(\frac{x}{3},\frac{3y}{4})\} \\ &=& \max\{\frac{2x}{3}+\frac{y}{4},\frac{x}{3}+\frac{3y}{4}\} \\ &\leq& \psi(\max\{x+y,\frac{4x}{3},\frac{5y}{4}\})=\psi(D_q(x,y)). \end{split}$$

$$\begin{array}{lll} \text{Case 4. If } \max\{\alpha_*(x,Sx)H_{d_q}(Sx,Ty),\,\alpha_*(y,Ty)H_{d_q}(Ty,Sx)\} &= \alpha_*(y,Ty)H_{d_q}(Ty,Sx),\,\text{then we have} \\ &\alpha_*(y,Ty)H_{d_q}(Ty,Sx) &= 1[\max\{\sup_{b\in Ty}d_q([\frac{x}{3},\frac{2x}{3}],b),\sup_{a\in Sx}d_q(a,[\frac{y}{4},\frac{3y}{4}])\} \\ &= \max\{\sup_{b\in Ty}d_q([\frac{x}{3},\frac{2x}{3}],\frac{3y}{4}),d_q(\frac{2x}{3},[\frac{y}{4},\frac{3y}{4}])\} \\ &= \max\{d_q([\frac{x}{3},\frac{3y}{4}),d_q(\frac{2x}{3},\frac{y}{4})\} \\ &= \max\{d_q(\frac{x}{3},\frac{3y}{4}),d_q(\frac{2x}{3},\frac{y}{4})\} \\ &= \max\{\frac{x}{3}+\frac{3y}{4},\frac{2x}{3}+\frac{y}{4}\} \\ &\leq \psi(\max\{y+x,\frac{5y}{4},\frac{4x}{3}\}) = \psi(D_q(y,x)). \end{array}$$

So the contractive condition holds on $\overline{B_{d_q}(x_0,r)} \cap \{TS(x_n)\}$. Also

$$\sum_{i=0}^{n} \max\{\psi^{i}(d_{q}(x_{1}, x_{0}), \psi^{i}(d_{q}(x_{0}, x_{1}))\} = \frac{4}{3} \sum_{i=0}^{n} (\frac{4}{5})^{i} < 8 = r.$$

Hence all the conditions of Theorem 2.1 are satisfied. Now we have $\{TS(x_n)\}$ is a sequence in $\overline{B_{d_q}(x_0,r)}$ and $\{TS(x_n)\} \to 0 \in \overline{B_{d_q}(x_0,r)}$. Also $\alpha(x_n,0) \ge 1$ or $\alpha(0,x_n) \ge 1$ for all $n \in \mathbb{N} \cup \{0\}$. Moreover, 0 is a common fixed point of S and T.

3. Fixed point results for graphic contractions

In this section, we present an application of Theorem 2.1 in graph theory. Jachymski [15] proved the contraction principle for mappings on a metric space with a graph. Let (X,d) be a metric space and \triangle represent the diagonal of the cartesian product $X \times X$. Assume that G is a directed graph and V(G) is the set of vertices along with X and the set E(G) denotes the edges of X included all loops, i.e., $E(G) \supseteq \triangle$. If G has no parallel edges, then we can unify G with pair (V(G), E(G)). Furthermore, we consider G as a weighted graph (see [15]) which showing to each edge the distance between its vertices. If I and I are the vertices in a graph I then a path in I from I to I of length I is a sequence I and I is a sequence I and I vertices such that $I_{O} = I$, $I_{N} = I$ and I_{N-1} , $I_{N-1} \in E(G)$ where I is a sequence I is a sequence I is connected if there is a path between any two vertices (for more details, see [9, 14, 28]).

Definition 3.1. Let X be a nonempty set and G = (V(G), E(G)) be a graph such that V(G) = X. Then $S: X \to CB(X)$ is said to be semi graph dominated on $A \subseteq X$ if, for each $x \in A$, $(x, y) \in E(G)$ for all $y \in Sx$. If A = X, then we say that S is graph dominated on X.

Theorem 3.2. Let (X, d_q) be a complete dislocated quasi metric space endowed with a graph G. Let r > 0, $x_0 \in \overline{B_{d_q}(x_0, r)}$, $S, T : X \to P(X)$ mappings and $\{TS(x_n)\}$ be a sequence in X generated by x_0 . Assume that the following hold:

- (i) S and T are semi graph dominated on $B_{d_q}(x_0, r)$;
- (ii) there exists $\psi \in \Psi$ and $D_q(x,y) = \max\{d_q(x,y), d_q(x,Sx), d_q(y,Ty)\}$ such that

$$\max \{H_{d_q}(Sx, Ty), H_{d_q}(Ty, Sx)\} \le \min\{\psi(D_q(x, y)), \psi(D_q(y, x))\}$$
(3.1)

for all $x, y \in \overline{B_{d_q}(x_0, r)} \cap \{TS(x_n)\}$ with $(x, y) \in E(G)$ or $(y, x) \in E(G)$;

(iii) $\sum_{i=0}^{n} \max\{\psi^{i}(d_{q}(x_{1}, x_{0}), \psi^{i}(d_{q}(x_{0}, x_{1}))\} \leq r \text{ for all } n \in \mathbb{N} \cup \{0\}.$

Then $\{TS(x_n)\}\$ is a sequence in $\overline{B_{d_q}(x_0,r)}$ and $\{TS(x_n)\} \to x^*$. Also if $(x_n,x^*) \in E(G)$ or $(x^*,x_n) \in E(G)$ for all $n \in \mathbb{N} \cup \{0\}$ and (3.1) holds for x^* , then S and T have a common fixed point x^* in $\overline{B_{d_q}(x_0,r)}$.

Proof. Define $\alpha: X \times X \to [0, \infty)$ by

$$\alpha(x,y) = \begin{cases} 1, & \text{if } x \in \overline{B_{d_q}(x_0,r)}, \ (x,y) \in E(G) \text{ or } (y,x) \in E(G) \\ 0, & \text{otherwise.} \end{cases}$$

Since S and T are semi graph dominated on $\overline{B_{d_q}(x_0,r)}$, for $x\in \overline{B_{d_q}(x_0,r)}$, $(x,y)\in E(G)$ for all $y\in Sx$ and $(x,y)\in E(G)$ for all $y\in Tx$. So $\alpha(x,y)=1$ for all $y\in Sx$ and $\alpha(x,y)=1$ for all $y\in Tx$. This implies that $\inf\{\alpha(x,y):y\in Sx\}=1$ and $\inf\{\alpha(x,y):y\in Tx\}=1$. Hence $\alpha_*(x,Sx)=1$, $\alpha_*(x,Tx)=1$ for all $x\in \overline{B_{d_q}(x_0,r)}$. So $S,T:X\to P(X)$ are semi α_* -dominated mappings on $\overline{B_{d_q}(x_0,r)}$. Moreover, (3.1) can be written as

$$\max\{\alpha_*(x, Sx)H_{dq}(Sx, Ty), \alpha_*(y, Ty)H_{dq}(Ty, Sx)\} \le \min\{\psi(D_q(x, y)), \psi(D_q(y, x))\}$$

for all x, y in $\overline{B_{d_q}(x_0, r)} \cap \{TS(x_n)\}$ with either $\alpha(x, y) \geq 1$ or $\alpha(y, x) \geq 1$. Also (iii) holds. Then, by Theorem 2.1, we have $\{TS(x_n)\}$ is a sequence in $\overline{B_{d_q}(x_0, r)}$ and $\{TS(x_n)\} \to x^* \in \overline{B_{d_q}(x_0, r)}$. Now $x_n, x^* \in \overline{B_{d_q}(x_0, r)}$ and either $(x_n, x^*) \in E(G)$ or $(x^*, x_n) \in E(G)$ implies that either $\alpha(x_n, x^*) \geq 1$ or $\alpha(x^*, x_n) \geq 1$. So all the conditions of Theorem 2.1 are satisfied. Hence by Theorem 2.1, S and T have a common fixed point x^* in $\overline{B_{d_q}(x_0, r)}$ and $d_q(x^*, x^*) = 0$.

References

- [1] A. Ahmed, N. Abdou, Common fixed point results for multivalued mappings with some examples, J. Nonlinear Sci. Appl. 9 (2016), 787–798.
- [2] M. Ali, T. Kamran, E. Karapınar, Further discussion on modified multivalued α^* - ψ -contractive type mapping, Filomat **29** (2015), 1893–1900.
- [3] M. Arshad, A. Azam, M. Abbas, A. Shoaib, Fixed point results of dominated mappings on a closed ball in ordered partial metric spaces without continuity, Politehn. Univ. Bucharest Sci. Bull., Ser. A Appl. Math. Phys. 76 (2014). 123–134.
- [4] M. Arshad, A. Shoaib, M. Abbas, A. Azam, Fixed points of a pair of Kannan type mappings on a closed ball in ordered partial metric spaces, Miskolc Math. Notes 14 (2013), 769–784.
- [5] M. Arshad, A. Shoaib, P. Vetro, Common fixed points of a pair of Hardy-Rogers type mappings on a closed ball in ordered dislocated metric spaces, J. Funct. Spaces 2013 (2013), Article ID 63818.
- [6] J. H. Asl, S. Rezapour, N. Shahzad, On fixed points of α - ψ contractive multifunctions, Fixed Point Theory Appl. **2012**, 2012:212.
- [7] A. Azam, M. Arshad, Fixed points of a sequence of locally contractive multi-valued maps, Comp. Math. Appl. 57 (2009), 96–100.
- [8] I. Beg, M. Arshad, A. Shoaib, Fixed point on a closed ball in ordered dislocated metric space, Fixed Point Theory 16 (2015), 195–206.
- [9] F. Bojor, Fixed point theorems for Reich type contraction on metric spaces with a graph, Nonlinear Anal. **75** (2012), 3895–3901.
- [10] M. F. Bota, C. Chifu, E. Karapinar, Fixed point theorem for generalized $(\alpha_* \psi)$ Ciric-type contractive multivalued operator in b-metric spaces, J. Nonlinear Sci. Appl. 9 (2016), 1165–1177.
- [11] P. Hitzler, A. K. Seda, Dislocated topologies, J. Electrical Engineering 51 (2000), No. 12, 3-7.
- [12] N. Hussain, J. Ahmad, A. Azam, Generalized fixed point theorems for multi-valued α - ψ -contractive mappings, J. Inequal. Appl. **2014**, 2014:348.
- [13] N. Hussain, S. Al-Mezel, P. Salimi, Fixed points for ψ -graphic contractions with application to integral equations, Abstr. Appl. Anal. **2013** (2013), Article ID 575869.
- [14] N. Hussain, M. Arshad, A. Shoaib, Fahimuddin, Common fixed point results for α - ψ -contractions on a metric space endowed with graph, J. Inequal. Appl. **2014**, 2014:136.

- [15] J. Jachymski, The contraction principle for mappings on a metric space with a graph, Proc. Am. Math. Soc. 136 (2008), 1359–1373.
- [16] S. G. Matthews, Partial metric topology, in: Proc. 8th Summer Conference on General Topology and Applications, in: Ann. New York Acad. Sci. 728 (1994), pp. 183–197.
- [17] E. Karapınar, H. Piri, H. H. Alsulami, Fixed points of modified F-contractive mappings in complete metric-like spaces, J. Funct. Spaces 2015 (2015), Article ID 270971.
- [18] E. Karapınar, İ.M. Erhan, A. Öztürk, Fixed point theorems on quasi-partial metric spaces, Math. Comp. Modelling 57 (2013), 2442–2448.
- [19] M. S. Khan, Common fixed point theorems for multivalued mappings, Pacific J. Math. 95 (1981), 337–347.
- [20] Jr. Nadler, Multi-valued contraction mappings. Pacific J. Math. 30) (1969), 475-478.
- [21] M. Sarwar, M. U. Rahman, G. Ali, Some fixed point results in dislocated quasi metric (dq-metric) spaces, J. Inequal. Appl. 2014, 2014:278.
- [22] T. Senapati, L. K. Dey, Common fixed point theorems for multivalued β_* - ψ -contractive mappings, Thai J. Math. (in press).
- [23] A. Shoaib, α - η dominated mappings and related common fixed point results in closed ball, J. Concrete Appl. Math. 13 (2015), 152–170.
- [24] A. Shoaib, Fixed point results for α_* - ψ -multivalued mappings on an intersection of a closed ball and a sequence endowed with a graph, Bull. Math. Anal. Appl. (in press).
- [25] A. Shoaib, M. Arshad, J. Ahmad, Fixed point results of locally cotractive mappings in ordered quasi-partial metric spaces, Scientific World J. 2013 (2013), Article ID 194897.
- [26] A. Shoaib, M. Arshad, M. A. Kutbi, Common fixed points of a pair of Hardy Rogers type mappings on a closed ball in ordered partial metric spaces, J. Comput. Anal. Appl. 17 (2014), 255–264.
- [27] A. Shoaib, A. Hussain, M. Arshad, A. Azam, Fixed point results for α_* - ψ -Ciric type multivalued mappings on an intersection of a closed ball and a sequence with graph, J. Math. Anal. 7 (2016), 41–50.
- [28] J. Tiammee, S. Suantai, Coincidence point theorems for graph-preserving multi-valued mappings, Fixed Point Theory Appl. 2014, 2014;70.
- [29] B. R. Wadkar, R. Bhardawaj, B. K.Singh, A common fixed point theorem in dislocared metric space, Int. J. Engg Research Devolpment 10 (2014), 14–17.
- [30] F. M. Zeyada, G. H. Hassan, M. A. Ahmed, A generalization of a fixed point theorem due to Hitzler and Seda in dislocated quasi-metric spaces, Arabian J. Sci. Eng. A 31 (2006), 111–114.
- [31] L. Zhu, C. Zhu, C. Chen, Z. Stojanović, Multidimensional fixed points for generalized Ψ-quasi-contractions in quasi-metric-like spaces, J. Inequal. Appl. **2014**, 2014:27.

Tahair Rasham

DEPARTMENT OF MATHEMATICS, INTERNATIONAL ISLAMIC UNIVERSITY, H-10, ISLAMABAD-44000, PAKISTAN E-mail address: tahir.resham@yahoo.com

Abdullah Shoaib

DEPARTMENT OF MATHEMATICS AND STATISTICS, RIPHAH INTERNATIONAL UNIVERSITY, ISLAMABAD-44000, PAKISTAN E-mail address: abdullahshoaib15@yahoo.com

CHOONKIL PARK

RESEARCH INSTITUTE FOR NATURAL SCIENCES, HANYANG UNIVERSITY, SEOUL 04763, REPUBLIC OF KOREA E-mail address: baak@hanyang.ac.kr

Muhammad Arshad

DEPARTMENT OF MATHEMATICS, INTERNATIONAL ISLAMIC UNIVERSITY, H-10, ISLAMABAD-44000, PAKISTAN E-mail address: marshad.zia@yahoo.com

TABLE OF CONTENTS, JOURNAL OF COMPUTATIONAL ANALYSIS AND APPLICATIONS, VOL. 25, NO. 5, 2018

Woo Jang, and Jongkyum Kwon,
Higher order generalization of Bernstein type operators defined by (p,q)-integers, M. Mursaleen, Md. Nasiruzzaman, Nurgali Ashirbayev, and Azimkhan Abzhapbarov,817
Fourier series of functions involving Genocchi polynomials, Taekyun Kim, Dae San Kim, Lee Chae Jang, and Dmitry V. Dolgy,
Lyapunov inequalities of quasi-Hamiltonian systems on time scales, Taixiang Sun, Fanping Zeng, Guangwang Su, and Bin Qin,
A new three-step iterative method for a countable family of pseudo-contractive mappings in Hilbert spaces, Qin Chen, Li Li, Nan Lin, and Baoguo Chen,
Harmonic analysis in the product of commutative hypercomplex systems, Hossam A. Ghany,876
Nonlinear delay fractional difference equations with applications on discrete fractional Lotka–Volterra competition model, J. Alzabut, T. Abdeljawad, and D. Baleanu,
Some sharp results on NLC-operators in G_p -metric spaces, Huaping Huang, Ljiljana Gajic, Stojan Radenovic, and Guantie Deng,
Most general Self Adjoint Operator Chebyshev-Grüss Inequalities, George A. Anastassiou,915
Fourier series of sums of products of poly-Bernoulli and Genocchi functions and their applications, Taekyun Kim, Dae San Kim, Lee Chae Jang, and Gwan-Woo Jang,934
Convergence of the Newton-HSS Method under the Lipschitz Condition with the L-average, Hong-Xiu Zhong, Guo-Liang Chen, and Xue-Ping Guo,
Oscillation for Fractional Neutral Functional Differential Systems, Yong Zhou, Ahmed Alsaedi, and Bashir Ahmad,965
Fixed point results for a pair of multi dominated mappings on a smallest subset in K-sequentially dislocated quasi metric space with an application, Tahair Rasham, Abdullah Shoaib, Choonkil Park, and Muhammad Arshad